Theory of Electromagnetic Fields, Experiment 3

Author: Ying Yiwen Number: 12210159

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1 Introduction

According to Biot-Savart law, we can calculate the strength of the magnetic field generated by the current element, which is:

$$d\mathbf{H} = \frac{\mathbf{I}d\mathbf{L} \times \mathbf{a}_R}{4\pi R^2} = \frac{\mathbf{I}d\mathbf{L} \times \mathbf{R}}{4\pi R^3}$$
 (1)

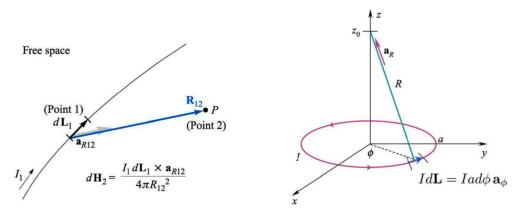
where **H** is the magnetic field intensity vector, $\mathbf{I}d\mathbf{L}$ is the current element vector, \mathbf{R} is the vector from the current element $\mathbf{I}d\mathbf{L}$ to the field point P, and its magnitude is R.

For the magnetic field generated by the current ring in space, the distribution of the magnetic field intensity on the central axis of the current ring is derived using the Biot-Savart law, and the results are as follows:

$$\mathbf{H} = \frac{I(\pi a^2)\mathbf{a}_z}{2\pi(a^2 + z_0^2)^{3/2}} \tag{2}$$

where a is the radius of the current ring, I is the size of the current flowing through the current ring, and z_0 is the coordinate of the field point (located on the central axis, the z axis).

Similar to the electric field, the magnetic field also follows the superposition principle, so we can also divide the current-carrying conductor into many current elements, and the magnetic field generated by the entire current-carrying conductor is the superposition of the magnetic field generated by these current elements. Based on this idea, we can use Matlab programming to solve the distribution of the magnetic field established by the current loop at any field point.



- (a) The Strength of the Magnetic Field Generated by the Current Element
- (b) The Strength of the Magnetic Field on the Central Axis of the Current Loop

Fig. 1: Sketch Map for Biot-Savart Law

2 Condition 1 - The Helmholtz Coil

Two current rings with radius of 2m, the same current direction, the size of the current is 500A, parallel to XY plane, the center of the circle is located respectively at O_1 (0, 0, -1), O_2 (0, 0, 1).

2.1 Results

By Matlab simulation, we can find out the magentic field, as follows:

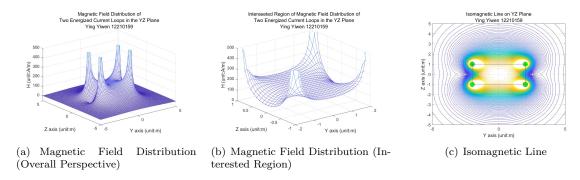


Fig. 2: Distribution of Magnetic Field Strength Values, the Helmholtz Coil

Similarly, we can also find out the magnetic field intensity vector distribution, as follows:

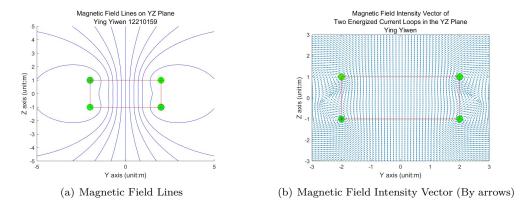


Fig. 3: Magnetic Field Intensity Vector Distribution, the Helmholtz Coil

From the results above, we can find that, in the Helmholtz coil, the magnetic field inside the coils (y in [-2,2], z in [-1,1] in this case) is almost uniform magnetic field.

