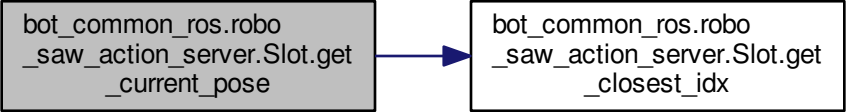


```
bot_common_ros.robo  
_saw_action_server.Slot.get  
_current_pose
```



```
graph LR; A["bot_common_ros.robo_saw_action_server.Slot.get_current_pose"] --> B["bot_common_ros.robo_saw_action_server.Slot.get_closest_idx"]
```

A diagram showing a flow from a function call to another. The first box, with a gray background, contains the text 'bot_common_ros.robo_saw_action_server.Slot.get_current_pose'. A blue arrow points from the right side of this box to the left side of a second box. The second box has a white background and contains the text 'bot_common_ros.robo_saw_action_server.Slot.get_closest_idx'.

```
bot_common_ros.robo  
_saw_action_server.Slot.get  
_closest_idx
```