
NOTES FOR ANALYSIS AND PDES

**Based on the Math 719(Cole)/720(M.Ifrim),
Folland and etc.**

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Contents

Part I

Sobolev Spaces

In the following chapters, we denote $\mathcal{D}(U)$ to be the test functions on an open set $U \subset \mathbb{R}^m$, i.e. the continuous functions with compact support on U , and V' to be the dual space of the vector space V .

1 Introduction to Sobolev Spaces

1.1 Sobolev spaces

Definiton 1.1.1. Let $u \in \mathcal{D}'(U)$, where $U \subset \mathbb{R}^d$ is open. The k -th order L^p -based Sobolev norm of u is

$$\|u\|_{W^{k,p}(U)} := \sum_{|\alpha| \leq k} \|D^\alpha u\|_{L^p}, \quad 1 \leq p < \infty,$$

where we are using the distributional derivative and assume that $D^\alpha u$ is an L^p function.

Definiton 1.1.2. Let U be an open subset of \mathbb{R}^d . The L^p -based Sobolev space of order k on U is

$$W^{k,p}(U) = \{u \in \mathcal{D}'(U) : \|u\|_{W^{k,p}(U)} < \infty\}.$$

Note that $\mathcal{D}(U) \subseteq W^{k,p}(U)$.

Definiton 1.1.3. The set of $u \in W^{k,p}(U)$ that vanish (to appropriate orders) on ∂U is

$$W_0^{k,p}(U) = \overline{\mathcal{C}_c^\infty(U)}_{W^{k,p}}^{\|\cdot\|} \subset W^{k,p}(U).$$

When $p = 2$, we introduce the notation

$$H^k(U) = W^{k,2}(U), \quad H_0^k(U) = W_0^{k,2}(U).$$

We can define an inner product on H^k by

$$\langle u, v \rangle_{H^k} = \sum_{|\alpha| \leq k} \langle D^\alpha u, D^\alpha v \rangle_{L^2}.$$

Proposition 1.1.1.

1. For all $k \in \mathbb{Z}_{\geq 0}$ and $1 \leq p \leq \infty$, the following Sobolev spaces $(W^{k,p}(U), \|\cdot\|_{W^{k,p}})$ and $(W_0^{k,p}(U), \|\cdot\|_{W^{k,p}})$ are Banach spaces.
2. For all $k \in \mathbb{Z}_{\geq 0}$, $(H^k(U), \langle \cdot, \cdot \rangle_{H^k})$ and $(H_0^k(U), \langle \cdot, \cdot \rangle_{H^k})$ are Hilbert spaces.
3. (Fourier-analytic characterization of H^k) Given $u \in H^k(U)$

$$\|u\|_{H^k} \simeq \|\hat{u}\|_{L^2} + \|\xi^k \hat{u}\|_{L^2} \simeq \|(1 + |\xi|^2)^{k/2} \hat{u}\|_{L^2},$$

where \simeq between norms are the equivalence.

Proof.

□

1.2 Negative Sobolev Spaces

It is natural to consider the dual space of the Sobolev spaces, which can be interpreted as the following space as well.

Definiton 1.2.1. For $k > 0$ and $1 < p < \infty$, define the *negative order Sobolev norm*

$$\|u\|_{W^{-k,p}(U)} = \inf \left\{ \sum_{|\alpha| \leq k} \|g_\alpha\|_{L^p} : u = \sum_{|\alpha| \leq k} D^\alpha g_\alpha \right\}.$$

and the *negative order Sobolev space* is

$$W^{-k,p}(U) = \left\{ u \in \mathcal{D}'(U) : u = \sum_{|\alpha| \leq k} D^\alpha g_\alpha, g_\alpha \in L^p(U) \right\}.$$

