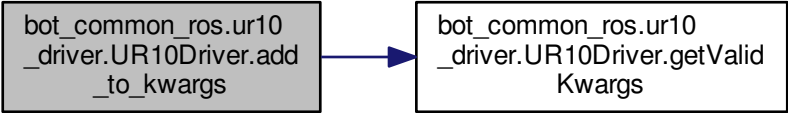


```
bot_common_ros.ur10  
_driver.UR10Driver.add  
_to_kwargs
```



```
graph LR; A["bot_common_ros.ur10_driver.UR10Driver.add_to_kwargs"] --> B["bot_common_ros.ur10_driver.UR10Driver.getValidKwargs"]
```

A diagram showing a flow from a function call to another. The first box, with a gray background, contains the text 'bot_common_ros.ur10_driver.UR10Driver.add_to_kwargs'. A blue arrow points from this box to a second box on the right, which has a white background and contains the text 'bot_common_ros.ur10_driver.UR10Driver.getValidKwargs'.

```
bot_common_ros.ur10  
_driver.UR10Driver.getValid  
Kwargs
```