

bot_common_ros.robo
_chisel_action_server.Robo
ChiselActionServer.MAIN

bot_common_ros.robo
_saw_action_server.RoboSaw
ActionServer.MAIN

bot_common_ros.actions.FSMAction
Server.fsm_register_op_waits

```
graph LR; A["bot_common_ros.robo_chisel_action_server.RoboChiselActionServer.MAIN"] --> C["bot_common_ros.actions.FSMActionServer.fsm_register_op_waits"]; B["bot_common_ros.robo_saw_action_server.RoboSawActionServer.MAIN"] --> C;
```

The diagram illustrates a dependency or data flow. Two separate components on the left, 'bot_common_ros.robo_chisel_action_server.RoboChiselActionServer.MAIN' and 'bot_common_ros.robo_saw_action_server.RoboSawActionServer.MAIN', both point via blue arrows to a single target component on the right, 'bot_common_ros.actions.FSMActionServer.fsm_register_op_waits'. The target box is shaded gray, while the source boxes are white with black borders.