Lecture 27: Pointer Analysis, Storage Management

Today

- Points-to analysis: an instance of static analysis for understanding pointers [Based on slides from R. Bodik].
- Andersen's algorithm via deduction
- Storage Managment and Garbage Collection

General Goals of Static Analysis

- Determine run-time properties statically at compilation.
- Sample property: "is variable x a constant?"
- Since we don't know the inputs, must consider all possible program executions.
- Conservative (err on the side of caution) for *soundness:*
  - allowed to say x is not a constant when it is,
  - but not that x is a constant when it is not .
- Many clients: optimization, verification, compilation.

Client 1: Optimizing virtual calls in Java

- Motivation: virtual calls are costly, due to method dispatch
- Idea:
  - determine the target of the call statically
  - if we can prove call has a single target method, call the target directly
- declared (static) types of pointer variables not precise enough for this, so, analyze their run-time (dynamic) types.

Client 1: Example

```
class A                 { void foo() {...} }
class B extends A       { void foo() {...} }
void bar(A a)           { a.foo() }  // OK to just call B.foo?
B myB = new B();
A myA = myB;
bar(myA);
```

- Declared type of a permits a.foo() to target both A.foo and B.foo.
- Yet we know only B.foo is the target.
- What program property would reveal this fact?

Client 2: Verification of casts

- In Java, casts are checked at run time: (Foo) e translates to

```
if (! (e instanceof Foo))
    throw new ClassCastException()
```

- Java generics help readability, but still cast.
- The exception prevents any security holes, but is expensive.
- Static verification useful to catch bugs.
- Goal: prove that no exception will happen at runtime

Client 2: Example

```
class SimpleContainer { Object a;
    void put (Object o) { a=o; }
    Object get() { return a; }   }
SimpleContainer c1 = new SimpleContainer();
SimpleContainer c2 = new SimpleContainer();
c1.put(new Foo()); c2.put(``Hello'');
Foo myFoo = (Foo) c1.get(); // Check not needed
```

What property will lead to desired verification?

Client 3: Non-overlapping fields in heap

```
E = new Thing (42);
for (j = 0; j < D.len; j += 1) {
    if (E.len >= E.max)) throw new OverflowException ();
    E.data[E.len] = D.data[i];  E.len += 1;
}
```

We assign to E.len, but we don't have to fetch from D.len every time; can save in register.

Pointer Analysis

- To serve these three clients, want to understand how pointers "flow," that is, how they are copied from variable to variable.
- Interested in flow from *producers* of objects (new Foo) to *users* (myFoo.f).
- Complication: pointers may flow via the heap: a pointer may be stored in an object's field and later be read from this field.
- For simplicity, assume we are analyzing Java without reflection, so that we know all fields of an object at compile time.

Analyses

- Client 1: virtual call optimization:
  - which producer expressions new T() produced the values that may flow to receiver p (a consumer) in a call?
  - Knowing producers tells us possible dynamic types of p, and thus also the set of target methods.
- Client 2: cast verification:
  - Same, but producers include expressions (Type) p.
- Client 3: non-overlapping fields: again, same question

Flow analysis as a constant propagation

- Initially, consider only new and assignments p=r:

```
if (...) p = new T1(); else p = new T2();
r = p; r.f();  // what are possible dynamic types of r?
```

- We (conceptually) translate the program to

```
if (...) p = o1; else p = o2;
r = p; r.f();  // what are possible symbolic constant values r?
```

Abstract objects

- The o_i constants are called abstract objects
- an abstract object o_i stands for any and all concrete objects allocated at the *allocation site* ('new' expression) with number i.
- When the analysis says a variable p may have value o_7,
- we know p may point to any object allocated at

  $\texttt{new}_7$ `Foo()`

Flow analysis: Add pointer dereferences

```
x = new Obj();      // o1
z = new Obj();      // o2
w = x;
y = x;
y.f = z;
v = w.f;
```

- To propagate the abstract objects through p.f, must keep track of the *heap state*—where the pointers point:
  - y and w point to same object
  - z and y.f point to same object, etc.

Flow-Insensitive Analysis

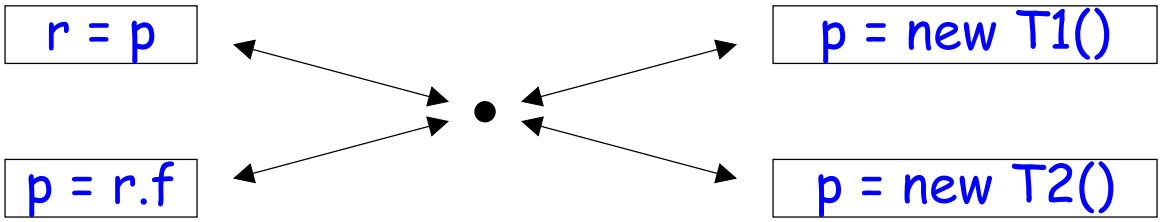
- The heap state may change at each statement, so ideally, track the heap state separately at each program point as in dataflow analysis.
- But to be scalable (i.e. practical), analyses typically don't do it.
- For example, to save space, can collapse all program points into one consequently, they keep a single heap state, and disregard the control flow of the program (*flow-insensitive* analysis):

  assume that statements can execute in any order, and any number of times

- So, flow-insensitive analysis transforms this program

```
if (...) p = new T1(); else p = new T2();
r = p; p = r.f;
```

into this CFG:



Flow-Insensitive Analysis, contd.

- Motivation: Just "version" of program state, hence less space
- Flow-insensitive analysis is *sound,* assuming we mean that *at least* all possible values of pointer from all possible executions found
- But it is generally *imprecise*:
  - In effect, adds many executions not present in the original program;
  - Does not distinguish value of p at various program points.

Canonical Statements

- Java pointers can be manipulated in complex statements, such as

  p.f().g.arr[i] = r.f.g(new Foo()).h

- To keep complexity under control, prefer a small set of *canonical statements* that accounts for everything our analysis needs to serve as intermediate representation:

```
p = new T()     new
p = r           assign
p = r.f         getfield
p.f = r         putfield
```

- Complex statements can be canonicalized

  p.f.g = r.f $\Longrightarrow$ t1 = p.f; t2 = r.f; t1.g = t2

- Can be done with a syntax-directed translation

Handling of method calls: Arguments and return values

- Translate calls into assignments. For example,

```
Object foo(T x) { return x.f }
r = new T; s = foo(r.g)
```

  could translate to

```
foo_retval = x.f;
r = new T; x = r.g; s = foo_retval;
```

  (have used flow-insensitivity: order irrelevant)

Handling of method calls: targets of virtual calls

- Call p.f() may call many possible methods
- To do the translation shown on previous slide, must determine what these targets are
- Suggest two simple methods:
  - Use declared type of p.
  - Check whole program to see which types are actually instantiated.

Handling of method calls: arrays

- We collapse all array elements into one.
- Represent this single element by a field named arr, so

  p.g[i] = r becomes p.g.arr = r

Andersen's Algorithm for flow-insensitive points-to analysis

- Goal: computes a binary relation between variables and abstract objects:

  o flowsTo x when abstract object o may be assigned to x.

- (Or, if you prefer, x pointsTo o.)
- Strategy: Deduce the flowsTo relation from program statements:
  - Statements are facts.
  - Analysis is a set of inference rules.
  - flowsTo relation is a set of facts inferred with analysis rules.

Statement facts

We'll write facts in the form x *predicate* y

`p = new`$_i$ `T()` $\Longrightarrow o_i$ *new p*

`p = r` $\Longrightarrow$ *r assign p*

`p = r.f` $\Longrightarrow$ *r gf(f) p* (get field)

`p.f = r` $\Longrightarrow$ *r pf(f) p* (put field)

and apply these *inference rules*:

- Rule 1) o_i *new p* $\Rightarrow$ o_i *flowsTo* p
- Rule 2) o_i *flowsTo r* $\wedge$ *r assign p* $\Rightarrow$ o_i *flowsTo p*
- Rule 3) o_i *flowsTo a* $\wedge$ *a pf(f) p* $\wedge$ *p alias r* $\wedge$ *r gf(f) b* $\Rightarrow$ o_i *flowsTo b*
- Rule 4) o_i *flowsTo x* $\wedge$ o_i *flowsTo y* $\Rightarrow$ *x alias y*

Meaning of the results

- When the analysis infers *o flowsTo y,* what did we prove?
- Nothing useful, usually, since *o flowsTo y* does not imply that there is a program input for which o will *definitely* flow to y.
- BUT the useful results are places where analysis *does not* infer that *o flowsTo y*:
- In those cases—because the analysis assumes conservatively that o flows to y if there appears to be any possibility of that happening—we can infer that not *o flowsTo y* for all inputs.
- Same arguments apply to alias, pointsTo relations and many other static analyses in general.

Inference Example

The program:

```
x = new Foo(); // o1
z = new Bar(); // o2
w = x;
y = x;
y.f = z;
v = w.f;
```

The six facts:

o_1 *new x*

o_2 *new z*

x assign w

x assign y

z pf(f) y

w gf(f) v

Sample inferences:

o_1 *new x* $\Rightarrow$ o_1 *flowsTo x*

o_2 *new z* $\Rightarrow$ o_2 *flowsTo z*

o_1 *flowsTo x* $\wedge$ *x assign w* $\Rightarrow$ o_1 *flowsTo w*

o_1 *flowsTo x* $\wedge$ *x assign y* $\Rightarrow$ o_1 *flowsTo y*

o_1 *flowsTo y* $\wedge$ o_1 *flowsTo w* $\Rightarrow$ *y alias w*

o_2 *flowsTo z* $\wedge$ *z pf(f) y* $\wedge$ *y alias w* $\wedge$ *w gf(f) v* $\Rightarrow$ o_2 *flowsTo v*

etc.

Inference Example, contd.

- The inference must continue until no more facts can be derived; only then do we know we have performed sound analysis.
- In this example:
  - We have inferred o_2 *flowsTo v*
  - But we have *not* inferred o_1 *flowsTo v*.
  - Hence we know *v* will point only to instances of *Bar* (assuming the example contains the whole program)
  - Thus, casts (Bar) v will succeed
  - Similarly, calls v.f() are optimizable.