2.2 Code

2.2.1 Set Parameters

2.2.2 Calculate the Magnetic Field

```
1 y=linspace(-ym,ym,n); % divide y
  z=linspace(-zm,zm,n); \% divide z
  [Y,Z]=meshgrid(y,z); % form coordinates
4 | theta0=linspace (0,2*pi,N+1); % divide the circle
  theta1=theta0(1:N); % start angle
   x1=a*cos(theta1); \% start x
   y1=a*sin(theta1); \% start y
   theta2=theta0(2:N+1); \% end angle
   x2=a*cos(theta2); \% end x
   y2=a*sin(theta2); \% end y
  xc=(x1+x2)/2; \% midpoint x
12 | yc = (y1+y2) / 2; \% \ midpoint \ y
  zc1=-ones(N); % midpoint z1
  zc2=ones(N); % midpoint z2
14
   dlx=x2-x1; % dlx
   dly=y2-y1; % dl y
16
   dlz = 0; \% dl z
17
18
  Hy=zeros(n); % build H for y component
  Hz=zeros(n); % build H for z component
  H=zeros(n); % build H (total)
21
   for i = 1:N
22
       X=zeros(n); \% x are all zeros because on yz plane
23
       \texttt{rx=\!X\!-\!xc(i);}~\%~r~x
24
       ry=Y-yc(i); % r y
25
       rz1=Z-zc1(i); \% r z1
26
       rz2=Z-zc2(i); % r z2
27
       r31 = sqrt(rx.^2 + ry.^2 + rz1.^2).^3; \% r^3 1
28
       r32 = sqrt(rx.^2 + ry.^2 + rz2.^2).^3; \% r^3 2
29
```

```
dlXr_y1=-dlx(i).*rz1; \% y component of dl\times r 1
31
       dlXr_y2=-dlx(i).*rz2; \% y component of dl \times r 2
       dlXr_z=dlx(i).*ry-dly(i).*rx; \% z component of <math>dl\times r
32
       Hy=Hy+C.*dlXr_y1./r31; % add to Hy 1
33
       Hy=Hy+C.*dlXr y2./r32; \% add to Hy 2
       Hz=Hz+C.*dlXr z./r31; % add to Hz 1
35
       Hz=Hz+C.*dlXr z./r32; \% add to Hz 2
36
       H=(Hy.^2+Hz.^2).^0.5; \% compute H
37
38
  end
```

2.2.3 Magnetic Field Distribution

```
figure; % magnetic distribution (whole)
   mesh(Y,Z,H); % draw distribution figure
   hold on; % keep the same graph
   title(sprintf('Magnetic_{\square}Field_{\square}Distribution_{\square}of \land nTwo_{\square}Energized_{\square}Current)
        _{\sqcup}Loops_{\sqcup}in_{\sqcup}the_{\sqcup}YZ_{\sqcup}Plane \setminus nYing_{\sqcup}Yiwen_{\sqcup}12210159'), "FontSize", 12); %
         title
    axis([-5,5,-5,5,-50,500]); \% xyz limits
   xlabel ('Y_{\square} axis_{\square} (unit:m)', 'FontSize',12); % x label ylabel ('Z_{\square} axis_{\square} (unit:m)', 'FontSize',12); % y label
   zlabel ('H_{\sqcup} (unit:A/m)', 'FontSize',12); % z label
    saveas (gcf, 'fig1-1.jpg'); \% save figure
    figure; \% magnetic distribution (-2,2,-1,1)
    mesh (Y, Z, H); % draw distribution figure
11
   hold on; % keep the same graph
12
   title(sprintf('Intereseted_{\square}Region_{\square}of_{\square}Magnetic_{\square}Field_{\square}Distribution_{\square}of)
        nTwo_{\sqcup}Energized_{\sqcup}Current_{\sqcup}Loops_{\sqcup}in_{\sqcup}the_{\sqcup}YZ_{\sqcup}Plane \setminus nYing_{\sqcup}Yiwen_{\sqcup}12210159
         '), "FontSize", 12); % title
    axis([-2,2,-1,1,-0,500]); \% xyz limits
    xlabel ('Y_{\square}axis_{\square}(unit:m)', 'FontSize',12); % x label ylabel ('Z_{\square}axis_{\square}(unit:m)', 'FontSize',12); % y label
    zlabel ('H_{\square} (unit:A/m)', 'FontSize',12); % z label
17
    saveas (gcf, 'fig1-2.jpg'); \% save figure
18
19
    figure: % isomagnetic
20
   Hmin=0; \% minimum H
21
   Hmax=200; \% maximum H
   H0=linspace (Hmin, Hmax, 100); % divide isomagnetic line
    contour (Y, Z, H, H0); % draw isomagnetic line
    grid on; % form grid
25
26
    hold on; % keep the same graph
    title (sprintf ('Isomagnetic Line on YZ Plane \nYing Yiwen 12210159'),"
         FontSize",12); % title
   axis([-5,5,-5,5]); \% xy limits
```

```
plot(-2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
       bisect
   plot(-2,1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
        direction
   plot (2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
   plot(2,1,'+','MarkerFaceColor','k','MarkerSize',12); % current flow
32
       direction
   plot(-2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
33
       bisect
   plot(-2,-1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current
34
       flow direction
   plot (2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
35
36
   plot(2,-1,'+','MarkerFaceColor','k','MarkerSize',12); % current flow
        direction
37
   rectangle ('Position', [-2, -1, 4, 2], 'EdgeColor', 'r'); % the interested
       region
   xlabel ('Y_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); % x label
   ylabel ('Z_{\square} axis_{\square} (unit:m)', 'FontSize',12); % y label
   saveas (gcf, 'fig1-3.jpg'); \% save figure
```

