## NOTES FOR STOCHASTIC ANALYSIS

# Based on the notes provided by Timo Seppalainen

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## Contents

#### 1 Stochastic Process

#### 1.1 Path Spaces

**Definition 1.1.1.** (Coordinate Variables and Shift maps) On the path space D, the **coordinate variables** are defined by  $X_t(\omega) = \omega(t)$  for  $\omega \in D$  and it can generate the natrual filtration  $\mathcal{F}_t = \sigma(X_s, s \leq t)$ .

The **shift maps**  $\theta_s: D \to D$  are defined by  $(\theta_s w)(t) = \omega(s+t)$ , for an event  $A \in \mathcal{B}_D$ , the inverse image

$$\theta_s^{-1}(A) = \theta_s \omega \in A$$

#### **Definiton 1.1.2.** (Markov Process)

An  $\mathbb{R}^d$ -valued Markov process is a collection  $\{P^x, x \in \mathbb{R}^d\}$  of probability measures on D such that

- $P^x(X_0 = x) = 1$ .
- For each  $A \in \mathcal{B}_D$ ,  $x \mapsto P^x(A)$  is measurable on  $\mathbb{R}^d$ .
- $P^x[\theta_t^{-1}A|\mathcal{F}_t](\omega) = P^{X_t(\omega)}(A)$  for  $P^x$ -almost every  $\omega$ , any x, A.

#### 1.2 Brownian Motion

#### **Definition 1.2.1.** (Brownian Motion)

For a probability space  $(\Omega, \mathcal{F}, P)$ , let  $\mathcal{F}_t$  be a filtration and  $B = \{B_t, 0 \leq t < \infty\}$  an adapted real-valued stochastic process. Then B is a one-dimensional **Brownian motion** w.r.t.  $\{\mathcal{F}_t\}$  if

- $t \mapsto B_t(\omega)$  is continuous for a.s.  $\omega$ .
- For  $0 \le s < t$ ,  $B_t B_s$  is independent of  $\mathcal{F}_s$  and has normal distribution with mean zero and variance t s.
- If  $B_0 = 0$  a.s., then call B a standard BM.

**Proposition 1.2.1.** The second property is equivalent with

$$E[Zh(B_t - B_s)] = E(Z) \cdot \frac{1}{\sqrt{2\pi(t-s)}} \int_{\mathbb{R}} h(x) \exp\left\{-\frac{x^2}{2(t-s)}\right\} dx$$

for some any bounded r.v.  $Z \in \mathcal{F}_s$  and bounded borel function h.

Proof.

We know for any  $h = \chi_B, Z = \chi_D, B$  is Borel and  $D \in \mathcal{F}_s$ , the equality holds. Then we may use the DCT to obtain the conclusion.

**Proposition 1.2.2.** The Brownian motion has stationary, independent increments.

#### **Definition 1.2.2.** (Multi-dimensional BM)

A d-dimensional standard Brownian motion is an  $\mathbb{R}^d$ -valued process  $B_t = (B_t^1, \dots, B_t^d)$  with the property that each component  $B_t^i$  is a one-dimensional standard Brownian motion and coordinates  $B_1, B_2, \dots, B_d$  are independent.

**Theorem 1.2.3.** There exists a Borel probability measure  $P^0$  on the path space  $C = C_{\mathbb{R}}[0,\infty)$ , which is metrized by

$$r(\eta, \xi) = \sum_{k=1}^{\infty} 2^{-k} \left(1 \wedge \sup_{0 \le t \le k} |\eta - \xi|\right)$$

such that B the coordinate process on  $(C, \mathcal{B}_C, P^0)$  is a standard one-dimensional Brownian motion w.r.t.  $\{\mathcal{F}_t^B\}$ .

**Proposition 1.2.4.** Suppose  $B = \{B_t\}$  is a Brownian motion w.r.t.  $\{\mathcal{F}_t\}$  on  $(\Omega, \mathcal{F}, P)$ . Then  $B_t$  and  $B_t^2 - t$  are martingales w.r.t.  $\mathcal{F}_t$ .

Proof.

We know for  $0 \le s < t$ ,

$$E(B_t|\mathcal{F}_s) = E(B_t - B_s + B_s|\mathcal{F}_s) = B_s$$

and

$$E(B_t^2 - t|\mathcal{F}_s) = E((B_t - B_s)^2 - B_s^2 + 2B_tB_s - t|\mathcal{F}_s) = B_s^2 - s$$

**Proposition 1.2.5.** Suppose  $B = \{B_t\}$  is a Brownian motion w.r.t.  $\{\mathcal{F}_t\}$  on  $(\Omega, \mathcal{F}, P)$ .

