Semidefinite Relaxation of Quadratic Optimization Problem (Zhi-Quan Luo)

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A CVX CODE FOR SDR

cvx_begin
  variable X(n,n) symmetric
  minimize(trace(C*X));
  subject to
   for i=1:p
      trace(A(:,:,i)*X) >= b(i);
  end
  for i=p+1:m
      trace(A(:,:,i)*X) == b(i);
  end
  X == semidefinite(n);

cvx_end
```

cvx代码如上:算法采用计算代数运算的次数,对于BQP问题,可以采用内点算法,算法复杂度

$$\mathcal{O}(n^{3.5}\log(1/\epsilon))$$

As an illustration, consider the intuitively appealing idea of applying a rank-one approximation on X^* . Specifically, let $r = \operatorname{rank}(X^*)$, and let

$$X^{\star} = \sum_{i=1}^{r} \lambda_i \boldsymbol{q}_i \boldsymbol{q}_i^T$$

考虑如上的eigen-decomposition, 所以可以定义

$$\widetilde{x} = \sqrt{\lambda_1} q_1$$

对于Boolean quadratic program(BQP)问题

$$\min_{\substack{x \in \mathbb{R}^n \\ \text{s.t.}}} x^T C x$$
s.t.
$$x_i^2 = 1, \quad i = 1, \dots, n.$$
 (2)

$$\hat{x} = \operatorname{sgn}(\tilde{x})$$

考虑MIMO detection问题,问题描述如下 N-input M-output model

$$y_C = H_C s_C + v_C. (7)$$

Here, $y_C \in \mathbb{C}^M$ is the received vector, $H_C \in \mathbb{C}^{M \times N}$ is the MIMO channel, $s_C \in \mathbb{C}^N$ is the transmitted symbol vector, and $v_C \in \mathbb{C}^M$ is an additive white Gaussian noise vector.

其中信号满足:

$$s_{C,i} \in \{\pm \ 1 \pm j\}$$

所以该算法等价于零散的最小二乘法(NP-hard problem)

$$\min_{s_C \in \{\pm 1 \pm j\}^N} \| \boldsymbol{y}_C - \boldsymbol{H}_C \boldsymbol{s}_C \|^2, \tag{8}$$

该问题常用 sphere decoding methods去解决,对于N<21的问题非常有用,但是平均下是 exponential in N.

该问题可以在 $\mathcal{O}(N^{3.5})$ 的算法复杂度解决,如果采用 SDR 方法,将该问题转化为一个实值的齐次 OCOP 问题:

$$y = \begin{bmatrix} \Re\{y_C\} \\ \Im\{y_C\} \end{bmatrix}, \quad s = \begin{bmatrix} \Re\{s_C\} \\ \Im\{s_C\} \end{bmatrix}, \quad H = \begin{bmatrix} \Re\{H_C\} \\ \Im\{H_C\} \end{bmatrix}, \quad \Re\{H_C\} \end{bmatrix},$$

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$$\min_{s \in \{\pm 1\}^{2N}} \|y - Hs\|^2. \tag{9}$$

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$$\min_{s \in \mathbb{R}^{2N}, t \in \mathbb{R}} ||ty - Hs||^{2}$$
s.t. $t^{2} = 1, s_{i}^{2} = 1, i = 1, \dots, 2N.$ (10)

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$$\min_{s \in \mathbb{R}^{2N}, t \in \mathbb{R}} \left[s^T \quad t \right] \begin{bmatrix} H^T H & -H^T y \\ -y^T H & ||y||^2 \end{bmatrix} \begin{bmatrix} s \\ t \end{bmatrix}$$
s.t. $t^2 = 1$, $s_i^2 = 1$, $i = 1, \dots, 2N$. (11)

$$\min_{x \in \mathbb{R}^n} \quad x^T C x
\text{s.t.} \quad x^T A_i x \triangleright_i b_i, \quad i = 1, \dots, m.$$
(12)

Now, let $X \in \mathbb{S}^n$ be an arbitrary symmetric positive semidefinite matrix. Consider a random vector $\boldsymbol{\xi} \in \mathbb{R}^n$ drawn according to the Gaussian distribution with zero mean and covariance X, or $\boldsymbol{\xi} \sim \mathcal{N}(0, X)$ for short. The intuition of randomization lies in

优化的思想:考虑如下的stochastic QCQP

considering the following stochastic QCQP:

$$\min_{X \in \mathbb{S}^n, X \geq 0} \quad \mathbf{E}_{\xi \sim \mathcal{N}(0,X)} \{ \xi^T C \xi \}$$
s.t.