New Topic: Storage Management and Garbage Collection

Storage Management

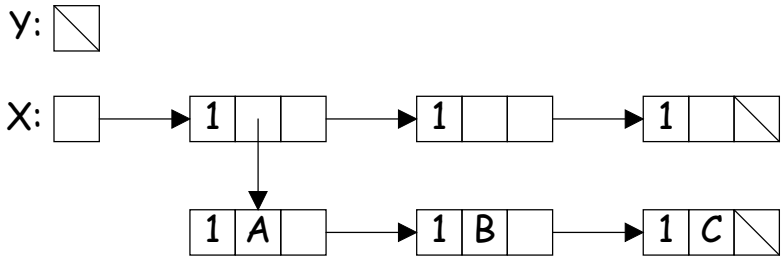
- Java has no means to free dynamic storage.
- However, when no expression in any thread can possibly be influenced by or change an object, it might as well not exist:

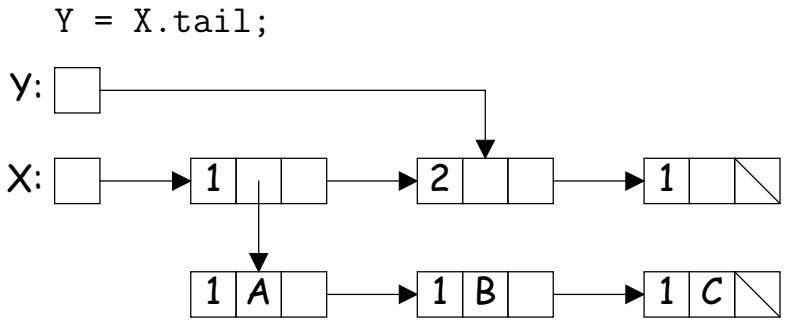
```
IntList wasteful ()
{
  IntList c = new IntList (3, new IntList (4, null));
  return c.tail;
  // variable c now deallocated, so no way
  // to get to first cell of list
}
```

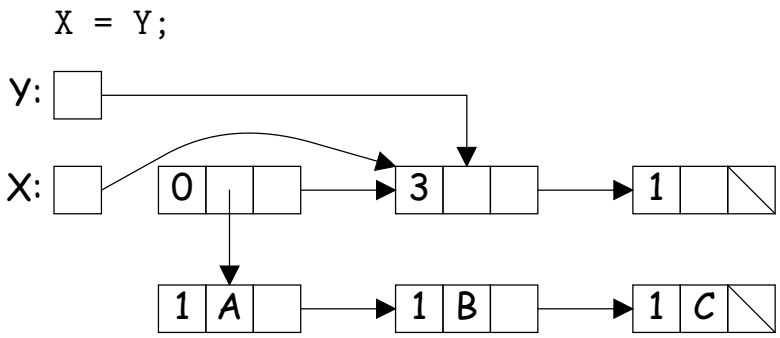
- At this point, Java runtime, like Scheme's, recycles the object `c` pointed to: *garbage collection*.

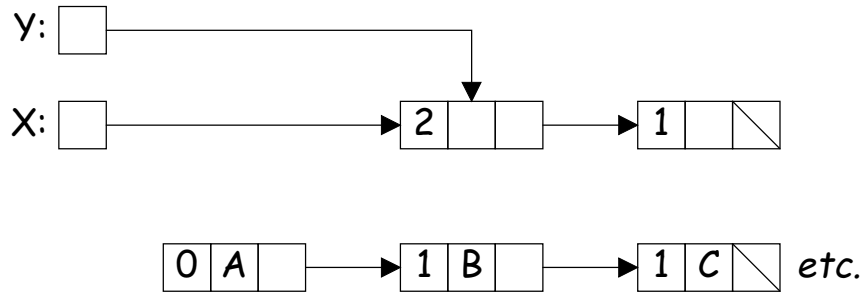
Garbage Collection: Reference Counting

- Idea: Keep count of number of pointers to each object.

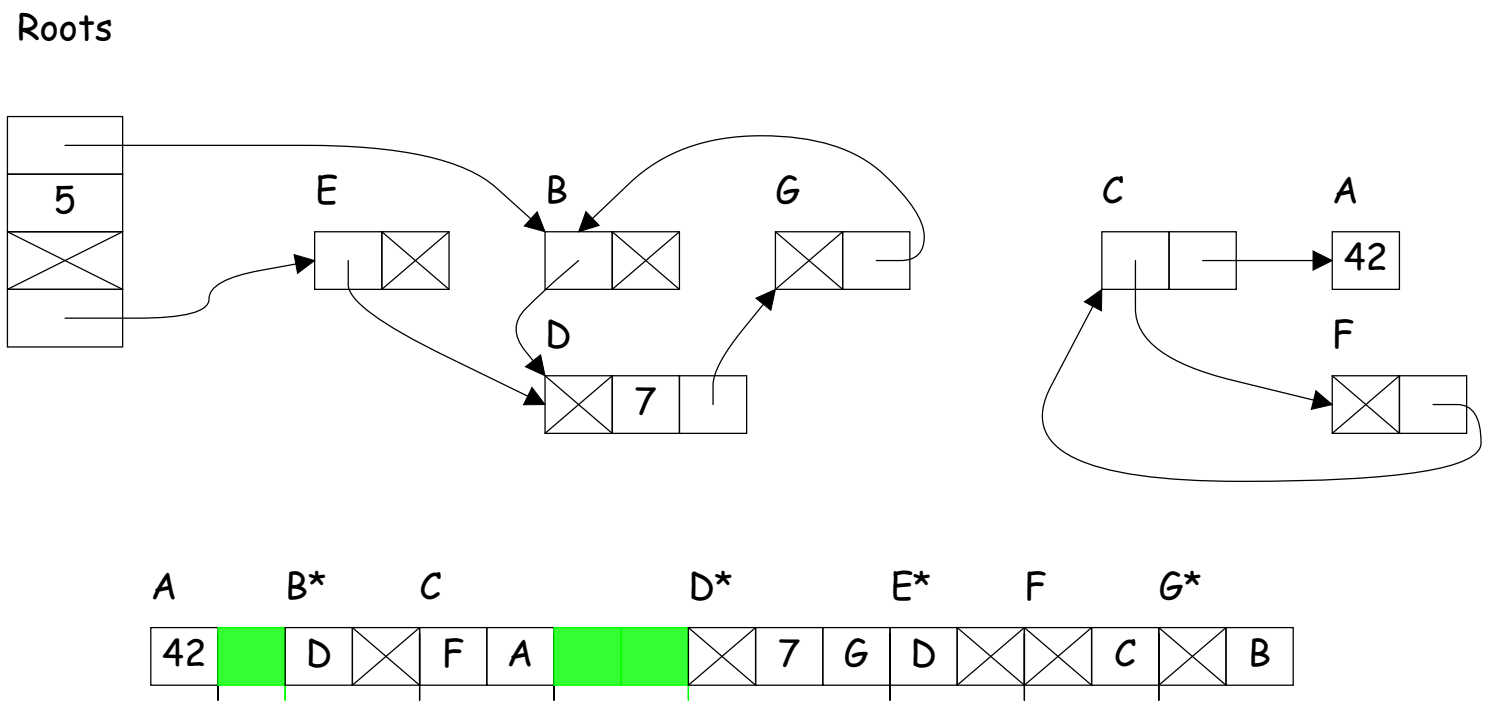








Garbage Collection: Mark and Sweep



- Start at roots (named variables, static and on stack)
- Perform graph traversal to find and mark all reachable storage.
- Sweep over memory, adding all unmarked storage to free list.

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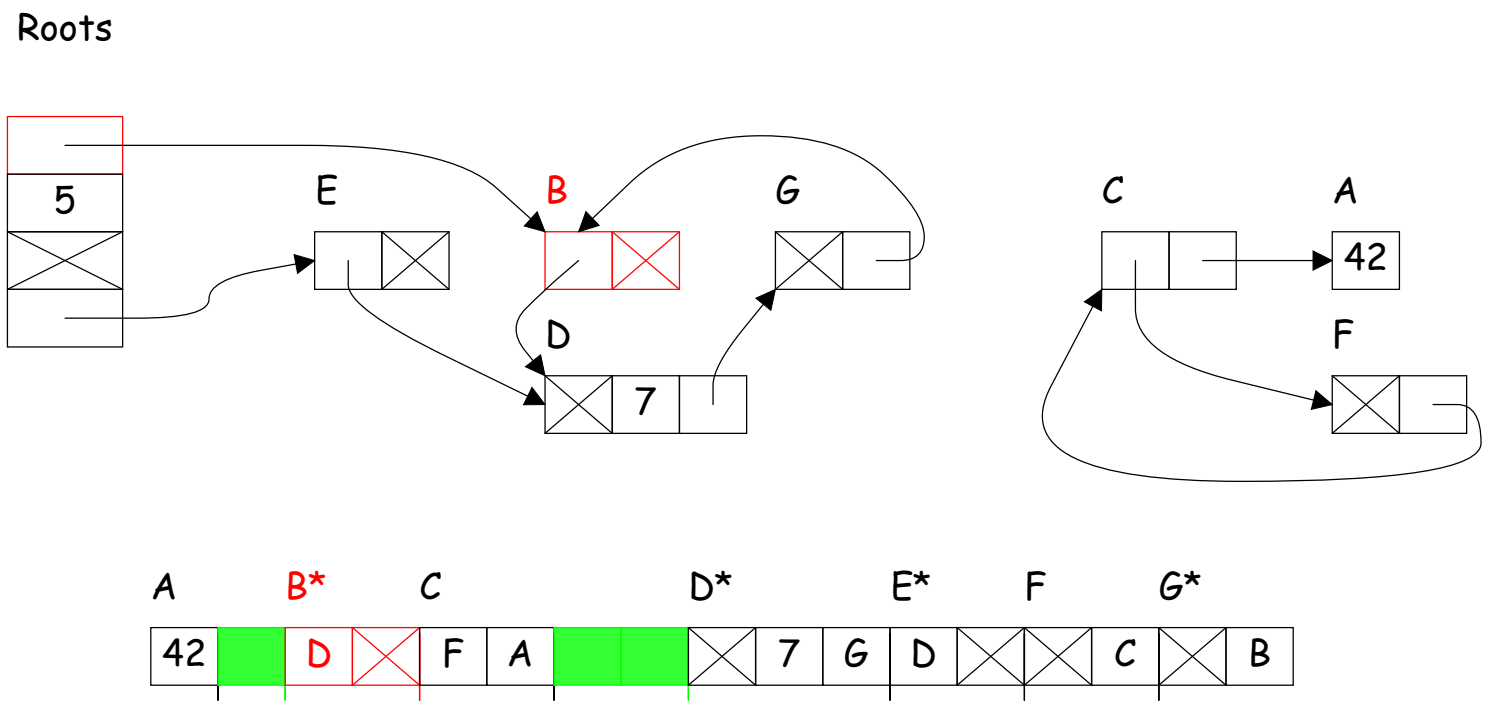