Proposition 1.2.1. For $k \in \mathbb{Z}_{\geq 0}$ and $1 < p < \infty$,

$$(W_0^{k,p}(U))^* = W^{-k,q}(U), \quad \frac{1}{p} + \frac{1}{q} = 1.$$

Proof. For $u \in \mathcal{D}(U)$ and some

$$v = \sum_{|\alpha| \leq k} D^\alpha g_\alpha, \quad g_\alpha \in L^q(U),$$

and we may define $(\cdot)^* : W^{-k,q}(U) \rightarrow (W_0^{k,p}(U))^*$ by

$$v^\flat(u) = \int vu = \sum_{|\alpha| \leq k} (-1)^{|\alpha|} \int g_\alpha D^\alpha u$$

which is well-defined since another representation is equal to this from the distributions' perspectives on $\mathcal{D}(U)$, where the equality can be extended to the whole $W_0^{k,p}(U)$ by the density argument that

$$|v^\flat(u)| \leq \sum_{|\alpha| \leq k} \left| \int g_\alpha u \right| \leq \sum_{|\alpha| \leq k} \|g_\alpha\|_{L^q} \|D^\alpha u\|_{L^p} \leq 2\|v\|_{W^{-k,q}(U)} \|u\|_{W^{k,p}(U)}$$

where we can choose the representation of v to make

$$\sum_{|\alpha| \leq k} \|g_\alpha\|_{L^p} \leq 2\|v\|_{W^{-k,q}(U)}$$

and this help us to make the extension.

From the other side, we need to show for any linear functional on $W_0^{k,p}(U)$ can be obtained by some element in the negative Sobolev space. Firstly, notice there is a natural inclusion of $W_0^{k,p}(U)$ to $L^p(U)^{\oplus K(k)}$, and define a linear map

$$T : \mathcal{D}(U)$$

□

1.3 Relationship between a priori estimates, existence, and uniqueness

Proposition 1.3.1. Let X, Y be Banach spaces, and $P : X \rightarrow Y$ be bounded linear operator. Denote $P^* : Y^* \rightarrow X^*$ as the adjoint, i.e. $\langle v, Pu \rangle = \langle P^*v, u \rangle$. Assume for any $u \in X$ we have $\|u\|_X \leq C\|Pu\|_Y$, then

1. If $Pu = 0$, then $u = 0$.
2. For all $g \in X^*$, there exists $v \in Y^*$ such that

$$P^*v = g, \quad \|v\|_{Y^*} \leq C\|g\|_{X^*}.$$

Proof. (1) is obvious. For (2), \square

Proposition 1.3.2. Let X, Y be Banach spaces, and let $P : X \rightarrow Y$ be bounded linear operator. Suppose $\|v\|_{Y^*} \leq C\|P^*v\|_{X^*}$. Then

1. If $v \in Y^*$ and $P^*v = 0$, then $v = 0$.
2. For all $f \in Y$, there exists a $u \in X$ such that $Pu = f$ and $\|u\|_X \leq C\|f\|_Y$.

Definiton 1.3.1. Let X be a Banach space, we call it *reflexive* if $u \rightarrow (v \mapsto \langle v, u \rangle)$ is an isomorphism.

Proposition 1.3.3. All sobolev spaces $W_0^{k,p}(U)$ with $1 < p < \infty$ are reflexive.

Definiton 1.3.2. Given $U \subset Y$, the *annihilator* of U is

$$U^\perp := \{v \in Y^* : \langle v, f \rangle = 0, \text{ for any } f \in U\}$$

and similarly, for some $V \subset X^*$, the *annihilator* of V is

$${}^\perp V := \{u \in X : \langle g, u \rangle = 0, \text{ for any } g \in V\}$$

Proposition 1.3.4. For the operators in (??) we have

$$(\text{ran } P)^\perp = \ker(P^*), \quad \ker(P) = {}^\perp (\text{ran } P^*)$$

Proposition 1.3.5. Let X, Y be Banach spaces, with X reflexive, and $P : X \rightarrow Y$ be a bounded linear operator. If $P(X) = Y$, then thre exists some $C > 0$ such that

$$\|v\|_{Y^*} \leq C\|P^*v\|_{X^*}$$

1.4 Approximation by smooth functions and smooth partition of unity

Lemma 1.4.1. Let ϕ be smooth, compactly supported i.e. $\phi \in C_0^\infty(U)$, and have

$$\int \phi dx = 1.$$

Let $u \in L^p(\mathbb{R}^d)$ with $1 \leq p < \infty$. Denote mollifiers

$$\phi_\epsilon(x) = \frac{1}{\epsilon^d} \phi(x/\epsilon) \quad (\text{so } \int \phi_\epsilon = 1).$$

