

Parallel Programming with the PThread API

- **POSIX Thread tutorials on the WEB:**

- Getting Started with POSIX Threads (online book): [click here](#)
 - PThread Primer (online book): [click here](#)
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- **The POSIX Threads API**

- The POSIX Thread API was the result of a **standardization effort** to make multi-threaded programs **portable** among different computer vendors

Before the POSIX standard, each computer vendor would implement its own thread library and the resulting programs were not portable across different computer systems.

- To use the POSIX threads (or "pthreads" for short), include the header file:

```
#include <pthread.h>
```

- And use the compiler options:

```
CC -mt [other flags] C++-program (Solaris)  
g++ -pthread [other flags] C++-program (Linux)
```

- **Note:**

- The C++ language has changed a bit in Linux

- You must use:

```
#include <iostream>  
using namespace std;
```

instead of:

```
#include <iostream.h>  
to access the cin and cout objects.
```

Creating Threads

- Creating a new thread of control

- Syntax:

```
int pthread_create(pthread_t *threadID,
                  const pthread_attr_t *attr,
                  void *(*start_routine)(void*),
                  void *arg);
```

Input Parameters:

- attr = contains the **attributes (properties)** of the **new thread**
 - **Thread attributes** are **discussed later**
- start_routine = **name** of the **function** that the **new thread** will **execute**
 - This **function** has **one parameter** of the **type** (**void ***)
 - The **return value type** of this **function** is **void ***
 - I.e.:

```
void * start_routine( void * arg ) ...  
{  
    ...  
}
```
- arg = the **argument** that will be **passed** to the **start_routine** function when it **executes**

Output parameters

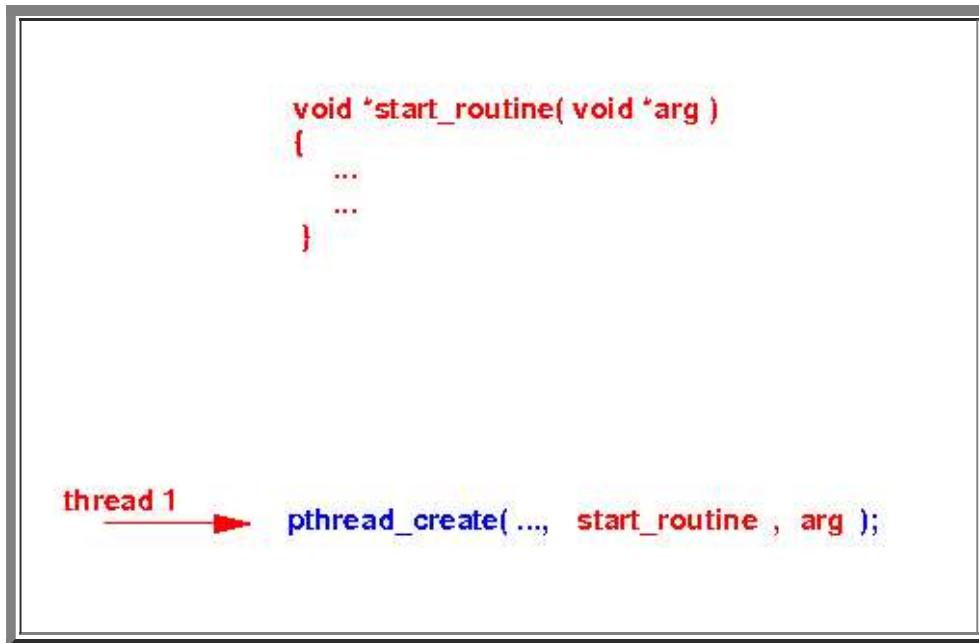
- threadID = the **identifier** of the **new thread**
 - We will use the **threadID** to **wait** for the **thread** to **finish**

Return value:

- Returns 0 if **thread** is created **successfully**
- Otherwise, returns an **error code**