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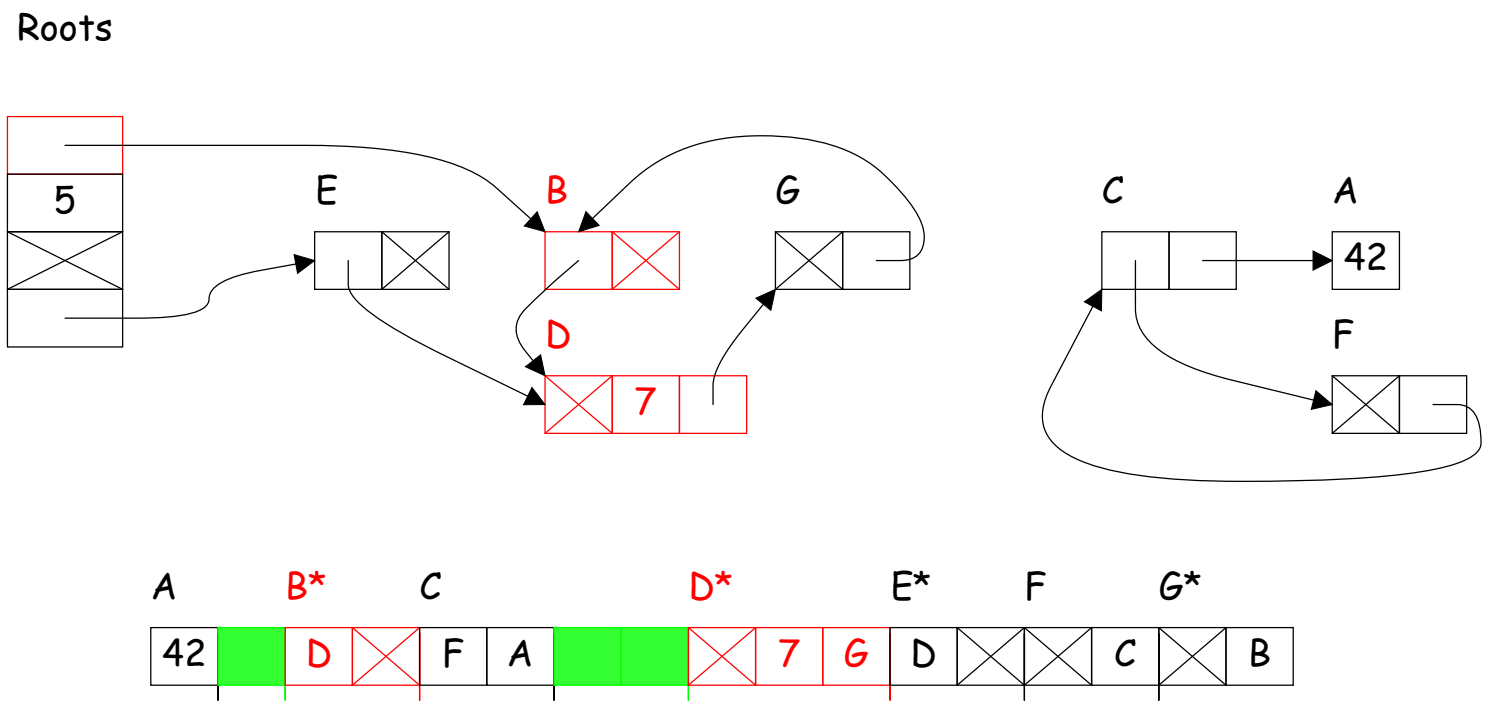

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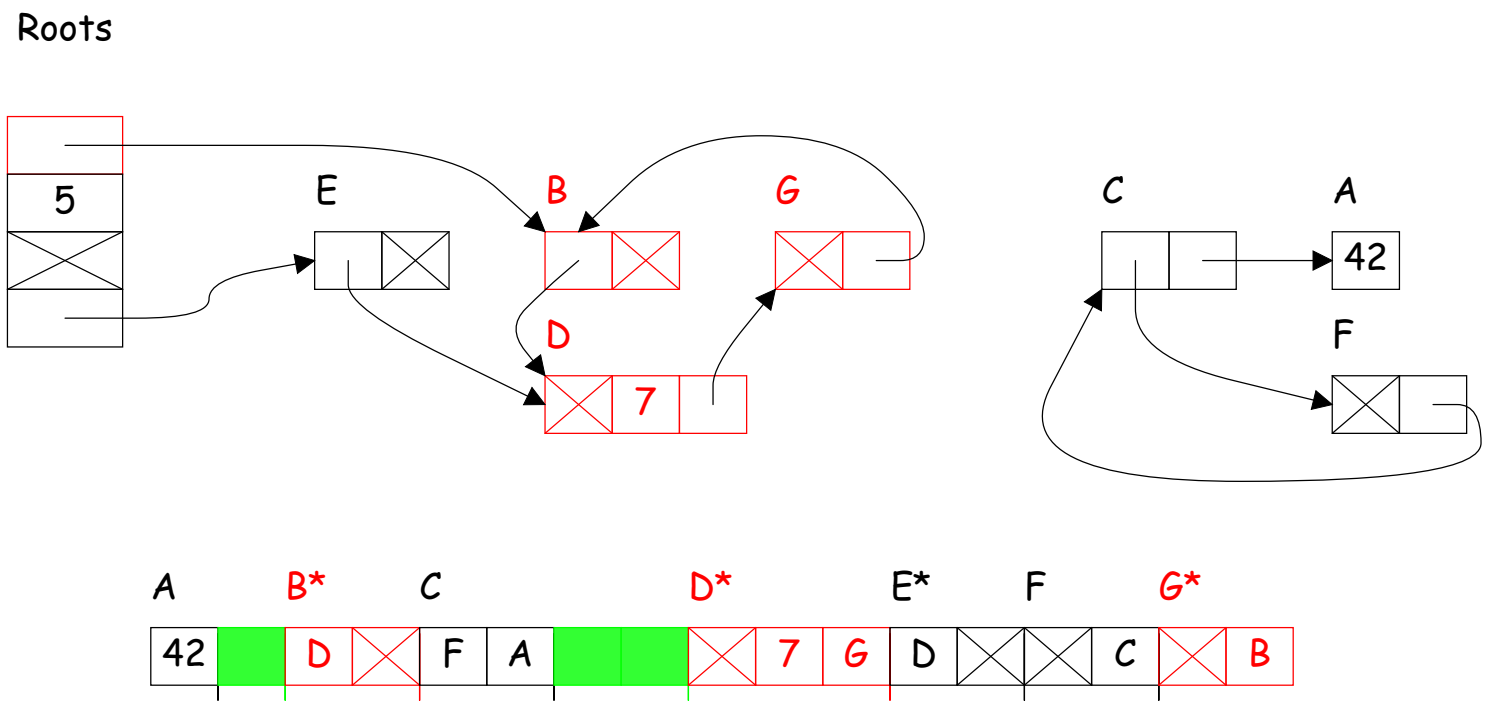

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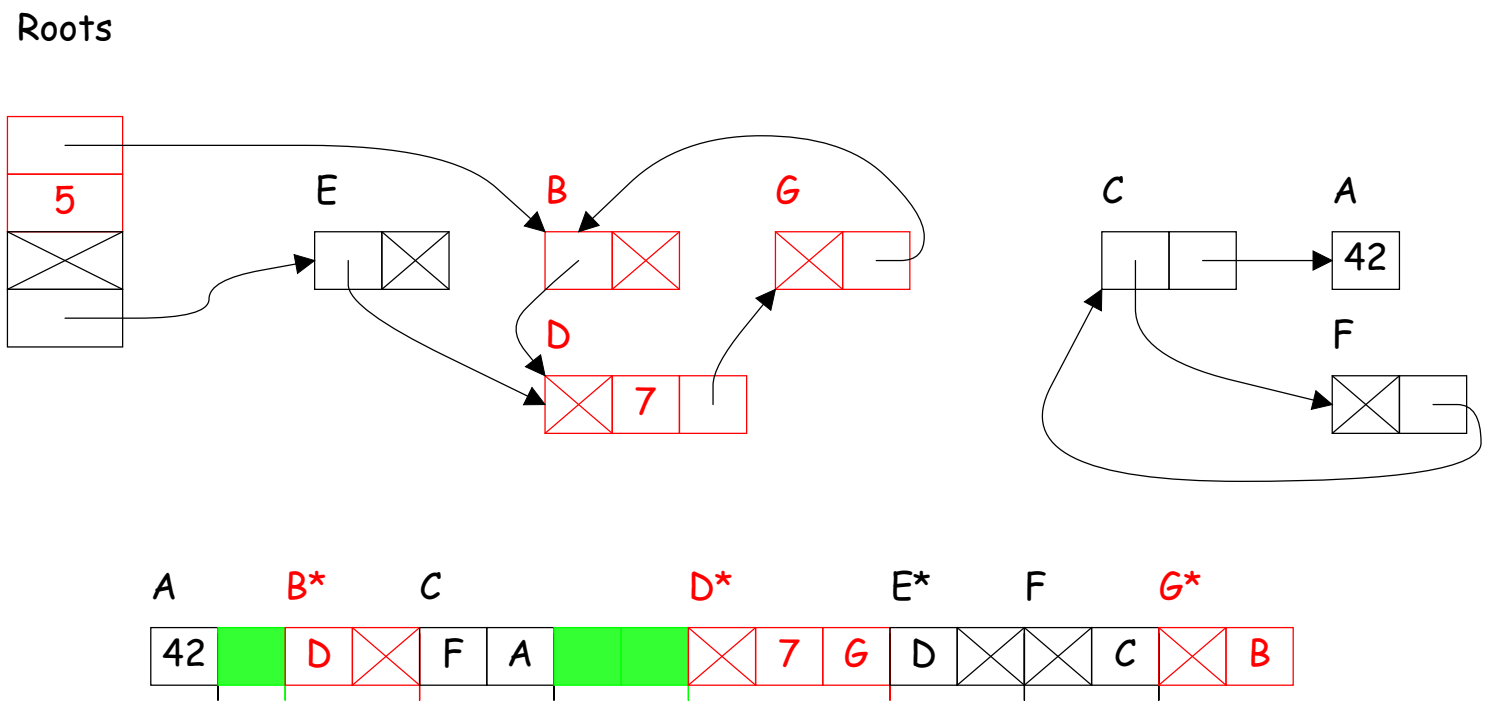

