

bot\_common\_ros.robo  
\_chisel\_action\_server.Robo  
ChiselActionServer.MAIN

bot\_common\_ros.robo  
\_saw\_action\_server.RoboSaw  
ActionServer.MAIN

bot\_common\_ros.actions.FSMAction  
Server.fsm\_register\_status\_changes

```
graph LR; A["bot_common_ros.robo_chisel_action_server.RoboChiselActionServer.MAIN"] --> C["bot_common_ros.actions.FSMActionServer.fsm_register_status_changes"]; B["bot_common_ros.robo_saw_action_server.RoboSawActionServer.MAIN"] --> C;
```

The diagram illustrates a dependency or data flow. Two separate components on the left, 'bot\_common\_ros.robo\_chisel\_action\_server.RoboChiselActionServer.MAIN' and 'bot\_common\_ros.robo\_saw\_action\_server.RoboSawActionServer.MAIN', both point via blue arrows to a single component on the right, 'bot\_common\_ros.actions.FSMActionServer.fsm\_register\_status\_changes'. The right-hand box is shaded gray, while the left-hand boxes are white with black borders.