2.2.4 Magnetic Field Lines

```
figure; % distribution of magnetic field lines
   theta=[0 50 60 70 80 90 100 110 120 130 180].*pi/180; % radian value
   ys=1.5*cos(theta); \% field line origin coordinates x
   zs=1.5*sin(theta); % field line origin coordinates y
   streamline (Y, Z, Hy, Hz, ys, zs); % draw magnetic field lines outward
   streamline (Y, Z, -Hy, -Hz, ys, zs); % draw magnetic field lines inward
   title(sprintf('Magnetic_{\square}Field_{\square}Lines_{\square}on_{\square}YZ_{\square}Plane \setminus nYing_{\square}Yiwen_{\square}12210159)
       '), "FontSize", 12); % title
   hold on; % keep the same graph
   axis([-5,5,-5,5]); \% xy limits
   plot(-2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
10
       bisect
   plot (-2,1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
11
        direction
   plot (2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
   plot(2,1,'+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
       direction
   plot(-2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
14
       bisect
   plot(-2,-1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current
15
       flow direction
16 |\operatorname{plot}(2,-1,'o','MarkerFaceColor','g','MarkerSize',12); \% (2,1) bisect
```

```
plot(2,-1, '+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
         direction
   rectangle ('Position', [-2,-1,4,2], 'EdgeColor', 'r'); % the interested
        region
   \verb|xlabel| ( Y_{\sqcup} axis_{\sqcup} ( unit : m ) ', 'FontSize', 12 ) ; \; \% \; x \; label|
   ylabel (Z_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); \% y label
20
   saveas (gcf, 'fig1-4.jpg'); \% save figure
21
22
   figure; % magnetic field strength vector diagram
23
   Hy=Hy./H; % normalization
24
   Hz=Hz./H; % normalization
   quiver (Y, Z, Hy, Hz); % draw vector diagram
   hold on; % keep the same graph
   title(sprintf('Magnetic_{\square}Field_{\square}Intensity_{\square}Vector_{\square}of \land nTwo_{\square}Energized_{\square}
        Current_{\sqcup}Loops_{\sqcup}in_{\sqcup}the_{\sqcup}YZ_{\sqcup}Plane \setminus nYing_{\sqcup}Yiwen', "FontSize", 12); %
        title
   axis([-3,3,-3,3]); \% xy limits
   plot(-2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
        bisect
   plot(-2,1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
         direction
   plot\left(2\,,1\,,\,'o\,',\,'MarkerFaceColor\,',\,'g\,',\,'MarkerSize\,',12\right);\,\,\,\%\,\,\left(2\,,1\right)\,\,\,bisect
   plot (2,1,'+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
33
   plot(-2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
34
        bisect
   plot(-2,-1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current
35
       flow direction
   plot (2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
36
   plot(2,-1,'+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
37
         direction
   rectangle ('Position', [-2, -1, 4, 2], 'EdgeColor', 'r'); % the interested
        region
   xlabel('Y_{\square}axis_{\square}(unit:m)', 'FontSize', 12); \% x label
   ylabel ('Z_{\square} axis_{\square} (unit:m)', 'FontSize',12); % y label
   saveas (gcf, 'fig1-5.jpg'); \% save figure
```

3 Condition 2 - The Helmholtz Coil with Oppsite Direction Loops

Two current rings with radius of 2m, the oppsite current direction, the size of the current is 500A, parallel to XY plane, the center of the circle is located respectively at O_1 (0, 0, -1), O_2 (0, 0, 1).