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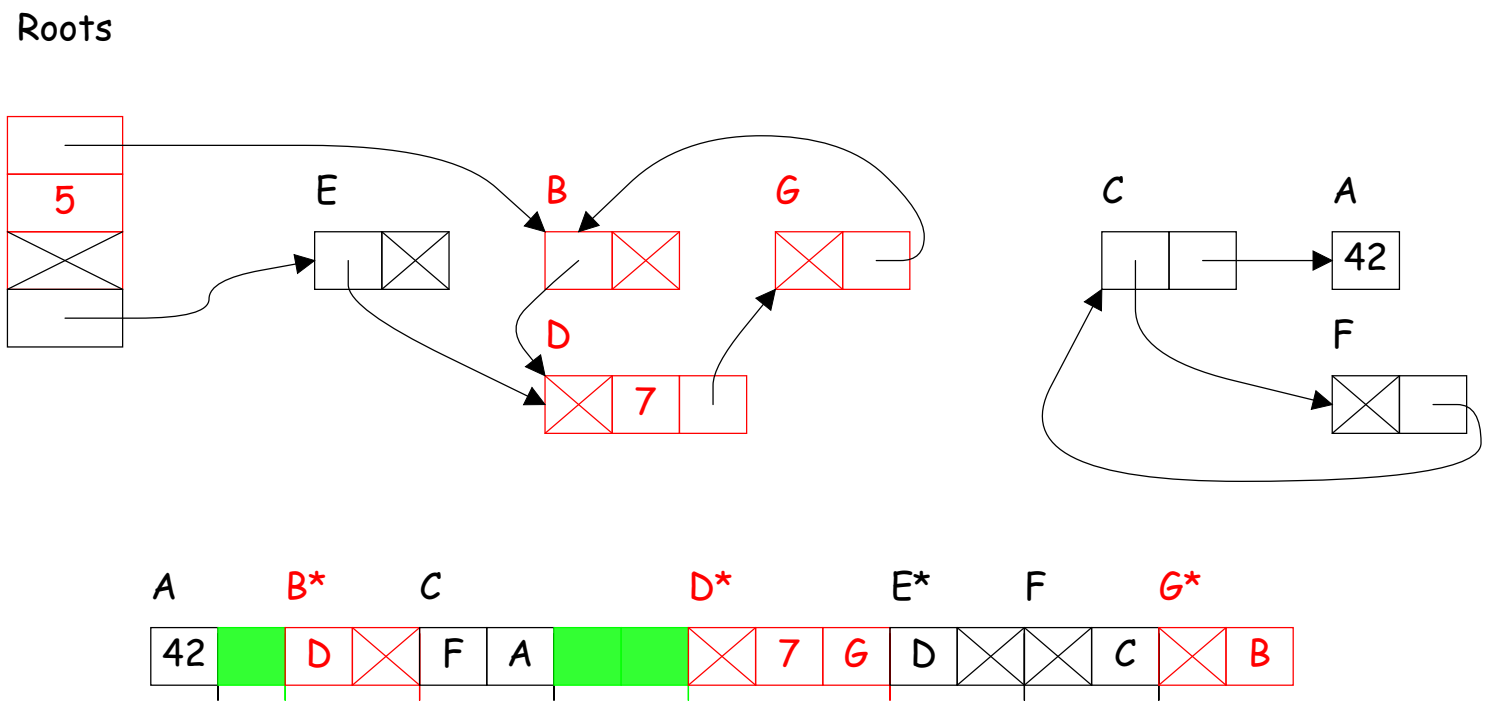

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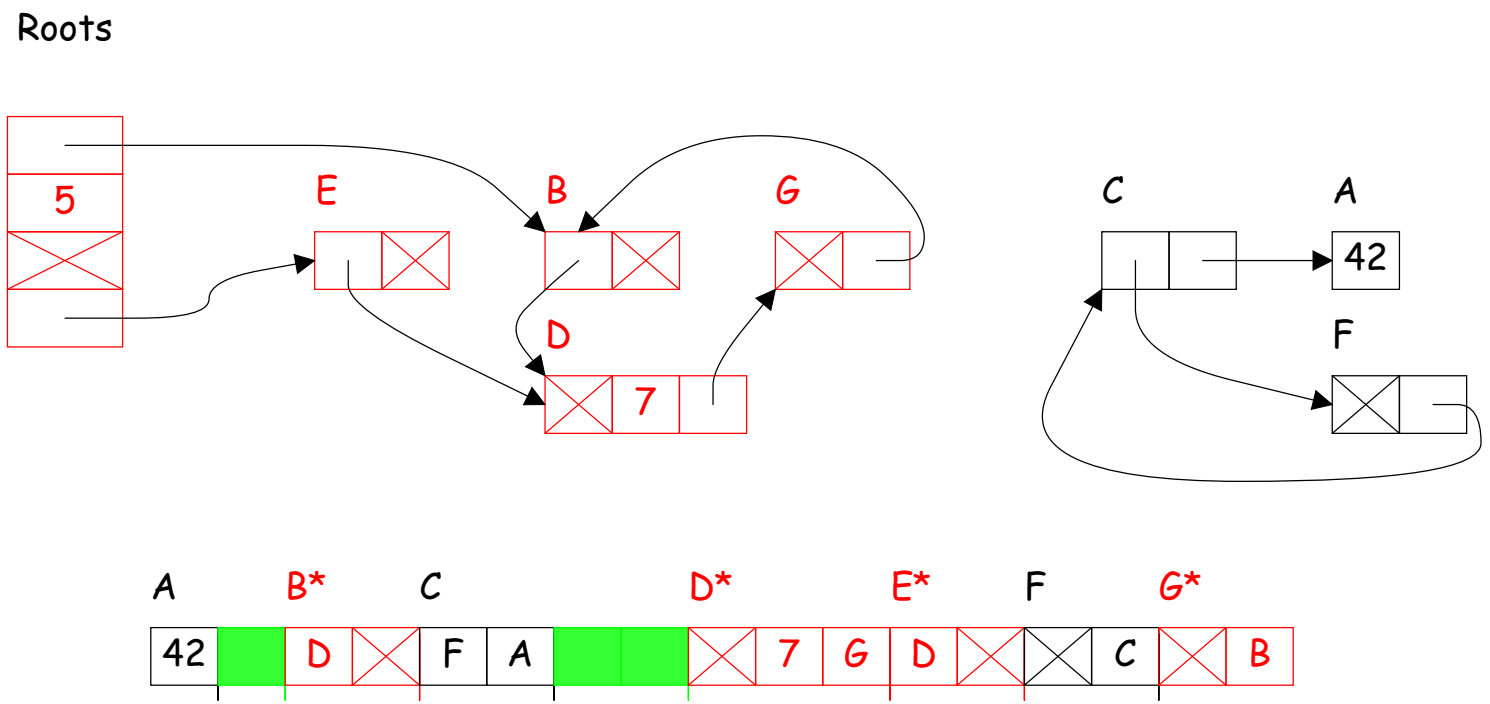

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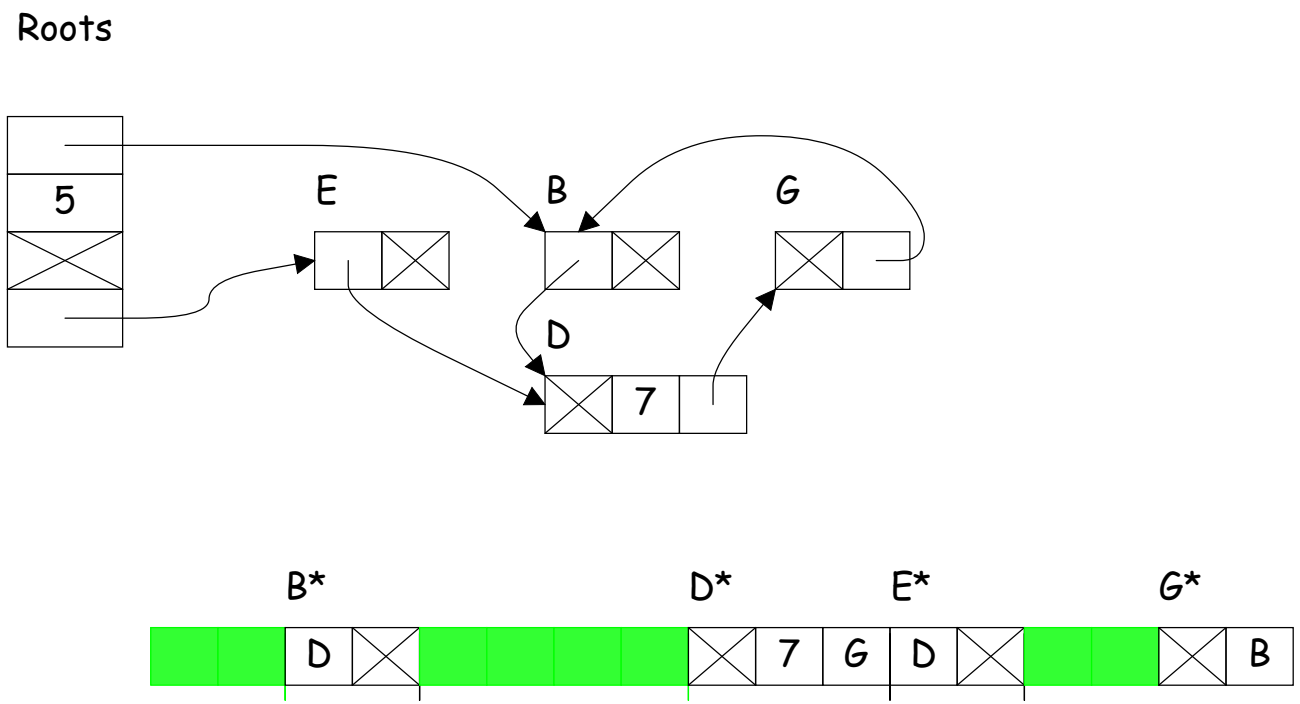

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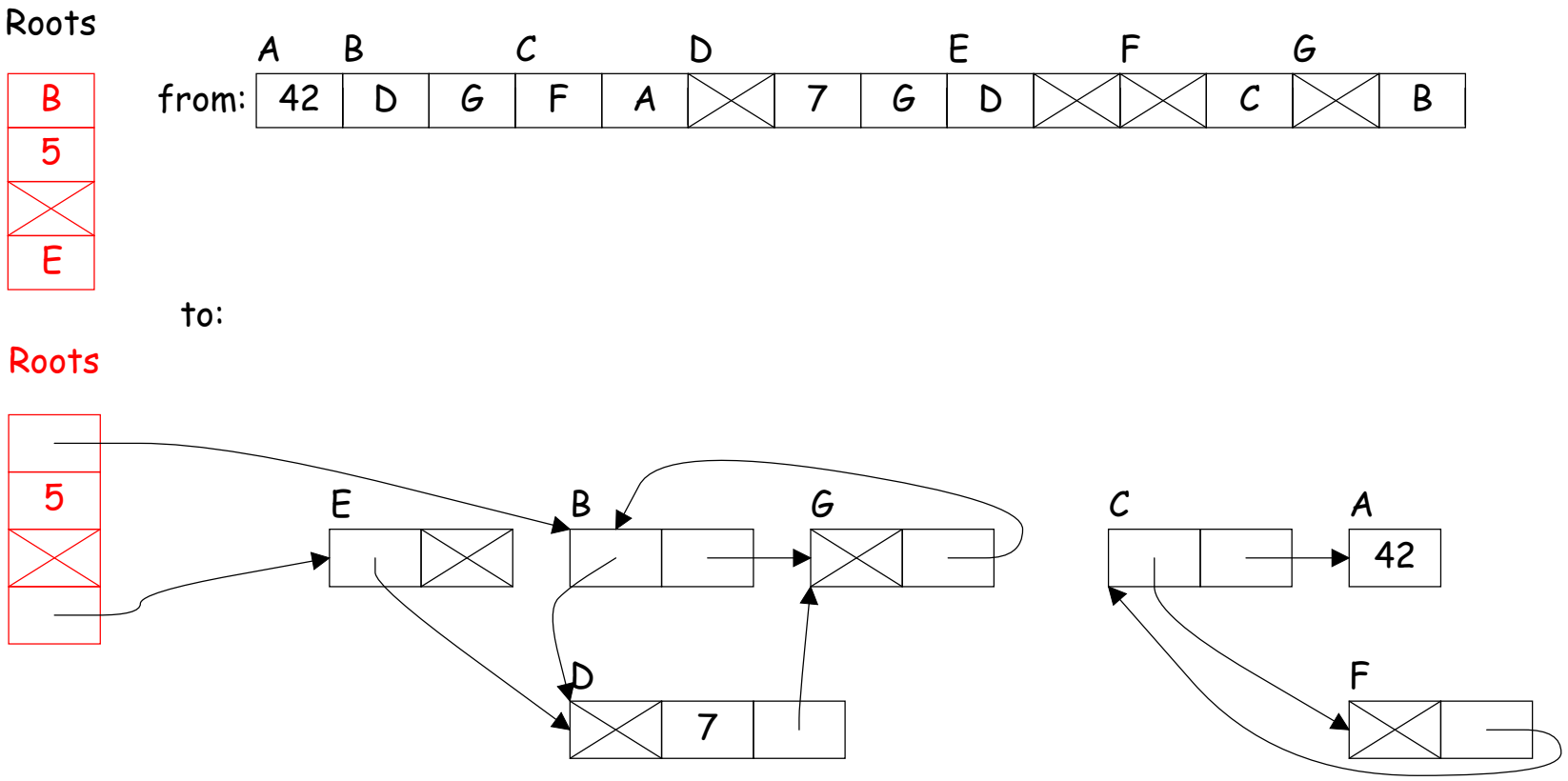
Copying Garbage Collection

