

# Chapter 1

## 1.1 Brownian Motion

### Definition 1.1

A real-valued stochastic process  $B = (B_t)_{t \geq 0}$  defined on a probability space  $(\Omega, \mathcal{F}; P)$  is called a Brownian motion if it satisfies the following conditions:

- Almost surely  $B_0 = 0$ .
- For all  $0 \leq t_1 < \dots < t_n$  the increments  $B_{t_n} - B_{t_{n-1}}, \dots, B_{t_2} - B_{t_1}$  are independent random variables.
- If  $0 \leq s < t$ , the increment  $B_t - B_s$  is a Gaussian random variable with mean zero and variance  $t - s$ .
- With probability one, the map  $t \rightarrow B_t$  is continuous.

A  $d$ -dimensional Brownian motion is defined as an  $\mathbb{R}^d$ -valued stochastic process  $B = (B_t)_{t \geq 0}$ ,  $B_t = (B_t^1, \dots, B_t^d)$ , where  $B^1, \dots, B^d$  are  $d$  independent Brownian motions.



### Proposition 1.1

Properties (a),(b),(c) are equivalent to that  $B$  is a Gaussian process, i.e. for any finite set of indices  $t_1, \dots, t_n$ ,  $(B_{t_1}, \dots, B_{t_n})$  is a multivariate Gaussian random variable, equivalently, any linear combination of  $B_{t_i}$  is normal distributed r.v., with mean zero and covariance function

$$\Gamma(s, t) = \min(s, t)$$



### Proof

Suppose (a),(b),(c) holds, then we know  $(B_{t_1}, \dots, B_{t_n})$  is normal for any finite indices and then

$$m(t) = E(B_t) = 0$$

$$\Gamma(s, t) = E(B_s B_t) = E(B_{\min(s, t)}^2) = \min(s, t)$$

Conversely, we know  $E(B_0^2) = 0$  and hence  $B_0 = 0$  a.s., then we know  $E(B_s^2) = s$  and for any  $0 < s < t$ ,

$$E(B_s(B_t - B_s)) = 0$$

and it is easy to check (c), and (b) is deduced by computing the covariance of the increments, notice that two r.v.s are independent iff  $\phi_{(X_1, X_2, \dots, X_n)} = \phi_{X_1} \phi_{X_2} \dots \phi_{X_n}$  which implies that normal r.v.s are independent iff they have zero covariances.

### Theorem 1.1

(Kolmogorov's continuity theorem) Suppose that  $X = (X_t)_{t \in [0, T]}$  satisfies

$$E(|X_t - X_s|^\beta) \leq K|t - s|^{1+\alpha}$$

for all  $s, t \in [0, T]$  and some constant  $\beta, \alpha, K > 0$ . Then there exists a version  $\tilde{X}$  of  $X$  such that if

$$\gamma < \alpha/\beta$$

then

$$|\tilde{X}_t - \tilde{X}_s| \leq G_\gamma |t - s|^\gamma$$

for all  $s, t \in [0, T]$  where  $G_\gamma$  is a random variable. The trajectories of  $\tilde{X}$  are Holder continuous of order  $\gamma$  for any  $\gamma < \alpha/\beta$ .



### Proposition 1.2

There exists a version of  $B$  with Holder-continuous trajectories of order  $\gamma$  for any  $\gamma < (k-1)/2k$  on any interval  $[0, T]$ .



**Proof**

Since we know  $B_t - B_s$  has the normal distribution  $\mathcal{N}(0, t - s)$  and then we know

$$E\left((B_t - B_s)^{2k}\right) = \frac{1}{\sqrt{2\pi(t-s)}} \int_{-\infty}^{\infty} x^{2k} \exp\left(-\frac{x^2}{2(t-s)}\right) dx = (2k-1)!!(t-s)^k = \frac{(2k)!}{2^k k!} (t-s)^k$$

and by the theorem 1.1, the proposition holds.