Then

$$\|\phi_\epsilon * u - u\|_{L^p} \xrightarrow{\epsilon \rightarrow 0} 0,$$

where

$$\phi_\epsilon * u = \int \phi_\epsilon(x-y)u(y)dy.$$

Proof. The key ingredient is the continuity of the translation operator on L^p . Define for $z \in \mathbb{R}^d$ and $u \in L^p$ the translation operator

$$\tau_z u(x) = u(x-z).$$

Then

$$\lim_{|z| \rightarrow 0} \|\tau_z u - u\|_{L^p} = 0,$$

which you can check. Now

$$\phi_\epsilon * u(x) - u(x) = \int u(x-y)\phi_\epsilon(y)dy - u(x).$$

Since $\int \phi_\epsilon = 1$

$$= \int (u(x-y) - u(x))\phi_\epsilon(y)dy.$$

Taking the L^p norm, we have

$$\begin{aligned} \|\phi_\epsilon * u(x) - u(x)\|_{L^p} &= \left\| \int (u(x-y) - u(x))\phi_\epsilon(y)dy \right\|_{L^p} \\ &\leq \int \|u(\cdot - y) - u(\cdot)\|_{L^p} |\phi_\epsilon(y)| dy. \end{aligned}$$

Since ϕ has compact support, $\text{supp } \phi_\epsilon \rightarrow \{0\}$ as $\epsilon \rightarrow 0$. Thus, the integrand goes to 0 as $\epsilon \rightarrow 0$. So we may apply the dominated convergence theorem to get

$$\|\phi_\epsilon * u - u\|_{L^p} \xrightarrow{\epsilon \rightarrow 0} 0.$$

□

Lemma 1.4.2. Suppose $\{U_\alpha\}_{\alpha \in A}$ be an open covering of U in \mathbb{R}^d . There exists a smooth partition of unity $\{\chi_\alpha\}_{\alpha \in A}$ on U subordinate to $\{U_\alpha\}_{\alpha \in A}$, i.e. 1. $\sum_\alpha \chi_\alpha(x) = 1$ on U and for all $x \in U$ there exist only finitely many nonzero $\chi_\alpha(x)$ 2. $\text{supp } \chi_\alpha \subseteq U_\alpha$ 3. χ_α is smooth.

Proof. Start from a continuous partition of unity and apply the previous lemma to approximate by smooth functions. □

2 Approximation in Bounded Domains and the Extension Theorem

2.1 Approximation theorems in bounded domains

Theorem 2.1.1. Let $k \geq 0$ be an integer and $1 \leq p < \infty$. (i) $C^\infty(\mathbb{R}^d)$ is dense in $W^{k,p}(\mathbb{R}^d)$.
(ii) $C_c^\infty(\mathbb{R}^d)$ is dense in $W^{k,p}(\mathbb{R}^d)$.

Proof. (a) This is an application of mollification. (b) Approximate by $f\chi(1/R)$, letting $R \rightarrow \infty$, where $\chi \in C_c^\infty(\mathbb{R}^d)$ is such that $\chi(0) = 1$. \square

Theorem 2.1.2. Let $k \geq 0$ be an integer, $1 \leq p < \infty$, and U an open subset of \mathbb{R}^d . Then $C^\infty(U)$ is dense in $W^{k,p}(U)$.

Proof. Let $u \in W^{k,p}(U)$, and fix $\epsilon > 0$. We want to find $v \in C^\infty(U)$ such that

$$\|u - v\|_{W^{k,p}} \leq \epsilon.$$

Define

$$U_j := \{x \in U : \text{dist}(x, \partial U) > 1/j\}, \quad V_j = U_j \setminus \overline{U_{j+1}}.$$

Then $U \subset \bigcup_{j=1}^{\infty} V_j$, so there is a smooth partition of unity χ_j subordinate to V_j .