- We can assume that  $\mathcal{F}_t$  contains every set A for which there exists  $N \in \mathcal{F}$  such that  $A \subset N$  and P(N) = 0. Furthermore,  $B = \{B_t\}$  is also a Brownian motion w.r.t.  $\{\mathcal{F}_{t+}\}$ .
- Fix  $s \in \mathbb{R}_+$  and define  $Y_t = B_{s+t} B_s$ , then Y is independent of  $\mathcal{F}_{s+}$  and it is a standard Brownian motion w.r.t.  $\mathcal{G} = \{\mathcal{G}_t = \mathcal{F}_{(s+t)+}\}$ .

Proof.

It remains to check that  $B_t - B_s$  is independence of  $\overline{F}_s$ . For any  $G \in \overline{F}_s$ , there exists A such that  $P(A \triangle G) = 0$  and hence P(GB) = P(AB) = P(A)P(B) = P(G)P(B) for any  $B \in \sigma(B_t - B_s)$  and we are done.

For any  $Z \in \mathcal{F}_{s+}$  bounded and h Borel bounded, we have for any  $0 \le s < s' < t$ ,

$$E[Zh(B_t-B_s')] = E(Z) \cdot \frac{1}{\sqrt{2\pi(t-s')}} \int h(x) \exp\left\{-\frac{x^2}{2(t-s')}\right\} dx$$

and use DCT to let  $s' \to s$  and we are done.

The rest part is easy to be checked.

**Lemma 1.2.6.** Suppose X is a right-continuous process adapted to a filtration  $\{\mathcal{F}_t\}$  and for all s < t the increment  $X_t - X_s$  is independent of  $\overline{\mathcal{F}}_s$ , then  $X_t - X_s$  is independent of  $\overline{\mathcal{F}}_{s+}$ .

#### **Definition 1.2.3.** (Path Space)

In the following part, we will consider the path space C and the coordinate process  $B_t(\omega) = \omega(t)$  and the filtration  $\mathcal{F}_t^B$  generated by B. For any x there exists a probability measure  $P^x$  such that B is a Brownian motion started at x. Expectation under  $P^x$  is denoted by  $E^x$ .

Proof.

We know  $\omega \mapsto x + \omega$  is a homeomorphism on C and hence we may define  $P^x(A) = P^0(-x + A)$  and then  $P^x(B_0 = x) = P^0(-x + \{B_0 = x\}) = P^0(\{B_0 = 0\}) = 1$ . The rest is similar to be checked.

#### **Definiton 1.2.4.** (Shift map)

The shift maps  $\{\theta_s: 0 \leq s < \infty\}$  defined by  $(\theta_x \omega)(t) = \omega(s+t)$ , the shift acts on B is defined by  $\theta_s B = \{B_{s+t}, t \geq 0\}$ .

**Proposition 1.2.7.** Let H be a bounded  $\mathcal{B}_C$ -measurable function on C.

- $E^x[H]$  is a Borel measurable function of x.
- For each  $x \in \mathbb{R}$

$$E^{x}[H \circ \theta_{s} | \mathcal{F}_{s+}^{B}](\omega) = E^{B_{s}(\omega)}[H]$$
 for  $P^{x}$  – almost every  $\omega$ 

In particular,  $\{P^x\}$  on C is a Markov process w.r.t.  $\mathcal{F}_t^B$ .

### 2 Martingales

#### 2.1 Basic Conclusions

#### Proposition 2.1.1.

- If M is a martingale and  $\phi$  is a convex function such that  $\phi(M_t)$  is integrable for all  $t \geq 0$ , then  $\phi(M_t)$  is a submartingale.
- If M is a submartingable and  $\phi$  a decreasing convex function such that  $\phi(M_t)$  is integrable for all  $t \geq 0$ , then  $\phi(M_t)$  is a submartingale.

Proof.

