CS61c Fall 2021 Lecture 14 Pipelining RISC-V



Review

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Controller

Tells universal datapath how to execute each instruction

Instruction timing

- Set by instruction complexity, architecture, technology
- Pipelining increases clock frequency, "instructions per second"
 - But does not reduce time to complete instruction

Performance measures

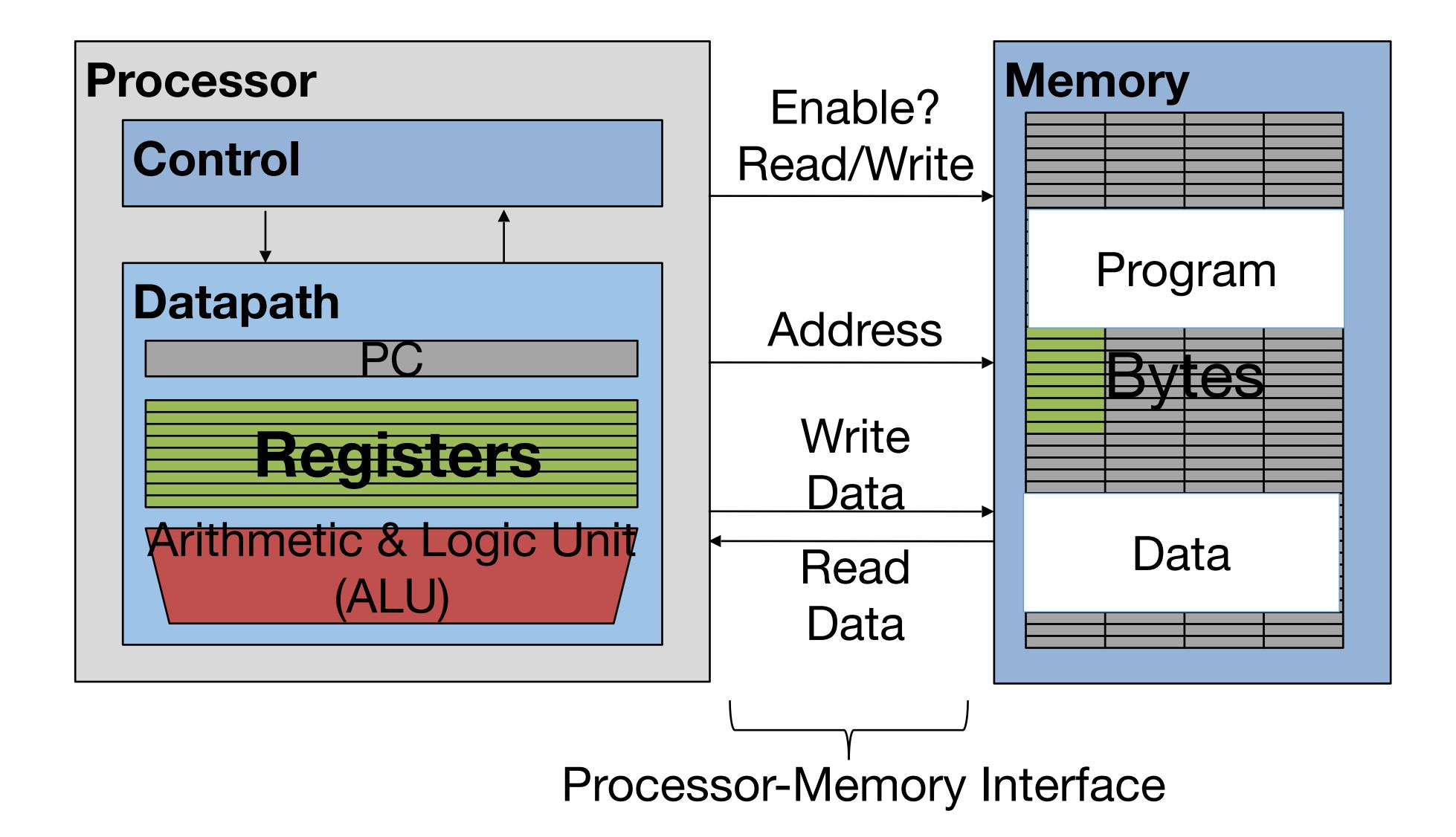
- Different measures depending on objective
 - Response time
 - Jobs / second
 - Energy Efficiency (joules/operation, joules/instruction)



Processor

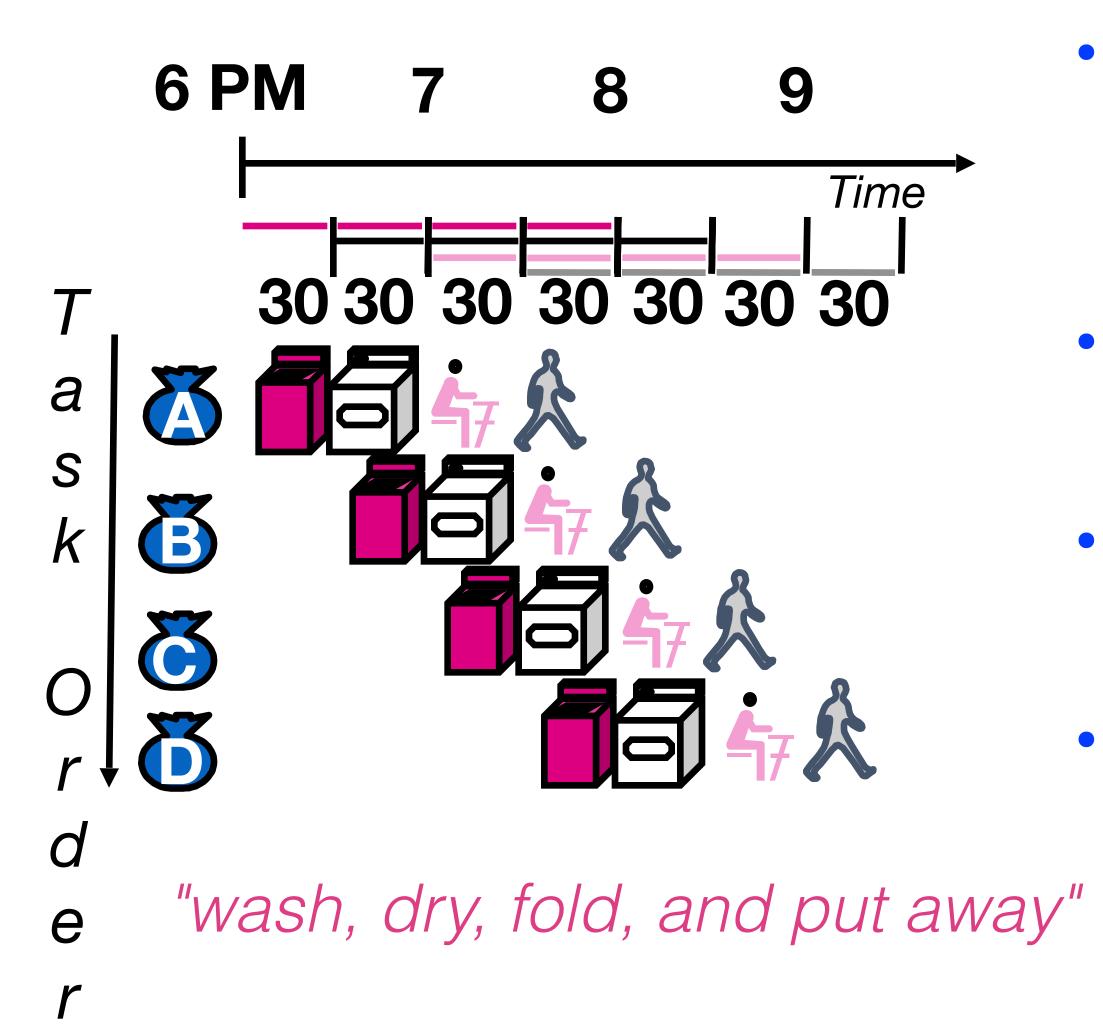
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Pipelining Overview (Review)



- Pipelining doesn't help *latency* of single task, it helps *throughput* of entire workload
- Multiple tasks operating simultaneously using different resources
- Potential speedup = Number pipe stages
- Time to "fill" pipeline and time to "drain" it reduces speedup:
 - 2.3X v. 4X in this example
 - With lots of laundry, approaches 4X



Agenda

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- RISC-V Pipeline
- Pipeline Control
- Hazards
 - Structural
 - Data
 - R-type instructions
 - Load
 - Control
- Superscalar processors



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Recap: Pipelining with RISC-V

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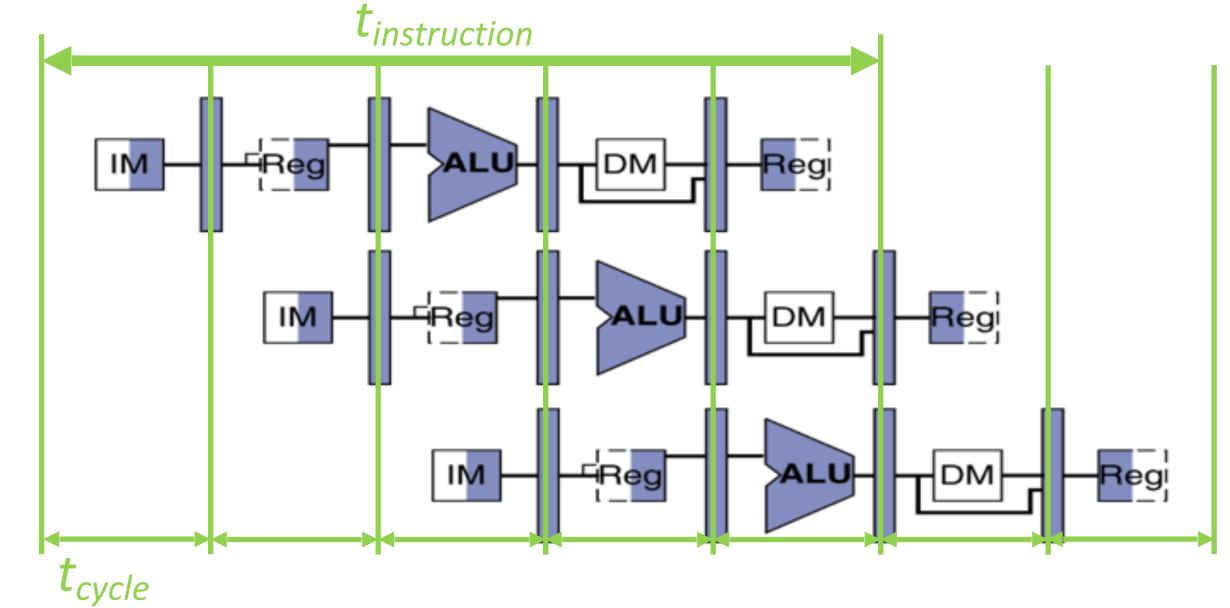
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instruction sequence

