## Chapter 3 Moving to Higher Dimensions

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Applied Multivariate Statistical Analysis

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March, 2, 2021

#### 3.1 Covariance

Covariance is a measure of dependency between random variables. Given two (random) variables X and Y the (theoretical) covariance is defined by

$$\sigma_{XY} = \mathbf{Cov}(X, Y) = \mathbf{E}(XY) - (\mathbf{E}X)(\mathbf{E}Y) \tag{3.1}$$

the covariance matrix is:

$$\Sigma = \begin{pmatrix} \sigma_{X_1 X_1} & \dots & \sigma_{X_1 X_p} \\ \vdots & \ddots & \vdots \\ \sigma_{X_p X_1} & \dots & \sigma_{X_p X_p} \end{pmatrix}.$$

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The correlation between two variables X and Y is defined from the covariance as the following:

$$\rho_{XY} = \frac{\mathbf{Cov}(X, Y)}{\sqrt{\mathbf{Var}(X)\mathbf{Var}(Y)}}$$
(3.7)

The empirical version of  $\rho_{XY}$  is as follows:

$$r_{XY} = \frac{s_{XY}}{\sqrt{s_{XX}s_{YY}}} \tag{3.8}$$

**Theorem 3.1** if X and Y are independent, then  $\rho(X, Y) = \text{Cov}(X, Y) = 0$ .

Example 3.4 Consider a standard normally distributed random variable X and a random variable  $Y=X^2$ , which is surely not independent of X. Here we have

$$Cov(X, Y) = E(XY) - E(X)E(Y) = E(X^3) = 0$$

(because  $\mathbf{E}(X)=0$  and  $\mathbf{E}(X^2)=1$ ). Therefore  $\rho(X,Y)=0$  ,as well. This example also shows that correlations and covariances measure only linear dependence. The quadratic dependence of  $Y=X^2$  on X is not reflected by these measures of dependence.

Fisher's Z-transformation,

$$W = \frac{1}{2}\log(\frac{1+r_{XY}}{1-r_{XY}}),\tag{3.11}$$

we obtain a variable that has a more accessible distribution. Under the hypothesis that  $\rho$ =0, W has an asymptotic normal distribution.

$$\mathbf{E}(W) pprox rac{1}{2} \log(rac{1 + 
ho_{XY}}{1 - 
ho_{XY}})$$

$$\mathbf{Var}(W) \approx \frac{1}{(n-3)} \tag{3.12}$$

#### Theorem 3.2

$$Z = \frac{W - \mathsf{E}(W)}{\sqrt{\mathsf{Cov}(W)}} \stackrel{\mathcal{L}}{\to} N(0,1) \tag{3.13}$$

Remark 3.2 The normalizing and variance stabilizing properties of W are asymptotic. In addition, the use of W in small samples (for n  $\leq$  25) is improved by Hotelling's transform Hotelling (1953):

$$W^* = W - \frac{3W + \tanh(W)}{4(n-1)}$$
 with  $Var(W^*) = \frac{1}{n-1}$ .

Remark 3.4 Under the assumptions of normality of X and Y, we may text their independence ( $\rho_{XY}=0$ ) using the exact t-distribution of the statistic

$$T = r_{XY} \sqrt{\frac{n-2}{1-r_{XY}^2}} \stackrel{\rho_{XY}=0}{\sim} t_{n-2}$$

Setting the probability of the first error type to  $\alpha$ , we reject the null hypothesis  $\rho_{XY}=0$  if  $|T|\geq t_{1-\alpha/2;n-2}$ .

$$\bar{x} = \begin{pmatrix} \bar{x_1} \\ \vdots \\ \bar{x_p} \end{pmatrix} = n^{-1} \mathcal{X}^T I_n \tag{3.17}$$

The empirical covariances are:

$$S = n^{-1} \mathcal{X}^T \mathcal{X} - \bar{\mathbf{x}} \bar{\mathbf{x}}^T = n^{-1} (\mathcal{X}^T \mathcal{X} - n^{-1} \mathcal{X}^T \mathbf{1}_n \mathbf{1}_n^T \mathcal{X})$$
(3.18)

Note that this matrix is equivalently defined by

$$S = \frac{1}{n} \sum_{i=1}^{N} (x_i - \bar{x})(x_i - \bar{x})^T$$

The covariance formula (3.18) can be rewritten as  $\mathcal{S} = n^{-1} \ \mathcal{X}^T \mathcal{H} \mathcal{X}$  with the *centering matrix* 

$$\mathcal{H} = \mathcal{I}_n - n^{-1} \mathbf{1}_n \mathbf{1}_n^T. \tag{3.19}$$

Note that the centering matrix is symmetric and idempotent.

