Clever Duckies

Simulation of Duck Behaviour Using Flocking and Finite State Machines

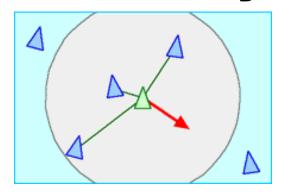


Emma Broman

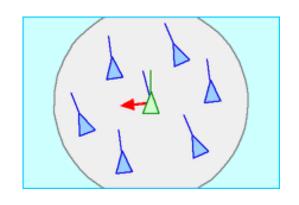
Agenda

- Flocking
- Finite State Machine (FSM)
- Demo
- Implementation
- Discussion
- Questions

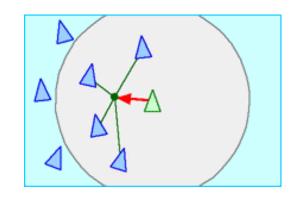
Boid Flocking







Alignment



Cohesion

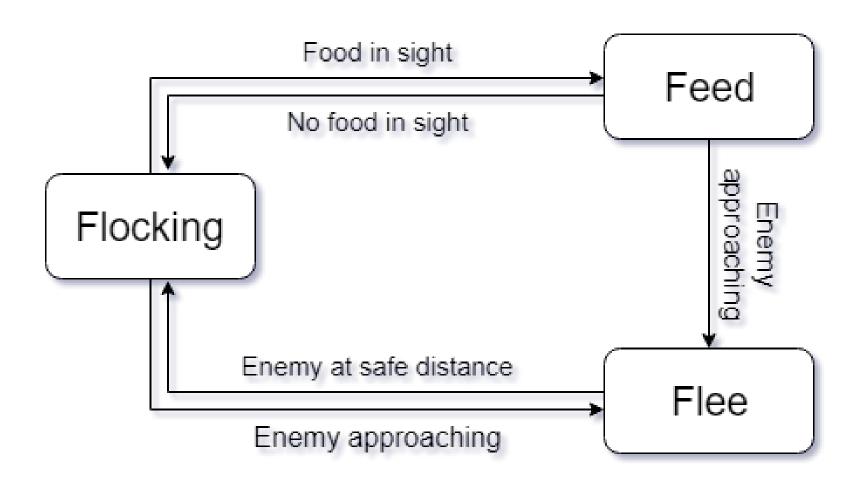
Source: Craig Reynolds, (2001). "Boids Algorithm" https://www.red3d.com/cwr/boids/

Finite State Machines (FSM)

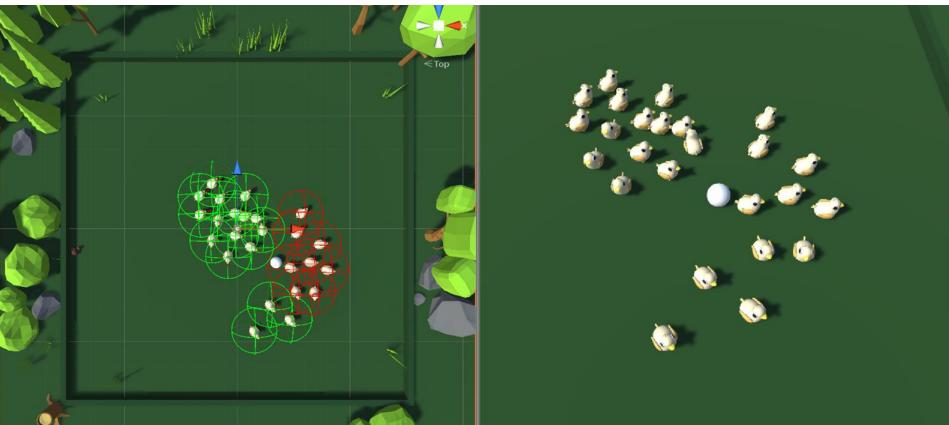
Describe behaviour using states

Agents can be in exactly one state at the time

Suitable for simple behaviours - few states and actions



Demo! (Unity)



Implementation

- Flocking
 - Find neighbors using collision
 - for each neighbor:
 - compute cohesion, separation and alignment contributions
 - boid.velocity += k * cohesion + l * separation + m * alignment

Implementation

• FSM:

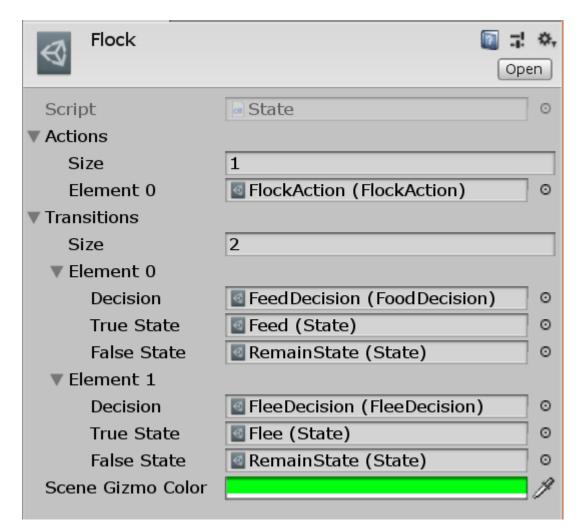
States Transitions + Actions

Actions

Decisions true/false

Transitions Decision + False State + True state

Pluggable machine, using ScriptableObjects in Unity



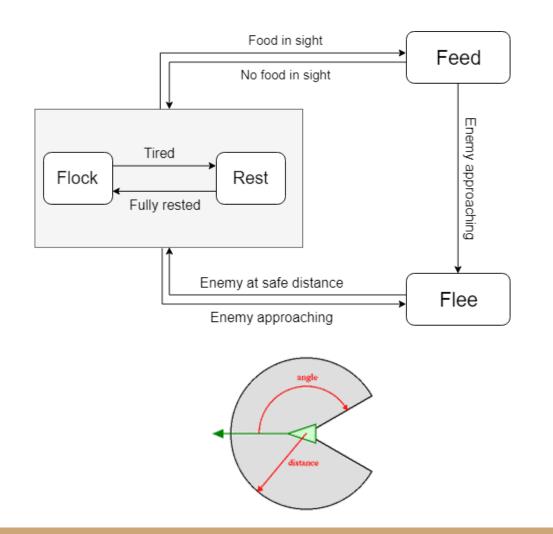
Discussion

- Why FSM?
 - Why not behaviour trees...?
 - Advantages/Disadvantages?
- Limitations?
 - Complexity of FSM can escalate quickly

Future Work

Hierarchical FSM for more complex behaviour

Make neighborhood angle dependent (cannot "see" behind itself)



Other improvements

- Pathfinding, better collision with edges
- Introduce some randomness
- FSM on Flock or Individual level?
- Learning? E.g. "How do I get the most food?"
- Game-ify!

Questions?