- Copy (and move) only reachable (useful) storage from 'from' space to 'to' space.
- The 'from' and 'to' areas are called *semispaces*. Need twice the virtual memory you actually use.
- As you copy, mark 'from' storage as moved, and leave behind a *forwarding pointer* that tells how to translate other references to the old storage.
- At end of algorithm, 'from' and 'to' swap roles, and the old 'from' area is freed *en masse*.
- Copied storage is *compacted* (gaps squeezed out) with possible advantages for memory access.

Copying Garbage Collection, Illustrated



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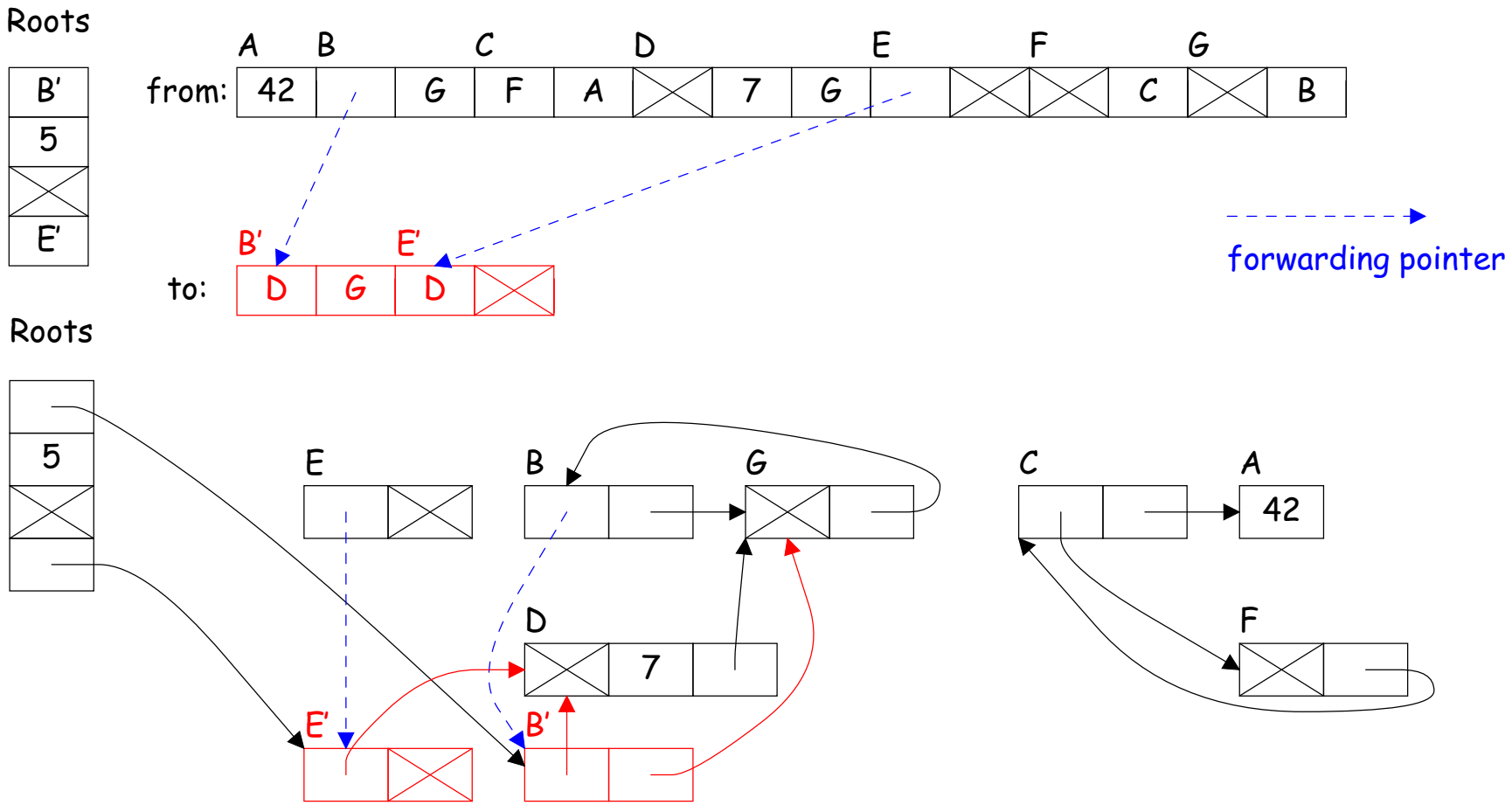

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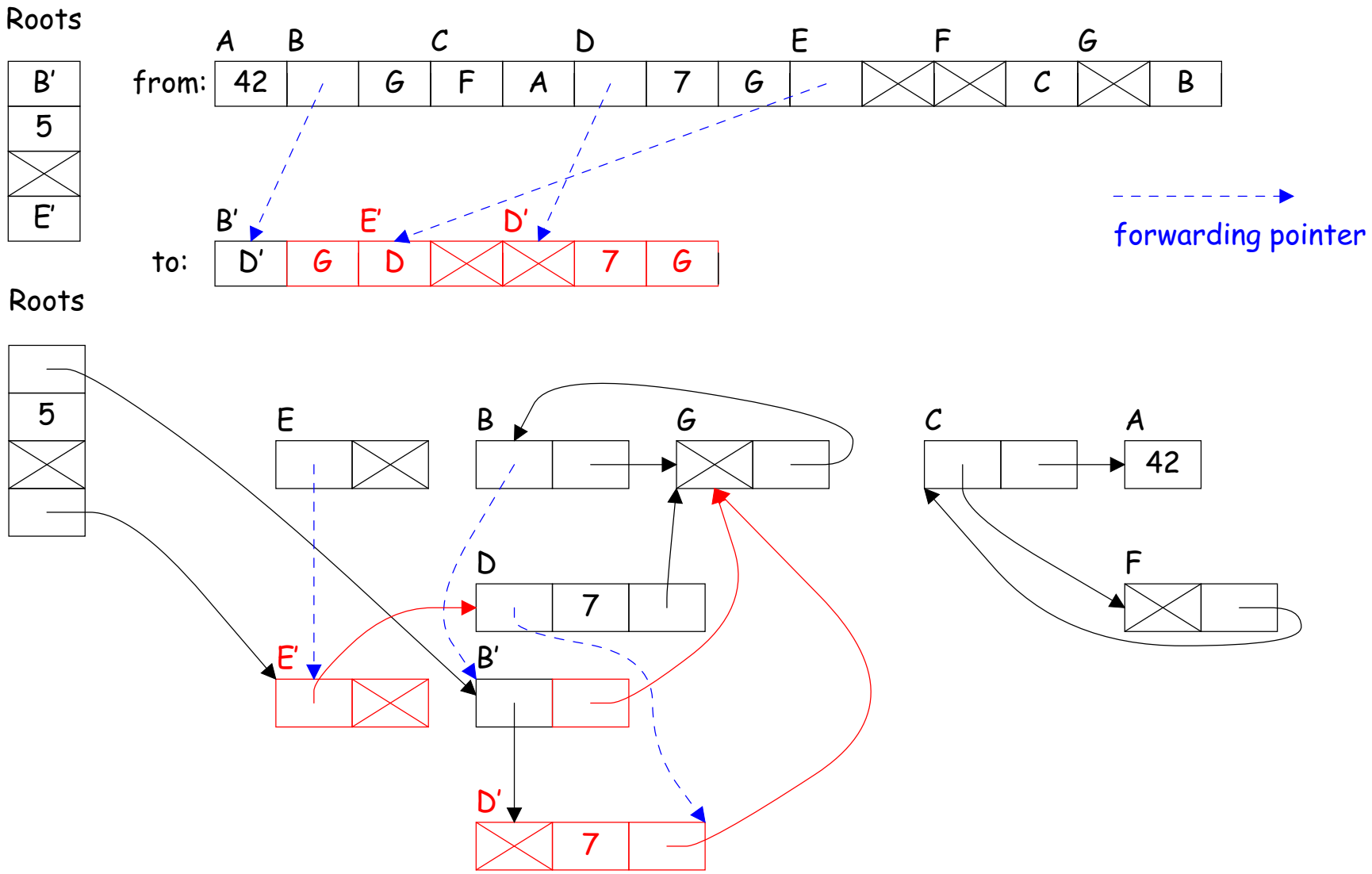

