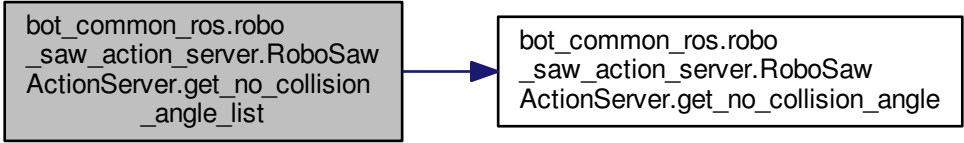


```
bot_common_ros.robo  
_saw_action_server.RoboSaw  
ActionServer.get_no_collision  
_angle_list
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'bot\_common\_ros.robo\_saw\_action\_server.RoboSawActionServer.get\_no\_collision\_angle\_list'. The right box has a white background and contains the text 'bot\_common\_ros.robo\_saw\_action\_server.RoboSawActionServer.get\_no\_collision\_angle'. The arrow indicates a mapping or transformation from the list-based representation on the left to the angle-based representation on the right.

```
bot_common_ros.robo  
_saw_action_server.RoboSaw  
ActionServer.get_no_collision_angle
```