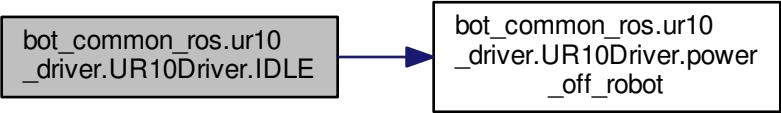


bot_common_ros.ur10
_driver.UR10Driver.IDLE



```
graph LR; A["bot_common_ros.ur10_driver.UR10Driver.IDLE"] --> B["bot_common_ros.ur10_driver.UR10Driver.power_off_robot"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'bot_common_ros.ur10_driver.UR10Driver.IDLE'. The right box has a white background and contains the text 'bot_common_ros.ur10_driver.UR10Driver.power_off_robot'.

bot_common_ros.ur10
_driver.UR10Driver.power
_off_robot