### Bandits on Stochastic Blockmodel Graphs

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Reinforcement Learning

January 2015

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#### Problem definition

N arms, T steps.

- The environment chooses losses for every arm noted  $l_{t,i}$  for the arm i at the step t.
- 2 Following the algorithm we hope would minimize as much as possible the regret the player draws an arm  $I_t$ .
- **3** The player receives the loss  $I_{t,l_t}$ .
- We define  $(O_t)_{i \in [N]}$  as the indicative function of observed loss at step t. We have:

$$O_{t,I_t} = 1$$
  $\forall i \neq I_t, O_{t,i} \sim B(r)$ 

- $\left(O_{t}\right)_{i\in[N]}$  corresponds to the value of the logic expression i is neighbor of  $I_{t}$  in the Erdös-Rényi random graph drawn at step t.
- **5** For all i such that  $O_{t,i} = 1$  the player can observe the loss  $I_{t,i}$ .

### Duplex tricks

#### Definition geometrical random variables

$$M_t^* = \min\{1 \le i < N : O'_{t-1,i} = 1\} \cup \{N\}$$
  
 $G_{t,i} = \min(K_{t,i}, M_t)$ 

#### Independence

$$p_{t+2,i} \propto w_{t+2,i} = \frac{1}{N} \exp\left(-\eta_{t+2} \hat{L}_{t,i}\right)$$

### Generalizing

ESTIMATE\_R gives a safe lower bounding on r.

If 
$$r = 0$$
, we run vanilla Exp3.

If 
$$\underline{r} \ge \frac{\log T}{N}$$
, we run vanilla DUPLEX.

If 
$$0 < \underline{r} < \frac{\log T}{N}$$
,  $A = \left\lceil \frac{\log T}{Nr} \right\rceil$  and run DUPLEX grouping  $A$  steps.

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## Random graph with Stochastic Block-Model

ZE figure!

# Probability of side information

- N clusters
- Labelled vertices
- $R = (r_{ij})_{1 \le i,j \le n}$  the matrix representing the probability of having side information.
- r<sub>ij</sub> represents the probability that a vertex of the cluster j reveals his loss to a given vertex of the cluster i

## Adapt $M_t$ sampling

#### Unbiased estimator

$$\hat{l}_{t,i}^* = \frac{O_{t,i}l_{t,i}}{p_{t,i} + (1 - p_{t,i})r_{C(l_t),C(i)}}$$

#### Using data...

$$\hat{l}_{t,i} = G_{t,i}O_{t,i}l_{t,i} \tag{1}$$

- Estimator  $G_{i,t} \sim G(p_{t,i} + (1 p_{t,i})r_{I_{t,i}})$
- $M_t^i$  truncated geometric law of parameter  $p_{t,i}$
- $\rightarrow G_{t,i} = \min(K_{t,i}, M_t^i)$

# Sampling $M_t^i$

- Using previous observations
- Ensure independence of  $M_t$  and  $O_t$
- Find the last  $O_{t'}$ , with  $t' \equiv t 1[2]$  in which C(I(t')) = C(I(t))
- Average the distance between two observation within cluster C(j).

# Lower bounding R

### Generalized algorithm

$$\begin{aligned} &\text{If } \underline{R} = 0, \\ &\text{If } \min_{i,j,\ \underline{r}_{i,j} > 0} \left(\underline{r}_{ij} \ N_j\right) \geq \log \ \mathcal{T}, \end{aligned}$$

Else,

we run vanilla Exp3.

we run adapted  $\mathrm{DUPLEX}.$ 

$$A = \left\lceil \frac{\log T}{r_{N^*}} \right\rceil \text{ where }$$

$$r_{N}* = \min_{i,j,\ \underline{r}_{i,j}>0} \left(\underline{r}_{ij}\ N_{j}\right)$$

and run DUPLEX grouping A steps.

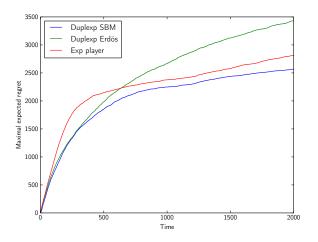
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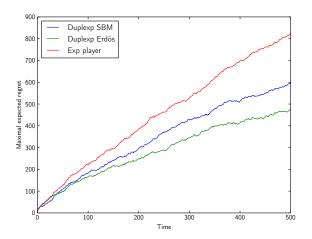
Results

# Heavily unbalanced graph



Outperformance of our algorithm

# Graph 'close' to Erdös-Rényi



Orginal algorithm outperforms our algorithm