3.1 Results

By Matlab simulation, we can find out the magentic field, as follows:

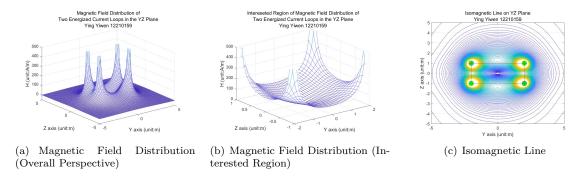


Fig. 4: Distribution of Magnetic Field Strength Values, the Helmholtz Coil with Oppsite Direction Similarly, we can also find out the magnetic field intensity vector distribution, as follows:

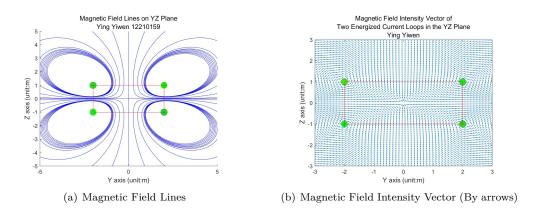


Fig. 5: Magnetic Field Intensity Vector Distribution, the Helmholtz Coil with Oppsite Direction

From the results above, we can find that, when the circuit directions are oppsite, the magnetic field inside the coils (y in [-2,2], z in [-1,1] in this case) is symmetric in y and z axis.

3.2 Code

3.2.1 Set Parameters

3.2.2 Calculate the Magnetic Field

```
1 y=linspace(-ym,ym,n); % divide y
  z=linspace(-zm, zm, n); \% divide z
  [Y,Z]=meshgrid(y,z); % form coordinates
  | \text{theta0=linspace}(0,2*\text{pi},N+1); \% \ divide \ the \ circle
  theta1=theta0(1:N); % start angle
   x1=a*cos(theta1); \% start x
   y1=a*sin(theta1); \% start y
   theta2=theta0(2:N+1); \% end angle
   x2=a*cos(theta2); \% end x
   y2=a*sin(theta2); \% end y
  xc=(x1+x2)/2; \% midpoint x
12 | yc = (y1+y2) / 2; \% \ midpoint \ y
  zc1=-ones(N); % midpoint z1
  zc2=ones(N); % midpoint z2
14
   dlx=x2-x1; % dlx
   dly=y2-y1; % dl y
16
   dlz = 0; \% dl z
17
18
  Hy=zeros(n); % build H for y component
  Hz=zeros(n); % build H for z component
  H=zeros(n); % build H (total)
21
   for i = 1:N
22
       X=zeros(n); \% x are all zeros because on yz plane
23
       \texttt{rx=\!X\!-\!xc(i);}~\%~r~x
24
       ry=Y-yc(i); % r y
25
       rz1=Z-zc1(i); \% r z1
26
       rz2=Z-zc2(i); % r z2
27
       r31 = sqrt(rx.^2 + ry.^2 + rz1.^2).^3; \% r^3 1
28
       r32 = sqrt(rx.^2 + ry.^2 + rz2.^2).^3; \% r^3 2
29
```

```
dlXr_y1=dlx(i).*rz1; \% y component of dl \times r 1
        dlXr_y2=-dlx(i).*rz2; \% y component of dl \times r 2
31
        dlXr_zl=-dlx(i).*ry+dly(i).*rx; \% z component of dl×r 1
32
        dlXr_z2=dlx(i).*ry-dly(i).*rx; \% z component of dl \times r 2
33
       Hy=Hy+C.*dlXr v1./r31; \% add to Hy 1
       \hbox{Hy=Hy+C.*dlXr\_y2./r32}\;;\;\;\%\;\;add\;\;to\;\;Hy\;\;2
35
       Hz=Hz+C.*dlXr_z1./r31; % add to Hz 1
36
37
       Hz=Hz+C.*dlXr_z2./r32; \% add to Hz 2
       H=(Hy.^2+Hz.^2).^0.5; \% compute H
   end
39
```

