AI and Machine Learning, Homework5

Author: Ying Yiwen Number: 12210159

Contents

1	Develop a Multilayer Perceptron Model	2
2	Implement Mini-batch and Stochastic Gradient Descent Updates	4
3	Cross-Validation Implementation	5
4	Generate the Dataset	6
5	The Result of Nonlinear Dataset by MBGD Method	7
6	The Result of Nonlinear Dataset by SGD Method	8
7	The Result of Classifier Dataset by MBGD Method	9
8	The Result of Classifier Dataset by SGD Method	11
9	Appendix	13

1 Develop a Multilayer Perceptron Model

In multilayer perceptron, we use the formula (1) to do forward propagation.

$$h_j(x) = f(v_{j0} + \sum_{i=1}^{D} x_i v_{ji})$$
(1)

```
def forward(self, inputs):

# Forward pass through the network

self.activations = [inputs] # Store activations of each layer

for i in range(self.num_layers - 1):

# Compute the weighted sum and apply activation function

z = np.dot(self.activations[i], self.weights[i]) + self.biases[i]

activation = self.activation(z)

self.activations.append(activation)

return self.activations[-1]
```

In multilayer perceptron, we use the formula (2) to do backward propagation.

$$W \leftarrow W - \eta \sum_{n=1}^{N} \frac{\partial E(o^{(n)}, t^{(n)})}{\partial W}$$
 (2)

```
def backward(self, inputs, targets, learning_rate):
2
     # Backpropagation process
     output errors = targets - self.activations[-1]
3
     output delta = output errors * self.activation derivative(self.activations[-1])
4
5
6
     # Update weights and biases for the output layer
7
     self.weights[-1] += self.activations[-1].T.dot(output\_delta) * learning\_rate
     self.biases[-1] += np.sum(output_delta, axis=0, keepdims=True) * learning_rate
8
9
     # Calculate errors and update weights for hidden layers
10
     hidden_errors = output_delta.dot(self.weights[-1].T) # initialize hidden_errors
11
         with output_delta for the last layer
     for i in range (self.num_layers -3, -1, -1):
12
       # Calculate hidden delta for the current layer
13
       hidden delta = hidden errors * self.activation derivative(self.activations[i +
14
            1])
15
       # Update weights and biases for the current hidden layer
16
       self.weights[i] += self.activations[i].T.dot(hidden delta) * learning rate
17
       self.biases[i] += np.sum(hidden_delta, axis=0, keepdims=True) * learning_rate
18
19
       # Update hidden_errors for the next layer's calculation
20
       hidden_errors = hidden_delta.dot(self.weights[i].T)
21
```

For the activation function, we use formula (3) to be activation function, and its derivative is formula (4).

$$\sigma(z) = \frac{1}{1 + exp(-z)} \tag{3}$$

$$\sigma'(z) = \sigma(z) \cdot (1 - \sigma(z)) \tag{4}$$

The sigma activation function has a limit of output from 0 to 1, so we need min-max normalization to put the target into the range, like,

$$x' = \frac{x - min}{x - max} \tag{5}$$

With forward propagation and backward propagation, we can estiamate the weights of the layers. Then we can create a model like this:

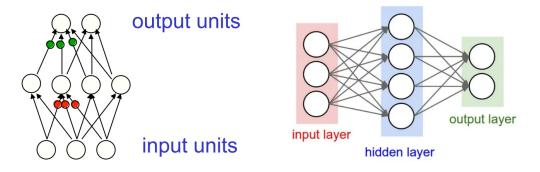


Fig. 1: Schematic of MLP

To achieve implementation of an MLP capable of handling any number of layers and units per layer, the model is able to initialize the layers by input layer number and neuron number.

```
_init___(self , layer_sizes , dataset_type):
    def
     # layer_sizes is a list containing the number of nodes in each layer
2
      self.layer sizes = layer sizes
3
      self.num_layers = len(layer_sizes)
4
5
     # Initialize weights and biases
6
      self.weights = []
7
      self.biases = []
8
9
10
     # Initialize weights and biases for each layer
      for i in range(self.num_layers - 1):
11
      weight = np.random.randn(layer_sizes[i], layer_sizes[i + 1])
12
      bias = np.zeros((1, layer\_sizes[i + 1]))
13
14
      self.weights.append(weight)
      self.biases.append(bias)
15
```