$$\mathbf{E}_{\xi \sim \mathcal{N}(0,X)} \{ \xi^T A_i \xi \} \succeq_i b_i, \quad i = 1, \dots, m,$$
(13)

算法如下:可以提供一个quasi-optimal bit -error-rate performance

GAUSSIAN RANDOMIZATION PROCEDURE FOR BQP

given an SDR solution X^* , and a number of randomizations L.

for
$$\ell = 1, ..., L$$

generate $\xi_{\ell} \sim N(0, X^*)$, and construct a QCQP-
feasible point

$$\widetilde{x}_{\ell} = \operatorname{sgn}(\xi_{\ell}). \tag{15}$$

end

determine $\ell^* = \arg\min_{\ell=1,\ldots,L} \widetilde{x}_\ell^T C \widetilde{x}_\ell$. output $\hat{x} = \widetilde{x}_{\ell^*}$ as the approximate QCQP solution.

然后可以得到该算法和原问题的解的接近程度(randomization之后所得到的结果)

$$v_{\text{QP}} = \min_{x \in \mathbb{R}^n} \quad x^T C x$$
s.t.
$$x^T A_i x \ge 1, \ i = 1, \dots, m$$

$$v_{\text{QP}} \le v(\hat{x}) \le \gamma v_{\text{QP}}, \tag{18}$$

where $\gamma=27m^2/\pi$ is the so-called <u>approximation ratio</u>. Notice 该结果是最坏情况下的结果。

考虑SDR的解的逼近情况:

$$v_{\rm SDR} \le v_{\rm QP} \le \gamma v_{\rm SDR},$$
 (19)

where $\gamma = 27m^2/\pi$ is as above.

Inhomogeneous problems

Consider a general inhomogeneous QCQP

$$\min_{x \in \mathbb{R}^n} \quad x^T C x + 2c^T x$$
s.t.
$$x^T A_i x + 2a_i^T x \triangleright_i b_i, \quad i = 1, \dots, m$$
 (22)

该问题可以齐次化为(增加一个分量)

$$\min_{x \in \mathbb{R}^n, t \in \mathbb{R}} \quad \begin{bmatrix} x^T & t \end{bmatrix} \begin{bmatrix} C & c \\ c^T & 0 \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix}
\text{s.t.} \quad t^2 = 1,
\begin{bmatrix} x^T & t \end{bmatrix} \begin{bmatrix} A_i & a_i \\ a_i^T & 0 \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix} \trianglerighteq_i b_i, \quad i = 1, \dots, m,$$

Complex-valued Problems

Consider a general complex-valued homogeneous QCQP

$$\min_{\substack{x \in \mathbb{C}^n \\ \text{s.t.}}} x^H C x$$
s.t.
$$x^H A_i x \succeq_i b_i, \quad i = 1, \dots, m, \tag{23}$$

where $C, A_1, \ldots, A_m \in \mathbb{H}^n$, with \mathbb{H}^n being the set of all complex $n \times n$ Hermitian matrices. Using the same SDR idea as in the 该问题可以使用SDR变为下列问题:

$$\min_{X \in \mathbb{H}^n} \operatorname{Tr}(CX)$$
s.t.
$$\operatorname{Tr}(A_i X) \trianglerighteq_i b_i, \quad i = 1, \dots, m,$$

$$X \geqslant 0, \tag{24}$$

Complex value problem可以用来解决k-ary quadratic program,如下:

$$\min_{x \in \mathbb{C}^n} x^H C x$$
s.t. $x_i \in \{1, e^{j2\pi/k}, \dots, e^{j2\pi(k-1)/k}\}, i = 1, \dots, n, (25)$

上面的k-ary quadratic program可以用下面的问题来近似: (理论和实际效果都还可以)

$$\min_{\substack{X \in \mathbb{H}^n \\ \text{s.t.}}} \operatorname{Tr}(CX)$$
s.t. $X \ge 0, X_{ii} = 1, i = 1, \dots, n.$ (26)

Separable QCQPs

定义为具有如下形式的QCQP:

Consider a QCQP of the form

$$\min_{\substack{x_1, \dots, x_k \in \mathbb{C}^n \\ \text{s.t.}}} \sum_{i=1}^k x_i^H C_i x_i$$
s.t.