add t0, t1, t2

or t3, t4, t5

sll t6, t0, t3



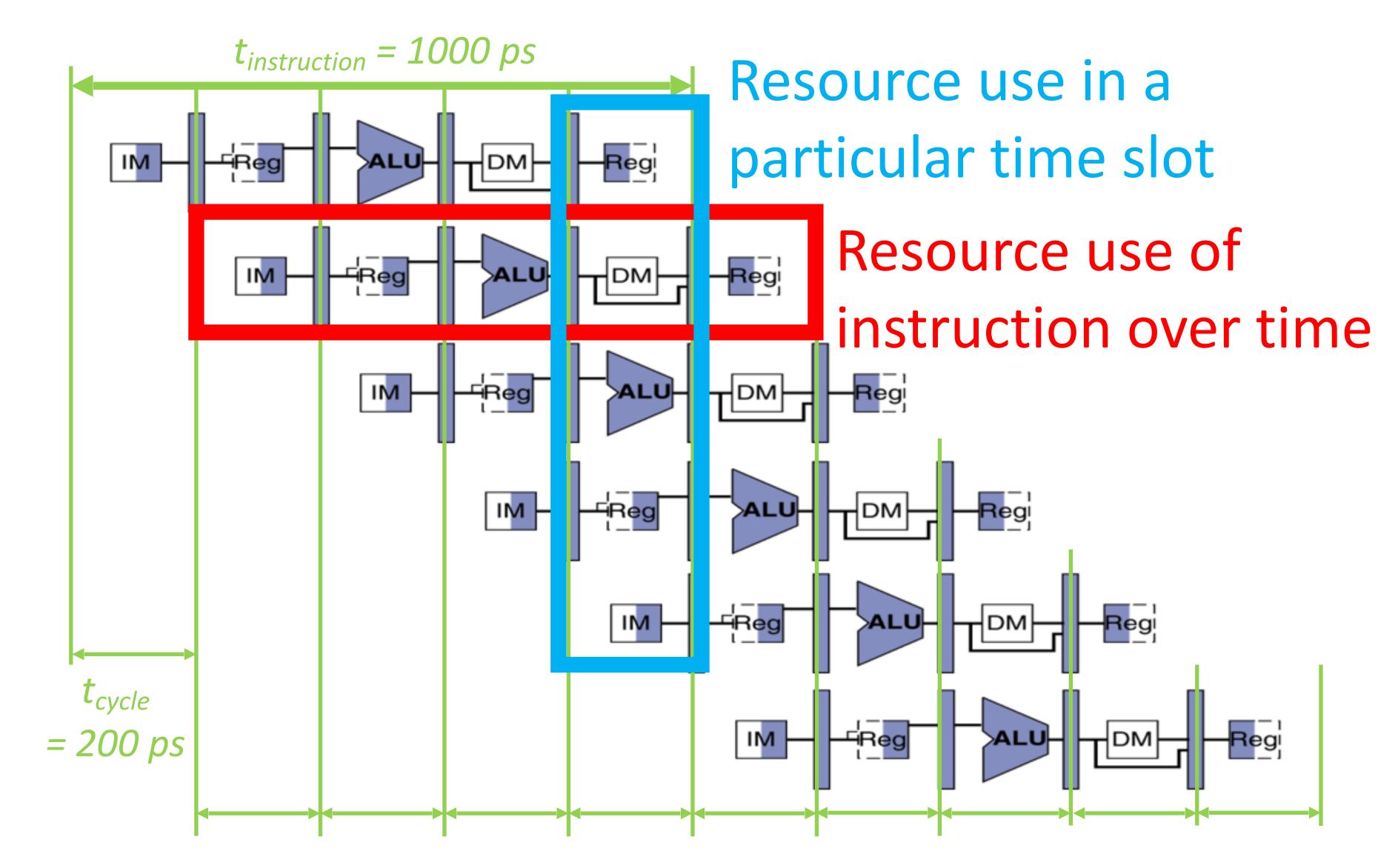
	Single Cycle	Pipelining
Timing	t _{step} = 100 200 ps	t_{cycle} = 200 ps
	Register access only 100 ps	All cycles same length
Instruction time, t _{instruction}	$= t_{cycle} = 800 \text{ ps}$	1000 ps
Clock rate, f_s	1/800 ps = 1.25 GHz	1/200 ps = 5 GHz
Relative speed	1 x	4 x



sw t0, 4(t3)

lw t0, 8(t3)

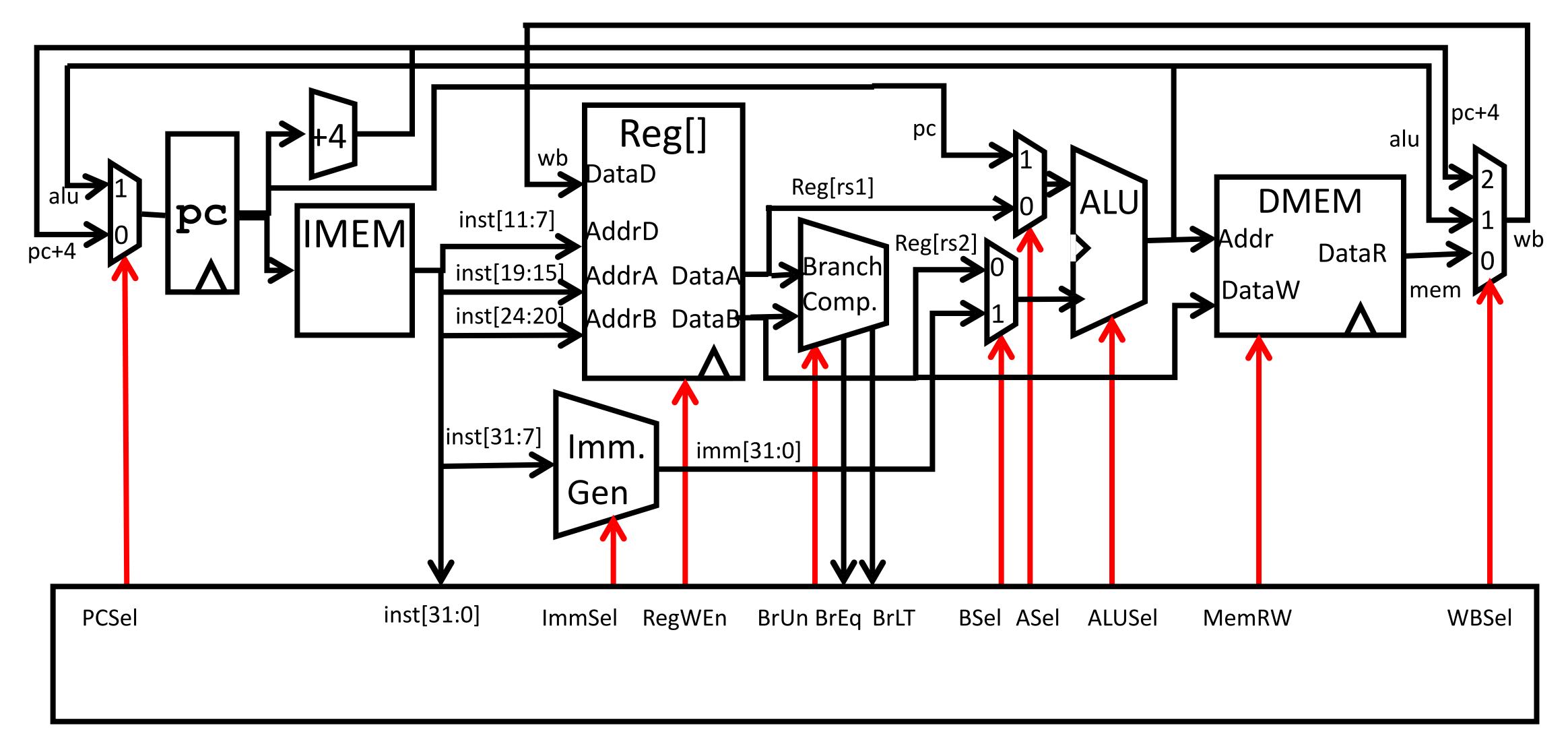
addi t2, t2, 1



sequence

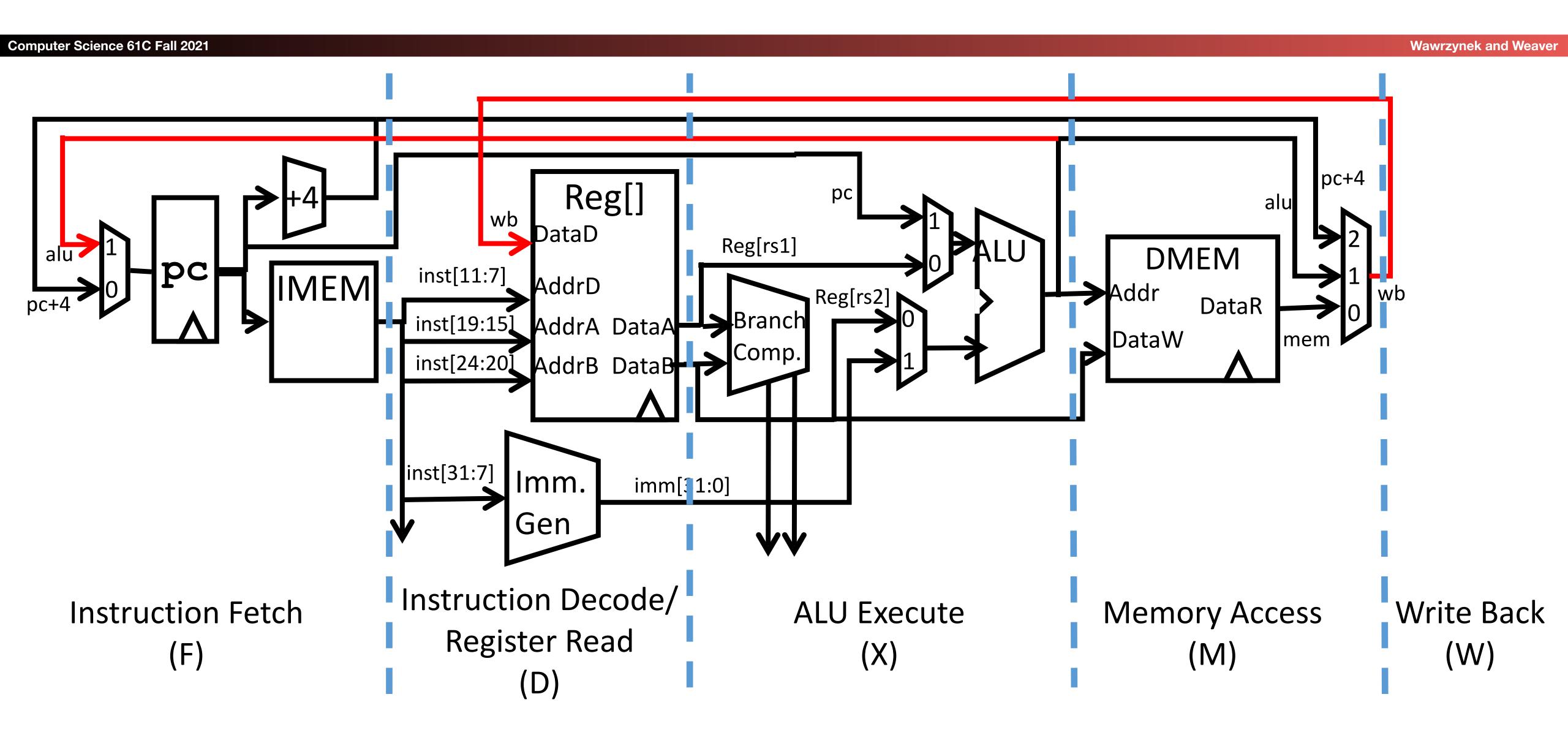
Single-Cycle RISC-V RV32I Datapath

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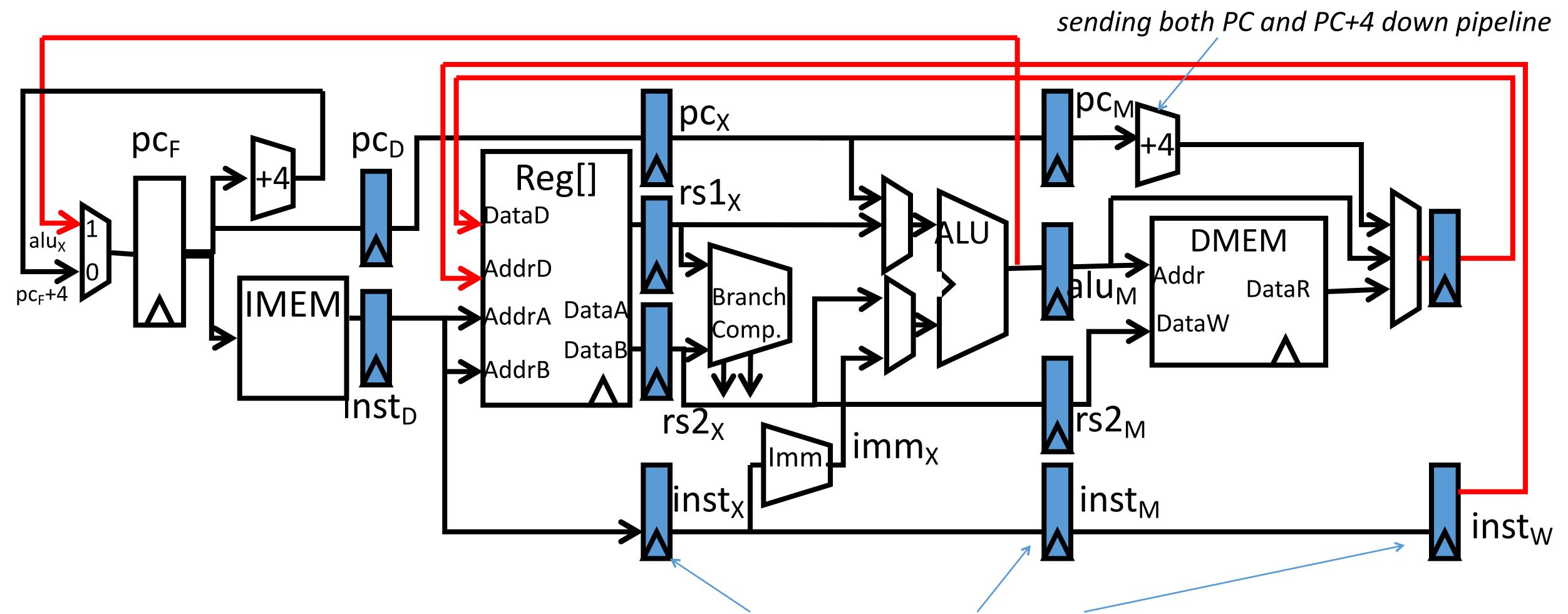
Pipelining RISC-V RV32I Datapath