3.2.3 Magnetic Field Distribution

```
figure; % magnetic distribution (whole)
   mesh (Y, Z, H); % draw distribution figure
   hold on; % keep the same graph
   title(sprintf('Magnetic_{\square}Field_{\square}Distribution_{\square}of \land nTwo_{\square}Energized_{\square}Current)
        _{\sqcup}Loops_{\sqcup}in_{\sqcup}the_{\sqcup}YZ_{\sqcup}Plane \setminus nYing_{\sqcup}Yiwen_{\sqcup}12210159'), "FontSize", 12); %
    axis([-5,5,-5,5,-50,500]); \% xyz limits
   xlabel ('Y_{\square} axis_{\square} (unit:m)', 'FontSize',12); % x label ylabel ('Z_{\square} axis_{\square} (unit:m)', 'FontSize',12); % y label
    zlabel ('H_{\square} (unit:A/m)', 'FontSize',12); % z label
    saveas (gcf, 'fig2-1.jpg'); \% save figure
    figure; \% magnetic distribution (-2,2,-1,1)
   mesh(Y,Z,H); % draw distribution figure
   hold on; % keep the same graph
12
   title(sprintf('Intereseted_{\square}Region_{\square}of_{\square}Magnetic_{\square}Field_{\square}Distribution_{\square}of)
        nTwo_{\sqcup}Energized_{\sqcup}Current_{\sqcup}Loops_{\sqcup}in_{\sqcup}the_{\sqcup}YZ_{\sqcup}Plane \setminus nYing_{\sqcup}Yiwen_{\sqcup}12210159
         '), "FontSize", 12); % title
    axis([-2,2,-1,1,-0,500]); \% xyz limits
    xlabel ('Y_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); % x label ylabel ('Z_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); % y label
16
    zlabel ('H_{\square} (unit:A/m)', 'FontSize',12); % z label
17
    saveas (gcf, 'fig2-2.jpg'); % save figure
18
19
   figure; % isomagnetic
20
   Hmin=0; \% minimum H
21
   Hmax=200; \% maximum H
   H0=linspace (Hmin, Hmax, 100); % divide isomagnetic line
   contour (Y, Z, H, H0); % draw isomagnetic line
    grid on; % form grid
25
   hold on; % keep the same graph
   title(sprintf('Isomagnetic_{l}Line_{l}on_{l}YZ_{l}Plane\setminus nYing_{l}Yiwen_{l}12210159'),"
        FontSize",12); % title
```

```
axis([-5,5,-5,5]); \% xy limits
   \operatorname{plot}(-2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
29
   plot(-2,1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
30
         direction
   plot (2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
31
   plot(2,1,'+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
       direction
   plot(-2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
       bisect
   plot(-2,-1,'+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current
34
       flow direction
   plot(2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (2,1) bisect
   plot(2,-1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
36
         direction
   rectangle ('Position', [-2,-1,4,2], 'EdgeColor', 'r'); % the interested
37
       region
   xlabel ('Y_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); % x label ylabel ('Z_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); % y label
38
   saveas (gcf, 'fig2-3.jpg'); \% save figure
```