As a consequence  $\mathcal S$  is positive semidefinite, i.e.,

$$S \ge 0 \tag{3.20}$$

The sample correlation coefficient between the *i*-th and *j*-th variables is  $r_{X_iX_j}$ , see (3.8). If  $\mathcal{D} = \text{diag}(s_{X_iX_i})$ , then the correlation matrix is

$$\mathcal{R} = \mathcal{D}^{-1/2} \mathcal{S} \mathcal{D}^{-1/2}, \tag{3.21}$$

where  $\mathcal{D}^{-1/2}$  is a diagonal matrix with elements  $(s_{X_iX_i})^{-1/2}$  on its main diagonal.

#### **Linear Transformation**

Let  $\mathcal A$  be a  $q \times p$  matrix and consider the transformed data matrix

$$\mathcal{Y} = \mathcal{X}\mathcal{A}^{T} = (y_1, \dots, y_n)^{T}. \tag{3.22}$$

The row  $y_i = (y_{i1}, \dots, y_{iq}) \in \mathbb{R}^q$  can be viewed as the *i*-th observation of a q-dimensional random variable  $Y = \mathcal{A}X$ . In fact we have  $y_i = x_i \mathcal{A}^T$ .

$$\bar{y} = \frac{1}{n} \mathcal{Y}^{\mathsf{T}} I_n = \frac{1}{n} \mathcal{A} \mathcal{X}^{\mathsf{T}} I_n = \mathcal{A} \bar{x}$$
 (3.23)

$$S_{\mathcal{Y}} = \frac{1}{n} \mathcal{Y}^{\mathsf{T}} \mathcal{H} \mathcal{Y} = \frac{1}{n} \mathcal{A} \mathcal{X}^{\mathsf{T}} \mathcal{H} \mathcal{X} \mathcal{A}^{\mathsf{T}} = \mathcal{A} S_{\mathcal{X}} \mathcal{A}^{\mathsf{T}}$$
(3.24)

Note that if the linear transformation is nonhomogeneous, i.e.,

$$y_i = Ax_i + b$$

only (3.23) changes: 
$$\bar{y} = A\bar{x} + b$$
.

$$q = 1$$
, i.e.,  $y = Xa$ , i.e.,  $y_i = a^T x_i$ ;  $i = 1, ..., n$ :

$$\bar{y} = a^T \bar{x}$$

$$S_y = a^T S_X a$$
.

Example 3.9 Suppose that  $\mathcal{X}$  is the pullover data set. The manager wants to compute his mean expenses for advertisement  $(X_3)$  and sales assistant $(X_4)$ .

$$Y = X_3 + 10X_4$$

and  $\mathcal{A}(4 \times 1)$  as

$$\mathcal{A} = \begin{pmatrix} 0, & 0, & 1, & 10, \end{pmatrix}$$
.

$$\overline{y} = A\overline{x} = (0, 0, 1, 10) \begin{pmatrix} 172.7 \\ 104.6 \\ 104.0 \\ 93.8 \end{pmatrix} = 1042.0$$

$$S_{\mathcal{Y}} = \mathcal{A}S_{\mathcal{X}}\mathcal{A}^{\top} = (0, 0, 1, 10) \begin{pmatrix} 1152.5 & -88.9 & 1589.7 & 301.6 \\ -88.9 & 244.3 & 102.3 & -101.8 \\ 1589.7 & 102.3 & 2915.6 & 233.7 \\ 301.6 & -101.8 & 233.7 & 197.1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 10 \end{pmatrix}$$

= 2915.6 + 4674 + 19710 = 27299.6



#### Mahalanobis Transformation

$$z_i = S^{-\frac{1}{2}}(x_i - \bar{x}), i = 1, ..., n.$$
 (3.25)

Note that for the transformed data matrix  $\mathcal{Z} = (z_1, \dots, z_n)^T$  ,

$$S_{\mathcal{Z}} = n^{-1} \mathcal{Z}^{\mathsf{T}} \mathcal{H} \mathcal{Z} = \mathcal{I}_{\mathsf{p}}. \tag{3.26}$$

So the Mahalanobis transformation eliminates the correlation between the variables and standardizes the variance of each variable.

