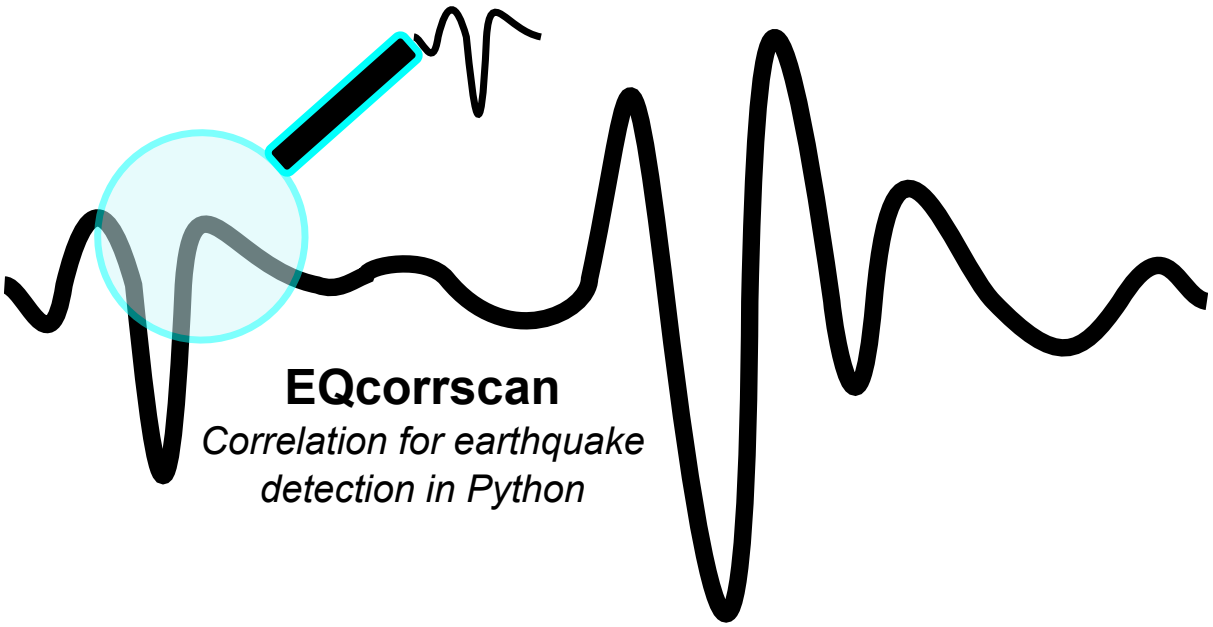

EQcorrscan Documentation

Release 0.0.5

Calum John Chamberlain

April 23, 2015

Contents:

CHAPTER

ONE

INTRODUCTION TO THE EQCORRSCAN PACKAGE

This document is designed to give you an overview of the capabilities and implimentation of the EQcorrscan python module.

1.1 Installation

Most codes should work without any effort on your part. However you must install the packages this package relies on yourself, this includes the follwing packages:

- matplotlib
- numpy
- scipy
- obspy
- joblib
- openCV (2)

This install has only been tested on Linux machines and even then has some issues when installing on 32-Bit versus 64-Bit machines. In this instance you should be prepared for small differences in the results of your correlations relating to foating-point truncation differences between 32 and 64-Bit machines.

If you plan to run the bright_lights.py routines you will need to have NonLinLoc installed on your machine. This is not provided here and should be sourced from NonLinLoc This will provide the Grid2Time routine which is required to set-up a lag-time grid for your velocity model. You should read the NonLinLoc documentation for more information regarding how this process works and the input files you are required to give.

1.2 Functions

This package is divided into sub-directories of *core*, *par* and *utils*. The *utils* directory contains simple functions for integration with seisan, these is the *Sfile_util.py* module and functions therein which are essentially barebones and do not have the full functionality that seisan can handle. *utils* also contains a simple peak-finding algorithm *find_peaks.py* which looks for peaks within noisy data above a certain threshold and within windows.

