

scripts.tests.node  
\_test\_ros\_action\_server.Async  
ChiselTestActionServer.new  
\_goal\_callback

```
graph LR; A["scripts.tests.node  
_test_ros_action_server.Async  
ChiselTestActionServer.new  
_goal_callback"] --> B["bot_common_ros.actions.Action  
Server._finish"]; A --> C["bot_common_ros.actions.Action  
Server._get_action_from_goal"]
```

bot\_common\_ros.actions.Action  
Server.\_finish

bot\_common\_ros.actions.Action  
Server.\_get\_action\_from\_goal