Now split

$$u = \sum_{j=1}^{\infty} u\chi_j := \sum_{j=1}^{\infty} u_j.$$

Then, as $\text{supp } \chi_j \subset V_j$, we have $\text{supp } u_j = \text{supp}(u\chi_j) \subset V_j$. Moreover, $u_j \in C_c^\infty(\mathbb{R}^d)$.

If we let $\phi \in C_c^\infty(\mathbb{R}^d)$ with $\int \phi = 1$ and $\text{supp } \phi \subset B_1(0)$ be a mollifier, let $v_j = \phi_{\epsilon_j} * u_j$, where ϵ_j is chosen to achieve

$$\|u_j - v_j\|_{W^{k,p}} \leq 2^{-j}\epsilon, \quad \text{supp } v_j \subset \tilde{V}_j = U_{j-1} \setminus \overline{U_{j+2}}.$$

Here, we make use of the fact that

$$\text{supp}(f * g) \subseteq \text{supp } f + \text{supp } g = \{x + y \in \mathbb{R}^d : x \in \text{supp } f, y \in \text{supp } g\}.$$

Now take

$$v = \sum_{j=1}^{\infty} v_j.$$

This is well-defined, as \tilde{V}_j is locally finite. This is also smooth, so $v \in C^\infty(U)$. On the other hand,

$$\|v - u\|_{W^{k,p}} \leq \sum_{j=1}^{\infty} \|v_j - u_j\|_{W^{k,p}} \leq \sum_{j=1}^{\infty} 2^{-j}\epsilon = \epsilon.$$

\square

2.2 The extension theorem

Theorem 2.2.1 (Extension theorem). Let $k \geq 0$ be a nonnegative integer, $1 \leq p < \infty$, and U a bounded domain with C^k boundary. Let V be an open set such that $V \supseteq \bar{U}$. Then there exists an operator

$$\mathcal{E} : W^{k,p}(U) \rightarrow W^{k,p}(\mathbb{R}^d)$$

such that (i) (Extension) $\mathcal{E}u|_U = u$ (ii) (Linear and bounded) \mathcal{E} is linear, and $\|\mathcal{E}u\|_{W^{k,p}(\mathbb{R}^d)} \leq C\|u\|_{W^{k,p}(U)}$. (iii) (Support prescription) $\text{supp } \mathcal{E}u \subseteq V$.

Proof. Observe that, by the previous approximation theorem, it suffices to consider $u \in C^\infty(\bar{U})$ (by density and the boundedness property (ii)).

Remark (what we will actually construct). We first build an extension locally near each boundary chart. The resulting locally extended functions will have support in a small neighborhood of the boundary chart. We then glue all pieces together (using a partition of unity) and finally multiply by a cutoff supported in V to enforce the support condition (iii).

Step 1 (Reduction to the half-ball case). As in Step 1 in the proof of the previous theorem, construct the open sets U_0, U_1, \dots, U_K and the partition of unity $\chi_0, \chi_1, \dots, \chi_K$.

Define $u_k := \chi_k u$, and observe that

• u_0 is already in $W^{k,p}(\mathbb{R}^d)$ and $\text{supp } u_0 \subseteq U_0 \subseteq V$,

• $u_k \in C^\infty(U)$ and $\text{supp } u_k \subseteq B_{r_0} \subseteq U_k \cap U$.

What the boundary chart means: For each $k \geq 1$, because ∂U is C^k , after a rigid motion of coordinates (translation and rotation) we may assume that in U_k the boundary is given by a graph

$$\partial U \cap U_k = \{(x', x_d) : x_d = \gamma(x')\}, \quad U \cap U_k = \{(x', x_d) : x_d > \gamma(x')\},$$

where $x' = (x^1, \dots, x^{d-1})$ and $\gamma \in C^k$. The point $x_0 = (x'_0, x'_0) \in \partial U$ is chosen in that chart. The purpose is to "flatten" this graph.

The way we do this flattening is via the following change of variables

$$y' = x' - x'_0, \quad y_d = x_d - \gamma(x'),$$

then $U_k \cap U$ gets mapped into $\{y \in B_{\tilde{r}}(0) : y^d > 0\}$.