Within *par* you will find parameter files which you will need to edit for each of the *core* scripts. *core* scripts often call on multiple *par* files so be sure to set them all up. The *template_gen_par.py* script is used by all *core* modules and must be set-up. Within this you will define all your template parameters. Currently the templates must all be of the same length, but this may change in a future release.

Within *core* you will find the core routines to generate templates, *(template_gen.py)* search for likely templates *(bright_lights.py)* and compute cross-channel correlations from these templates *(match_filter.py)*.

CHAPTER

TWO

EQCORRSCAN TUTORIAL

THIS TUTOTIAL IS NOT REALLY WRITTEN YET!

You must first set-up your parameter files in the *par* directory. You can leave these as the default settings for now, but study the parameters so that you understand what each one is doing.

Then run the *LFE_search.py* routine in this top directory, running this will run all the *core* routines to search for templates, generate templates and compute the cross-channel cross-correlation values for the templates. Finally it will output detections from these templates.

The following is verbatim the LFEserach.py routine which outlines usage of this package:

```
#!/usr/bin/python

#------------------------------------------------------------------------------
#   Purpose:    Script to call all elements of EQcorrscan module to search
#               continuous data for likely LFE repeats
#   Author:     Calum John Chamberlain
#------------------------------------------------------------------------------

"""
LFEsearch - Script to generate templates from previously picked LFE's and then
serach for repeats of them in contnuous data.
"""

import sys, os, glob
sys.path.insert(0,"/home/processor/Desktop/EQcorrscan")


from par import template_gen_par as templatedef
from par import match_filter_par as matchdef
#from par import lagcalc as lagdef
from obspy import UTCDateTime, read as obsread
# First generate the templates
from core import template_gen

templates=[]
delays=[]
stations=[]
print 'Template generation parameters are:'
print 'sfilebase: '+templatedef.sfilebase
print 'samp_rate: '+str(templatedef.samp_rate)+' Hz'
print 'lowcut: '+str(templatedef.lowcut)+' Hz'
print 'highcut: '+str(templatedef.highcut)+' Hz'
print 'length: '+str(templatedef.length)+' s'
print 'swin: '+templatedef.swin+'\n'
for sfile in templatedef.sfiles:
    print 'Working on: '+sfile+'\r'
    if not os.path.isfile(templatedef.saveloc+'/'+sfile+'_template.ms'):
        template=template_gen.from_contbase(templatedef.sfilebase+'/'+sfile)
```

```
        print 'saving template as: '+templatedef.saveloc+'/'+\
                str(template[0].stats.starttime)+'.ms'
        template.write(templatedef.saveloc+'/'+\
                   sfile+'_template.ms',format="MSEED")
    else:
        template=obsread(templatedef.saveloc+'/'+sfile+'_template.ms')
    templates+=[template]
    # Will read in seisan s-file and generate a template from this,
    # returned name will be the template name, used for parsing to the later
    # functions


    # Calculate the delays for each template, do this only once so that we
    # don't have to do it heaps!
    # Get minimum start time
    mintime=UTCDateTime(3000,1,1,0,0)
    for tr in template:
        if tr.stats.starttime < mintime:
            mintime=tr.stats.starttime
    delay=[]
    # Generate list of delays
    for tr in template:
        delay.append(tr.stats.starttime-mintime)
    delays.append(delay)
    # Generate list of stations in templates
    for tr in template:
        stations.append(tr.stats.station+'.'+tr.stats.channel[0]+\
                        '*'+tr.stats.channel[2])

# Template generation and processing is over, now to the match-filtering

# Sort stations into a unique list - this list will ensure we only read in data
# we need, which is VERY important as I/O is very costly and will eat memory
stations=list(set(stations))

# Now run the match filter routine
from core import match_filter
from obspy import read as obsread
from obspy.signal.filter import bandpass
from obspy import Stream, Trace
import numpy as np
from utils import pre_processing

# Loop over days
ndays=int((matchdef.enddate-matchdef.startdate)/86400)+1
newsfiles=[]
f=open('detections/run_start_'+str(UTCDateTime().year)+\
