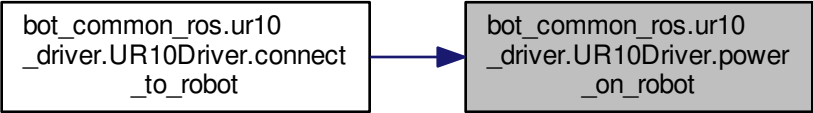


```
bot_common_ros.ur10  
_driver.UR10Driver.connect  
_to_robot
```



```
bot_common_ros.ur10  
_driver.UR10Driver.power  
_on_robot
```