

# Greedy Algorithms, Independence Systems, and Matroids.

Endre Boros  
26:711:653: Discrete Optimization

# Independence systems

- ▶ A hypergraph  $(E, \mathcal{F})$ ,  $\mathcal{F} \subseteq 2^E$  is called an **independence system** if it satisfies the following two axioms:

(M0)  $\emptyset \in \mathcal{F}$

(M1) If  $X \subseteq Y \in \mathcal{F}$  then  $X \in \mathcal{F}$ .

- ▶ Sets in  $\mathcal{F}$  are called **independent**, while those in  $2^E \setminus \mathcal{F}$  are called **dependent**.
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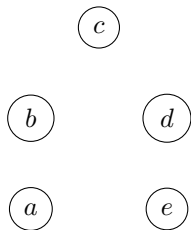
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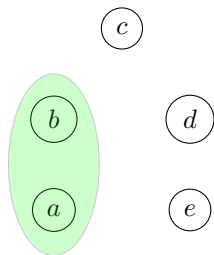
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# Example for an independence system



- ▶  $E = \{a, b, c, d, e\}$
- ▶  $\{a, b\}$  is a maximal hyperedge edge
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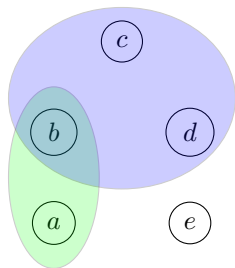
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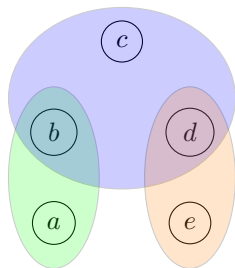


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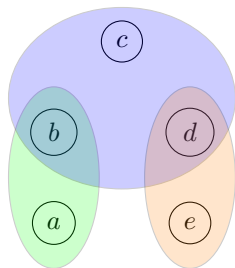
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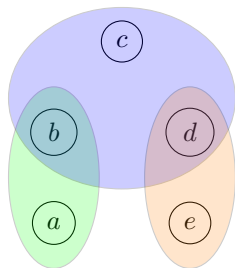
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- ▶ Given an independence system  $(E, \mathcal{F})$  ( $\mathcal{F} \subseteq 2^E$ ) and nonnegative real weights  $c : \mathcal{F} \mapsto \mathbb{R}_+$ , find an independent set (a hyperedge)  $F \in \mathcal{F}$  such that

$$c(F) = \sum_{e \in F} c(e)$$

is as large as possible.

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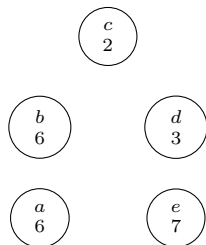
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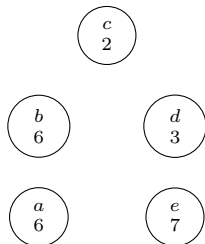
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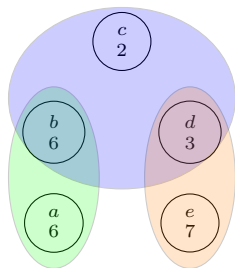
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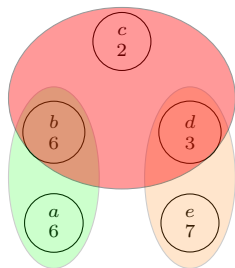


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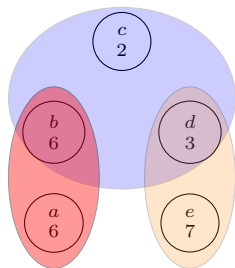
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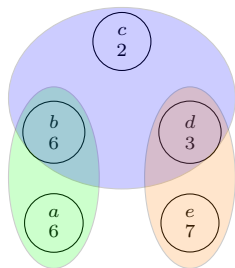
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- ▶ Independence systems are typically not given explicitly, but via an independence **oracle**: for a given  $S \subseteq E$  such an oracle tells if  $S \in \mathcal{F}$  or not.

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- ▶ Given a hypergraph  $\mathcal{H} \subseteq 2^V$ , a subset  $S \subseteq V$  is called **independent** (stable) if  $H \not\subseteq S$  for all  $H \in \mathcal{H}$ .
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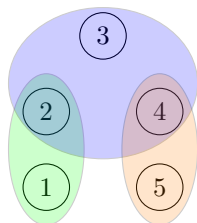
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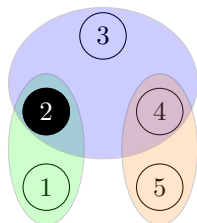
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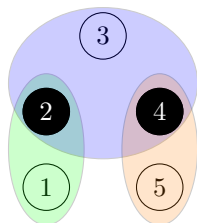
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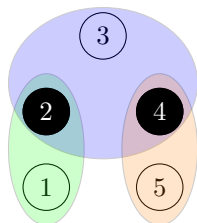
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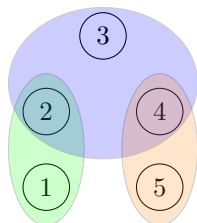
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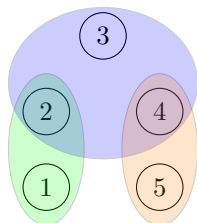
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- ▶ Consider  $V = \{1, 2, 3, 4, 5\}$  and  $\mathcal{H} = \{12, 234, 45\} \subseteq 2^V$
- ▶  $S = \{2\}$  is an independent set
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- ▶  $\mathcal{B} = \{134, 135, 235, 24\}$  is the family of maximal independent sets of  $\mathcal{H}$  (bases of  $\mathcal{F}$ ).
- ▶  $|\mathcal{B}|$  can be exponentially large in  $|V|$  and  $|\mathcal{H}|!$