       str(UTCDateTime().month).zfill(2)+\
       str(UTCDateTime().day).zfill(2)+'T'+\
       str(UTCDateTime().hour).zfill(2)+str(UTCDateTime().minute).zfill(2),'w')
f.write('template, detect-time, cccsum, threshold, number of channels\n')
print 'Will loop through '+str(ndays)+' days'
for i in range(0,ndays):
    if 'st' in locals():
        del st


    # Set up where data are going to be read in from
    day=matchdef.startdate+(i*86400)
    if matchdef.baseformat=='yyyy/mm/dd':
        daydir=str(day.year)+'/'+str(day.month).zfill(2)+'/'+\
                str(day.day).zfill(2)
    elif matchdef.baseformat=='Yyyyy/Rjjj.01':
```

```
        daydir='Y'+str(day.year)+'/R'+str(day.julday).zfill(3)+'.01'
    elif matchdef.baseformat=='yyyymmdd':
        daydir=str(day.year)+str(day.month).zfill(2)+str(day.day).zfill(2)


    # Read in data using obspy's reading routines, data format will be worked
    # out by the obspy module
    # Note you might have to change this bit to match your naming structure
    actual_stations=[] # List of the actual stations used
    for stachan in stations:
        # station is of the form STA.CHAN, to allow these to be in an odd
        # arrangements we can seperate them
        station=stachan.split('.')[0]
        channel=stachan.split('.')[1]
        if glob.glob(matchdef.contbase+'/'+daydir+'/*'+station+'*.'+channel+'.*'):
            if 'st' in locals():
                st+=obsread(matchdef.contbase+'/'+daydir+'/*'+station+'*.'+channel+'.*')
            else:
                st=obsread(matchdef.contbase+'/'+daydir+'/*'+station+'*.'+channel+'.*')
            actual_stations.append(station) # Add to this list only if we have the data
        else:
            print 'No data for '+stachan+' for day '+daydir+' in '+matchdef.contbase
    actual_stations=list(set(actual_stations))

    if not 'st' in locals():
        print 'No data found for day: '+str(day)
    elif len(actual_stations) < matchdef.minsta:
        print 'Data from fewer than '+str(matchdef.minsta)+' stations found, will not detect'
    else:
        # Process data
        print 'Processing the data for day '+daydir
        st=pre_processing.dayproc(st, templatedef.lowcut, templatedef.highcut,\
                                  templatedef.filter_order, templatedef.samp_rate,\
                                  matchdef.debug, day)

        # Call the match_filter module - returns detections, a list of detections
        # containted within the detection class with elements, time, template,
        # number of channels used and cross-channel correlation sum.
        print 'Running the detection routine'
        detections=match_filter.match_filter(templatedef.sfiles, templates, delays, st,
                                              matchdef.threshold, matchdef.threshtype,
                                              matchdef.trig_int,  matchdef.plot)

        for detection in detections:
            # output detections to file
            f.write(detection.template_name+', '+str(detection.detect_time)+\
                    ', '+str(detection.detect_val)+', '+str(detection.threshold)+\
                    ', '+str(detection.no_chans)+'\n')
            print 'template: '+detection.template_name+' detection at: '\
                +str(detection.detect_time)+' with a cccsum of: '+str(detection.detect_val)
        if detections:
            f.write('\n')
f.close()
```

CHAPTER

THREE

UTILS

Codes to run basic utility functions for integration with seisan and to find peaks in noisey data.

3.1 Sfile_util

Part of the EQcorrscan module to read nordic format s-files and write them EQcorrscan is a python module designed to run match filter routines for seismology, within it are routines for integration to seisan and obspy. With obspy integration (which is necessary) all main waveform formats can be read in and output.

This main section contains a script, LFE_search.py which demonstrates the usage of the built in functions from template generation from picked waveforms through detection by match filter of continuous data to the generation of lag times to be used for relative locations.

The match-filter routine described here was used a previous Matlab code for the Chamberlain et al. 2014 G-cubed publication. The basis for the lag-time generation section is outlined in Hardebeck & Shelly 2011, GRL.