3.2.4 Magnetic Field Lines

```
figure; % distribution of magnetic field lines
   theta = \begin{bmatrix} 0 & 50 & 60 & 70 & 80 & 90 & 100 & 110 & 120 & 130 & 180 & 230 & 240 & 250 & 260 & 270 & 280 \end{bmatrix}
       290 300 310].*pi/180; % radian value
   ys=1.5*cos(theta); \% field line origin coordinates x
   zs=1.5*sin(theta); \% field line origin coordinates y
   streamline (Y, Z, Hy, Hz, ys, zs); % draw magnetic field lines outward
   streamline (Y, Z, -Hy, -Hz, ys, zs); % draw magnetic field lines inward
   title(sprintf('Magnetic_{\square}Field_{\square}Lines_{\square}on_{\square}YZ_{\square}Plane \setminus nYing_{\square}Yiwen_{\square}12210159)
        '), "FontSize", 12); % title
   hold on; % keep the same graph
   axis([-5,5,-5,5]); \% xy limits
9
   plot(-2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
10
       bisect
   plot (-2,1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
        direction
   plot(2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
   plot(2,1,'+','MarkerFaceColor','k','MarkerSize',12); % current flow
13
       direction
   plot(-2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
14
       bisect
15 | plot (-2,-1, '+', 'MarkerFaceColor', 'k', 'MarkerSize', 12); % current
       flow direction
```

```
\texttt{plot}\left(2,-1,\text{ 'o'},\text{ 'MarkerFaceColor'},\text{ 'g'},\text{ 'MarkerSize'},12\right); \; \% \; (2,1) \; \; bisect
17
   plot(2,-1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
         direction
   rectangle ('Position', [-2,-1,4,2], 'EdgeColor', 'r'); % the interested
18
   \verb|xlabel| ( Y_{\square} axis_{\square} ( unit : m ) ', 'FontSize', 12 ) ; \; \% \; x \; label|
19
   ylabel ('Z_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize', 12); % y label
21
   saveas (gcf, 'fig2-4.jpg'); \%  save figure
22
   figure; % magnetic field strength vector diagram
23
   Hy=Hy./H; % normalization
   Hz=Hz./H; % normalization
   quiver (Y, Z, Hy, Hz); % draw vector diagram
27
   hold on; % keep the same graph
   title(sprintf('Magnetic_{\square}Field_{\square}Intensity_{\square}Vector_{\square}of \setminus nTwo_{\square}Energized_{\square}
        Current_{\sqcup}Loops_{\sqcup}in_{\sqcup}the_{\sqcup}YZ_{\sqcup}Plane \setminus nYing_{\sqcup}Yiwen'), "FontSize", 12); %
   axis([-3,3,-3,3]); \% xy limits
   plot(-2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
30
   plot(-2,1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
31
         direction
   plot (2,1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize',12); % (2,1) bisect
32
   plot (2,1,'+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
        direction
   plot(-2,-1, 'o', 'MarkerFaceColor', 'g', 'MarkerSize', 12); \% (-2,1)
        bisect
   plot(-2,-1, '+', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current
        flow direction
   \texttt{plot}\left(2,-1,\, \text{'o'},\, \text{'MarkerFaceColor'},\, \text{'g'},\, \text{'MarkerSize'},12\right); \,\,\% \,\,\left(2,1\right) \,\,bisect
   plot(2,-1, '*', 'MarkerFaceColor', 'k', 'MarkerSize',12); % current flow
37
         direction
   rectangle ('Position', [-2,-1,4,2], 'EdgeColor', 'r'); % the interested
38
   xlabel ('Y_{\sqcup} axis_{\sqcup} (unit:m)', 'FontSize',12); % x label
   ylabel (Z_{\square} axis_{\square} (unit:m), 'FontSize',12); % y label
   saveas (gcf, 'fig2-5.jpg'); \% save figure
```

4 Experience

Master the ability to simulate the magnetic field generated by paralleled loops. Observe the magnetic field distribution of Helmholtz coils, and also the condition when the current direction is oppsite. Be rather proficient in using latex for report writing.

A Helmholtz coil is a device that creates a uniform magnetic field over a small area. The open nature of the Helmholtz coil makes it easy to place other instruments in or out of it, as well as to make direct visual observations. In some applications, Helmholtz coils can be used to counteract geomagnetic fields, creating areas of near-zero magnetic field.

In this experiment, I verified the properties of the Helmholtz coil by simulating the abstract theoretical results and observed that the Helmholtz coil was indeed able to construct a uniform magnetic field. In turn, it is able to construct a symmetrical magnetic field when the coil currents are in opposite directions. Such interesting properties may be used frequently in experiments where a magnetic field needs to be established.