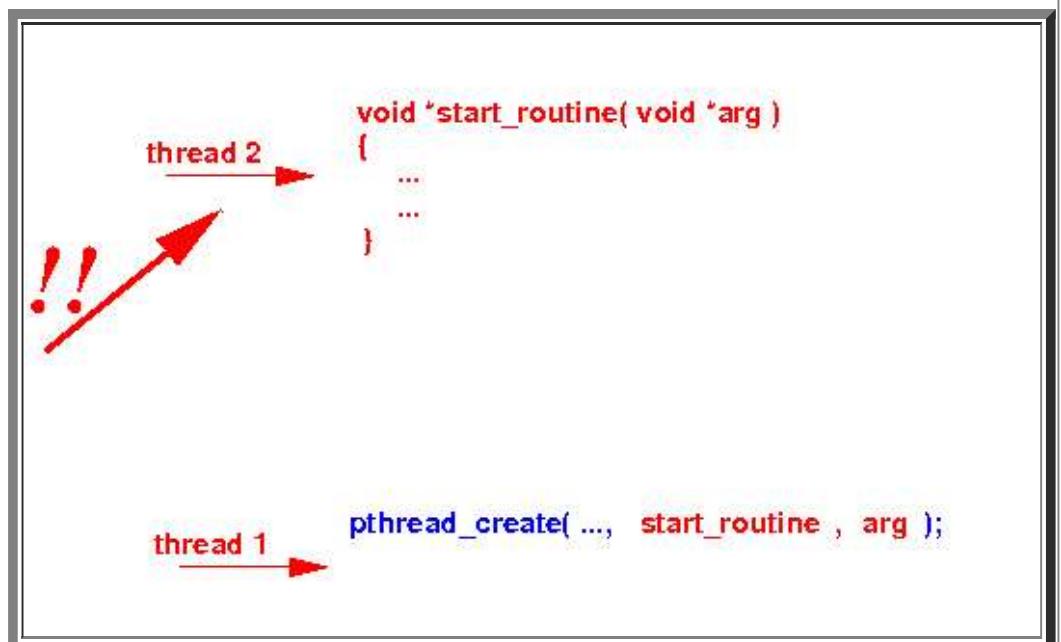
- Effect of the `pthread_create(..., start_routine, ...)` call:

- Before the `pthread_create()` call:



Thread 1 is executing the `pthread_create()` call

- After the `pthread_create()` call:



Thread 1 will **continue execution** the **statements after** the `pthread_create()` call

A **new thread** Thread 2 will **start** its **execution** with the **function start_routine**

- **Setting attributes for new threads**

- The attributes for a newly created thread is defined by the user using a special **bit-variable** of the type "pthread_attr_t".

The following definition will define one such variable; and the name of our variable is "attr" (you can call the variable any name that you like):

```
pthread_attr_t attr;
```

- Once such "pthread_attr_t" variable is defined, you must first **reset all properties** to their **default values** using the function "pthread_attr_init()":

```
pthread_attr_init(&attr);
```

- The following is a list of "thread attributes" and their default values

Attribute	Default	Meaning of default
contentionscope	PTHREAD_SCOPE_PROCESS	Thread will compete for resources within the process
detachstate	PTHREAD_CREATE_JOINABLE	Thread is joinable by other threads
stackaddr	NULL	Workspace (stack) used by thread is allocated (reserved) by the operating system
stacksize	NULL	Workspace size used by thread is determined by the operating system
priority	0	Priority of the thread (the lower the priority value, the higher the priority...)
policy	SCHED_OTHER	The scheduling policy is determined by the system
inheritsched	PTHREAD_EXPLICIT_SCHED	scheduling policy and parameters are not inherited but explicitly defined by the attribute object
guardsize	PAGESIZE	size of guard area for a thread's created stack (this area will help

determine if the thread has exceeded the total amount of space that was allocated for the thread)

- o **Changing the default values:**

- ***There is no need to change MOST of the default values***

(In fact, my examples always use the **default values**)

- If you have the need to change some value, you must **invoke specific functions to set parameters** in the **attr** variable (after clearing the bits):

- `pthread_attr_setscope()`: change contentionscope
 - `pthread_attr_setdetachstate()`: change detachstate
 - `pthread_attr_setstackaddr()`: pick your own stack location
 - `pthread_attr_setstacksize()`: pick your own stack size
 - .. etc
 -
 - See: ***man pthread_attr_init*** for more functions.
 - See: ***man pthread_attr_setscope*** for more details on the `pthread_attr_setscope` function, etc.

