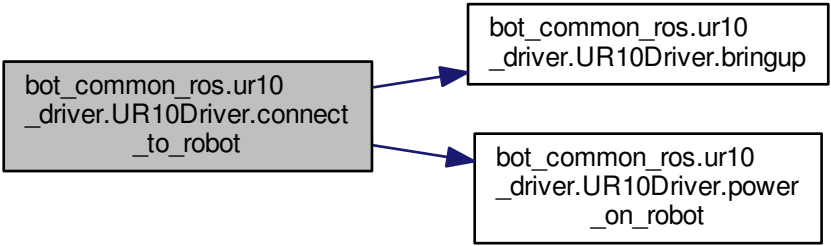


bot\_common\_ros.ur10  
\_driver.UR10Driver.connect  
\_to\_robot



```
graph LR; A["bot_common_ros.ur10_driver.UR10Driver.connect_to_robot"] --> B["bot_common_ros.ur10_driver.UR10Driver.bringup"]; A --> C["bot_common_ros.ur10_driver.UR10Driver.power_on_robot"]
```

bot\_common\_ros.ur10  
\_driver.UR10Driver.bringup

bot\_common\_ros.ur10  
\_driver.UR10Driver.power  
\_on\_robot