We also achieve an auto increasing strategy to get the best choice of layers.

```
for layers in range(initial_layers, max_layers + 1):
layer_sizes = [inputs.shape[1]] + self.get_neurons_for_layers(layers) + [1]
```

The function get_neurons_for_layers use the sequence of predefined numbers. The numbers are set by test. The output is like: [2, 6, 14, 26, 38, 19, 13, 7, 3, 1].

There should be an early stopping judgement to reduce the running time. If the performance doesn't go well above the tolerance in the patience turns, we can stop the training.

```
# Early stopping mechanism
if average_accuracy >= best_score:
```

```
if average_accuracy - best_score > tolerance:
3
       no_improve_count = 0 # Reset counter
4
5
     best score = average accuracy
     best model = model
6
7
     no improve count += 1 # Increment counter if no significant improvement
8
9
   # Stop if no significant improvement for consecutive 'patience' times
10
11
   if no_improve_count >= patience:
      print("Early stopping triggered")
12
13
      break
```

2 Implement Mini-batch and Stochastic Gradient Descent Updates

There are several update methods, like mini-batch gradient descent, batch gradient descent and stochastic gradient descent. The principle is almost the same as those in the past assignments.

```
def mbgd_train(self, inputs, targets, learning_rate, epochs, batch_size=32):
     # Train the model over specified epochs with mini-batch gradient descent
2
3
     for epoch in range (epochs):
       \# Shuffle training data for each epoch to improve generalization
4
       indices = np.arange(inputs.shape[0])
5
       np.random.shuffle(indices)
6
       inputs train = inputs[indices]
7
       targets train = targets [indices]
8
9
       # Process each mini-batch
10
       for start in range(0, len(inputs_train), batch_size):
11
         end = min(start + batch_size, len(inputs_train))
12
         batch_inputs = inputs_train[start:end]
13
14
         batch targets = targets train[start:end]
15
         # Forward pass and get predictions
16
         predictions = self.forward(batch inputs)
17
         # Backward pass for the mini-batch
18
19
          self.backward(batch inputs, batch targets, learning rate)
20
         # Calculate loss for the current mini-batch
21
         batch_loss = self.mean_squared_error(predictions, batch_targets)
22
```

```
1
   def sgd_train(self, inputs, targets, learning_rate, epochs):
     # Train the model over specified epochs using stochastic gradient descent
2
     for epoch in range (epochs):
3
       \# Shuffle training data for each epoch to improve generalization
4
       indices = np.arange(len(inputs))
5
       np.random.shuffle(indices)
6
7
       inputs_train = inputs[indices]
       targets train = targets [indices]
8
g
10
       # Iterate over each sample in the training set
       for i in range(len(inputs_train)):
11
12
         # Forward pass for a single sample
         predictions = self.forward(inputs_train[i:i+1])
13
```

```
# Backward pass for the same sample
self.backward(inputs_train[i:i+1], targets_train[i:i+1], learning_rate)

# Calculate loss for the current sample
batch_loss = self.mean_squared_error(predictions, targets_train[i:i+1])
```

3 Cross-Validation Implementation

In each test of layer size, we use k-fold cross-validation to test the performance of the model. According to the common sense, we choose k to be 5.