# Examples for MWISP: maximum weight stable set



- ▶ Given a hypergraph  $\mathcal{H} \subseteq 2^V$ , a subset  $S \subseteq V$  is called **independent** (stable) if  $H \not\subseteq S$  for all  $H \in \mathcal{H}$ .
- ▶ **The family  $\mathcal{F}$  of all stable sets form an independence system. (WHY?)**
- ▶ The hypergraph  $(V, \mathcal{H})$  serves as an independence oracle for  $\mathcal{F}$ :
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# List of MWISP examples

- ▶ Maximum weight (cardinality) stable set
- ▶ Maximum weight matching
- ▶ Minimum weight perfect matching
- ▶ Maximum weight spanning tree
- ▶ Shortest path
- ▶ Generalized knapsack
- ▶ Set covering
- ▶ Some of the above are easy (polynomial), while others are hard (NP-hard).
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# Best-in-Greedy

**Input:** An independence system  $(E, \mathcal{F})$ , and weights  $c : E \rightarrow \mathbb{R}$ .

**Initialize:** Set  $F^G = \emptyset$ , and **sort**  $E = \{e_1, e_2, \dots, e_m\}$  such that  
$$c(e_1) \geq c(e_2) \geq \dots \geq c(e_m).$$

**Main Loop:** **For**  $k = 1, \dots, m$  **do:**

**If**  $F^G \cup \{e_k\} \in \mathcal{F}$  **then**  $F^G = F^G \cup \{e_k\}$ .

**Output:**  $F^G$ .

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# Correctness and Running time of Best-in-Greedy

**Complexity:** Sorting in **Initialization** takes  $O(m \log m)$  time, while **Main Loop** can be executed in  $O(m)$  time with  $O(m)$  calls to the independence oracle. Thus, the total time needed to run (BEST-IN) GREEDY is  $O(m \log m + mI)$ , where  $I$  is the worst case time we need to run the independence oracle.

**Correctness:** It is easy to verify that we have  $F^G \in \mathcal{F}$  upon termination, since in the **Main Loop**  $F^G$  is updated only if it remains independent.

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# Analysis of Best-in-Greedy

- ▶ To a subset  $X \subseteq E$  we associate the **induced sub-hypergraph**  $\mathcal{F}_X = \{X \cap F \mid F \in \mathcal{F}\}$ , and let us denote by  $\mathcal{B}_X$  the set of bases of  $\mathcal{F}_X$ .
- ▶ Let us define the **rank** of a subset  $X \subseteq E$  by

$$r(X) = \max_{F \in \mathcal{F}} |F \cap X| = \max_{B \in \mathcal{B}_X} |B|.$$

- ▶ Let the **lower rank** of  $X$  be defined by

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# Analysis of Best-in-Greedy cont'd

## Lemma 1

*We have the following relations hold for all independent sets  $F \in \mathcal{F}$ , subsets  $X \subseteq E$ , and bases  $B \in \mathcal{B}_X$  of the induced independence system  $\mathcal{F}_X$ :*

$$|B| \geq \rho(X) \qquad = \min_{A \in \mathcal{B}_X} |A|. \qquad (1a)$$

$$\frac{\rho(X)}{r(X)} \geq q(E, \mathcal{F}) \qquad = \min_{Y \subseteq E} \frac{\rho(Y)}{r(Y)} \qquad (1b)$$

$$|F \cap X| \leq r(X) \qquad = \max_{F \in \mathcal{F}} |F \cap X| \qquad (1c)$$

□

# Analysis of Best-in-Greedy cont'd

## Theorem 2 (Jenkins (1976), Korte and Hausmann (1978))

*Given an independence system  $(E, \mathcal{F})$  and weights  $c : E \mapsto \mathbb{R}_+$ , let  $F^G$  denote the solution obtained by the best-in-greedy procedure, and let  $F^{OPT}$  denote the optimal solution. Then we have*

$$q(E, \mathcal{F}) \leq \frac{c(F^G)}{c(F^{OPT})} \leq 1.$$

*Furthermore, for every independence system there exist weights such that the lower bound is attained in the above statement.*

► Guarantee  $q(E, \mathcal{F})$  does not depend on the weights  $c : E \mapsto \mathbb{R}_+$ !!!

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