$$\sum_{l=1}^k x_l^H A_{i,l} x_l \trianglerighteq_i b_i, \quad i = 1, \dots, m. \tag{27}$$

该问题的SDR版本为:

Let $X_i = x_i x_i^H$ for i = 1, ..., k. By relaxing the rank constraint on each X_i , we obtain the following SDR of (27):

$$\min_{X_1, \dots, X_k \in \mathbb{H}^n} \quad \sum_{i=1}^k \operatorname{Tr}(C_i X_i)$$
s.t.
$$\sum_{l=1}^k \operatorname{Tr}(A_{i,l} X_l) \trianglerighteq_i \ b_i, \quad i = 1, \dots, m,$$

$$X_1 \geqslant 0, \dots, X_k \geqslant 0. \tag{28}$$

Semidefinite Problem中的Rand Reduction,步骤如下:

- formulate the problem as a rank-constrained SDP
- remove the rank constraint to obtain a SDP
- extract a feasible solution of the original rank-constrained SDP

关于SDP问题最优解的rank的一些结果:

(Shapiro-Barvinok-Pataki)对于下列的问题: 如果该问题有解

$$\min_{X \in \mathbb{S}^n} \operatorname{Tr}(CX)$$
s.t.
$$\operatorname{Tr}(A_i X) \trianglerighteq_i b_i, \quad i = 1, \dots, m,$$

$$X \geqslant 0.$$
(6)

则存在最优解满足:, $\operatorname{rank}(X^{\star}) \leq \lfloor (\sqrt{8m+1}-1)/2 \rfloor$.

(Huang and Palomar)对于下列的问题,如果该问题有解

Consider a general complex-valued homogeneous QCQP

$$\min_{\substack{x \in \mathbb{C}^n \\ \text{s.t.}}} x^H C x$$
s.t.
$$x^H A_i x \succeq_i b_i, \quad i = 1, \dots, m, \tag{23}$$

where $C, A_1, \ldots, A_m \in \mathbb{H}^n$, with \mathbb{H}^n being the set of all complex $n \times n$ Hermitian matrices. Using the same SDR idea as in the

则存在最优解满足: $\operatorname{rank}(X^{\star}) \leq \sqrt{m}$.

([27])对于complex-valued separable QCQPs:如果该问题有解

Consider a QCQP of the form

$$\min_{\substack{x_1, \dots, x_k \in \mathbb{C}^n \\ \text{s.t.}}} \sum_{i=1}^k x_i^H C_i x_i$$
s.t.
$$\sum_{l=1}^k x_l^H A_{i,l} x_l \trianglerighteq_i b_i, \quad i = 1, \dots, m. \tag{27}$$

则存在最优解,满足:

sible. Then, as shown in [16], there exists a solution $\{X_i^*\}_{i=1}^k$ to (28) whose ranks satisfy

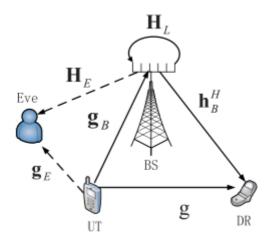
$$\sum_{i=1}^k \operatorname{rank}(X_i^{\star})^2 \le m.$$

对于real-valued separable QCQPs:如果该问题有解,则存在解满足:

$$\sum_{i=1}^k \frac{\operatorname{rank}(X_i^{\star})(\operatorname{rank}(X_i^{\star})+1)}{2} \leq m.$$

Robust Beamforming and Jamming for Enhancing the Physical Layer Security of Full Duplex Radios (Zhengmin Kong)

模型: FD cellular system, 如下图所示:



- BS: base station (Full duplex base station) 作用: downlink transmission
- DR: 单天线 legitimate receiver
- UT: 单天线 legitimate UT 作用: uplink transmission
- Eve: 多天线 Eve

Eve的信息: N_E receiving antennas,

 N_T transmitting antennas and N_R receiving antennas

假设: $N_T \geq N_E + 1$,

- downlink的信息
 - \circ from BS to Eve channel information: $\mathbf{H}_E \in \mathbb{C}^{N_E imes N_T}$
 - o from BS to DR channel information: $\mathbf{h}_{R}^{H} \in \mathbb{C}^{1 \times N_{T}}$ o residual self-interference channel: $\mathbf{H}_{L} \in \mathbb{C}^{N_{R} \times N_{T}}$

 - BS transmits the confidential signal plus AN:
 - \circ total available power of the BS: $P_{
 m tot}$

o 功率限制:
$$\underline{\operatorname{tr}\left(\mathbf{v}\mathbf{v}^{H}+\Omega\right)} \leq P_{\mathrm{tot}}.$$
 (2)

- uplink的信息
 - \circ UT transmits the confidential signal: $z \sim \mathcal{CN}(0,1)$
 - \circ UT transmits the signal: power $\,P_{t}$.