Code generated by Calum John Chamberlain of Victoria University of Wellington, 2015.

class Sfile_util.**PICK**(*station*, *channel*, *impulsivity*, *phase*, *weight*, *polarity*, *time*, *coda*, *amplitude*, *peri*, *azimuth*, *velocity*, *AIN*, *SNR*, *azimuthres*, *timeres*, *finalweight*, *distance*, *CAZ*)

Pick information for seisan implimentation

Sfile_util.**blanksfile**(*wavefile*, *evtype*, *userID*, *outdir*, *overwrite*)

Module to generate an empty s-file with a populated header for a given waveform.

Arguments are the path of a wavefile (multiplexed miniseed file required) # Event type (L,R,D) and user ID (four characters as used in seisan)

Example s-file format: # 2014 719 617 50.2 R 1 # ACTION:ARG 14-11-11 10:53 OP:CALU STATUS: ID:20140719061750 I # 2014/07/2014-07-19-0617-50.SAMBA_030_00 6 # STAT SP IPHASW D HRMM SECON CODA AMPLIT PERI AZIMU VELO AIN AR TRES W DIS CAZ7

Sfile_util.**float_conv**(*string*)

Convenience tool to convert from string to float, if empty string return NaN rather than an error

Sfile_util.**int_conv**(*string*)

Convenience tool to convert from string to integer, if empty string return a 999 rather than an error

Sfile_util.**populateSfile**(*sfilename*, *picks*)

Module to populate a blank nordic format S-file with pick information, arguments required are the filename of the blank s-file and the picks where picks is a dictionary of picks including station, channel, impulsivity, phase, weight, polarity, time, coda, amplitude, peri, azimuth, velocity, SNR, azimuth residual, Time-residual, final weight, epicentral distance & azimuth from event to station.

This is a full pick line information from the seisan manual, P. 341

Sfile_util.**readwavename**(*sfilename*)
Convenience function to extract the waveform filename from the s-file, returns a list of waveform names found in the s-file as multiples can be present.

3.2 findpeaks

Function to find peaks in data above a certain threshold as part of the EQcorr package written by Calum Chamberlain of Victoria University of Wellington in early 2015.

findpeaks.**find_peaks**(*arr*, *thresh*, *trig_int*)
Function to determine peaks in an array of data above a certain threshold.

EXPERIMENTAL CODE, DOES NOT WORK EFFICIENTLY, RECOMEND USING find_peaks2

Parameters

- **arr** (*ndarray*) – 1-D numpy array is required
- **thresh** (*float*) – The threshold below which will be considered noise and peaks

will not be found in. :type trig_int: int :param trig_int: The minimum difference in samples between triggers, if multiple peaks within this window this code will find the highest.

Return peaks, locs Lists of peak values and locations.

findpeaks.**find_peaks2**(*arr*, *thresh*, *trig_int*, *debug=0*, *starttime=UTCDateTime(1970*, *1*, *1*, *0*, *0)*, *samp_rate=1.0*)
Function to determine peaks in an array of data above a certain threshold. Improvement on find_peaks, speed-up of approx 250x.

Parameters

- **arr** (*ndarray*) – 1-D numpy array is required
- **thresh** (*float*) – The threshold below which will be considered noise and peaks

will not be found in. :type trig_int: int :param trig_int: The minimum difference in samples between triggers, if multiple peaks within this window this code will find the highest. :type debug: int :param debug: Optional, debug level 0-5

Return peaks, locs Lists of peak values and locations.

CHAPTER

FOUR

PAR

User-editable codes to input parameters for *core* files. Scripts are coded in the files with a full description of the parameters Outline definitions for match filter python code Outline definitions for template generation

CHAPTER

FIVE

CORE

Core programs for the EQcorrscan project.

5.1 bright_lights

Code to determine the birghtness function of seismic data according to a three- dimensional travel-time grid. This travel-time grid should be generated using the grid2time function of the NonLinLoc package by Anthony Lomax which can be found here: http://alomax.free.fr/nlloc/ and is not distributed within this package as this is a very useful stand-alone library for seismic event location.