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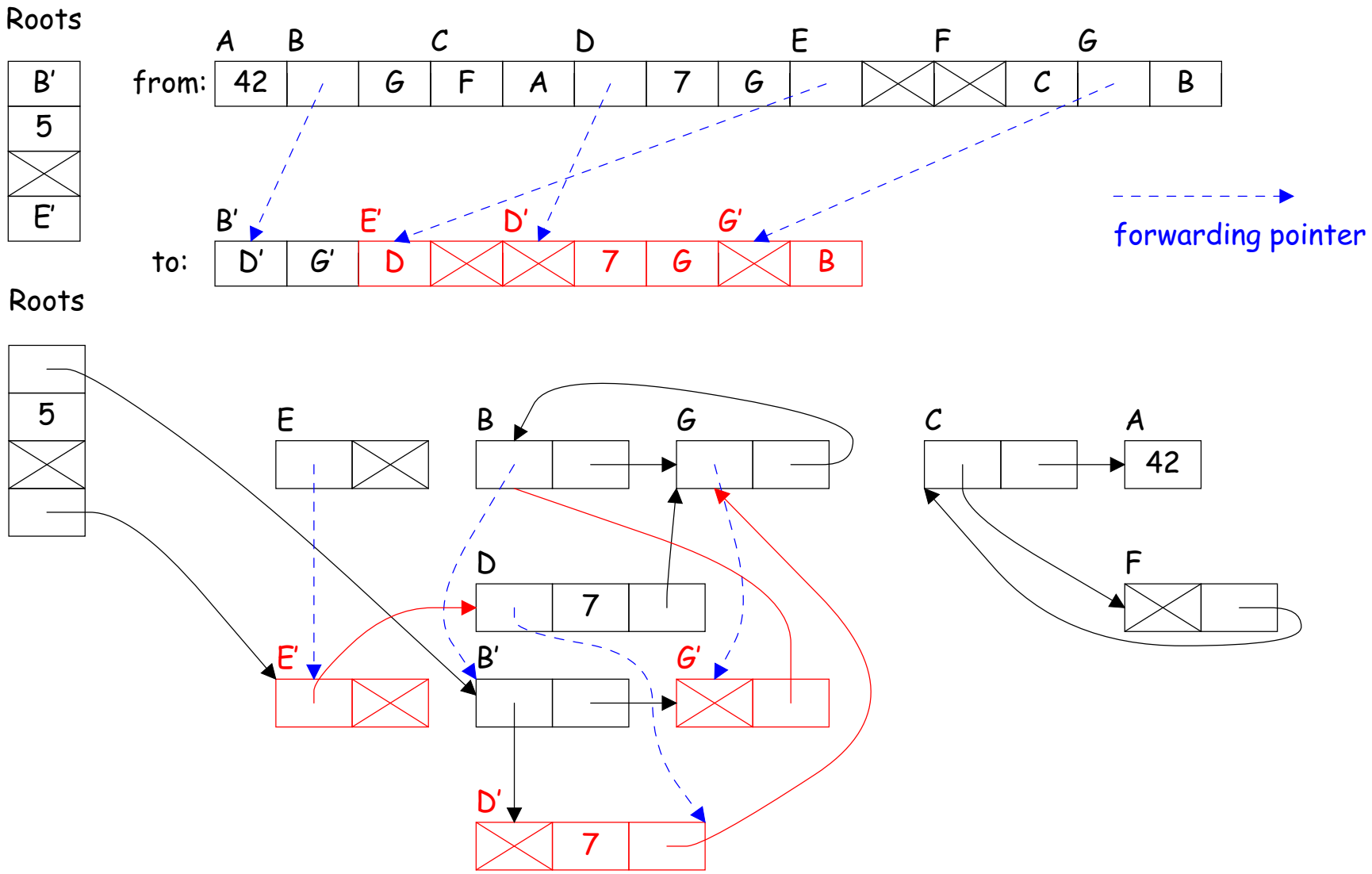

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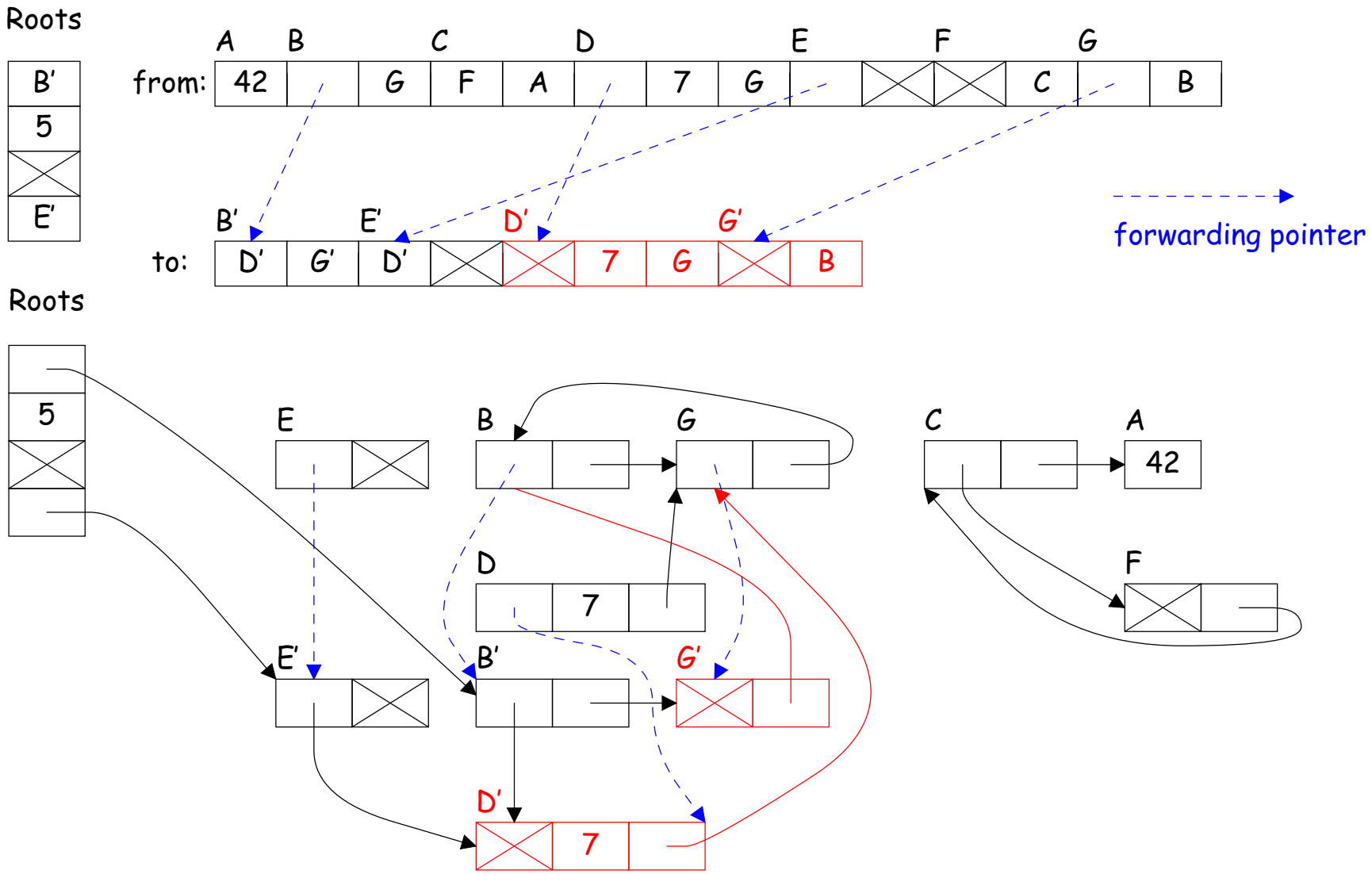

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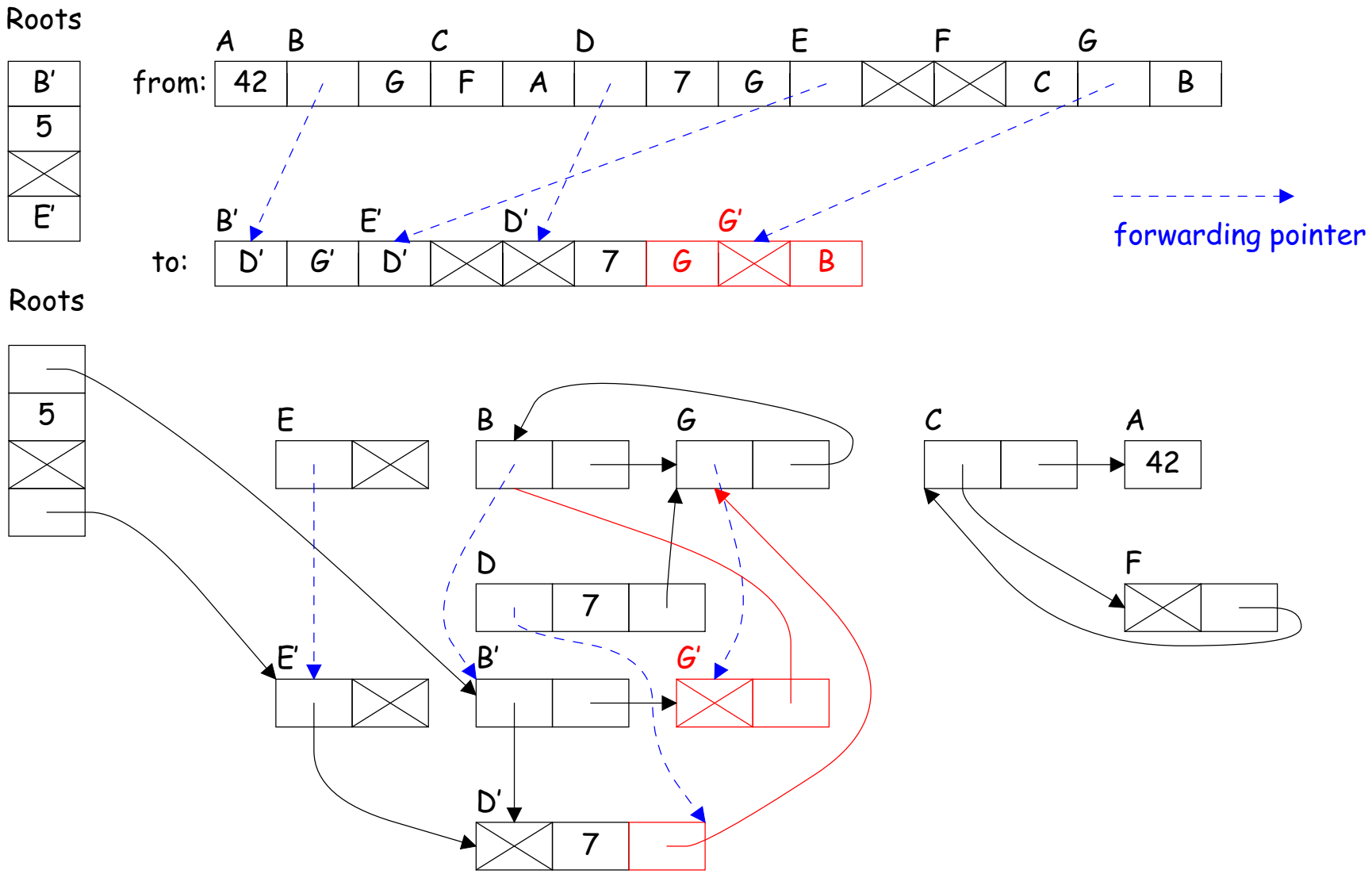