Pipelined RISC-V RV32I Datapath

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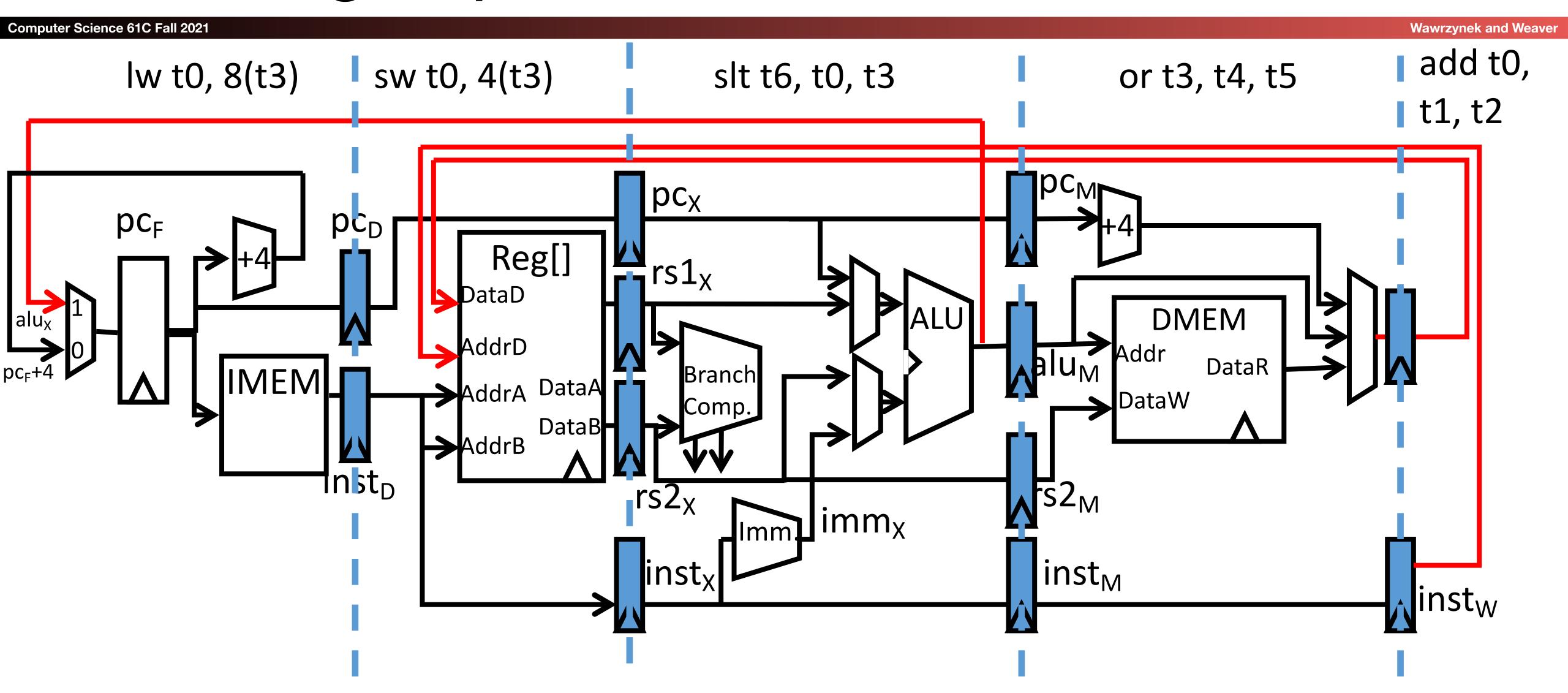




Must pipeline instruction along with data, so control operates correctly in each stage

Recalculate PC+4 in M stage to avoid

Each stage operates on different instruction





Pipeline registers separate stages, hold data for each instruction in flight

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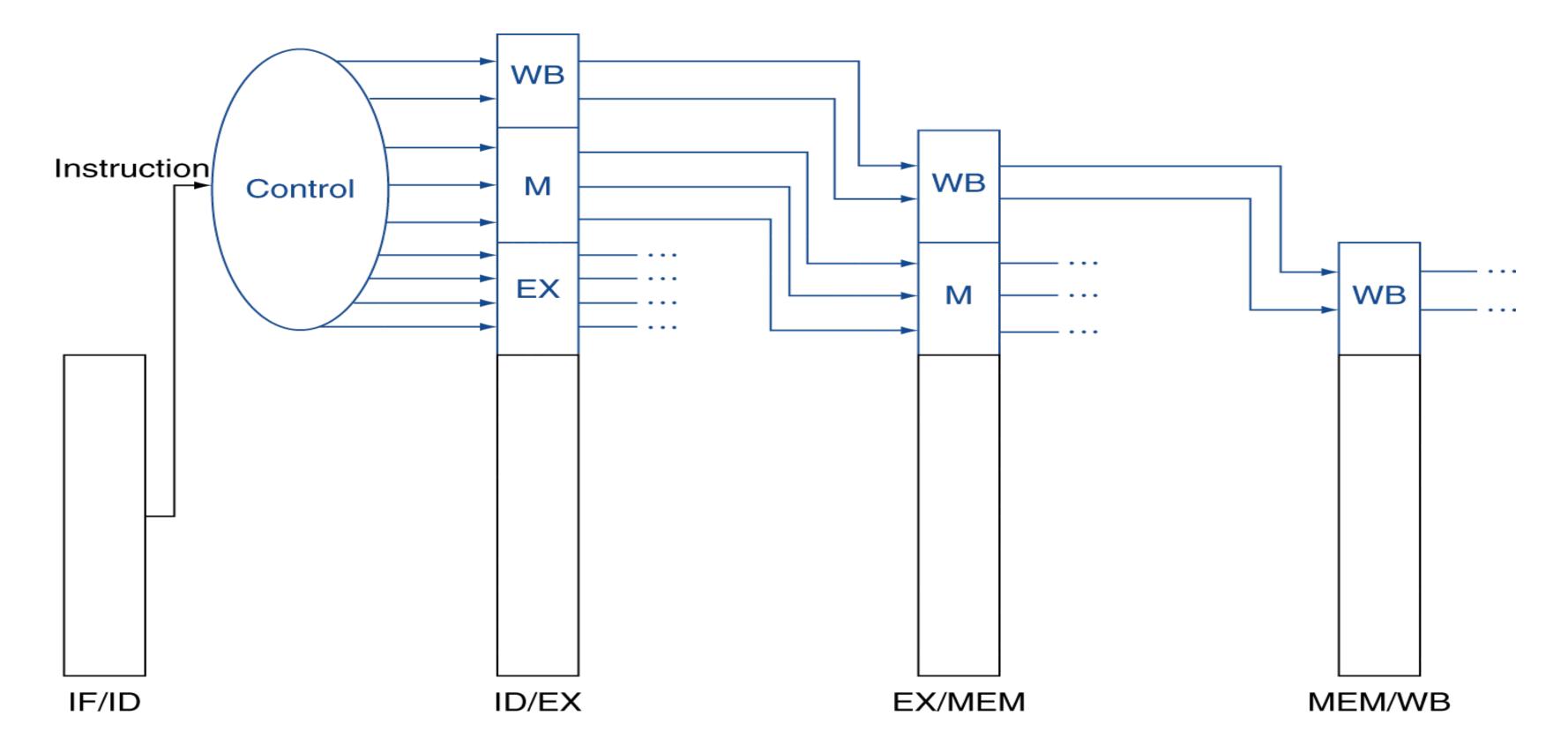


Pipelined Control

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- Control signals derived from instruction
 - As in single-cycle implementation
 - Information is stored in pipeline registers for use by later stages





1 / throughput

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Pipelining the single-cycle processor can increase processor performance by:

	Instructions /program	Cycles/ instruction	Time/cycle
A	decrease	decrease	same
В	same	increase	decrease
C	same	same	decrease
D	increase	decrease	increase



Hazards Ahead

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Structural Hazard

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- Problem: Two or more instructions in the pipeline compete for access to a single physical resource
- **Solution 1:** Instructions take turns to use resource, some instructions have to stall
- Solution 2: Add more hardware to machine
 - Can always solve a structural hazard by adding more hardware



Regfile Structural Hazards

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- Each instruction:
 - can read up to two operands in decode stage
 - can write one value in writeback stage
 - therefore two different instructions might be accessing the register file on the same cycle!
- Avoid structural hazard by having separate "ports"
 - two independent read ports and one independent write port
- Reads from one instruction and writes from another can happen simultaneously



Structural Hazard: Memory Access

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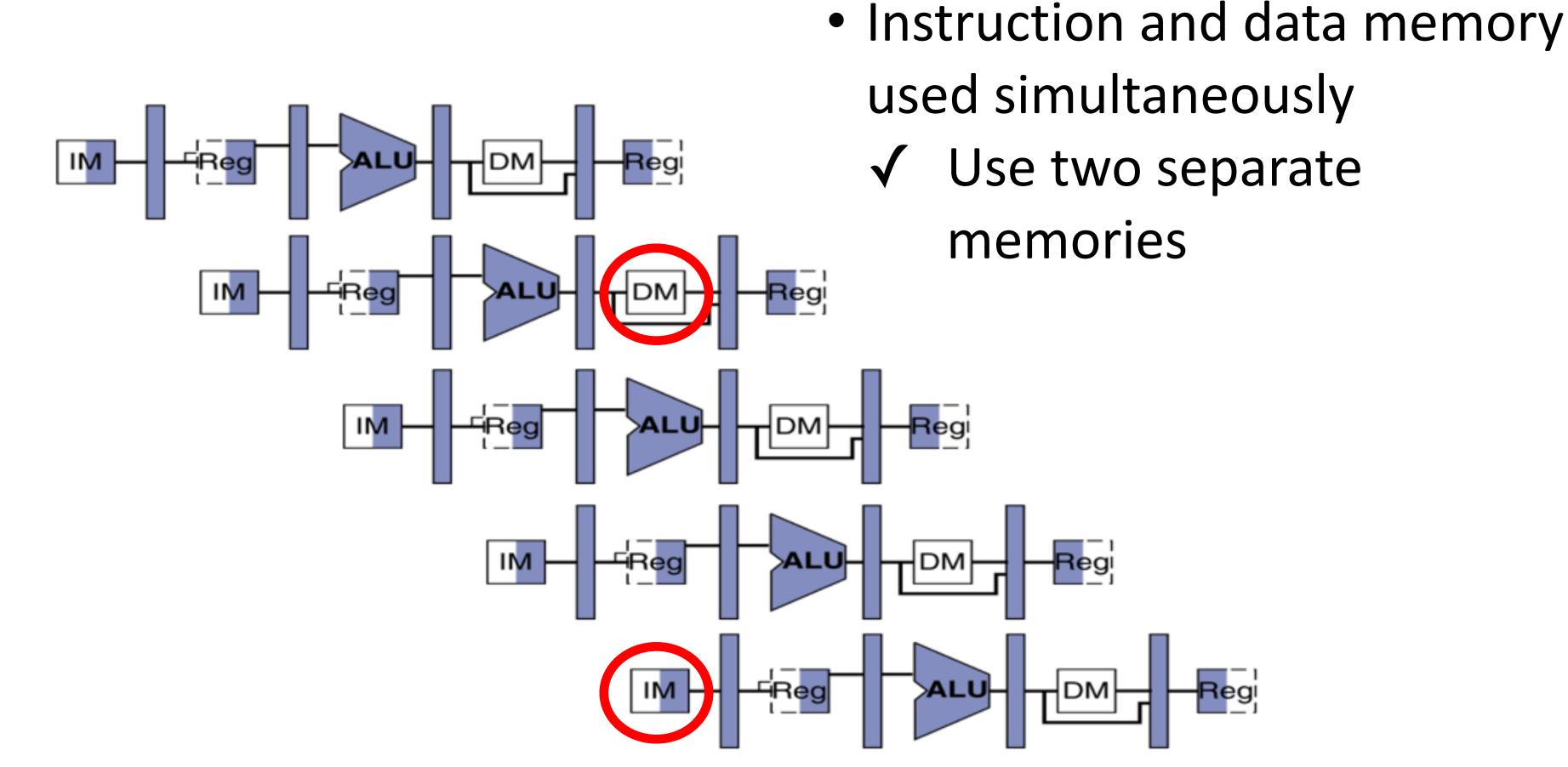
add t0, t1, t2

sw t0, 4(t5)

slt t6, t0, t3

or t3, t4, t5

lw t0, 8(t3)



