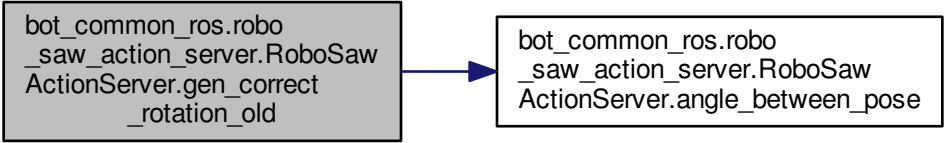


```
bot_common_ros.robo  
_saw_action_server.RoboSaw  
ActionServer.gen_correct  
_rotation_old
```



A diagram consisting of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains the text 'bot\_common\_ros.robo\_saw\_action\_server.RoboSawActionServer.gen\_correct\_rotation\_old'. The right box has a white background and contains the text 'bot\_common\_ros.robo\_saw\_action\_server.RoboSawActionServer.angle\_between\_pose'.

```
bot_common_ros.robo  
_saw_action_server.RoboSaw  
ActionServer.angle_between_pose
```