This code is based on the method of Frank & Shapiro 2014

Part of the EQcorrscan module to integrate seisan nordic files into a full cross-channel correlation for detection routine. EQcorrscan is a python module designed to run match filter routines for seismology, within it are routines for integration to seisan and obspy. With obspy integration (which is necessary) all main waveform formats can be read in and output.

This main section contains a script, LFE_search.py which demonstrates the usage of the built in functions from template generation from picked waveforms through detection by match filter of continuous data to the generation of lag times to be used for relative locations.

The match-filter routine described here was used a previous Matlab code for the Chamberlain et al. 2014 G-cubed publication. The basis for the lag-time generation section is outlined in Hardebeck & Shelly 2011, GRL.

Code generated by Calum John Chamberlain of Victoria University of Wellington, 2015.

Pre-requisites: gcc - for the installation of the openCV correlation routine python-joblib - used for parallel processing python-obspy - used for lots of common seismological processing

- **requires:** numpy scipy matplotlib

python-pylab - used for plotting NonLinLoc - used outside of all codes for travel-time generation

`bright_lights._node_loop`(*stations*, *node*, *lags*, *stream*, *threshold*, *thresh_type*)
Internal function to allow for parallelisation of brightness

`bright_lights._read_tt`(*path*, *stations*, *phase*)
Function to read in .csv files of slowness generated from Grid2Time (part of NonLinLoc by Anthony Lomax) and convert this to a useful format here.

It should be noted that this can read either P or S travel-time grids, not both at the moment.

Parameters

- **path** (*str*) – The path to the .csv Grid2Time outputs
- **stations** (*list*) – List of station names to read slowness files for.

Returns list stations, list of lists of tuples nodes, :class: 'numpy.array' lags station[1] refers to nodes[1] and lags[1] nodes[1][1] refers to station[1] and lags[1][1] nodes[n][n] is a tuple of latitude, longitude and depth

bright_lights.**_resample_grid**(*stations*, *nodes*, *lags*, *volume*, *resolution*)

Function to resample the lagtime grid to a given volume. For use if the grid from Grid2Time is too large or you want to run a faster, downsampled scan.

Parameters

- **stations** (*list*) – List of station names from in the form where stations[i] refers to nodes[i][:] and lags[i][:]
- **nodes** (*list, tuple*) – List of node points where nodes[i] referes to stations[i] and nodes[:][:][0] is latitude in degrees, nodes[:][:][1] is longitude in degrees, nodes[:][:][2] is depth in km.
- **lags** – Array of arrays where lags[i][:] refers to stations[i]. lags[i][j] should be the delay to the nodes[i][j] for stations[i] in seconds :type volume: tuple
- **volume** – list of tuples: [(mindepth, maxdepth),(minlat, maxlat),(minlong, maxlong)]. This will be interpreted as a cuboid.

Returns list stations, list of lists of tuples nodes, :class: 'numpy.array' lags station[1] refers to nodes[1] and lags[1] nodes[1][1] refers to station[1] and lags[1][1] nodes[n][n] is a tuple of latitude, longitude and depth.

bright_lights.**brightness**(*stations*, *nodes*, *lags*, *stream*, *threshold*, *thresh_type*)

Function to calculate the brightness function in terms of energy for a day of data over the entire network for a given grid of nodes.

Note data in stream must be all of the same length and have the same sampling rates.

Parameters

- **stations** (*list*) – List of station names from in the form where stations[i] refers to nodes[i][:] and lags[i][:]
- **nodes** (*list, tuple*) – List of node points where nodes[i] referes to stations[i] and nodes[:][:][0] is latitude in degrees, nodes[:][:][1] is longitude in degrees, nodes[:][:][2] is depth in km.
- **lags** – Array of arrays where lags[i][:] refers to stations[i]. lags[i][j] should be the delay to the nodes[i][j] for stations[i] in seconds.
- **data** – Data through which to look for detections.
- **threshold** (*float*) – Threshold value for detection of template within the brightness function
- **thresh_type** (*str*) – Either MAD or abs where MAD is the Mean Absolute Deviation and abs is an absoulte brightness.