## 3.4 Linear Model for Two Variables

A slope line is a linear relationship between X and Y:

$$y_i = \alpha + \beta x_i + \varepsilon_i, i = 1, \dots, n.$$
 (3.27)

Here,  $\alpha$  is the intercept and  $\beta$  is the slope of the line. The errors(or deviations from the line ) are denoted as  $\varepsilon_i$  and are assumed to have zero mean and finite variance  $\sigma^2$ .  $(\hat{\alpha},\hat{\beta})$  via graphical techniques. A very common numerical and statistical technique is to use those  $\hat{\alpha}$  and  $\hat{\beta}$  that minimize:

$$(\hat{\alpha}, \hat{\beta}) = \arg\min_{(\alpha, \beta)} \sum_{i=1}^{n} (y_i - \alpha - \beta x_i)^2$$
 (3.28)

$$\hat{\beta} = \frac{\mathsf{s}_{XY}}{\mathsf{s}_{XX}} \tag{3.29}$$

$$\hat{\alpha} = \bar{y} - \hat{\beta}\bar{x} \tag{3.30}$$

### 3.4 Linear Model for Two Variables

The variance of  $\hat{\beta}$  is

$$\mathbf{Var}(\hat{\beta}) = \frac{\sigma^2}{n \cdot s_{XX}} \tag{3.31}$$

and

$$t = \frac{\hat{\beta}}{SE(\hat{\beta})} \tag{3.33}$$

and rejects the hypothesis at a 5% significance level if  $|t| \ge t_{0.975;n-2}$  where the 97.5% quantile of the Student's  $t_{n-2}$  distribution is clearly the 95% critical value for the two-sided test.

# 3.5 Simple Analysis of Variance

The goal of a simple ANOVA is to analyze the observation structure

$$y_{kl} = \mu_l + \varepsilon_{kl} \text{ for } k = 1, \dots, m, \text{ and } l = 1, \dots, p.$$
 (3.41)

$$\sum_{l=1}^{p} \sum_{k=1}^{m} (y_{kl} - \bar{y})^2 = m \sum_{l=1}^{p} (\bar{y}_l - \bar{y})^2 + \sum_{l=1}^{p} \sum_{k=1}^{m} (y_{kl} - \bar{y}_l)^2$$
 (3.42)

# 3.5 Simple Analysis of Variance

$$SS(reduced) = \sum_{l=1}^{p} \sum_{k=1}^{m} (y_{kl} - \bar{y})^2$$
 (3.43)

$$SS(full) = \sum_{l=1}^{p} \sum_{k=1}^{m} (y_{kl} - \bar{y}_l)^2$$
 (3.44)

$$F = \frac{\frac{SS(\text{reduced}) - SS(\text{full})}{df(r) - df(f)}}{\frac{SS(\text{full})}{df(f)}}$$
(3.45)

# 3.6 Multiple Linear Model

$$y = \mathcal{X}\beta + \varepsilon \tag{3.50}$$

where  $\varepsilon$  are the errors. The least squares solution is given by  $\hat{\beta}$ :

$$\hat{\beta} = \arg\min_{\beta} (y - \mathcal{X}\beta)^{T} (y - \mathcal{X}\beta) = \arg\min_{\beta} \varepsilon^{T} \varepsilon$$
 (3.51)

Suppose that  $(\mathcal{X}^T\mathcal{X})$  is of full rank and thus invertible. Minimizing the expression (3.51) with respect to  $\beta$  yields

$$\hat{\beta} = (\mathcal{X}^T \mathcal{X})^{-1} \mathcal{X}^T y \tag{3.52}$$

The fitted value  $\hat{y} = \mathcal{X}\hat{\beta} = \mathcal{X}(\mathcal{X}^T\mathcal{X})^{-1}\mathcal{X}^Ty = \mathcal{P}y$  is the projection of y onto  $C(\mathcal{X})$  as computed in (2.47).

## 3.6 Multiple Linear Model

The least squares residuals are

$$e = y - \hat{y} = y - \mathcal{X}\hat{\beta} = \mathcal{Q}y = (\mathcal{I}_n - \mathcal{P})y.$$

The vector e is the projection of y onto the orthogonal complement of  $C(\mathcal{X})$ .

**Properties of**  $\hat{\beta}$ 

$$\begin{aligned} \mathbf{E}(\hat{\beta}) &= \beta \\ \mathbf{Var}(\hat{\beta}) &= \sigma^2 (\mathcal{X}^T \mathcal{X})^{-1} \\ \hat{\sigma^2} &= \frac{1}{n - (p+1)} (y - \hat{y})^T (y - \hat{y}) \end{aligned}$$