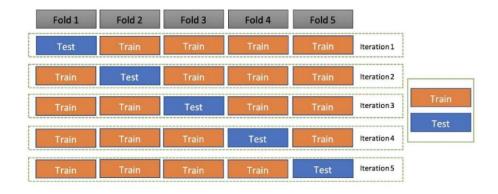


Fig. 2: Schematic of k-fold cross-validation

```
def k fold split (self, length, k):
     indices = np.arange(length)
2
    np.random.shuffle(indices) # shuffle the indices
3
     folds = np.array split (indices, k) \# split the data into k folds
4
    # yield the train and validation indices
5
     for i in range(k):
6
       train_indices = np.concatenate(folds[:i] + folds[i+1:]) # train set
7
       val indices = folds[i] # validation set
8
       yield train_indices, val_indices
```

```
for train indices, val indices in self.k fold split(len(inputs), k):
     model = MultiLayerPerceptron(layer_sizes, dataset_type='classify')
2
3
     # Train on training set
4
     model.train(inputs[train_indices], targets[train_indices], learning_rate=
5
         learning rate, epochs=epochs, method=method)
6
     # Validate on validation set
7
     accuracy, precision, recall, f1 = model.evaluate(inputs[val indices], targets[
8
         val indices])
     accuracy_scores.append(accuracy)
9
     precision scores.append(precision)
10
     recall scores.append(recall)
11
     f1_scores.append(f1)
12
13
```

```
print(f"Layers: {layer_sizes}, Fold Accuracy: {accuracy:.3f}, Fold Precision: {
14
         precision: .3 f}, Fold Recall: {recall: .3 f}, Fold F1 score: {f1:.3 f}")
     model.visualize_predictions_classifier(inputs[val_indices], targets[val_indices]
15
16
   average accuracy = np.mean(accuracy scores)
17
   average precision = np.mean(precision scores)
18
   average_recall = np.mean(recall_scores)
19
   average_f1 = np.mean(f1\_scores)
20
   print(f"In this layer test: {layer_sizes}, Average Accuracy: {average_accuracy},
21
       Average Precision: {average_precision}, Average Recall: {average_recall},
       Average F1 score: {average f1}")
   print ("-
22
```

4 Generate the Dataset

To test the model, we use to dataset to train it.

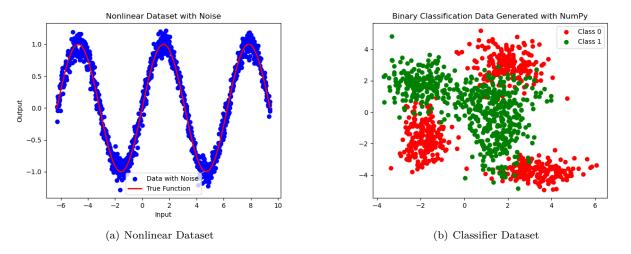


Fig. 3: Generate the Dataset

The nonlinear dataset has 1 input and 1 output to do regression. We use stuff like this:

```
# generate input features
X = np.linspace(-2 * np.pi, 3 * np.pi, n_samples).reshape(-1, 1)
noise_level = 0.1 # Adjust this value to control the noise level
# generate output labels
y = np.sin(X) + np.random.normal(0, noise_level, X.shape)
```

The classifier dataset has 2 input and 1 output to do classification. We use stuff like this:

```
X. append (x1)
y.append(1)
```

The Result of Nonlinear Dataset by MBGD Method 5

MBGD method takes advantage of SGD and BGD, it's quickly and effectively. As linear dataset can be easily done regression problem, nonlinear dataset can better prove the performance of our model.

I take sin funcion to be the dataset. Those sample points that are far from the origin require very many iterations to fit gradually. After many attempts, we chose the following parameters: learning rate: 0.1, epochs: 10000, method: mbgd

We do the choices in the main function:

```
dataset = 'nonlinear'
2
     n \text{ samples} = 1000
     learning rate, epochs = 0.1, 10000
3
     method = 'mbgd'
4
     k = 5, tolerance = 1e-4, patience = 3
```

The training courses is as follows:

```
In this layer test: [1, 9, 1], Average MSE: 0.0036760063793220125
In this layer test: [1, 9, 6, 1], Average MSE: 0.003466735412638111
In this layer test: [1, 9, 21, 6, 1], Average MSE: 0.0019875823724081034
In this layer test: [1, 9, 21, 14, 6, 1], Average MSE: 0.00209688022635737
In this layer test: [1, 9, 21, 39, 14, 6, 1], Average MSE: 0.0019867735818585924
In this layer test: [1, 9, 21, 39, 26, 14, 6, 1], Average MSE: 0.002136578738297147
Then it triggers early stopping. Take all samples into account, Best Model - MSE: 0.38383448075092513
```



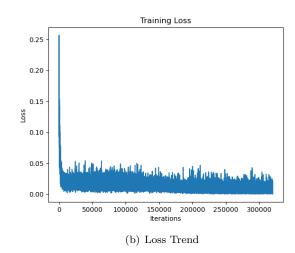


Fig. 4: The Traning Course of Nonlinear Function by MBGD Method

The model can perfectly fit the input data.