**Proposition 1.3**

*Brownian motion are basic properties:*

- For any  $a > 0$ , the process  $(a^{-1/2} B_{at})_{t \geq 0}$  is a Brownian motion.
- For any  $h > 0$ , the process  $(B_{t+h} - B_h)_{t \geq 0}$  is a Brownian motion.
- The process  $(-B_t)_{t \geq 0}$  is a Brownian motion.
- Almost surely  $\lim_{t \rightarrow \infty} B_t/t = 0$  and the process  $X_t = tB_{1/t}$  for  $t > 0$ ,  $X_t = 0$  for  $t = 0$  is a Brownian motion. ♠

**Proof**

- Consider  $0 \leq t_1 < t_2 < \dots < t_n$  and we may calculate the covariance matrix for

$$a^{-1/2} B_{at_n} - a^{-1/2} B_{at_{n-1}}, \dots, a^{-1/2} B_{at_2} - a^{-1/2} B_{at_1}$$

by

$$\begin{aligned} & E[(a^{-1/2} B_{at_j} - a^{-1/2} B_{at_{j-1}})(a^{-1/2} B_{at_k} - a^{-1/2} B_{at_{k-1}})] \\ &= a^{-1}(at_j \wedge at_k) - a^{-1}(at_j \wedge at_{k-1}) - a^{-1}(at_{j-1} \wedge at_k) + a^{-1}(at_{j-1} \wedge at_{k-1}) \\ &= \begin{cases} t_j - t_{j-1} - t_{j-1} + t_{j-1} = t_j - t_{j-1} & \text{if } j = k \\ t_j - t_j - t_{j-1} + t_{j-1} = 0 & \text{if } j < k \\ 0 & \text{if } j > k \end{cases} \end{aligned}$$

and hence  $(a^{-1/2} B_{at})_{t \geq 0}$  satisfies the property (b) in definition 1.1, a,d are obvious and c is easy to be checked.

- Obvious.
- Obvious.
- Notice  $B$  is Holder continuous. Now we only need to check that

$$E(tB_{1/t} sB_{1/s}) = ts(1/t \wedge 1/s) = (t \wedge s)$$

and the rest is easy to be checked.

**Theorem 1.2**

*(The law of the iterated logarithm)*

$$\limsup_{t \rightarrow s^+} \frac{|B_t - B_s|}{\sqrt{2|t-s| \ln \ln |t-s|}} = 1, \quad a.s.$$

**Proposition 1.4**

*Fix a time interval  $[0, t]$  and consider the following subdivision  $\pi$  of this interval:*

$$0 = t_0 < t_1 < \dots < t_n = t$$

*The norm of the subdivision  $\pi$  is defined as  $|\pi| = \max_{0 \leq j \leq n-1} (t_{j+1} - t_j)$ . Then*

$$\lim_{|\pi| \rightarrow 0} \sum_{j=0}^{n-1} (B_{t_{j+1}} - B_{t_j})^2 = t$$

*in  $L^2(\Omega)$ .* ♠

**Proof**


Consider let  $\xi_j = (B_{t_{j+1}} - B_{t_j})^2 - (t_{j+1} - t_j)$  and we know  $\xi_j$  are independent with mean 0 and hence

$$\begin{aligned} E\left(\sum_{j=0}^{n-1} (B_{t_{j+1}} - B_{t_j})^2 - t\right)^2 &= \sum_{j=0}^{n-1} E\xi_j^2 = \sum_{j=0}^{n-1} (3(t_{j+1} - t_j)^2 - 2(t_{j+1} - t_j)^2 + (t_{j+1} - t_j)^2) \\ &= 2 \sum_{j=0}^{n-1} (t_{j+1} - t_j)^2 \leq 2t|\pi| \rightarrow 0 \end{aligned}$$

### Proposition 1.5

The total variation of Brownian motion on an interval  $[0, t]$  defined by

$$V = \sup_{\pi} \sum_{i=1}^{n-1} |B_{t_{i+1}} - B_{t_i}|$$

where  $\pi$  is any partition of  $[0, t]$ , is infinite with probability 1. 

### Proof

Here we know

$$\sum_{j=0}^{n-1} (B_{t_{j+1}} - B_{t_j})^2 \leq V \sup_j |B_{t_{j+1}} - B_{t_j}|$$

and hence if  $V < \infty$ , then

$$\lim_{|\pi| \rightarrow 0} \sum_{j=0}^{n-1} (B_{t_{j+1}} - B_{t_j})^2 = 0$$

which means  $P(V < \infty) = 0$ .

### Definition 1.2

(Wiener integral) Let  $\mathcal{E}_0$  be the set of step functions in  $\mathbb{R}_+$ , i.e.

$$\phi(t) = \sum_{j=0}^{n-1} a_j \chi_{[t_j, t_{j+1})}(t)$$

where  $n \geq 1$  is an integer,  $a_i \in \mathbb{R}$  and  $0 = t_0 < \dots < t_n$ . And we may define Wiener integral of a step function by

$$\int_0^\infty \phi dB_t = \sum_{i=0}^{n-1} a_i (B_{t_{i+1}} - B_{t_i})$$



### Proposition 1.6

The Wiener integral is a linear isometry from  $\mathcal{E}_0 \subset L^2(\mathbb{R}^+)$  to  $L^2(\Omega)$ . 