Returns list of templates as :class: *obspy.Stream* objects

5.2 template_gen

Function to generate template waveforms and information to go with them for the application of cross-correlation of seismic data for the detection of repeating events.

Part of the EQcorrscan module to read nordic format s-files EQcorrscan is a python module designed to run match filter routines for seismology, within it are routines for integration to seisan and obspy. With obspy integration (which is necessary) all main waveform formats can be read in and output.

This main section contains a script, LFE_search.py which demonstrates the usage of the built in functions from template generation from picked waveforms through detection by match filter of continuous data to the generation of lag times to be used for relative locations.

The match-filter routine described here was used a previous Matlab code for the Chamberlain et al. 2014 G-cubed publication. The basis for the lag-time generation section is outlined in Hardebeck & Shelly 2011, GRL.

Code generated by Calum John Chamberlain of Victoria University of Wellington, 2015.

Pre-requisites: gcc - for the installation of the openCV correlation routine python-joblib - used for parallel processing python-obspy - used for lots of common seismological processing

- **requires:** numpy scipy matplotlib

python-pylab - used for plotting

`template_gen.`**`_template_gen`**(*picks*, *st*, *length*, *swin*)

Function to generate a cut template in the obspy Stream class from a given set of picks and data, also in an obspy stream class. Should be given pre-processed data (downsampled and filtered)

float, float, string: picks must be in the form of a makeSfile.pick class type, stream must be an obspy data stream, all other arguments can be numbers save for swin which must be either P, S or all (case-sensitive).

`template_gen.`**`from_contbase`**(*sfile*)

Function to read in picks from sfile then generate the template from the picks within this and the wavefiles from the continous database of day-long files. Included is a section to sanity check that the files are daylong and that they start at the start of the day. You should ensure this is the case otherwise this may alter your data if your data are daylong but the headers are incorrectly set.

sfilename must be the path to a seisan nordic type s-file containing waveform and pick information, all other arguments can be numbers save for swin which must be either P, S or all (case-sensitive).

`template_gen.`**`from_sfile`**(*sfile*)

Function to read in picks from sfile then generate the template from the picks within this and the wavefile found in the pick file.

path to a seisan nordic type s-file containing waveform and pick information, all other arguments can be numbers save for swin which must be either P, S or all (case-sensitive).

5.3 match_filter

Function to cross-correlate templates generated by template_gen function with data and output the detecitons. The main component of this script is the normxcorr2 function from the openCV image processing package. This is a highly optimized and accurate normalized cross-correlation routine. The details of this code can be found here:

http://www.cs.ubc.ca/research/deaton/remarks_ncc.html

The cpp code was first tested using the Matlab mex wrapper, and has since been ported to a python callable dynamic library.

Part of the EQcorrscan module to integrate seisan nordic files into a full cross-channel correlation for detection routine. EQcorrscan is a python module designed to run match filter routines for seismology, within it are routines for integration to seisan and obspy. With obspy integration (which is necessary) all main waveform formats can be read in and output.

This main section contains a script, LFE_search.py which demonstrates the usage of the built in functions from template generation from picked waveforms through detection by match filter of continuous data to the generation of lag times to be used for relative locations.

The match-filter routine described here was used a previous Matlab code for the Chamberlain et al. 2014 G-cubed publication. The basis for the lag-time generation section is outlined in Hardebeck & Shelly 2011, GRL.

Code generated by Calum John Chamberlain of Victoria University of Wellington, 2015.

Pre-requisites: gcc - for the installation of the openCV correlation routine python-joblib - used for parallel processing python-obspy - used for lots of common seismological processing

- **requires:** numpy scipy matplotlib

python-pylab - used for plotting

class match_filter.**DETECTION**(*template_name*, *detect_time*, *no_chans*, *detect_val*, *threshold*, *typeofdet*, *chans=None*)

Information required for a full detection based on cross-channel correlation sums.