We can visualize the predictions and true labels. At the same time, we visualize the distribution of weights and bias.

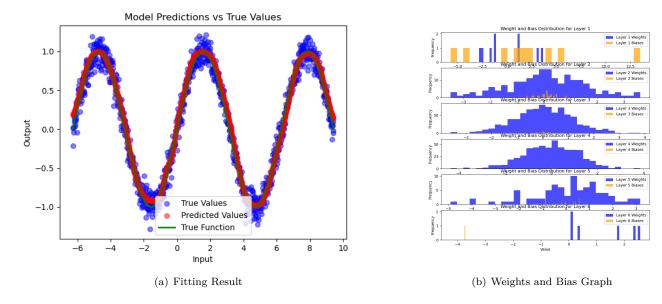


Fig. 5: Nonlinear Dataset - Using MBGD

6 The Result of Nonlinear Dataset by SGD Method

SGD uses less memory, thus can deal with large amounts of samples, but it isn't capable of parallel processing, so it works slowly. As linear dataset can be easily done regression problem, nonlinear dataset can better prove the performance of our model.

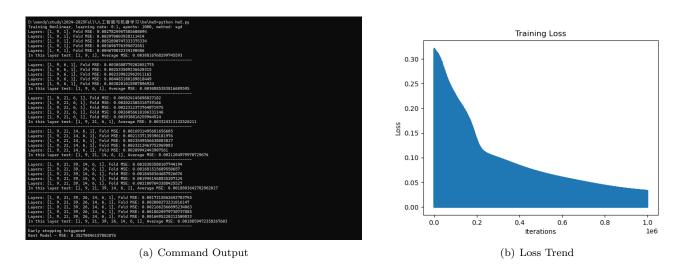


Fig. 6: The Traning Course of Nonlinear Function by SGD Method

I take sin funcion to be the dataset. Those sample points that are far from the origin require very many iterations to fit gradually. After many attempts, we chose the following parameters: learning rate: 0.1, epochs: 1000, method: sgd

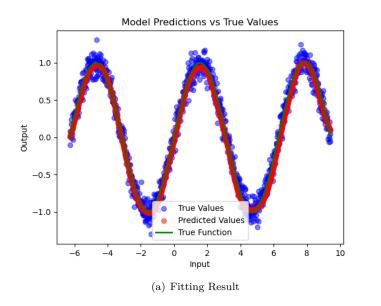
We do the choices in the main function:

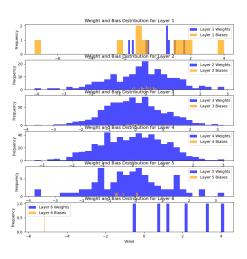
```
dataset = 'nonlinear'
```

The training courses is as follows:

In this layer test: [1, 9, 1], Average MSE: 0.0038816768299745593In this layer test: [1, 9, 6, 1], Average MSE: 0.0030885383816689595In this layer test: [1, 9, 21, 6, 1], Average MSE: 0.003324313132526211In this layer test: [1, 9, 21, 14, 6, 1], Average MSE: 0.0021204979970729674In this layer test: [1, 9, 21, 39, 14, 6, 1], Average MSE: 0.0018803642782962017In this layer test: [1, 9, 21, 39, 26, 14, 6, 1], Average MSE: 0.0018859472358267603

Then it triggers early stopping. Take all samples into account, Best Model - MSE: 0.35270846157802876





(b) Weights and Bias Graph

Fig. 7: Nonlinear Dataset - Using SGD

The model can perfectly fit the input data.