 - o BS, DR, Eve所接收到的信号:

$$y_B = \mathbf{r}^H \left(\sqrt{P_t} \mathbf{g}_B z + \mathbf{H}_L \mathbf{x}_b + \mathbf{n}_B \right), \tag{3}$$

$$y_D = \mathbf{h}_B^H \mathbf{x}_b + \sqrt{P_t} gz + n_D, \tag{4}$$

$$\mathbf{y}_E = \mathbf{H}_E \mathbf{x}_b + \sqrt{P_t} \mathbf{g}_E z + \mathbf{n}_E, \tag{5}$$

其中perfect state information \mathbf{H}_L 对于BS未知,其中 采用maximum ration combining receiver (MRC),而不是minimum mean-square error (MMSE) receiver,也就是采用 $\mathbf{r}=rac{\mathbf{g}_B}{||\mathbf{g}_B||_F}$,

Channel State Information Model

假设BS只能获得 imperfect estimate of channel state information:

$$\mathbf{H}_E = \bar{\mathbf{H}}_E + \Delta \mathbf{H}_E, \quad \mathbf{g}_E = \bar{\mathbf{g}}_E + \Delta \mathbf{g}_E, \tag{6}$$

对于CSI估计的不确定性,我们采用deterministic uncertainty model.

$$\{\mathbf{H}_L: ||\mathbf{H}_L||_F \leq \delta_{\mathbf{H}_L}\}, \, \xi_{\mathbf{H}_E} \triangleq \{\Delta \mathbf{H}_E: ||\Delta \mathbf{H}_E||_F \leq \delta_{\mathbf{H}_E}\}$$

以及:

$$\zeta_{\mathbf{g}_E} \triangleq \left\{ \Delta \mathbf{g}_E : ||\Delta \mathbf{g}_E||_F \leq \delta_{\mathbf{g}_E} \right\}$$

则问题可以转化为优化为:

$$\max_{\mathbf{v}, \Omega \succeq \mathbf{0}} \min_{\Delta \mathbf{H}_{E} \in \xi_{\mathbf{H}_{E}}, \mathbf{H}_{L} \in \xi_{\mathbf{H}_{L}}, \Delta \mathbf{g}_{E} \in \xi_{\mathbf{g}_{E}}} \ln (1 + \eta_{1}) + \ln (1 + \eta_{2})$$

$$- \ln \det \left(\mathbf{I}_{N_{E}} + \mathbf{Z} \mathbf{N}^{-1} \right)$$
s.t. rank $(\mathbf{Q}) = 1$,
$$\operatorname{tr} (\mathbf{Q} + \Omega) \leq P_{\text{tot}}, \tag{7}$$
where $\eta_{1} \triangleq \frac{\mathbf{h}_{B}^{H} \mathbf{Q} \mathbf{h}_{B}}{P_{t} |g|^{2} + \mathbf{h}_{B}^{H} \Omega \mathbf{h}_{B} + 1}, \ \eta_{2} \triangleq \frac{P_{t} ||\mathbf{g}_{B}||_{F}^{2}}{\mathbf{r}^{H} \mathbf{H}_{L} (\mathbf{Q} + \Omega) \mathbf{H}_{L}^{H} \mathbf{r} + 1}, \ \mathbf{Z} \triangleq \mathbf{H}_{E} \mathbf{Q} \mathbf{H}_{E}^{H} + P_{t} \mathbf{g}_{E} \mathbf{g}_{E}^{H}, \ \mathbf{N} \triangleq \mathbf{H}_{E} \mathbf{\Omega} \mathbf{H}_{E}^{H} + \mathbf{I}_{N_{E}}.$