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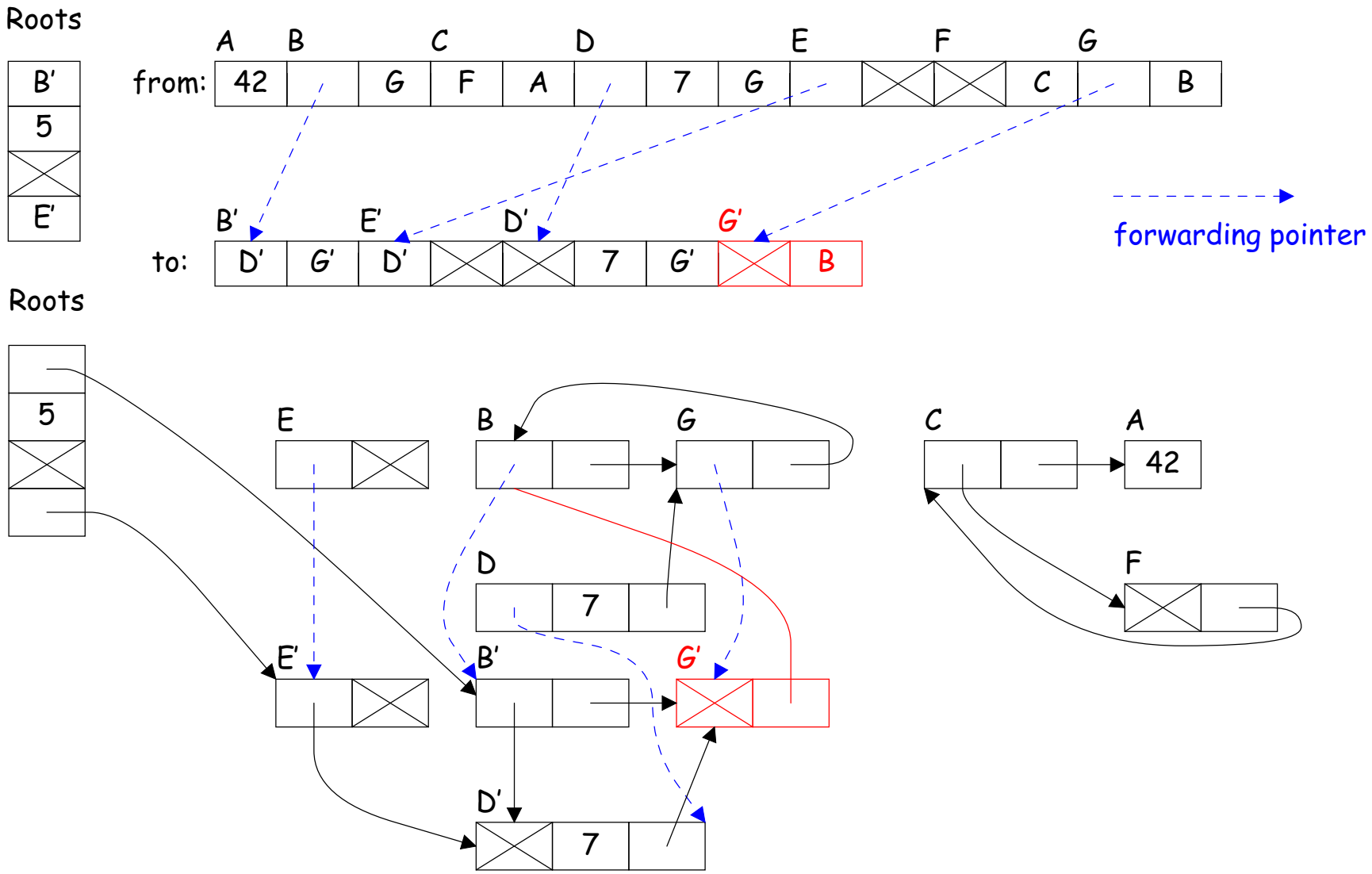

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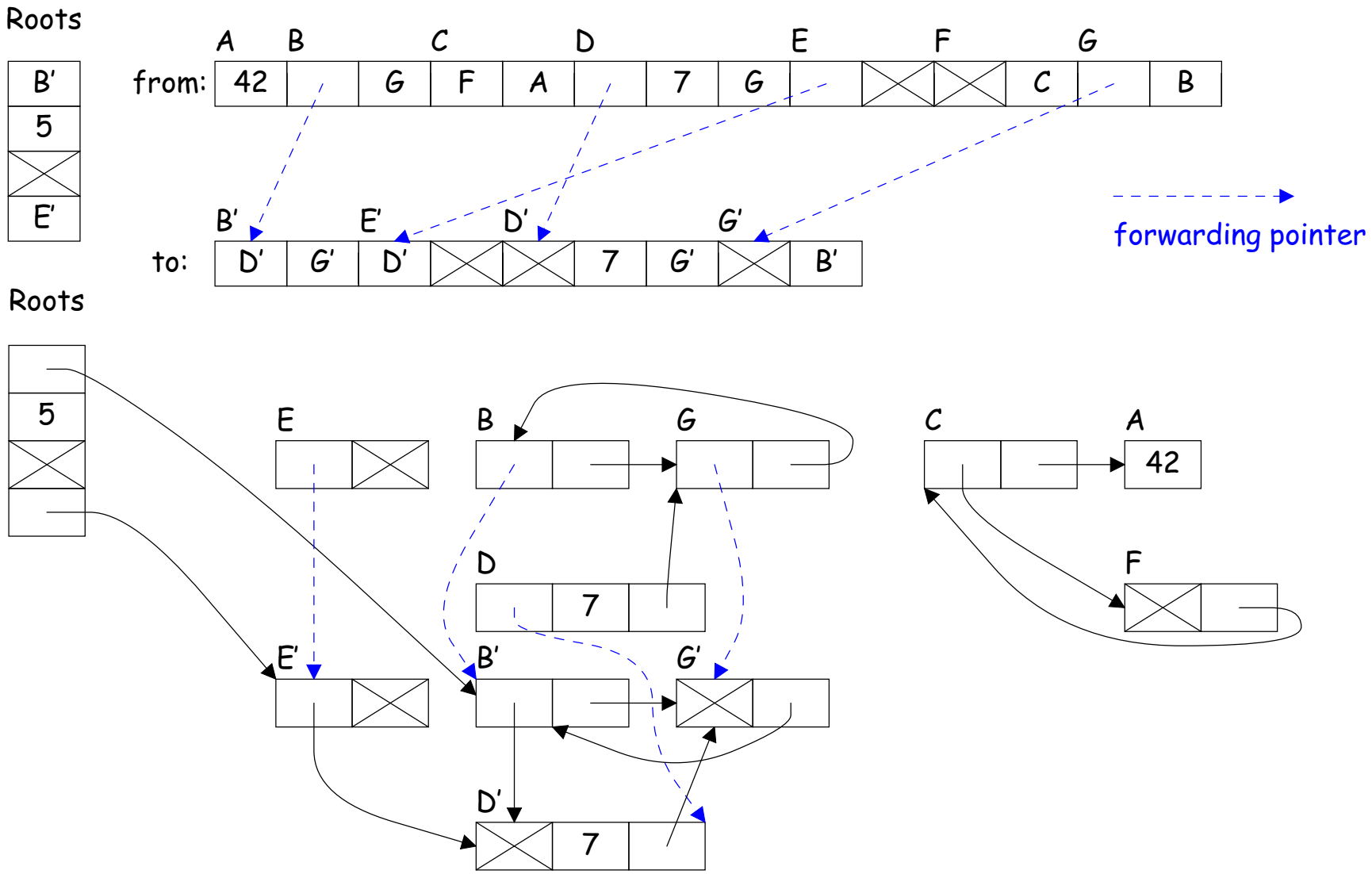

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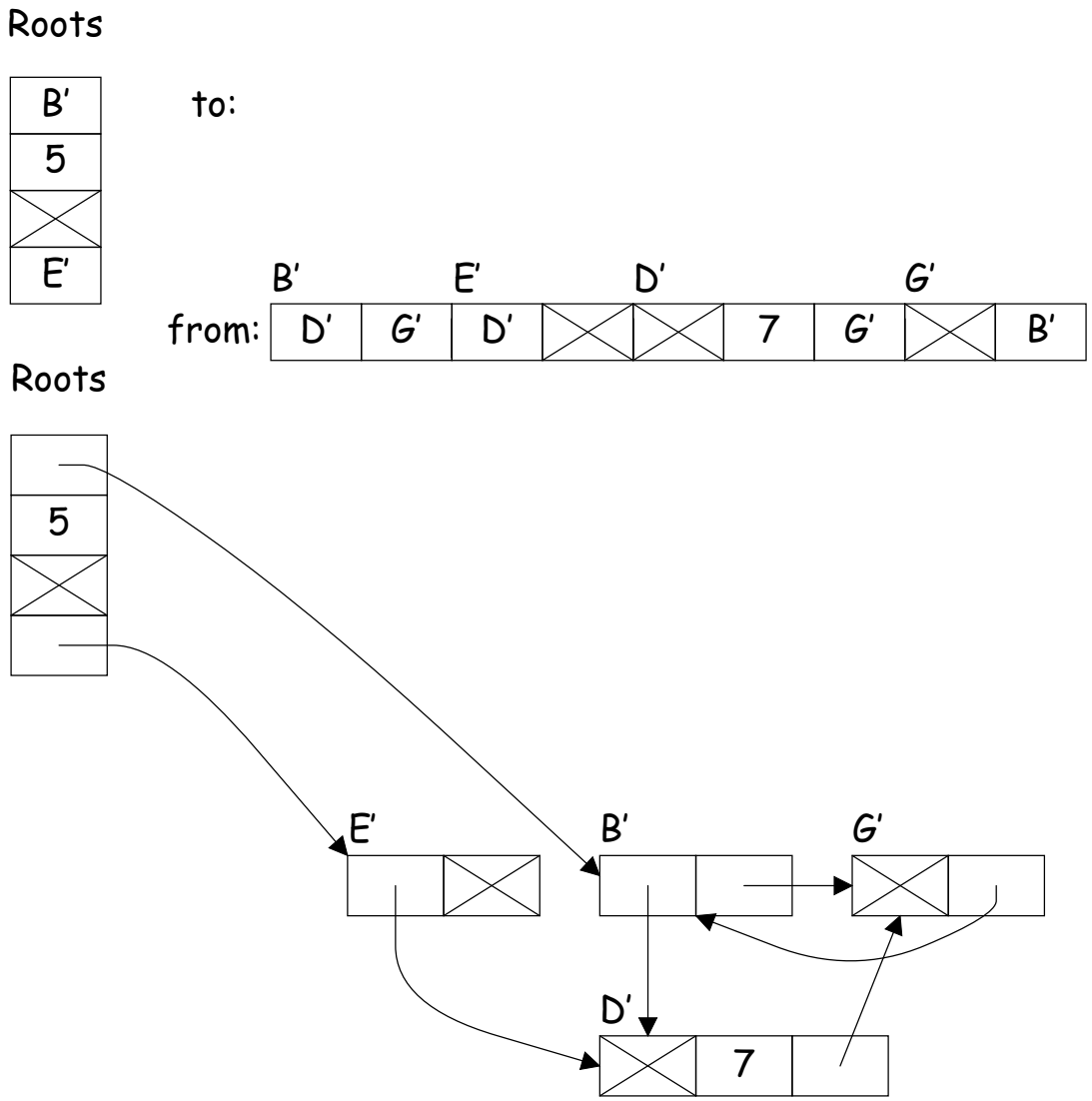


Roots and Other Pointers

- Above methods require that we know locations of roots and of pointer fields in objects.
- Positions of some roots change during execution.
- Compiler keeps tables mapping PC to where roots are.
- Runtime type information (virtual tables) keep information of where pointer fields are.
- Implementation must guarantee that fields are initialized.