One can wonder why this is the right change of variables? It might sound like over explaining but this is the idea: The map $x \mapsto y$ is designed so that the boundary graph becomes flat: if $x_d = \gamma(x')$ (a boundary point), then $y_d = 0$. If $x_d > \gamma(x')$ (an interior point), then $y_d > 0$. Thus the image of $U \cap U_k$ is a region above the hyperplane $\{y_d = 0\}$. The translation $y' = x' - x'_0$ just moves the boundary point to the origin. Because we work in a small ball around x_0 and γ is C^k , the image is contained in a half-ball $B_{\tilde{r}}(0) \cap \{y_d > 0\}$ for some $\tilde{r} > 0$.

In fact $x \mapsto y$ is a C^k diffeomorphism (locally). Write $\Phi(x', x_d) = (y', y_d) = (x' - x'_0, x_d - \gamma(x'))$. Then

$$D\Phi = \begin{pmatrix} I_{d-1} & 0 \\ -\nabla \gamma & 1 \end{pmatrix}.$$

Hence $D\Phi$ is invertible everywhere in the chart, and Φ is locally bijective with explicit inverse

$$\Phi^{-1}(y', y_d) = (y' + x'_0, y_d + \gamma(y' + x'_0)),$$

which is also C^k . So Φ is a C^k diffeomorphism between the chart neighborhood and its image.

Note that the change of variables $x \mapsto y$ is C^k , and u_k is smooth, so $\tilde{u}_k(y) = u_k(x(y))$ satisfies, by the chain rule,

$$\|\tilde{u}_k\|_{W_y^{k,p}(\tilde{U})} \leq C \|u_k\|_{W_x^{k,p}}.$$

Step 2 (Extension in the half-ball case). Now we have $U = B_r^+(0)$, $W = B_{r/2}^+(0)$, and $\text{supp } u \subseteq W$, and we want to extend u . The idea is the higher order reflection method. After flattening, we may assume u is defined on the upper half-ball

$$B_r^+(0) = \{x \in B_r(0) : x_d > 0\},$$

and moreover $\text{supp } u \subset B_{r/2}^+(0)$ so it stays away from the spherical boundary $\partial B_r(0)$. We only need to extend across the flat boundary $\{x_d = 0\}$, while keeping $W^{k,p}$ regularity up to order k .

Define

$$\tilde{u}(x) = \sum_{j=0}^k \alpha_j u(x', -\beta_j x_d), \quad x_d < 0,$$

where the scaling factor $0 < \beta_j < 1$ is chosen so that $(x^1, \dots, x^{d-1}, -\beta_j x^d) \in B_r^+(0)$.

Remark: Why we must "shrink" (the role of $\beta_j < 1$). If $x \in B_r(0)$ has $x_d < 0$, then the reflected point $(x', -x_d)$ might lie outside $B_r(0)$ when x is close to the spherical boundary. Choosing $0 < \beta_j < 1$ ensures that $-\beta_j x_d$ is smaller in magnitude than $-x_d$, i.e. it moves the point closer to the plane $\{x_d = 0\}$. Because $\text{supp } u \subset B_{r/2}^+(0)$, we can choose a fixed finite set of $\beta_j \in (0, 1)$ so that whenever $x \in B_r(0)$ and $x_d < 0$, all points $(x', -\beta_j x_d)$ remain inside $B_r^+(0)$ (indeed inside the region where u is defined). This is the local reason for the shrink: it avoids leaving the chart.