**Proof** Notice

$$E\left[\left(\int_0^\infty \phi dB_t\right)^2\right] = \sum_{i=0}^{\infty} a_i^2 (t_{i+1} - t_i) = \|\phi\|_2^2$$

### Definition 1.3

We have already known Wiener integral is a linear isometry from a dense subspace from  $L^2(\mathbb{R}_+)$  to  $L^2(\Omega)$ , and hence we may call the extension of the linear isometry to be the Wiener integral and for any  $\phi \in L^2(\mathbb{R}_+)$ , denote

$$\int_0^\infty \phi dB_t$$

to be its image of the isometry. 

**Definition 1.4**

Let  $D$  be a Borel subset of  $\mathbb{R}^m$ , a white noise on  $D$  is a centered Gaussian family of random variables

$$\{W_A, A \subset \mathcal{B}(\mathbb{R}^m), A \subset D, m(A) < \infty\}$$

such that

$$E(W_A W_B) = m(A \cap B)$$

**Proposition 1.7**

$\chi_A \rightarrow W_A$  is a linear isometry from  $L^2(D) \rightarrow L^2(\Omega)$ .

**Definition 1.5**

Similarly, we may define the integral r.s.t.  $W$  of  $\phi \in L^2(D)$  denoted by

$$\phi \mapsto \int_D \phi W(dx)$$

by extending the linear isometry.

**Definition 1.6**

Consider a Brownian motion  $B$  defined on a probability space  $(\Omega, \mathcal{F}, P)$ . For any time  $t \geq 0$ , define  $\mathcal{F}_t$  the  $\sigma$ -algebra by  $B_s, 0 \leq s \leq t$  and the null events in  $\mathcal{F}$ , we call  $\mathcal{F}_t$  the natural filtration of Brownian motion on the probability space  $(\Omega, \mathcal{F}, P)$ .

**Lemma 1.1**

Suppose  $X$  and  $Y$

**Theorem 1.3**

For any measurable and bounded (or nonnegative) function  $f : \mathbb{R} \rightarrow \mathbb{R}, s \geq 0$  and  $t \geq 0$ , we have

$$E(f(B_{s+t}) | \mathcal{F}_s) = (P_t f)(B_s)$$

where

$$(P_t f)(x) = \int_{\mathbb{R}} f(y) p_t(x - y) dy$$

where

$$p_t = \frac{1}{\sqrt{2\pi t}} e^{-\frac{x^2}{2t}}$$



Check Durrett Theorem 7.2.1.

**Proposition 1.8**

The family of operators  $P_t$  satisfies the semigroup property  $P_t \circ P_s = P_{t+s}$  and  $P_0 = Id$ .

**Proof**

$$\begin{aligned} P_t \circ P_s(f)(x) &= \int_{\mathbb{R}} P_s f(y) p_t(x - y) dy \\ &= \int_{\mathbb{R}} \int_{\mathbb{R}} f(z) p_s(y - z) p_t(x - y) dz dy \\ &= \int_{\mathbb{R}} f(z) \int_{\mathbb{R}} \frac{1}{2\pi\sqrt{st}} e^{-\left(\frac{(y-z)^2}{2s} + \frac{(x-y)^2}{2t}\right)} dy dz \\ &= \int_{\mathbb{R}} f(z) \int_{\mathbb{R}} \frac{1}{2\pi\sqrt{st}} e^{-\left(\frac{(\sqrt{s+t}y - (2tz + 2sx)/\sqrt{s+t})^2 - (tz + sx)^2/(s+t) + tz^2 + sx^2}{2st}\right)} dy dz \end{aligned}$$

and the rest is easy to be checked.

**Theorem 1.4**

The processes  $B_t$ ,  $(B_t^2 - t)$  and  $e^{aB_t - a^2t/2}$ ,  $a \in \mathbb{R}$  are  $\mathcal{F}_t$  martingales.

**Definition 1.7**

The Brownian hitting time is defined by

$$\tau_a = \int \{t \geq 0, B_t = a\}$$

**Proposition 1.9**

Fix  $a > 0$ . Then, for all  $\alpha > 0$

$$E(e^{-\alpha\tau_a}) = e^{-\sqrt{2\alpha}a}$$

**Theorem 1.5**