

bot_common_ros.robo
_chisel_action_server.Robo
ChiselActionServer.MAIN

bot_common_ros.robo
_saw_action_server.RoboSaw
ActionServer.MAIN

bot_common_ros.actions.Action
Server.start

```
graph LR; A["bot_common_ros.robo_chisel_action_server.RoboChiselActionServer.MAIN"] --> C["bot_common_ros.actions.ActionServer.start"]; B["bot_common_ros.robo_saw_action_server.RoboSawActionServer.MAIN"] --> C;
```

The diagram illustrates a dependency or call relationship. Two boxes on the left, representing specific action server main functions, have arrows pointing to a single box on the right, representing a common action server start function. The top box is 'bot_common_ros.robo_chisel_action_server.RoboChiselActionServer.MAIN' and the bottom box is 'bot_common_ros.robo_saw_action_server.RoboSawActionServer.MAIN'. Both point to 'bot_common_ros.actions.ActionServer.start'.