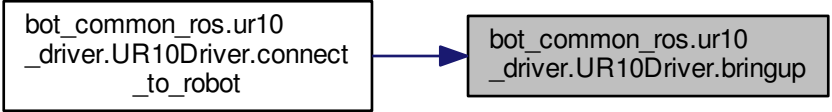


```
bot_common_ros.ur10  
_driver.UR10Driver.connect  
_to_robot
```



```
graph LR; A["bot_common_ros.ur10_driver.UR10Driver.connect_to_robot"] --> B["bot_common_ros.ur10_driver.UR10Driver.bringup"]
```

A flow diagram consisting of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'bot_common_ros.ur10_driver.UR10Driver.connect_to_robot'. The right box is gray with a black border and contains the text 'bot_common_ros.ur10_driver.UR10Driver.bringup'.

```
bot_common_ros.ur10  
_driver.UR10Driver.bringup
```