Conservative Garbage Collection

- With C, you have none of the needed information.
- But easy to know the addresses of allocated storage, and sizes of allocated objects (allocator keeps them around).
- So, guess that any word that looks like an address of allocated storage is a valid address.
- Do mark-and-sweep on this assumption (look at whole stack and static storage for roots).
- Marks some garbage, but can be surprisingly effective.

Generational Garbage Collection

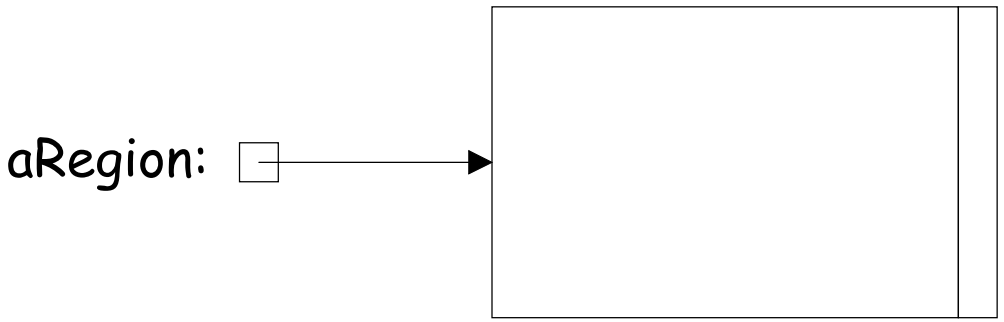
- Heap storage tends to "die young."
- So divide memory into young and old storage, and do copying only on young storage.
- Must add old storage that points to young storage to roots.
- When young storage survives a GC (or two), move it to old storage.
- Every now and then, stop the world and do a full garbage collection.
- This technique significantly speeds up GC.

Region-Based Allocation

- Garbage collection (all forms) does incur overheads, which can be unpredictable,
- While manual freeing is prone to error and inconvenient.
- One compromise is *region-based allocation*.
- Idea:
  - Create a data structure known as a region (or zone, or arena, or various other names).
  - Provides two operations: allocate object, and free *all* objects.
- Thus, to perform calculation that creates lots of temporary heap objects,
  - Create region (a local variable).
  - Allocate all the temporary storage in this region.
  - Delete whole region at end.

Region Implementation

- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.



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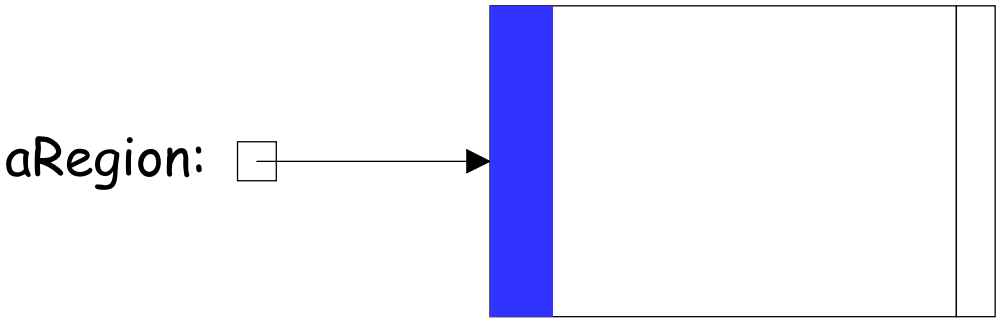
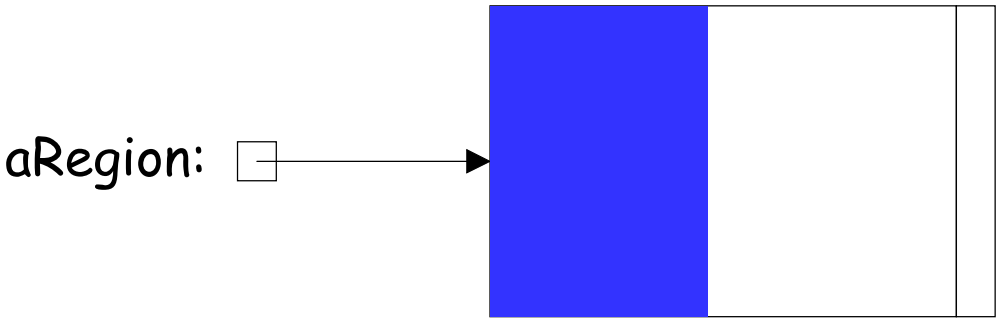



```
x = aRegion.alloc (40);
```

Region Implementation

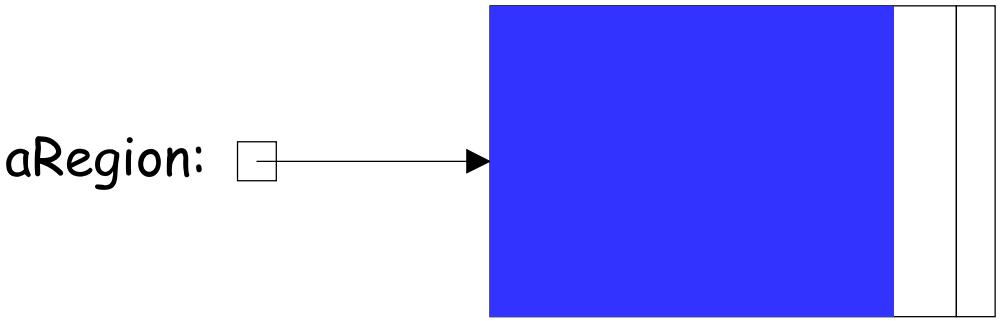
- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.




```
x = aRegion.alloc (40);
y = aRegion.alloc (100);
```

Region Implementation

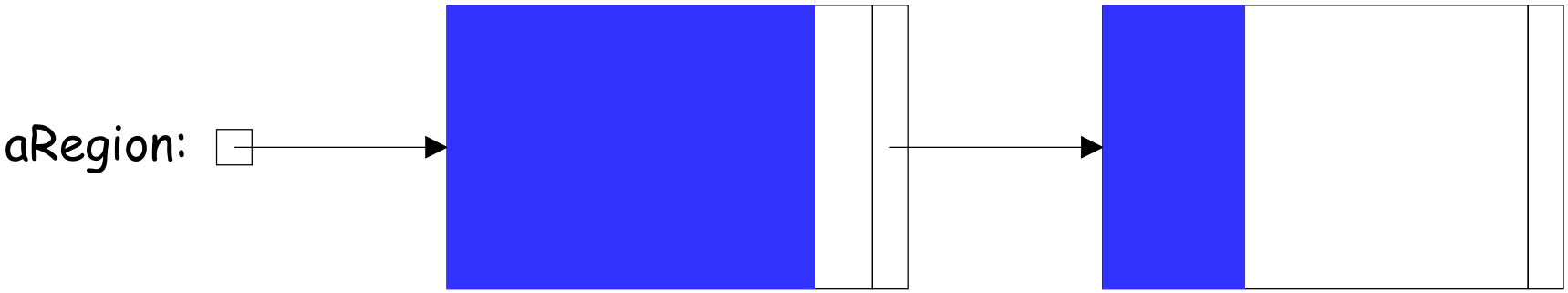
- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.




```
x = aRegion.alloc (40);
y = aRegion.alloc (100);
z = aRegion.alloc (120);
```

Region Implementation

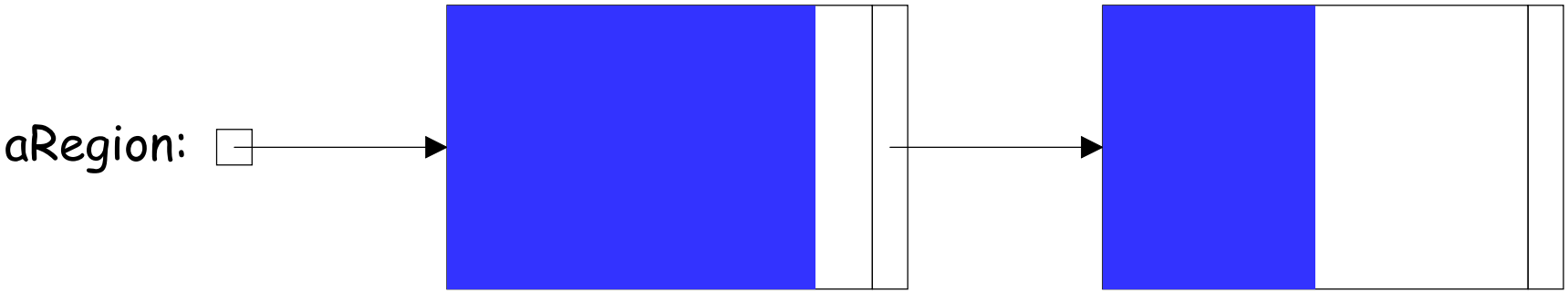
- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.




```
x = aRegion.alloc (40);
y = aRegion.alloc (100);
z = aRegion.alloc (120);
v = aRegion.alloc (100);
```

Region Implementation

- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.




```
x = aRegion.alloc (40);
y = aRegion.alloc (100);
z = aRegion.alloc (120);
v = aRegion.alloc (100);
w = aRegion.alloc (50);
```

Region Implementation

- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.

aRegion: 

```
x = aRegion.alloc (40);
y = aRegion.alloc (100);
z = aRegion.alloc (120);
v = aRegion.alloc (100);
w = aRegion.alloc (50);
aRegion.freeAll ();
```

Region Implementation

- Simple implementation: allocate storage in big blocks, and allocate objects sequentially in the blocks.
- Freeing all blocks frees all the objects quickly.

```
x = aRegion.alloc (40);
y = aRegion.alloc (100);
z = aRegion.alloc (120);
v = aRegion.alloc (100);
w = aRegion.alloc (50);
aRegion.freeAll ();
```

- Potential problem: using x, y, z, . . . after freeAll.