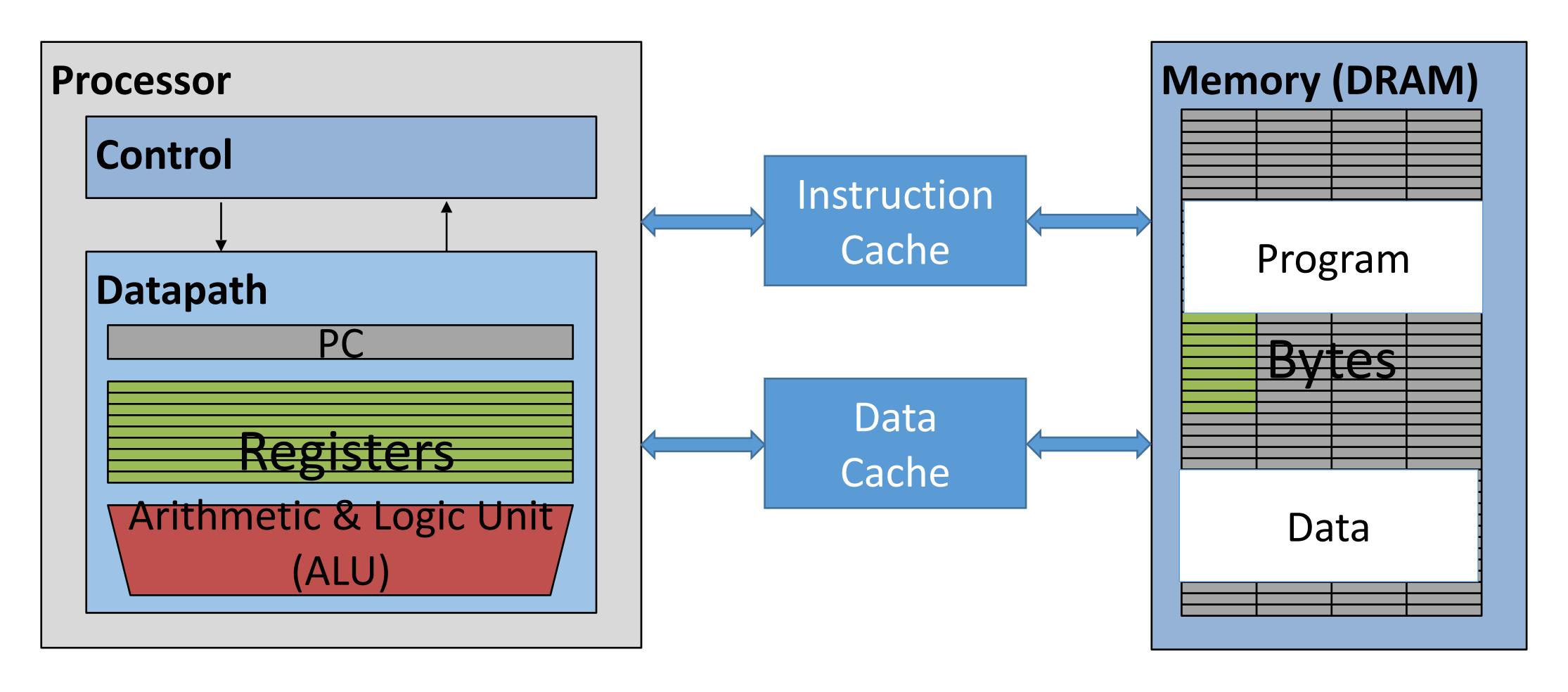


instruction

sequence

Instruction and Data Caches

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Caches: relatively small and fast "buffer" memories



Structural Hazards – Summary

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- Conflict for use of a resource
- In RISC-V pipeline with a single memory
 - Load/store requires data access
 - Without separate memories, instruction fetch would have to stall for that cycle
 - All other operations in pipeline would have to wait
- Pipelined datapaths require separate instruction/data memories
 - Or at least separate instruction/data caches
- Multi-ported register file
- RISC ISAs (including RISC-V) designed to avoid structural hazards
 - e.g. at most one memory access/instruction
 - limited operands per instruction



Agenda

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- Separate ports, but what if write to same value as read?
- Does sw in the example fetch the old or new value?

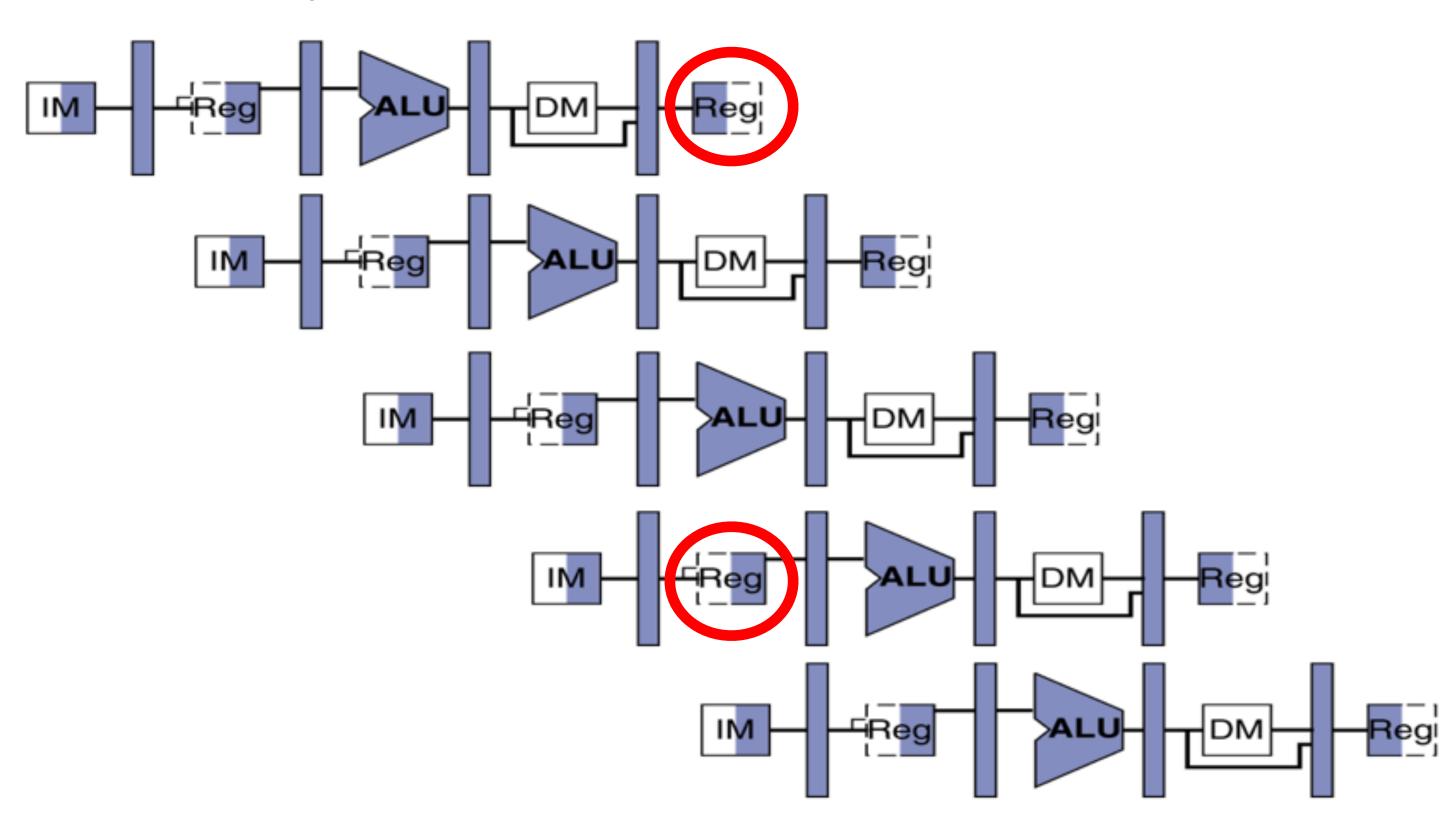
add t0, t1, t2

or t3, t4, t5

slt t6, t4, t3

sw t0, 4(t3)

lw t0, 8(t3)



instruction

sequen

Register Access Policy

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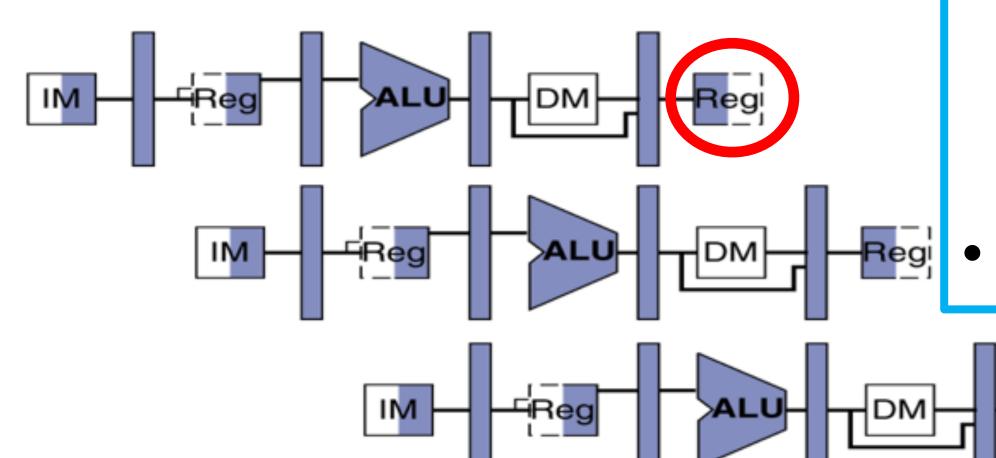
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add t0, t1, t2 or t3, t4, t5

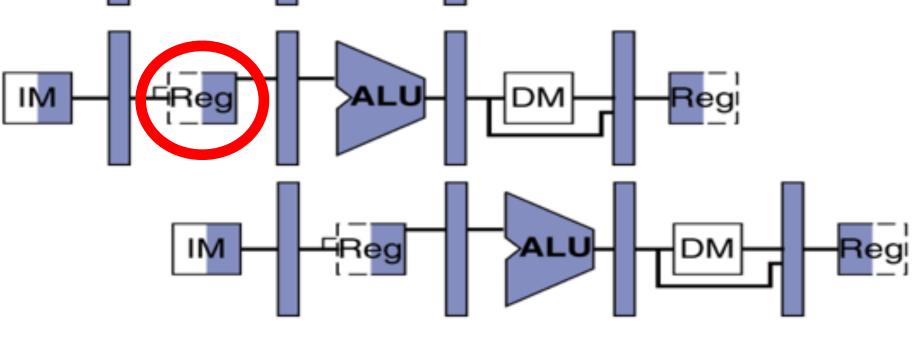
slt t6, t4, t3

sw t0, 4(t3)

lw t0, 8(t3)



- Exploit high speed of register file (100 ps)
 - 1) WB updates value
 - 2) ID reads new value
 - Indicated in diagram by shading



Might not always be possible to write then read in same cycle, especially in high-frequency designs.

