


```
bot_common_ros.ur_utils.image  
_depth.__init__
```



```
graph LR; A["bot_common_ros.ur_utils.image  
_depth.__init__"] --> B["bot_common_ros.ur_utils.image  
_depth.image_depth_listener"]
```

A diagram showing a call from the `__init__` method of the `image_depth` class to the `image_depth_listener` method of the same class. The left box is shaded gray and the right box is white. A blue arrow points from the left box to the right box.

```
bot_common_ros.ur_utils.image  
_depth.image_depth_listener
```