We only need to consider  $S_{\phi} = \{l(x) = ax + b, l(x) \leq \phi(x) \text{ for any } x\}$  and  $\phi(x) = \sup_{l \in S_{\phi}} l(x)$ , then

$$E(\phi(M_t)|\mathcal{F}_s) = E(\sup l(M_t)|\mathcal{F}_s) \ge \sup l(E(M_t|\mathcal{F}_s)) = \phi(M_s)$$

and for M is submartingale, we have

$$E(\phi(M_t)|\mathcal{F}_s) = E(\sup l(M_t)|\mathcal{F}_s) \ge \sup l(E(M_t|\mathcal{F}_s)) = \phi(E(M_t|\mathcal{F}_s)) \ge \phi(M_s)$$

#### **Definition 2.1.1.** (Uniformly Integrable)

Let  $\{X_{\alpha}\}_{{\alpha}\in A}$  be a collection of random variables, call them **uniformly integrable** if

$$\lim_{M \to \infty} \sup_{\alpha \in A} E[|X_{\alpha}|; |X_{\alpha}| \ge M] = 0$$

**Lemma 2.1.2.** Let X be an integrable random variable, then  $\{E(X|\mathcal{A})\}_{\mathcal{A}\subset\mathcal{F} \text{ sub-}\sigma\text{-algebra}}$  is uniformly integrable.

Proof.

Recall that if X is integrable, we may know that  $E(|X|; |X| \ge M) \to 0$  with  $M \to \infty$ , and  $P(|X| \ge M) \to 0$ , so for any  $\epsilon > 0$ , we may choose M such that  $E(|X|; |X| \ge M) < \epsilon/2$  and then  $\delta = \epsilon/2M$  will satisfy that for any  $A, P(A) < \delta$ ,  $E(|X|; A) < \epsilon$ .

With the fact above, we know that since

$$|E(X|\mathcal{A})| \le E(|X||\mathcal{A})$$

then

$$P(|E(X|A)| \ge M) \le M^{-1}E(|E(X|A)|) \le M^{-1}E|X|$$

and for any  $\epsilon > 0$ , let M such that  $M^{-1}E|X| < \delta$ , then

$$E(|E(X|\mathcal{A})|; |E(X|\mathcal{A})| \ge M) \le E(|X|; |E(X|\mathcal{A})| \ge M) < \epsilon$$

and we are done.

**Lemma 2.1.3.** Suppose  $X_n \to X$  in  $L^1$ , for any sub- $\sigma$ -algebra  $\mathcal{A} \subset \mathcal{F}$ , there exists  $\{n_j\}$  such that  $E[X_{n_j}|\mathcal{A}] \to E[X|\mathcal{A}]$  a.s.

Proof.

It suffices to show that  $E(X_n|\mathcal{A}) \to E(X|\mathcal{A})$  in  $L^1$ , which is because

$$E(|E(X_n|\mathcal{A}) - E(X|\mathcal{A})|) = E(|E(X_n - X|\mathcal{A})|) \le E|X_n - X|$$

and we are done.

**Proposition 2.1.4.** Suppose M is a right-continuous submartingale w.r.t. a filtration  $\{\mathcal{F}_t\}$ , then M is a submartingale also w.r.t.  $\{\mathcal{F}_{t+}\}$ .

Proof.

To show this conclusion, we shall consider  $M \vee c$  is a submartingale and then

$$E[M_t \vee c | \mathcal{F}_{s+}] > E[M_{s+n^{-1}} \vee c | \mathcal{F}_{s+}]$$

for some n, since  $M_{s+n^{-1}} \vee c \to M_s \vee c$ , then by lemma 2.1.2, we will have this is also a convergence in  $L^1$  and hence we will find a subsequence such that  $E(M_{s+n_j^{-1}} \vee c|\mathcal{F}_{s+}) \to E(M_s \vee c|\mathcal{F}_{s+})$  and we have

$$E[M_t \vee c | \mathcal{F}_{s+}] \geq M_s$$

and let  $c \to \infty$ , we are done.

**Proposition 2.1.5.** Suppose the filtration  $\{\mathcal{F}_t\}$  satisfies the usual events, in other words  $\mathcal{F}$  is complete and  $\mathcal{F}_t = \mathcal{F}_{t+}$ . Let M be a submartingale, such that  $t \to EM_t$  is right-continuous. Then there exists a cadlag modification of M that is an  $\mathcal{F}_t$ -submartingale.

#### 2.2 Optimal Stopping

**Lemma 2.2.1.** Let M be a submaringale. Let  $\sigma, \tau$  two stopping times whose values lie in an ordered countable set  $\{s_1 < s_2 < s_3 < \cdots\} \cup \{\infty\}$  where  $s_j$  increases to  $\infty$ . Then for any  $T < \infty$ ,

$$E[M_{\tau \wedge T}\mathcal{F}_{\sigma}] > M_{\sigma \wedge \tau \wedge T}$$

Proof.