Attributes:

type template_name str

param template_name The name of the template for which this detection was made

type detect_time

class 'obspy.UTCDateTime'

param detect_time Time of detection as an obspy UTCDateTime object

type no_chans int

param no_chans The number of channels for which the cross-channel correlation sum was calculated over.

type chans list of str

param chans List of stations for the detection

type cccsum_val float

param cccsum_val The raw value of the cross-channel correlation sum for this detection.

type threshold float

param threshold The value of the threshold used for this detection, will be the raw threshold value related to the cccsum.

type typeofdet str

param typeofdet Type of detection, STA, corr, bright

match_filter.**_channel_loop**(*tr*, *stream*, *delay*)

Intermediate step which can be run in parallel to correlate a single channel template with a single channel of data only if the channel and template match header values. Written to allow parallelisation at this step.

Parameters

- **tr** – Single trace of template seismic data
- **chan** – Single trace of day-long seismic data to be used as an image
- **delay** (*float*) – time in seconds to apply a lag to the data by.

Returns

class 'numpy.array' of single channel cross-correlation values

match_filter.**_template_loop**(*templates*, *delays*, *stream*, *plotvar*)

Higher level routine to handle correlation of a Stream of day-long data channels with a series of templates. The idea is to run this in parallel as these correaltions can be run incredibly quickly at little cost. The most memory efficient way to run this would be to run the correlations in parallel for each channel.

Parameters **template** – A list of templates, where each one should be an

obspy.Stream object containing multiple traces of seismic data and the relevant header information. :type delays: float :param delays: A list of lists of delays order in the same way as the templates, e.g. delays[1][1] referes to the first trace in templates[1] :type stream: :class: 'obspy.Stream' :param stream: A single obspy.Stream object containing daylong seismic data to be correlated through using the templates. This is in effect the image

Returns New list of :class: 'numpy.array' objects. These will contain the

correlation sums for each template for this day of data. :return: list of ints as number of channels used for each cross-correlation

match_filter.**match_filter**(*template_names*, *templates*, *delays*, *stream*, *threshold*, *threshold_type*, *trig_int*, *plotvar*)

Over-arching code to run the correlations of given templates with a day of seismic data and output the detections based on a given threshold.

Parameters **templates** (*list :class: 'obspy.Stream'*) – A list of templates of which each template is a Stream of

obspy traces containing seismic data and header information. :type stream: :class: 'obspy.Stream' :param stream: An obspy.Stream object containing all the data available and required for the correlations with templates given. For efficiency this should contain no excess traces which are not in one or more of the templates. :type threshold: float :param threshold: A threshold value set based on the threshold_type :type threshold_type: str :param threshold:type: The type of threshold to be used, can be MAD, absolute or av_chan_corr. MAD threshold is calculated as the threshold*(mean(abs(cccsum))) where cccsum is the cross-correlation sum for a given template. absolute threhsold is a true absolute threshold based on the cccsum value av_chan_corr is based on the mean values of single-channel cross-correlations assuming all data are present as required for the template, e.g. av_chan_corr_thresh=threshold*(cccsum/len(template)) where template is a single template from the input and the length is the number of channels within this template.

Returns

class 'DETECTIONS' detections for each channel formatted as

Class 'obspy.UTCDateTime' objects.

match_filter.**normxcorr2**(*template*, *image*)

Base function to call the c++ correlation routine from the openCV image processing suite. Requires you to have installed the openCV python bindings, which can be downloaded on Linux machines using:

sudo apt-get install python-openCV

Here we use the cv2.TM_CCOEFF_NORMED method within openCV to give the normalized cross-correaltion. Documentation on this function can be found here:

http://docs.opencv.org/modules/imgproc/doc/object_detection.html?highlight=matchtemplate#cv2.matchTemplate

Parameters **image** – Requires two numpy arrays, the template and the image to scan

the template through. The order of these matters, if you put the template after the imag you will get a reversed correaltion matrix

Returns New :class: 'numpy.array' object of the correlation values for the

correaltion of the image with the template.

b

f

m

s

t

Symbols

B

D

F

I

M

N

P

R

S

T