We need to match the normal derivatives on $\{x^d = 0\}$ up to order k . Observe that

$$\partial_{x^d}^j(u(x^1, \dots, x^{d-1}, -\beta_j x^d)) = (-\beta_j)^j (\partial_{x^d}^j u)(x^1, \dots, x^{d-1}, -\beta_j x^d).$$

Deriving the matching conditions carefully. For $x_d < 0$, we define

$$\tilde{u}(x', x_d) = \sum_{m=0}^k \alpha_m u(x', -\beta_m x_d).$$

Fix $\ell \in \{0, 1, \dots, k\}$. Differentiate ℓ times in the normal variable:

$$\partial_{x^d}^\ell \tilde{u}(x', x_d) = \sum_{m=0}^k \alpha_m \partial_{x^d}^\ell \left(u(x', -\beta_m x_d) \right) = \sum_{m=0}^k \alpha_m (-\beta_m)^\ell (\partial_{x^d}^\ell u)(x', -\beta_m x_d).$$

Now take the limit $x_d \rightarrow 0^-$: then $-\beta_m x_d \rightarrow 0^+$, so

$$\partial_{x_d}^\ell \tilde{u}(x', 0^-) = \sum_{m=0}^k \alpha_m (-\beta_m)^\ell (\partial_{x_d}^\ell u)(x', 0^+).$$

On the other hand, for $x_d > 0$, $\tilde{u} = u$, hence

$$\partial_{x_d}^\ell \tilde{u}(x', 0^+) = (\partial_{x_d}^\ell u)(x', 0^+).$$

To ensure $\tilde{u} \in W^{k,p}$ across the interface, we impose equality of these traces:

$$\partial_{x_d}^\ell \tilde{u}(x', 0^-) = \partial_{x_d}^\ell \tilde{u}(x', 0^+), \quad \ell = 0, \dots, k.$$

Since $(\partial_{x_d}^\ell u)(x', 0^+)$ is common to both sides, it is enough to require

$$\sum_{m=0}^k \alpha_m (-\beta_m)^\ell = 1, \quad \ell = 0, \dots, k.$$

This is equivalent to

$$\begin{pmatrix} 1 & 1 & \cdots & 1 \\ -\beta_0 & -\beta_1 & \cdots & -\beta_k \\ (-\beta_0)^2 & (-\beta_1)^2 & \cdots & (-\beta_k)^2 \\ \vdots & \vdots & \ddots & \vdots \\ (-\beta_0)^k & (-\beta_1)^k & \cdots & (-\beta_k)^k \end{pmatrix} \begin{pmatrix} \alpha_0 \\ \alpha_1 \\ \vdots \\ \alpha_k \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}.$$

Written in matrix form, this is a linear system involving a Vandermonde matrix. So the β_j are known and then we want to solve for the α 's this system is solvable (explicit determinant), because the matrix is a Vandermonde matrix with nodes $t_j = -\beta_j$. Its determinant is

$$\det V = \prod_{0 \leq i < j \leq k} (t_j - t_i) = \prod_{0 \leq i < j \leq k} ((-\beta_j) - (-\beta_i)) = \prod_{0 \leq i < j \leq k} (\beta_i - \beta_j).$$

If the β_j are pairwise distinct, then $\det V \neq 0$, so V is invertible and the system has a unique solution $(\alpha_0, \dots, \alpha_k)$. Importantly, these coefficients depend only on the chosen β_j (hence only on k), not on u .

Why this produces a $W^{k,p}$ extension. Because the matching conditions hold for $\ell = 0, \dots, k$ the traces of $\partial_{x_d}^\ell \tilde{u}$ from above and below coincide at $x_d = 0$ up to order k . Away from $x_d = 0$, \tilde{u} is a finite sum of smooth compositions of u , hence has the same $W^{k,p}$ regularity. The only potential problem is the interface $x_d = 0$; the derivative matching prevents the creation of distributional boundary terms when taking weak derivatives. Concretely, if you test $\partial_{x_d}^\ell \tilde{u}$ against a smooth compactly supported test function and integrate by parts separately on $\{x_d > 0\}$ and $\{x_d < 0\}$, the boundary terms at $x_d = 0$ cancel precisely because the traces match. Therefore all weak derivatives of \tilde{u} up to order k lie in L^p , so $\tilde{u} \in W^{k,p}(B_r(0))$. Moreover, since the construction is linear and involves only finitely many terms,

$$\|\tilde{u}\|_{W^{k,p}(B_r(0))} \leq C \|u\|_{W^{k,p}(B_r^+(0))},$$

with C depending on k, p and the chosen β_j .