We can visualize the predictions and true labels. At the same time, we visualize the distribution of weights and bias.

7 The Result of Classifier Dataset by MBGD Method

 ${
m MBGD}$ method takes advantage of SGD and BGD, it's quickly and effectively. MLP model can also do classification problem, especially for those without linear bounds.

I put in six clusters of data labeled 0 and 1. The different categories have various intersections and overlaps, so it is a very challenging task. In that case, we can use MLP to validate our model. After many attempts, we chose the following parameters:

learning rate: 0.01, epochs: 500, method: mbgd

We do the choices in the main function:

```
dataset = 'classifier'
n_samples = 1200
```

```
3     learning_rate, epochs = 0.01, 500
4     method = 'mbgd'
5     k = 5, tolerance = 1e-4, patience = 3
```

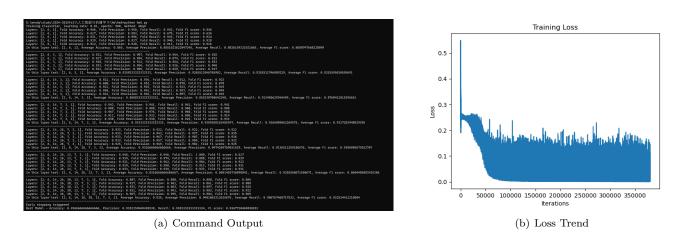


Fig. 8: The Traning Course of Classifier Problem by MBGD Method

The traning courses is as follows:

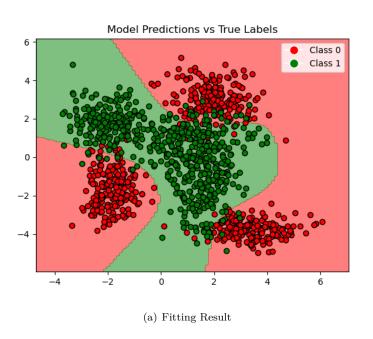
In this layer test: [2, 6, 1], Average Accuracy: 0.865, Average Precision: 0.8551023622047245, Average Recall: 0.8826159321021665, Average F1 score: 0.8680747668228099

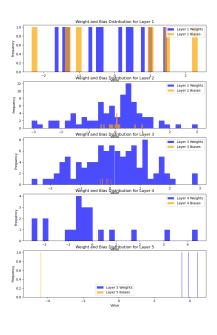
In this layer test: [2, 6, 14, 3, 1], Average Accuracy: 0.8608333333333333, Average Precision: 0.855330760642248, Average Recall: 0.913485629346499, Average F1 score: 0.8768421015396651

In this layer test: [2, 6, 14, 26, 13, 7, 3, 1], Average Accuracy: 0.83166666666666667, Average Precision: 0.8501455736898842, Average Recall: 0.9255550671550671, Average F1 score: 0.8660485083425306

In this layer test: [2, 6, 14, 26, 38, 13, 7, 3, 1], Average Accuracy: 0.925, Average Precision: 0.9401063212625675, Average Recall: 0.906767460717532, Average F1 score: 0.922524412210004

Then it triggers early stopping. Take all samples into account, Best Model - Accuracy: 0.9366666666666666, Precision: 0.9352159468438538, Recall: 0.93833333333333334, F1 score: 0.9367720465890182





(b) Weights and Bias Graph

Fig. 9: Classification Dataset - Using MBGD

The model can perfectly fit the input data.

We can visualize the predictions and true labels. At the same time, we visualize the distribution of weights and bias.

8 The Result of Classifier Dataset by SGD Method

SGD uses less memory, thus can deal with large amounts of samples, but it isn't capable of parallel processing, so it works slowly. MLP model can also do classification problem, especially for those without linear bounds.



