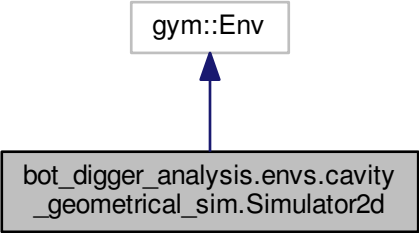


gym::Env



```
graph BT; Simulator2d[bot_digger_analysis.envs.cavity_geometrical_sim.Simulator2d] --> Env[gym::Env]
```

bot\_digger\_analysis.envs.cavity  
\_geometrical\_sim.Simulator2d