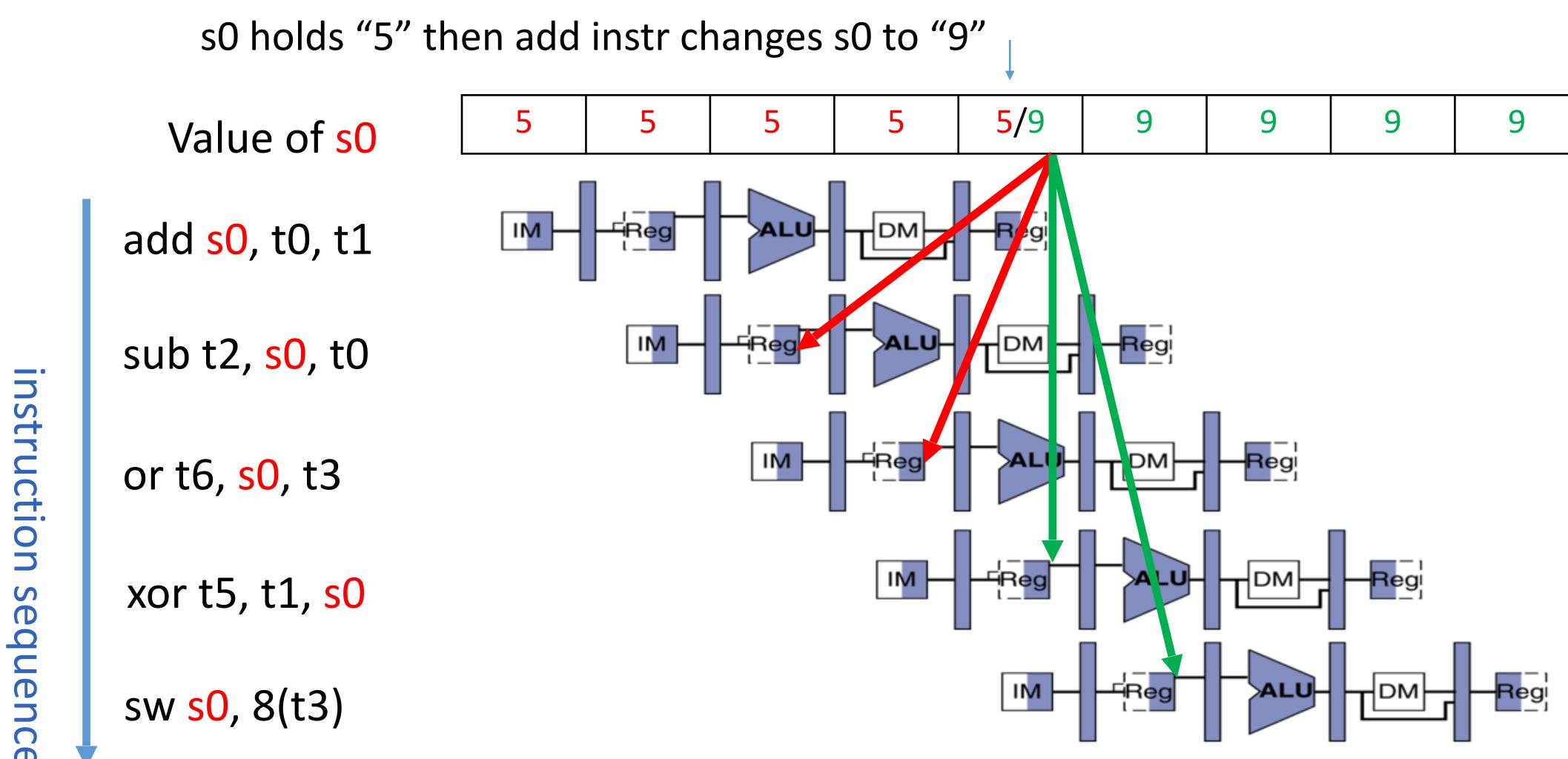


sequence

Data Hazard: ALU Result

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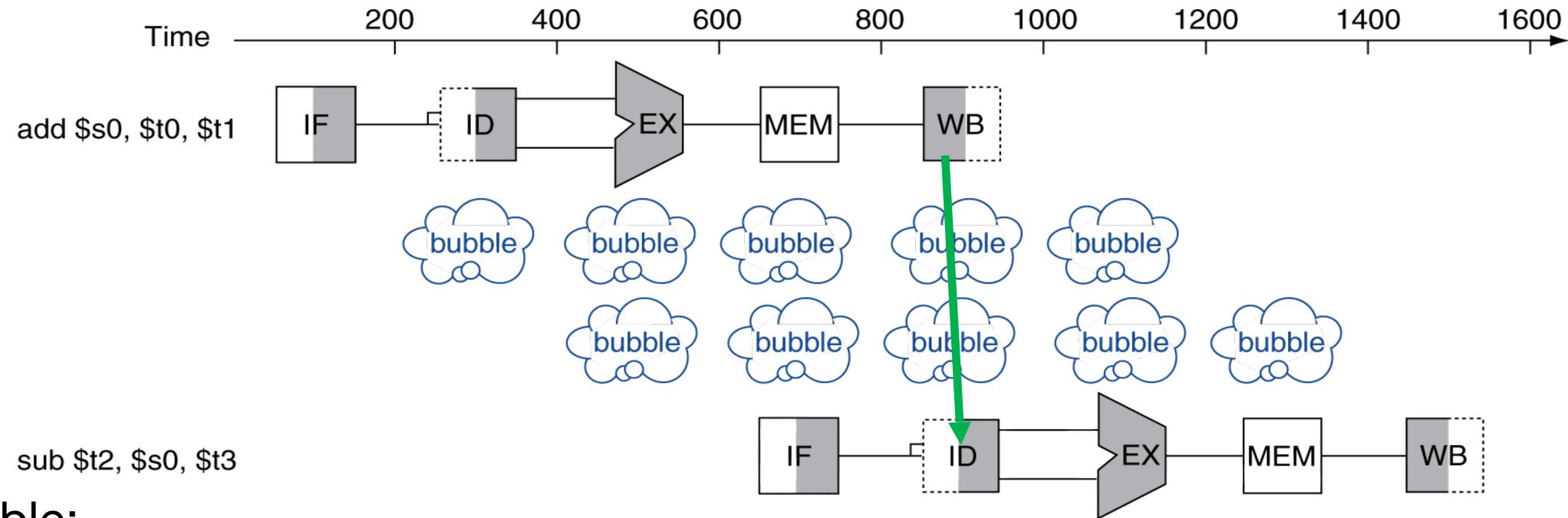
Solution 1: Stalling

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Problem: Instruction depends on result from previous instruction

add s0, t0, t1sub t2, s0, t3



- Bubble:
 - stall the dependent instruction
 - effectively NOP: affected pipeline stages do "nothing"



Stalls and Performance

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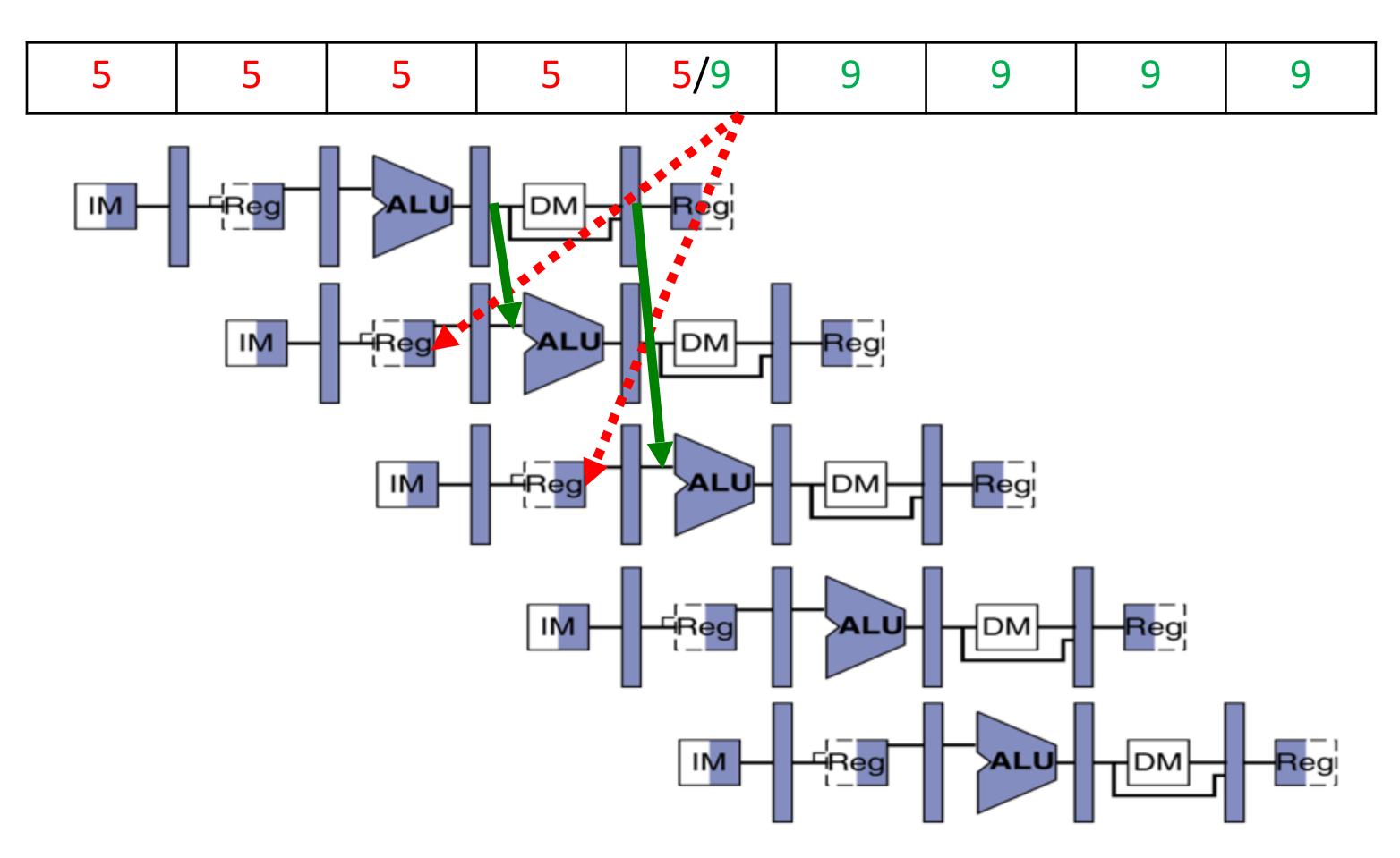
- Stalls reduce performance
 - But stalls might be required to get correct results
- Compiler could try to arrange code to avoid hazards and stalls
 - Requires knowledge of the pipeline structure



Solution 2: Forwarding

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Value of t0 add t0, t1, t2 or t3, t0, t5 instruction sequenc sub t6, t0, t3 xor t5, t1, t0 sw t0, 8(t3)



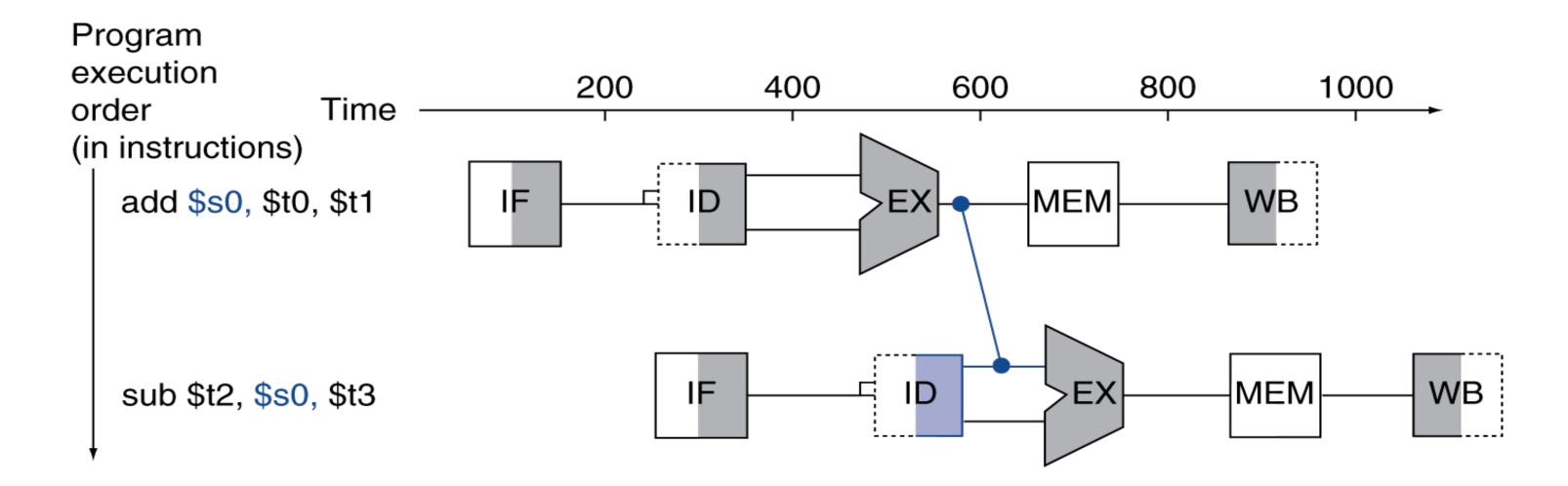
Forwarding: grab operand from pipeline stage, rather than register file

Forwarding (aka Bypassing)

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- Access result before it is stored in a register
- Requires extra connections in the datapath





1) Detect Need for Forwarding (example)

