

1. (i) A matrix is diagonalizable if it has a complete set of linearly independent eigenvectors.

First, compute $|A - \lambda I| = 0$. We get $\lambda_1 = 1$, $\lambda_2 = -3$, $\lambda_3 = -3$.

For $\lambda_1 = 1$, calculate the corresponding eigenvector using $(A - \lambda_1 I)x_1 = 0$.

We get $x_1 = (-1, -2, 2)^T$.

For $\lambda_2 = \lambda_3 = -3$, calculate the corresponding eigenvector using $(A - \lambda_2 I)x_2 = 0$.

We get $x_2 = (1, 0, 1)^T$.

Thus, A is not diagonalizable.

Using a similar method, we get

$$\lambda_1 = 1, \quad x_1 = (-1, -2, 2)^T$$

$$\lambda_2 = \lambda_3 = -3, \quad x_2 = (1, 1, 0)^T, \quad x_3 = (1, 0, 1)^T$$

Thus, B is diagonalizable.

(2) Using a similarity transformation, $P = (x_1, x_2, x_3) = \begin{pmatrix} -1 & 1 & 1 \\ -2 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix}$.

$$P^{-1} = \begin{pmatrix} -1 & 1 & 1 \\ -2 & 3 & 2 \\ 2 & -2 & -1 \end{pmatrix}.$$

$$\text{Thus, } D = P^{-1}AP = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & -3 \end{pmatrix}.$$

2. (1) Consider the block matrix $\begin{pmatrix} \lambda I_n & A \\ \lambda A & \lambda I_m \end{pmatrix}$.

Thus, the determinant of this block matrix is

$$\det(\lambda I_n) \det(\lambda I_m - \lambda A (\lambda I_n)^{-1} A) = \lambda^n \det(\lambda I_m - AB).$$

It also can be expressed as

$$\det(\lambda I_m) \det(\lambda I_n - B (\lambda I_m)^{-1} A \lambda) = \lambda^m \det(\lambda I_n - BA).$$

$$\text{Thus, } \lambda^m \det(\lambda I_n - BA) = \lambda^n \det(\lambda I_m - AB).$$

(2) We set $\lambda = 1$ in (1) and get $\det(I_n - BA) = \det(I_m - AB)$.

We see $m = n$, and thus AB and BA have the same characteristic polynomial.

(3) Without loss of generality, we assume $m > n$.

$$\text{Thus } \lambda^{m-n} \det(\lambda I_n - BA) = \det(\lambda I_m - AB).$$

Next, we prove AB and BA have the common non-zero eigenvalues.

Given the eigenvalue λ and eigenvector x of AB , $ABx = \lambda x$.

We multiply both sides of this equation by B on the left and get

$$BABx = \lambda Bx.$$

When $\lambda \neq 0$, we see λ is also the eigenvalue of BA .

Thus, AB and BA have the same non-zero eigenvalues.

Then, it is obvious that the extra eigenvalues are all 0. The proof is complete.

(iv) For some eigenvalue λ of A , consider X such that its column form a basis for the nullspace of $(A - \lambda I)$, which is the ~~eigenspace~~ eigenspace of A corresponding to λ . That is, X satisfies $(A - \lambda I)X = 0$.

Since $AB = BA$, we have $(A - \lambda I)B = B(A - \lambda I) \Rightarrow (A - \lambda I)BX = B(A - \lambda I)X = B \cdot 0 = 0$.

Thus, BX is also in the nullspace of $(A - \lambda I)$. Consequently, there exists a matrix P such that:

$$BX = XP.$$

Matrix P here transforms the basis of the eigenspace of A under the action of B . Since $BX = XP$, P represents B relative to the basis provided by X . As P is square matrix of size equal to the dimension of the eigenspace of A corresponding to λ , it has at least one eigenpair (μ, v) , where v is an eigenvector of P and μ is an eigenvalue. Thus, $B(Xv) = XPv = X\mu v = \mu Xv$.

Thus, Xv is an eigenvector of B corresponding to eigenvalue μ , and also an eigenvector of A corresponding to eigenvalue λ . The proof is complete.

Problem 3
3.1. (a) If λ is an eigenvalue of A , then there exists a non-zero vector x such that $Ax = \lambda x$.

Since A is column-stochastic, we have $A^T \cdot 1 = 1 \Rightarrow 1^T A = 1^T$.

This equation shows that the row vector 1^T is the left eigenvector of A with the corresponding eigenvalue $\lambda = 1$. Thus, $\lambda = 1$ is also a right eigenvalue of A . The proof is complete.