Now use the fact that if all the β_j are distinct, then this matrix is invertible. This means that there is a choice of $(\alpha_0, \dots, \alpha_K)$ so that these equations hold. This defines \tilde{u} on $B_r(0)$, which extends u and matches all derivatives up to order K on the boundary $\{x^d = 0\}$.

Step 3 (Extension to \mathbb{R}^d). Final localization and support in V . At this stage, \tilde{u} is defined only in the local chart ball $B_r(0)$. To obtain a global extension in \mathbb{R}^d and enforce $\text{supp}(\mathcal{E}u) \subset V$, we proceed as follows:

1 Extend \tilde{u} by zero outside $B_r(0)$. Because $\text{supp } u \subset B_{r/2}^+(0)$ and we may choose a cutoff later, this does not create boundary issues (the cutoff makes the function vanish near $\partial B_r(0)$). Choose a smooth cutoff $\chi_V \in C_c^\infty(V)$ such that $\chi_V \equiv 1$ on \bar{U} (or at least on a neighborhood containing all supports of the glued pieces inside U). Define $\mathcal{E}u := \chi_V \tilde{u}$ (and similarly for each localized boundary piece). This forces the global support to lie inside V while preserving the values on U because $\chi_V \equiv 1$ there.

Finally, put an appropriate smooth cutoff $\chi_V = 1$ on U with $\text{supp } \chi_V \subseteq V$ to define $\mathcal{E}u$, i.e.

$$\mathcal{E}u = \chi_V \tilde{u}.$$

(How the full operator is obtained). Repeat the construction for each boundary chart U_k (with its own flattening map Φ_k), extend each $u_k = \chi_k u$, and then sum the finitely many extended pieces together with the interior extension u_0 . Linearity is clear at every step, and the global $W^{k,p}$ bound follows from summing finitely many estimates. \square \square

3 Trace and Extension Theorems and Introduction to Sobolev Inequalities

3.1 The trace theorem

Definiton 3.1.1. For $u \in C^1(\bar{U})$, we define the trace to be

$$\text{tr}_{\partial U} u := u|_{\partial U}.$$

We wish to extend this operation to all of $W^{1,p}(U)$. Note that $\text{tr}_{\partial U}$ is linear, so we can extend it if we know it is bounded.

Theorem 3.1.1 (Trace theorem, non-sharp). Let U be a bounded open subset of \mathbb{R}^d with C^1 boundary ∂U , and let $1 < p < \infty$. Then for $u \in C^1(\bar{U})$

$$\|\text{tr}_{\partial U} u\|_{L^p(\partial U)} \leq C \|u\|_{W^{1,p}(U)}.$$

(i) As a consequence, $\text{tr}_{\partial U}$ extends uniquely by continuity (and density of $C^1(\bar{U}) \subset W^{1,p}(U)$) to a bounded linear map

$$\text{tr}_{\partial U} : W^{1,p}(U) \rightarrow L^p(\partial U).$$

(ii) Moreover, $u \in W_0^{1,p}(U)$ if and only if $\text{tr}_{\partial U} u = 0$.

The map $\text{tr}_{\partial U} : W^{1,p}(U) \rightarrow L^p(\partial U)$ is not surjective.

Theorem 3.1.2 (Sharp trace theorem). For $u \in C^\infty(\overline{\mathbb{R}_+^d}) \cap H^1(\mathbb{R}_+^d)$,

$$\|\operatorname{tr}_{\partial U} u\|_{H^{1/2}(\mathbb{R}^{d-1})} \leq C \|u\|_{H^1(\mathbb{R}_+^d)}.$$

Proof. Let $u \in C^\infty(\overline{\mathbb{R}_+^d}) \cap H^1(\mathbb{R}_+^d)$.

Step 0 (What the extension procedure is, and why we use it). The trace we want to estimate is the boundary value $u(x', 0)$, which lives on \mathbb{R}^{d-1} . The Fourier proof below is most transparent if we can treat u as a function on all of \mathbb{R}^d , because then we can use the full Fourier transform in $\xi = (\xi', \xi_d)$ and identify the H^1 norm with $\|(1 + |\xi|^2)^{1/2}\tilde{u}\|_{L_\xi^2}$. So we first extend u from the half- space \mathbb{R}_+^d to a function \tilde{u} on \mathbb{R}^d with a controlled H^1 norm.