- **Example: Changing the default STACKSIZE**

- The **only** default value that you would ever feel the need to change is: **stacksize**

The stack is used to store:

- local variables
 - parameter variables

- You will need to **increase the stack size** if the function run by a thread uses:

- 1. many local variables**

- 2. is recursive** (because the function will create **multiple copies** of parameter and local variables !!!)

- How to set your own stacksize (workspace size) for your threads:

```
int pthread_attr_setstacksize(pthread_attr_t *attr,  
                           size_t stacksize);
```

Example:

```
pthread_attr_t attr; . . . . .  
pthread_attr_init(&attr); . . . . .  
pthread_attr_setstacksize(&attr, 10000000); // 10000000 bytes stack . . . . .
```

- **Joinable and detached threads**

- As many parallel applications often have interspersed sequential and parallel steps, where the execution of the sequential step must wait until all threads in the parallel step has finished execution; you often find that threads must sometimes **WAIT** on each other.
- The crucial difference between **joinable** and **detached** threads is precisely this waiting property
- **Detached threads** run independently from other threads and cannot wait for other threads.

The waiting on other threads is accomplished by using the function **pthread_join()** (more later).

- **Joinable threads** may call `pthread_join()` to wait on another thread.
- The default value is **joinable**, you do NOT want to change this (unless you are going to provide some kind of barrier synchronization routine yourself....)

- **Summary thread creation...**

- The following code fragment summarizes how to create a thread:

```
pthread_t ..... TID; /* Thread ID - used for signaling */  
pthread_attr_t .. attr; /* Thread attribute values for creation */  
  
int ..... param;  
  
/* -----  
   Clear out thread attributes (use default values)  
----- */  
if (pthread_attr_init(&attr) != 0)  
{ perror("Problem: pthread_attr_init");  
  exit(1);  
}  
  
/* -----  
   Optionally, set thread attributes if needed (often not)  
----- */  
if ( pthread_attr_setstacksize(&attr, 10000000) != 0)  
{ perror("Problem: pthread_attr_setstacksize");  
  exit(1);  
}  
  
param = some value....;
```

```

/*
... Create thread (once created, thread starts running my_proc()

... Note: the C operator & means: address of ...
----- */

if (pthread_create(& TID, & attr, my_proc, & param) != 0)
{ perror("Problem: pthread_create");
  exit(1);
}

```

We must also provide a function for the thread to execute:

```

void *my_proc((void *) x) ..... <---- new thread will begin
{                                execution with this function
  ....
}

```

- **Example: Hello World in threads**

- **Program:**

```

#include <pthread.h>

/*
===== Thread prints "Hello World"
=====
*/
void *worker(void *arg)
{
  cout << "Hello World !" << endl;

  return(NULL); /* Thread exits (dies) */
}

/*
===== MAIN: create a trhead and wait for it to finish
=====
*/
int main(int argc, char *argv[])
{
  pthread_t tid;

  /*
  ----- Create threads
  -----
  */
  if ( pthread_create(&tid, NULL, worker, NULL) )
  {
    cout << "Cannot create thread" << endl;
    exit(1);
  }

  cout << "Main waits for thread to finish...." << endl ;

  pthread_join(tid, NULL);

  exit(0);
}

```

- o **Example Program:** (Demo above code)

Example

- Prog file: [click here](#)

How to run the program:

- Right click on link and **save** in a scratch directory
- To compile: `gcc -pthread HelloWorld.c`
- To run: `./a.out`