(b) According to the Gershgorin circle theorem, every eigenvalue of a matrix lies within at least one of the Gershgorin circle in the complex plane, where each circle is centered at a diagonal entry of the matrix and has a radius equal to the sum of absolute values of the non-diagonal entries in that row. For a column-stochastic matrix A , the sum of the entries in each column is 1. Since the matrix is positive, each element a_{ij} of A satisfies $0 \leq a_{ij} \leq 1$.

For each i -th diagonal element a_{ii} of A , the Gershgorin circle centered at a_{ii} has a radius: $\sum_{j \neq i} a_{ij}$. Given the sum of elements in each column is 1, we have $a_{ii} + \sum_{j \neq i} a_{ij} = 1$.

Therefore, the radius of the Gershgorin circle is $1 - a_{ii}$.

Thus, each Gershgorin circle is contained within the disk centered at a_{ii} with radius $1 - a_{ii}$, which lies within the unit disk centered at the origin with radius 1.

Therefore, all eigenvalues λ satisfy: $|\lambda| \leq 1$.

Problem 3

2. (a) Assume by contradiction that λ is an eigenvalue of A and corresponds to an eigenvector x .

That means

$$Ax = (D + \alpha vv^T)x = \lambda x \Rightarrow (D - \lambda I)x = -\alpha vv^T x.$$

Since D is diagonal, $D - \lambda I$ is also diagonal with entries $(\lambda_i - \lambda)$. If $\lambda = \lambda_i$ for some i , then

the matrix $D - \lambda I$ has a zero on the diagonal at the i -th position, making it singular and therefore non-invertible.

If we assume $\lambda = \lambda_i$, the left side of the equation becomes zero for the i -th component. For the right

$$\text{side: } vv^T x = (v^T x)v.$$

$v^T x$ is a scalar, and thus the entire right side is a non-zero scalar multiple of v .

This implies that x must be parallel to v . Substituting $x = kv$ into the equation, we obtain

$$(\lambda_i - \lambda)kv = -\alpha k vv^T v,$$

which is contradictory since $(\lambda_i - \lambda) > 0$ implies the left side is zero but the right side is ~~non-zero~~.

Therefore, no λ_i can be an eigenvalue of A .

(b) We look for ξ such that $\det(D + \alpha vv^T - \xi I) = 0$. Using the matrix determinant lemma for a rank-one

update to a matrix, we find

$$\det(D + \alpha vv^T - \xi I) = \det(D - \xi I) \det(1 + \alpha v^T (D - \xi I)^{-1} v).$$

Given $D - \xi I$ is diagonal, its inverse is also diagonal with entries $\frac{1}{\lambda_i - \xi}$. Thus,

$$V^T (D - \xi I)^{-1} V = \sum_{i=1}^n \frac{v_i^2}{\lambda_i - \xi}$$

and $f(\xi)$ becomes $f(\xi) = 1 + \alpha \sum_{i=1}^n \frac{v_i^2}{\lambda_i - \xi}$.

So the eigenvalues of A are solutions to $f(\xi) = 0$.

Problem 4

(i) First, observe the applying A multiple times yields:

$$A^2 x = A(Ax) = A(\lambda x) = \lambda Ax = \lambda^2 x.$$

This can be generalized for any positive integer n :

$$A^n x = \lambda^n x.$$

Given that $p(A) = \alpha_0 I + \alpha_1 A + \dots + \alpha_k A^k$, we apply $p(A)$ to x :

$$p(A)x = (\alpha_0 I + \alpha_1 A + \dots + \alpha_k A^k)x.$$

Using the linearity of matrix operations, this becomes:

$$p(A)x = \alpha_0 x + \alpha_1 Ax + \dots + \alpha_k A^k x.$$

Substituting $A^n x = \lambda^n x$: $p(A)x = \alpha_0 x + \alpha_1 \lambda x + \dots + \alpha_k \lambda^k x.$

Factoring out x from each term:

$$p(A)x = (\alpha_0 + \alpha_1 \lambda + \alpha_2 \lambda^2 + \dots + \alpha_k \lambda^k)x = p(\lambda)x$$

Since $p(A)x = p(\lambda)x$, $(p(A), x)$ is indeed an eigenpair of $p(A)$.

(2) (a) Given that (λ_k, x) is an eigenpair, we have $Ax = \lambda_k x$.

Rewrite $A - \epsilon I$ and apply to x :

$$(A - \epsilon I)x = Ax - \epsilon x = \lambda_k x - \epsilon x = (\lambda_k - \epsilon)x.$$

Since $\epsilon \neq \lambda(A)$, $\lambda_k - \epsilon \neq 0$.