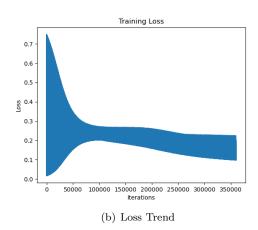


Fig. 10: The Traning Course of Classifier Problem by SGD Method

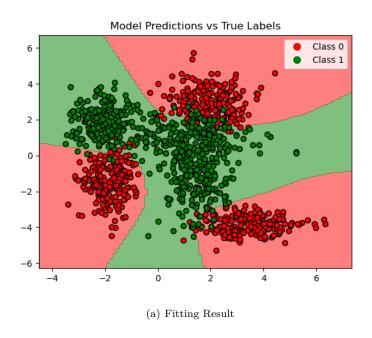
I put in six clusters of data labeled 0 and 1. The different categories have various intersections and overlaps, so it is

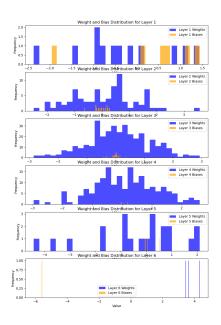
a very challenging task. In that case, we can use MLP to validate our model. After many attempts, we chose the following parameters:

learning rate: 0.01, epochs: 300, method: sgd

We do the choices in the main function:

```
dataset = 'classifier'
n_samples = 1200
learning_rate, epochs = 0.01, 300
method = 'sgd'
k = 5, tolerance = 1e-4, patience = 3
```





(b) Weights and Bias Graph

Fig. 11: Classification Dataset - Using SGD

The training courses is as follows:

In this layer test: [2, 6, 1], Average Accuracy: 0.9225, Average Precision: 0.9130794450264071, Average Recall: 0.9335886144765455, Average F1 score: 0.923075913246875

In this layer test: [2, 6, 3, 1], Average Accuracy: 0.929166666666668, Average Precision: 0.930753232431031, Average Recall: 0.9273300978830064, Average F1 score: 0.9287820181690787

In this layer test: [2, 6, 14, 26, 7, 3, 1], Average Accuracy: 0.9400000000000001, Average Precision: 0.9442426449664371, Average Recall: 0.936822218082464, Average F1 score: 0.9394350892404711

The model can perfectly fit the input data.

We can visualize the predictions and true labels. At the same time, we visualize the distribution of weights and bias.

9 Appendix

The code achieve the implementation of multi-layer perceptron. Like the main function tells:

```
dataset = 'nonlinear' # 'classify' or 'nonlinear'
2
   if dataset == 'classify':
3
     inputs, targets = generate_data_classifier(n_samples=200)
4
     method = 'mbgd'
5
     learning\_rate, epochs = 0.01, 1000
6
     print(f"Training Classifier, learning rate: {learning_rate}, epochs: {epochs},
7
         method: {method}")
     initial layers = 1
8
     max_layers = 10
9
     mlp = MultiLayerPerceptron(layer sizes=[inputs.shape[1]], dataset type='classify
10
     best_model = mlp.incremental_model_training_classifier(inputs, targets,
11
         initial_layers, max_layers, learning_rate, epochs, method=method)
12
     # Evaluate the best model
13
     accuracy, precision, recall, f1 = best_model.evaluate(inputs, targets)
14
     print(f"Best Model - Accuracy: {accuracy}, Precision: {precision}, Recall: {
15
         recall \}, F1 score: \{f1\}")
     best_model.visualize_predictions_classifier(inputs, targets)
16
     best_model.plot_weights_and_biases()
17
18
   elif dataset == 'nonlinear':
19
20
     inputs, targets = generate_nonlinear_dataset(n_samples=1000)
     learning\_rate, epochs = 0.1, 10000
21
     method = 'mbgd'
22
      print(f"Training Nonlinear, learning rate: {learning rate}, epochs: {epochs},
23
         method: {method}")
      initial layers = 1
24
     max_layers = 10
25
     mlp = MultiLayerPerceptron(layer_sizes = [1], dataset_type='nonlinear')
26
     best_model = mlp.incremental_model_training_nonlinear(inputs, targets,
27
         initial layers, max layers, learning rate, epochs, method=method)
28
29
     # Visualize the predictions
     mse = best_model.mean_squared_error(best_model.predict(inputs), targets)
30
      print(f"Best Model - MSE: {mse}")
31
     best model.visualize predictions nonlinear (inputs, targets)
32
     best model.plot weights and biases()
33
```