• Passing a parameter to a thread

- o The **function** executed by a **thread** can have **one parameter**

Multiple parameters:

- **Multiple parameters** can be passed by **passing the address** of a **data structure** as the **parameter**

- o To **accommodate different types** of **parameter**, the **casting (type conversion)** operation is usually needed
- o **Example: passing an integer parameter to a thread**

```
/*
... Worker thread will receive an INTEGER input parameter
... */
void *worker(void *arg)
{
    int *p; // Pointer (reference, address) to an integer variable
    int x; // An integer variable

    p = (int *) arg; // Casting "(void *)" type to "(int *)"
    x = *p

    cout << "Hi, my input parameter is " << x << endl;

    return(NULL); /* Thread exits (dies) */
}
```

```
/*
... Main creates thread and passes param to new thread
... */
int main(int argc, char *argv[])
{
    pthread_t tid;
    int param; // Integer

    param = 12345;
```

```

    ... pthread_create(&tid[i], &attr, worker, & param);
    ... // This should be inside an if to check error...
}

pthread_join(tid, NULL); // Wait for the thread to end...
}

```

- **Example Program:** (Pass parameter to thread) --- [click here](#)

Example

- Compile with: `g++ -pthread param.C`

- Try changing the type from **int** to **float**
 - Only in main
 - Only in worker
 - In both main and worker
 - You will see that they must agree !

- **Waiting for worker threads to finish....**

- You have seen it in some examples before, I just want to spell out the effect of the function ***pthread_join()*** explicitly.
- When a thread **A** calls the function

Thread A invokes:

```

    ... pthread_join(B, &status); ...

```

... B = ID of a thread

... status = variable to receive the exit state of thread.

Then the following will happen:

- The calling thread (**A**) is **suspended** until the target thread (**B**) completes
The thread **B** completes if the function (that thread **B** executes) returns or thread **B** executes the ***pthread_exit()*** function
- Note that thread **B** must be **JOINABLE**

Example: waiting for **1 thread** (**Hello World**)

- **Program:**

```

#include <pthread.h>

```

```

/*
=====
 Thread prints "Hello World"
=====
*/
void *worker(void *arg)
{
    cout << "Hello World !" << endl;

    return(NULL); /* Thread exits (dies) */
}

/*
=====
 MAIN: create a thread and wait for it to finish
=====
*/
int main(int argc, char *argv[])
{
    pthread_t tid;

    /*
     Create threads
    */
    if ( pthread_create(&tid, NULL, worker, NULL) )
    {
        cout << "Cannot create thread" << endl;
        exit(1);
    }

    cout << "Main waits for thread to finish...." << endl ;
    pthread_join(tid, NULL);

    exit(0);
}

```

- **Example Program:** (Demo above code)

Example

- Prog file: [click here](#)

How to run the program:

- **Right click** on link and **save** in a scratch directory
- To compile: `gcc -pthread HelloWorld.c`
- To run: `./a.out`

- **Example 2:** waiting a *multiple threads*

```

int main(int argc, char *argv[])
{
    int i, num_threads;
    thread_t tid[100];      /* Thread ID used for thread_join() */
    int param[100];         /* Parameters for threads */

    num_threads = ... (number of threads to create);

    /*
    */

```

```

Create threads
----- */
for (i = 0; i < num_threads; i = i + 1)
{
    param[i] = ... ; ... // Initialize parameter for thread i

    if ( pthread_create(&tid[i], &attr, worker, & param[i]) != 0 )
    {
        printf("Cannot create thread\n");
        exit(1);
    }
}

/*
----- Wait for ALL threads to finish
----- */
for (i = 0; i < num_threads; i = i + 1)
    pthread_join(tid[i], NULL);
}

```

Previous example: **thread01.C**

- o **Example Program:** (Demo above code)

Example

- Prog file: [click here](#)

How to run the program:

- Right click on link and save in a scratch directory
- To compile: `g++ -pthread thread01.C`
- To run: `./a.out`