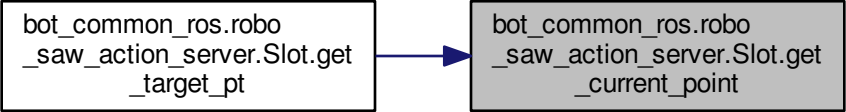


```
bot_common_ros.robo  
_saw_action_server.Slot.get  
_target_pt
```



A diagram consisting of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'bot\_common\_ros.robo\_saw\_action\_server.Slot.get\_target\_pt'. The right box is gray with a black border and contains the text 'bot\_common\_ros.robo\_saw\_action\_server.Slot.get\_current\_point'. A blue arrow points from the right side of the left box to the left side of the right box.

```
bot_common_ros.robo  
_saw_action_server.Slot.get  
_current_point
```