Applying the inverse operator, we find $(A - \epsilon I)^{-1}((\lambda_k - \epsilon)x) = x$.

$$\text{Hence, } (A - \epsilon I)^{-1}x = \frac{x}{\lambda_k - \epsilon}.$$

$$(b) \quad (A + x d^T)x = Ax + x(d^T x) = \lambda_k x + (d^T x)x = (\lambda_k + d^T x)x$$

This shows that x is an eigenvector of $A + x d^T$ with eigenvalue $\lambda_k + d^T x$.

5. (i) We start by finding the characteristic polynomial $\det(M - \lambda I) = 0$.

$$\det(M - \lambda I) = \det \begin{pmatrix} \frac{1}{6} \begin{bmatrix} 2a+3b+1-b\lambda & 2(1-a) & 2a-3b+1 \\ 2(1-a) & 2(a+2)-b\lambda & 2(1-a) \\ 2a-3b+1 & 2(1-a) & 2a+3b+1 \end{bmatrix} \end{pmatrix}$$

$$= -36ab\lambda + 24b^2a + 6a\lambda^2 - 36ba\lambda + 6b\lambda^2 - 36b^2\lambda - \lambda^3 + 6\lambda^2 = 0$$

The eigenvalues of the matrix M are b , ba and $6b$.

(ii) Determine the corresponding eigenvectors by solving the system $(M - \lambda I)v = 0$, where v is an eigenvector associated with eigenvalue λ .

For $\lambda = b$, the eigenvector is $[1, 2, 1]^T$.

For $\lambda = ba$, the eigenvector is $[1, -1, 1]^T$.

For $\lambda = 6b$, the eigenvector is $[-1, 0, 1]^T$.

We can express M in its eigendecomposition form using these eigenvectors and eigenvalues:

$$M = PDP^{-1},$$

where P is the matrix form by the eigenvectors, and D is the diagonal matrix of eigenvalues:

$$P = \begin{bmatrix} 1 & 1 & -1 \\ 2 & -1 & 0 \\ 1 & 1 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} b & 0 & 0 \\ 0 & ba & 0 \\ 0 & 0 & 6b \end{bmatrix}.$$

13) As $n \rightarrow \infty$, the limits of the eigenvalues are

① For $\lambda = b$, the limit remains b .

② For $\lambda = ba$, $a = (\frac{1+n}{n})^2$, the limit ^{approaches} ~~is~~ b .

③ For $\lambda = b$, $b = \frac{1}{n}$, the limit approaches 0 .

Using the eigendecomposition, $\lim_{n \rightarrow \infty} M^n = P D^n P^{-1}$

$$= \begin{bmatrix} 1 & 1 & -1 & -1 \\ 2 & -1 & 0 & 0 \\ 1 & 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} b^n & 0 & 0 \\ 0 & b^n & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & -1 \\ 2 & -1 & 0 \\ 1 & 1 & 1 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} \frac{b^n}{2} & 0 & \frac{b^n}{2} \\ 0 & \frac{b^n}{3} & 0 \\ \frac{b^n}{2} & 0 & \frac{b^n}{2} \end{bmatrix}$$

b. iv) Define the degree of a vertex v_i , denoted as $d(v_i)$, as the number of edges incident to v_i .

The average degree of vertices in G is given by $d_{avg} = \frac{1}{|V|} \sum_{i=1}^{|V|} d(v_i) = \frac{1}{|V|} \sum_{i=1}^{|V|} \sum_{j=1}^{|V|} a_{i,j}$

By the Perron-Frobenius theorem, for non-negative matrices, λ_1 is at least as large as the average row sum of A , which in the case of an adjacency matrix of an undirected graph, equals the average degree of the vertices. The largest eigenvalue λ_1 satisfies: $\lambda_1 \geq \frac{\sum_{i=1}^{|V|} \sum_{j=1}^{|V|} a_{i,j}}{|V|} = d_{avg}$.

(12) Using Rayleigh Quotient : For a symmetric matrix M and a vector x ,

$$R(M, x) = \frac{x^T M x}{x^T x}$$

By definition of eigenvalues via Rayleigh quotient :

$$\alpha_1 = \max_{x \neq 0} R(A, x)$$

$$\beta_1 = \max_{y \neq 0} R(B, y)$$

Extend y to a vector x in \mathbb{R}^n by appending zero, making $x = [y; 0]$.

$$\text{The } R(A, x) = R(B, y)$$

Hence, β_1 as maximum of $R(B, y)$ is at most $R(A, x)$ for some extension x , indicating $\beta_1 \leq \alpha_1$.