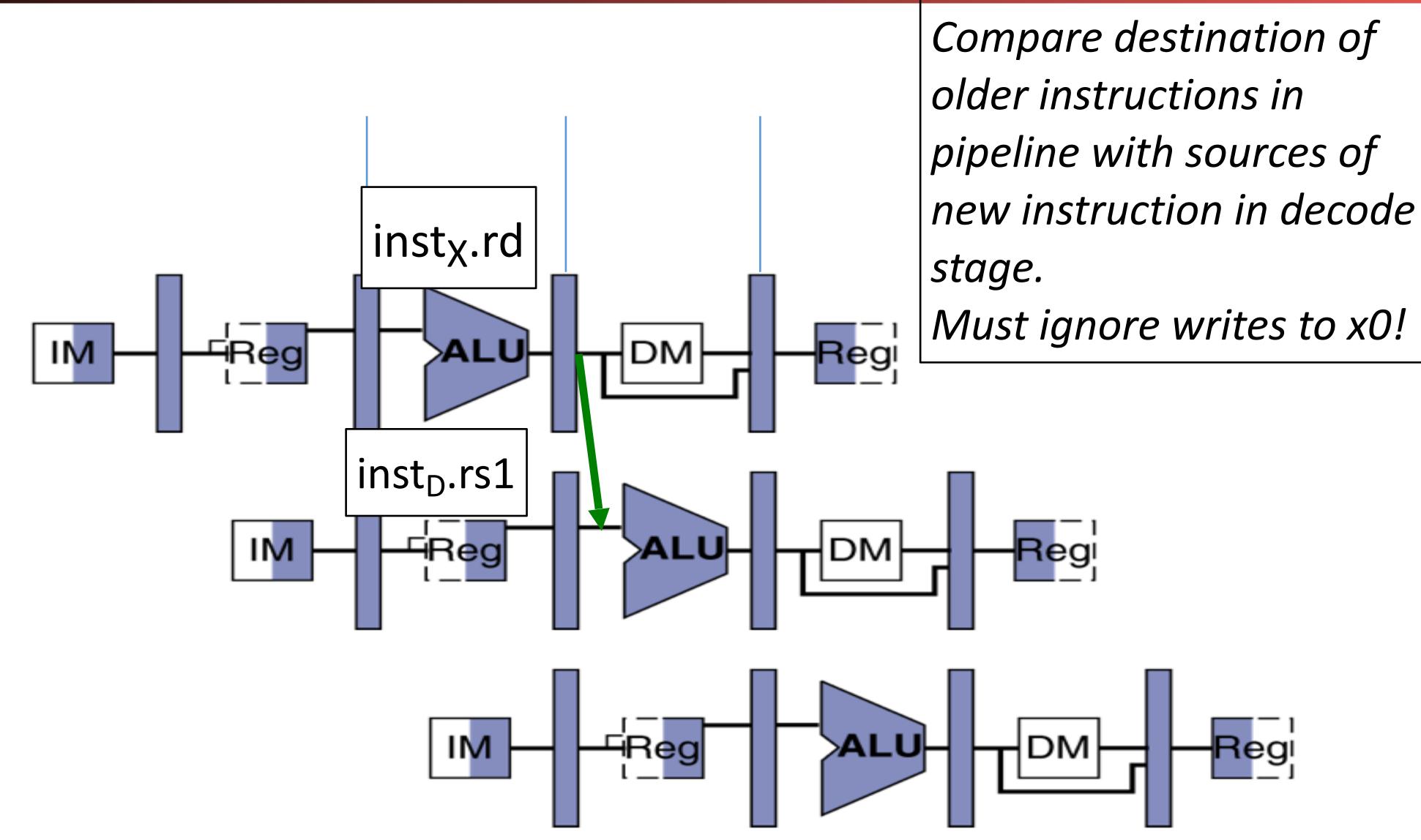
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add t0, t1, t2

or t3, t0, t5

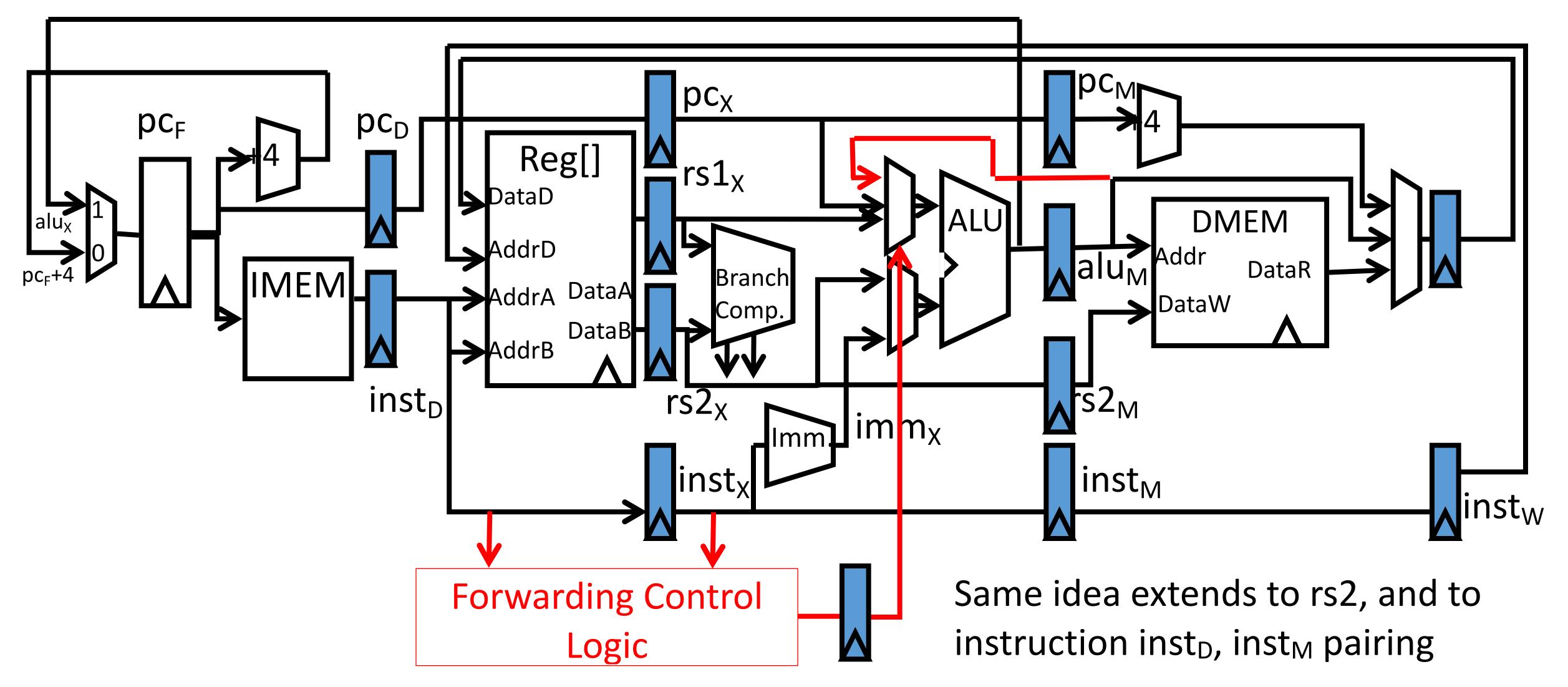
sub t6, t0, t3



Example Forwarding Path

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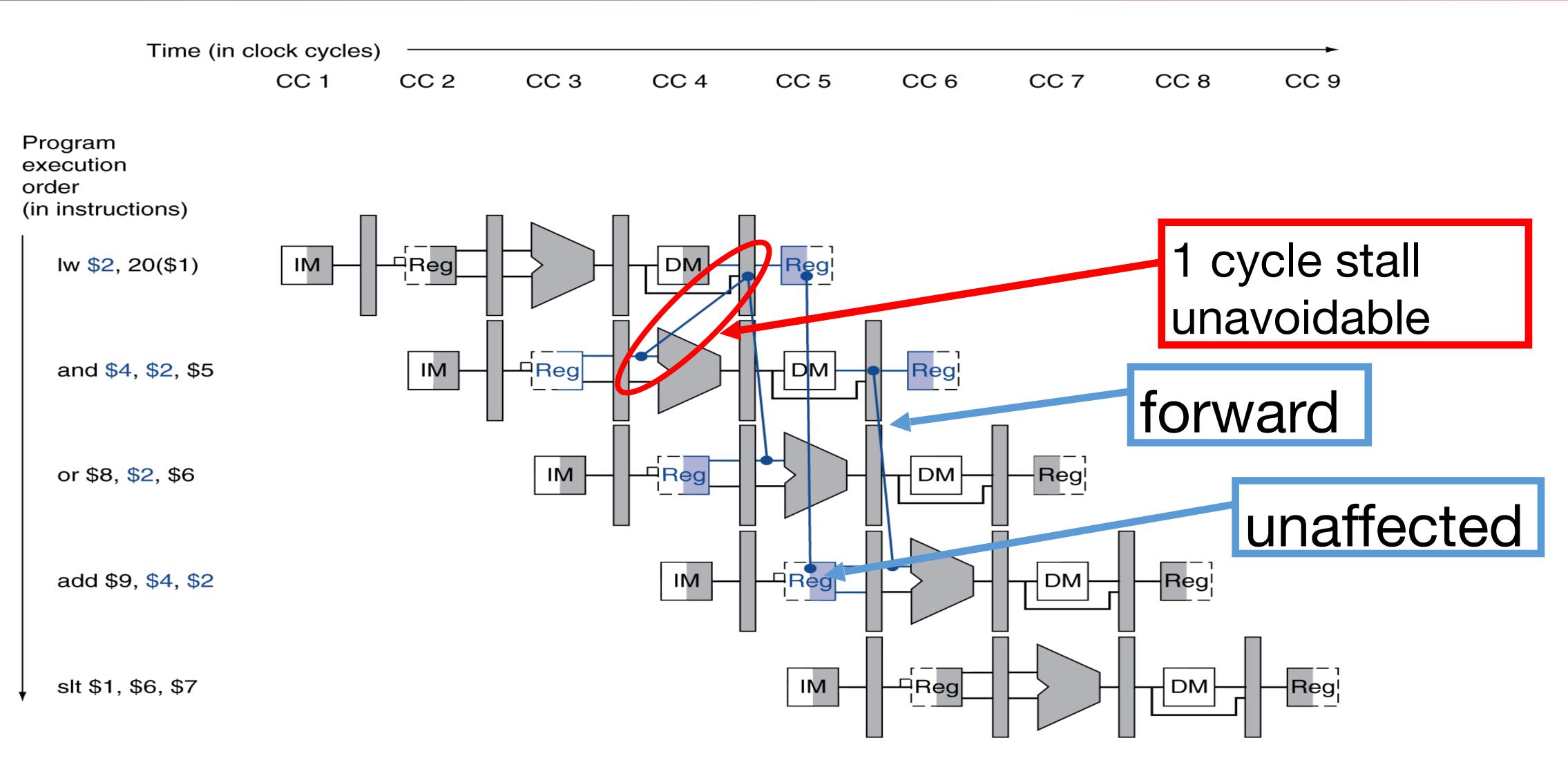
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Load Data Hazard

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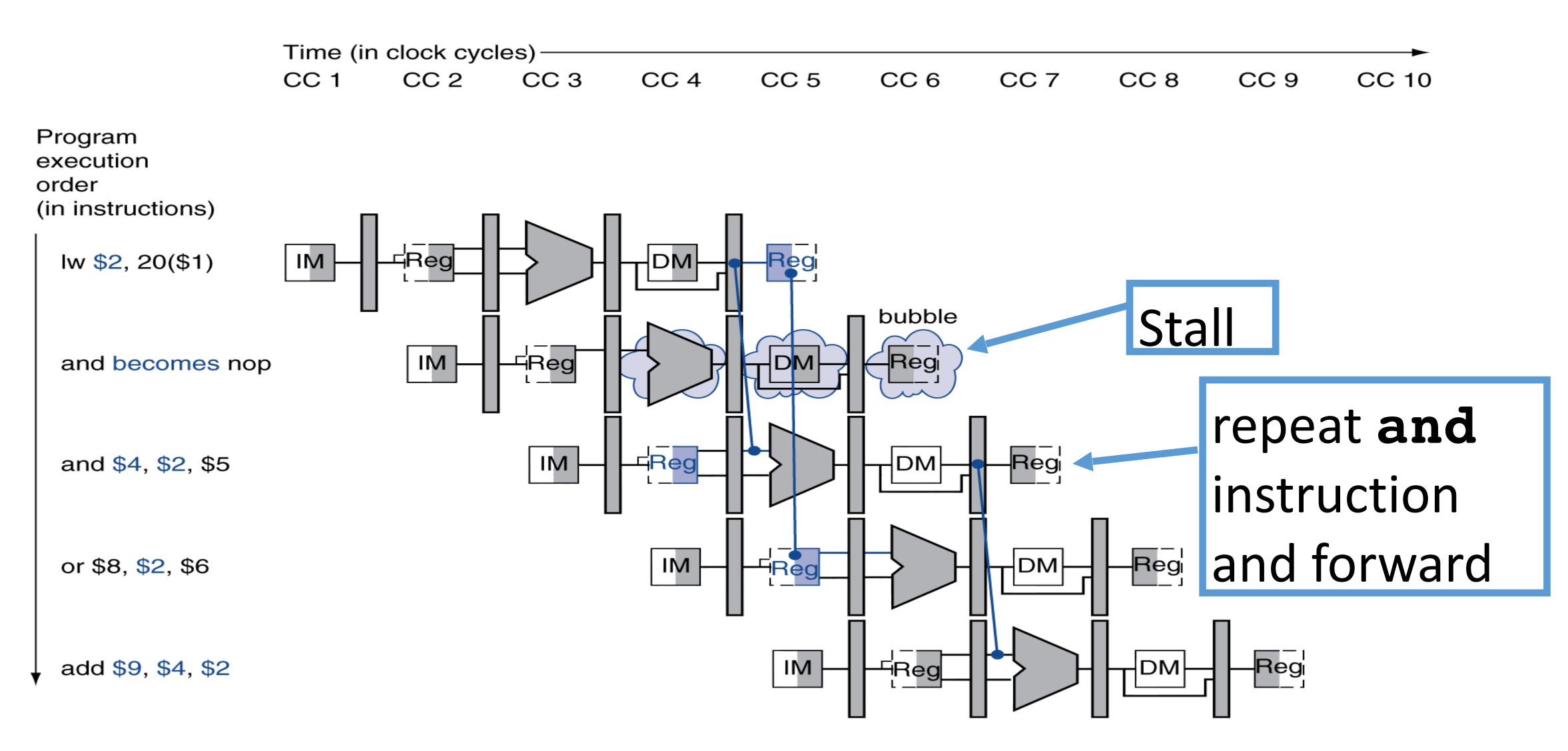