Extension procedure (for the half- space). Define the even reflection across the boundary $\{x_d = 0\}$ by

$$\tilde{u}(x', x_d) := u(x', |x_d|), \quad (x', x_d) \in \mathbb{R}^{d-1} \times \mathbb{R}.$$

Then $\tilde{u} \in H^1(\mathbb{R}^d)$ and $\tilde{u} = u$ on \mathbb{R}_+^d . Moreover,

$$\|\tilde{u}\|_{L^2(\mathbb{R}^d)}^2 = \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}} |\tilde{u}(x', x_d)|^2 dx_d dx' = 2 \int_{\mathbb{R}^{d-1}} \int_0^\infty |u(x', x_d)|^2 dx_d dx' = 2 \|u\|_{L^2(\mathbb{R}_+^d)}^2,$$

and for tangential derivatives ∂_{x_j} , $j \leq d - 1$,

$$\|\partial_{x_j} \tilde{u}\|_{L^2(\mathbb{R}^d)}^2 = 2 \|\partial_{x_j} u\|_{L^2(\mathbb{R}_+^d)}^2.$$

For the normal derivative, observe that for $x_d \neq 0$,

$$\partial_{x_d} \tilde{u}(x', x_d) = \operatorname{sgn}(x_d) \partial_{x_d} u(x', |x_d|),$$

hence

$$\|\partial_{x_d} \tilde{u}\|_{L^2(\mathbb{R}^d)}^2 = 2 \|\partial_{x_d} u\|_{L^2(\mathbb{R}_+^d)}^2.$$

Therefore

$$\|\tilde{u}\|_{H^1(\mathbb{R}^d)} \leq C \|u\|_{H^1(\mathbb{R}_+^d)}, \quad (1)$$

and the extension procedure is justified: it is linear, preserves the boundary values (since $\tilde{u}(x', 0) = u(x', 0)$), and gives a uniform H^1 bound.

Step 1 (Write the trace using Fourier in the normal variable). Since \tilde{u} is defined on \mathbb{R}^d and $\tilde{u}(x', 0) = u(x', 0)$, we have

$$\operatorname{tr}_{\partial U} u(x') = u(x', 0) = \tilde{u}(x', 0).$$

Using the inverse Fourier transform in the x_d variable (with the convention $\mathcal{F}_{x_d} f(\xi_d) = \int_{\mathbb{R}} e^{-ix_d \xi_d} f(x_d) dx_d$), we obtain

$$\tilde{u}(x', 0) = \int_{\mathbb{R}} \mathcal{F}_{x_d} \tilde{u}(x', \xi_d) \frac{d\xi_d}{2\pi}.$$

Taking the Fourier transform in x' , Fubini gives

$$\mathcal{F}_{x'}(\operatorname{tr}_{\partial U} u)(\xi') = \int_{\mathbb{R}} \tilde{u}(\xi', \xi_d) \frac{d\xi_d}{2\pi},$$

where $\tilde{u} = \mathcal{F}_x \tilde{u}$ denotes the full Fourier transform in \mathbb{R}^d .

On Wednesday Feb 4 we will pick up from here. □

A Functional Analysis

A.1 Banach Spaces

Theorem A.1.1 (Hahn-Banach Theorem).

Let \mathcal{X} be a real vector space, p a sublinear functional, i.e.

$$p(x + y) \leq p(x) + p(y), \quad p(\lambda x) = \lambda p(x) \text{ for any } x, y \in \mathcal{X} \text{ and } \lambda \geq 0$$

on \mathcal{X} , \mathcal{M} a subspace of \mathcal{X} , and f a linear functional on \mathcal{M} such that $f(x) \leq p(x)$ for all $x \in \mathcal{M}$. Then there exists a linear functional F on \mathcal{X} such that $F(x) \leq p(x)$ for all $x \in \mathcal{X}$ and $F|_{\mathcal{M}} = f$.