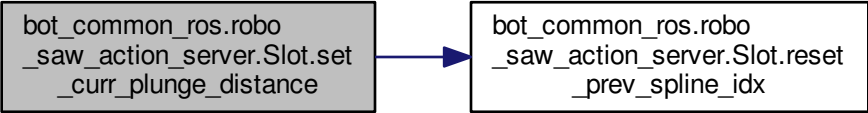


```
bot_common_ros.robo  
_saw_action_server.Slot.set  
_curr_plunge_distance
```



```
graph LR; A["bot_common_ros.robo_saw_action_server.Slot.set_curr_plunge_distance"] --> B["bot_common_ros.robo_saw_action_server.Slot.reset_prev_spline_idx"]
```

```
bot_common_ros.robo  
_saw_action_server.Slot.reset  
_prev_spline_idx
```