Stall Pipeline

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1w Data Hazard

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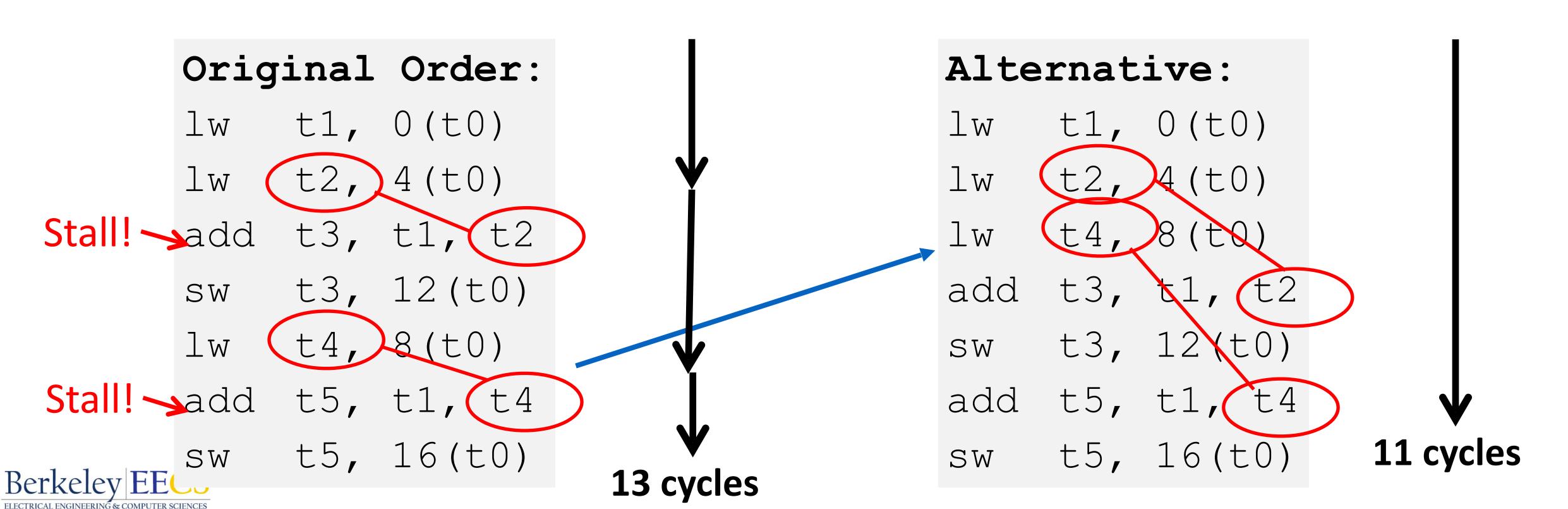
- Slot after a load is called a load delay slot
 - If that instruction uses the result of the load, then the hardware will stall for one cycle
 - Equivalent to inserting an explicit nop in the slot
 - except the latter uses more code space
 - Performance loss!
- Idea:
 - Put unrelated instruction into load delay slot
 - No performance loss!



Code Scheduling to Avoid Stalls

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- Reorder code to avoid use of load result in the next instruction!
- RISC-V code for D=A+B; E=A+C;



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Control Hazards

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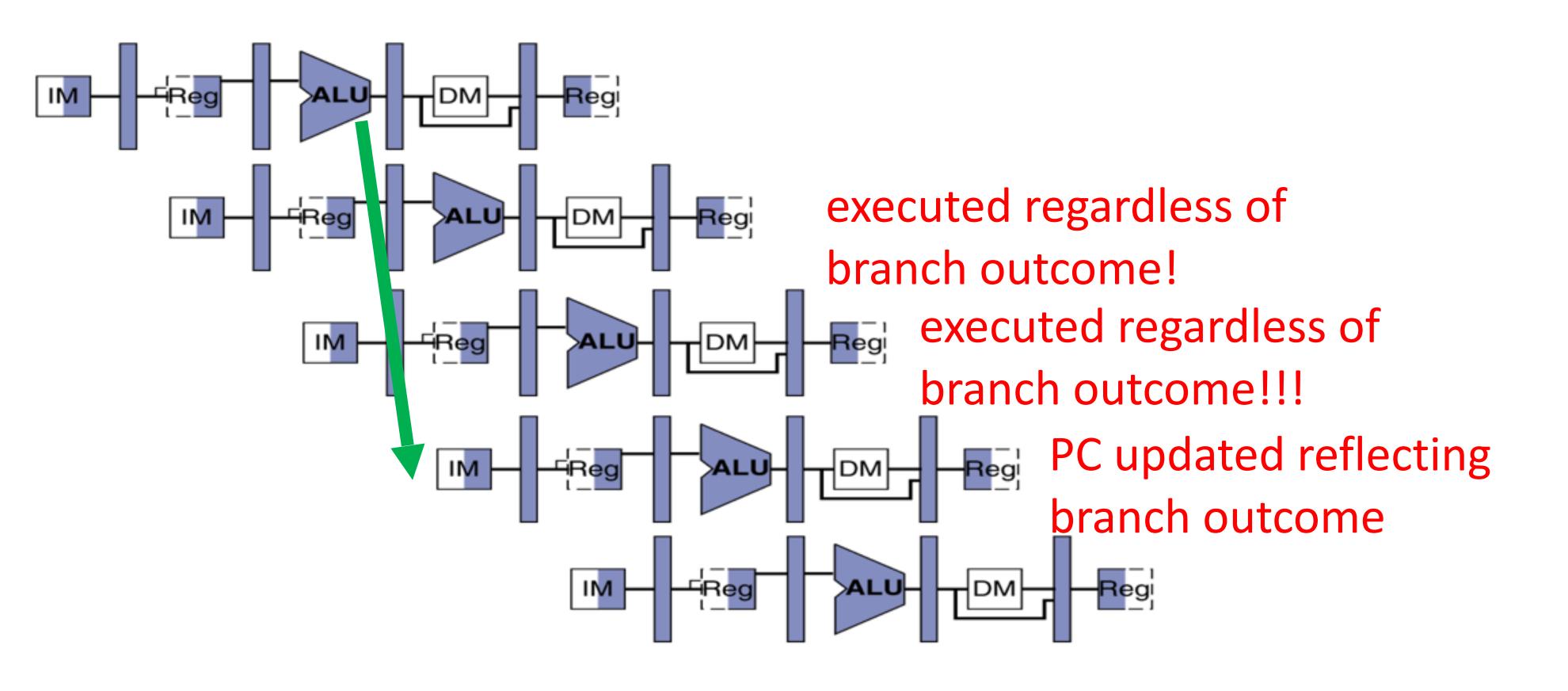
beq t0, t1, label

sub t2, s0, t5

or t6, s0, t3

xor t5, t1, s0

sw s0, 8(t3)





Observation

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- If branch not taken, then instructions fetched sequentially after branch are correct
- If branch or jump taken, then need to flush incorrect instructions from pipeline by converting to NOPs



Kill Instructions after Branch if Taken

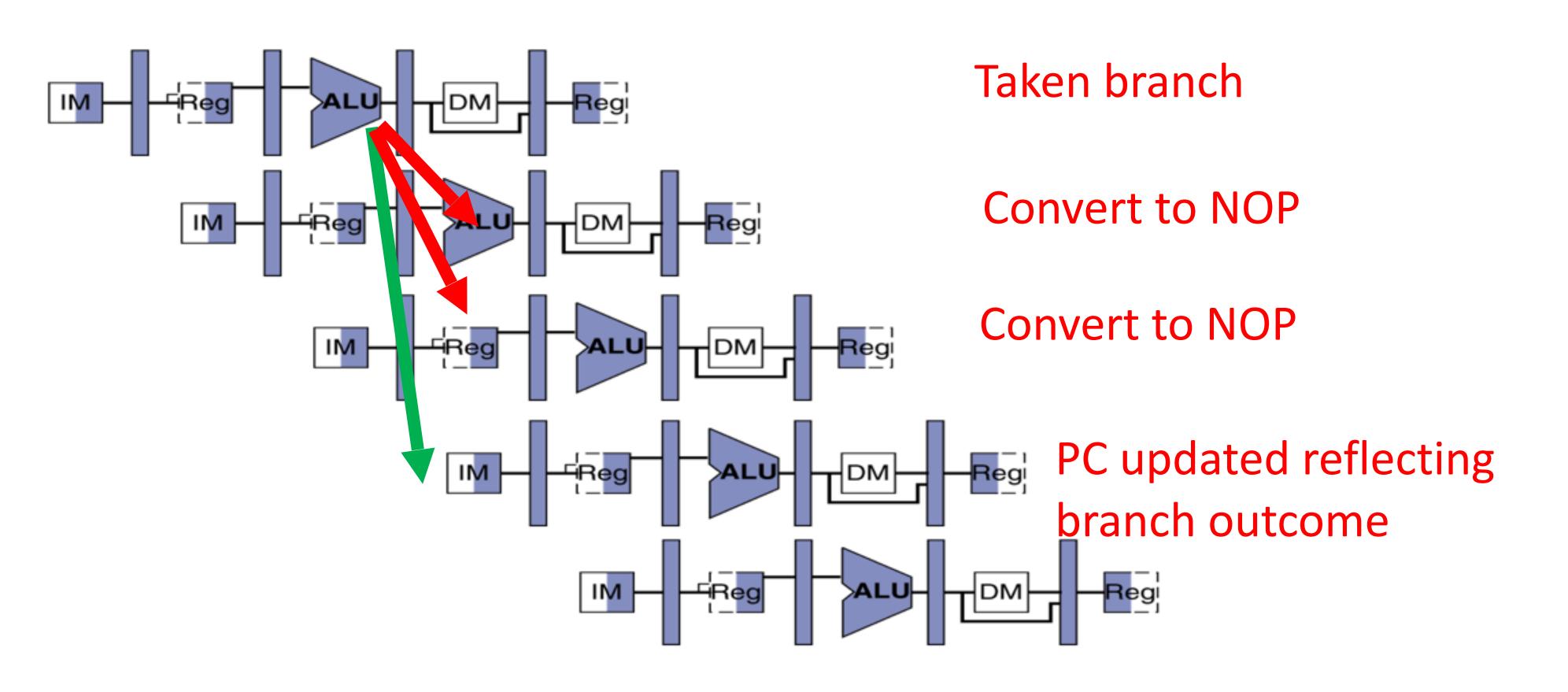
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beq t0, t1, label

sub t2, s0, t5

or t6, s0, t3

label: xxxxxx





Reducing Branch Penalties

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- Every taken branch in simple pipeline costs 2 dead cycles
- To improve performance, use "branch prediction" to guess which way branch will go earlier in pipeline
- Only flush pipeline if branch prediction was incorrect



Branch Prediction

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Taken branch beq t0, t1, label Guess next PC! label: Check guess correct



Implementing Branch Prediction...

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- This is a CS152 topic, but some ideas:
 - Branch prediction is critical for performance on deeper pipelines/superscalar as the "Misprediction penalty" is vastly higher
- Keep a branch prediction buffer/cache: Small memory addressed by the lowest bits of PC
 - During instruction decode, if branch: Look up whether branch was taken last time?
 - If yes, compute PC + offset and fetch that (or store actual branch target address from last time)
 - If no, stick with PC + 4
 - If branch hasn't been seen before
 - Assume forward branches are not taken, backward branches are taken
 - Update state on predictor with results of branch when it is finally calculated



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Increasing Single Processor Core Performance

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1. Clock rate

- Limited by technology and power dissipation
- 2. Pipelining
 - "Overlap" instruction execution
 - Deeper pipeline: 5 => 10 => 15 stages

 - But more potential for hazards (CPI > 1)
 - Depth limited by max clock rate and power dissipation
- 3. Multi-issue "superscalar" processor



Superscalar Processor

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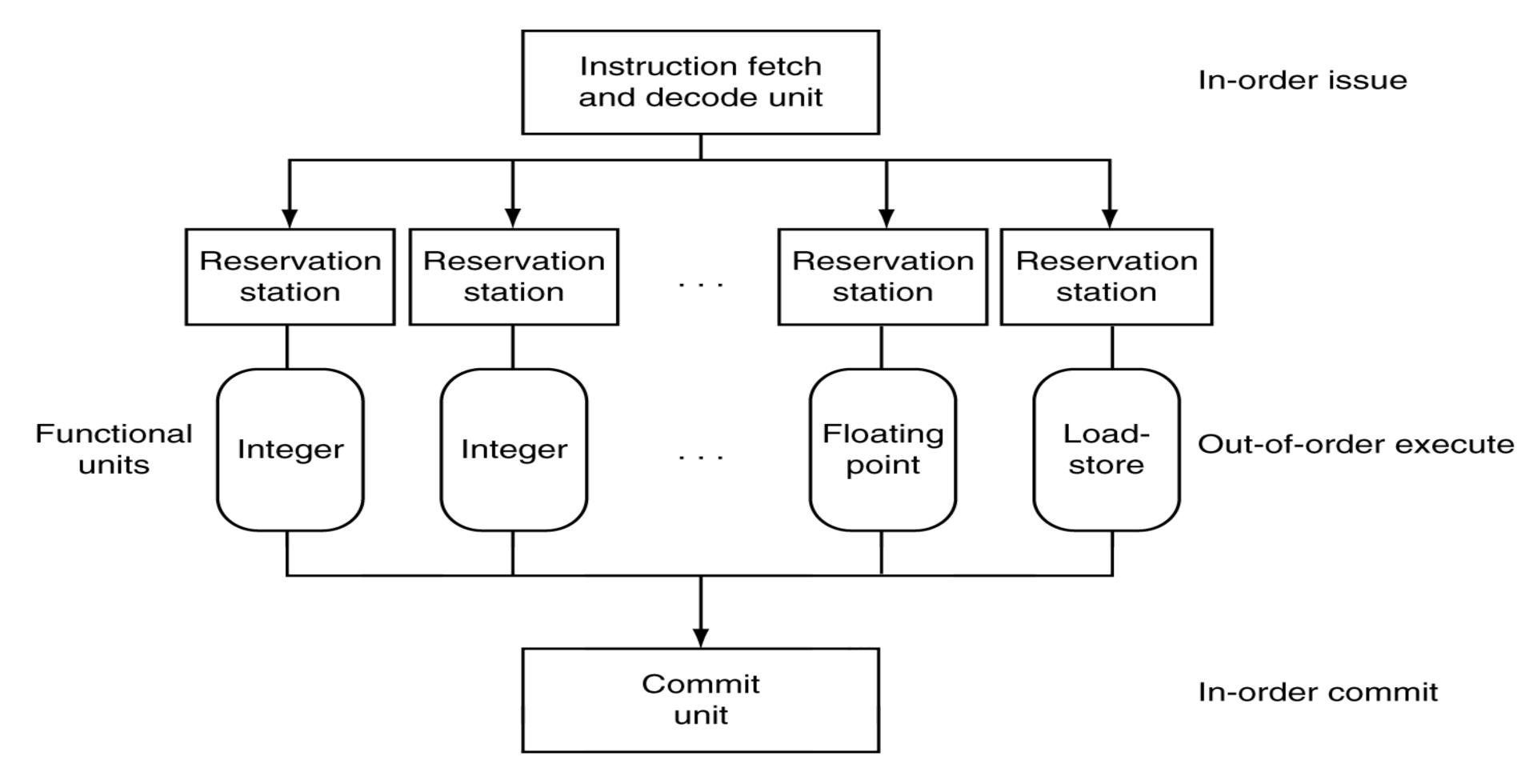
- Multiple issue "superscalar"
 - Replicate pipeline stages ⇒ multiple pipelines
 - Start multiple instructions per clock cycle
 - CPI < 1, so use Instructions Per Cycle (IPC)
 - E.g., 4GHz 4-way multiple-issue
 - 16 BIPS, peak CPI = 0.25, peak IPC = 4
 - Dependencies reduce this in practice
- "Out-of-Order" execution
 - Reorder instructions dynamically in hardware to reduce impact of hazards:
 EG, memory/cache misses
- CS152 discusses these techniques!



Out Of Order Superscalar Processor

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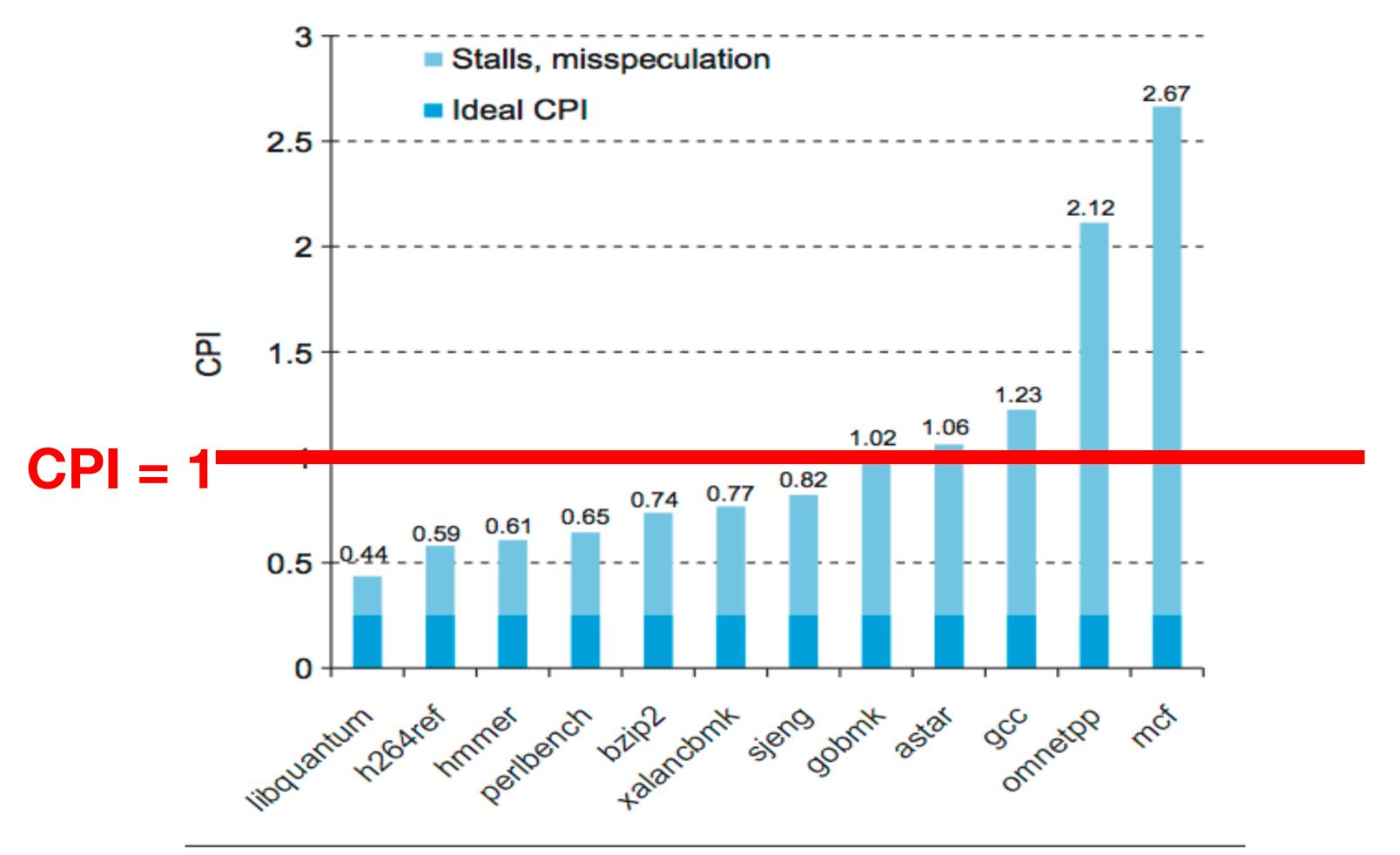


P&H p. 340



Benchmark: CPI of Intel Core i7

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CPI of Intel Core i7 920 running SPEC2006 integer benchmarks.

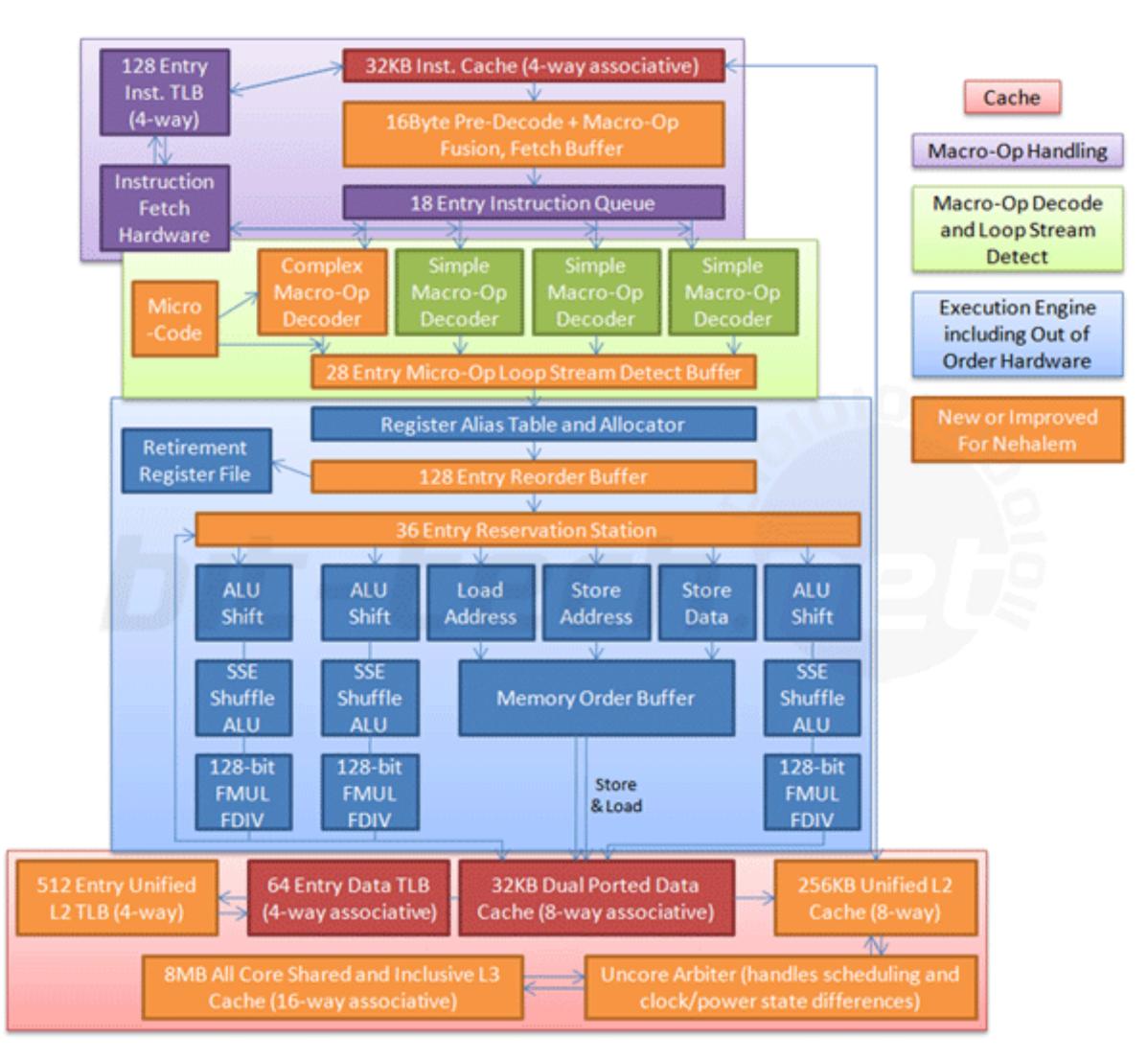


And That Is A Beast...

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- 6 separate functional units
 - 3x ALU
 - 3 for memory operations
- 20-24 stage pipeline
- Aggressive branch prediction and other optimizations
 - Massive out-of-order capability:
 Can reorder up to 128 micro-operation instructions!
- And yet it still barely averages a 1 on CPI!





Pipelining and ISA Design

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RISC-V ISA designed for pipelining

- All instructions are 32-bits in the RV-32 ISA
 - Easy to fetch and decode in one cycle
 - Variant additions add 16b and 64b instructions,
 but can tell by looking at just the first bytes what type it is
 - Versus x86: 1- to 15-byte instructions
 - Requires additional pipeline stages for decoding instructions
- Few and regular instruction formats
 - Decode and read registers in one step
- Load/store addressing
 - Calculate address in 3rd stage, access memory in 4th stage
- Alignment of memory operands
 - Memory access takes only one cycle



In Conclusion

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- Pipelining increases throughput by overlapping execution of multiple instructions
- All pipeline stages have same duration
 - Choose partition that accommodates this constraint
- Hazards potentially limit performance
 - Maximizing performance requires programmer/compiler assistance
- Superscalar processors use multiple execution units for additional instruction level parallelism
 - Performance benefit highly code dependent

