### Transformers

Machine Learning Course - CS-433 Nov 12, 2024 Nicolas Flammarion

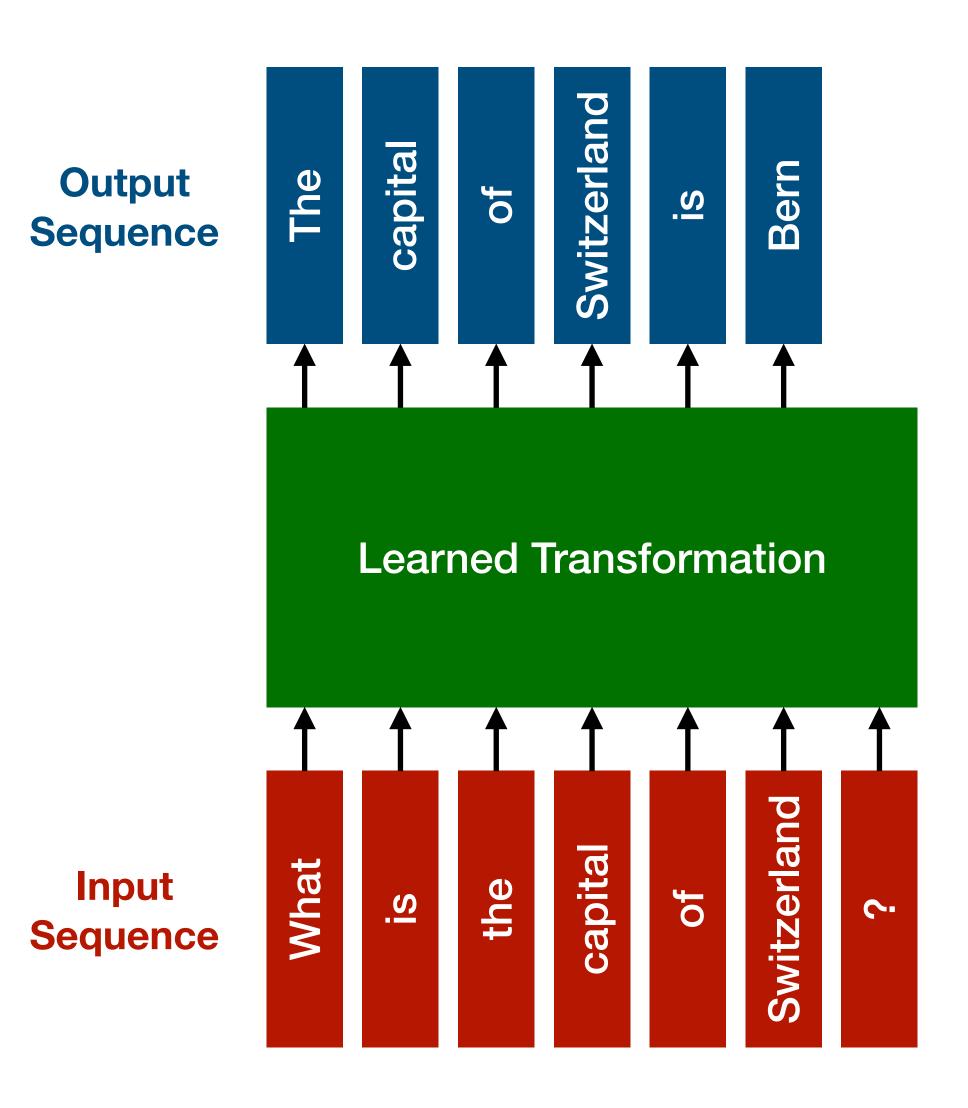


# Sequence-to-Sequence Transformations

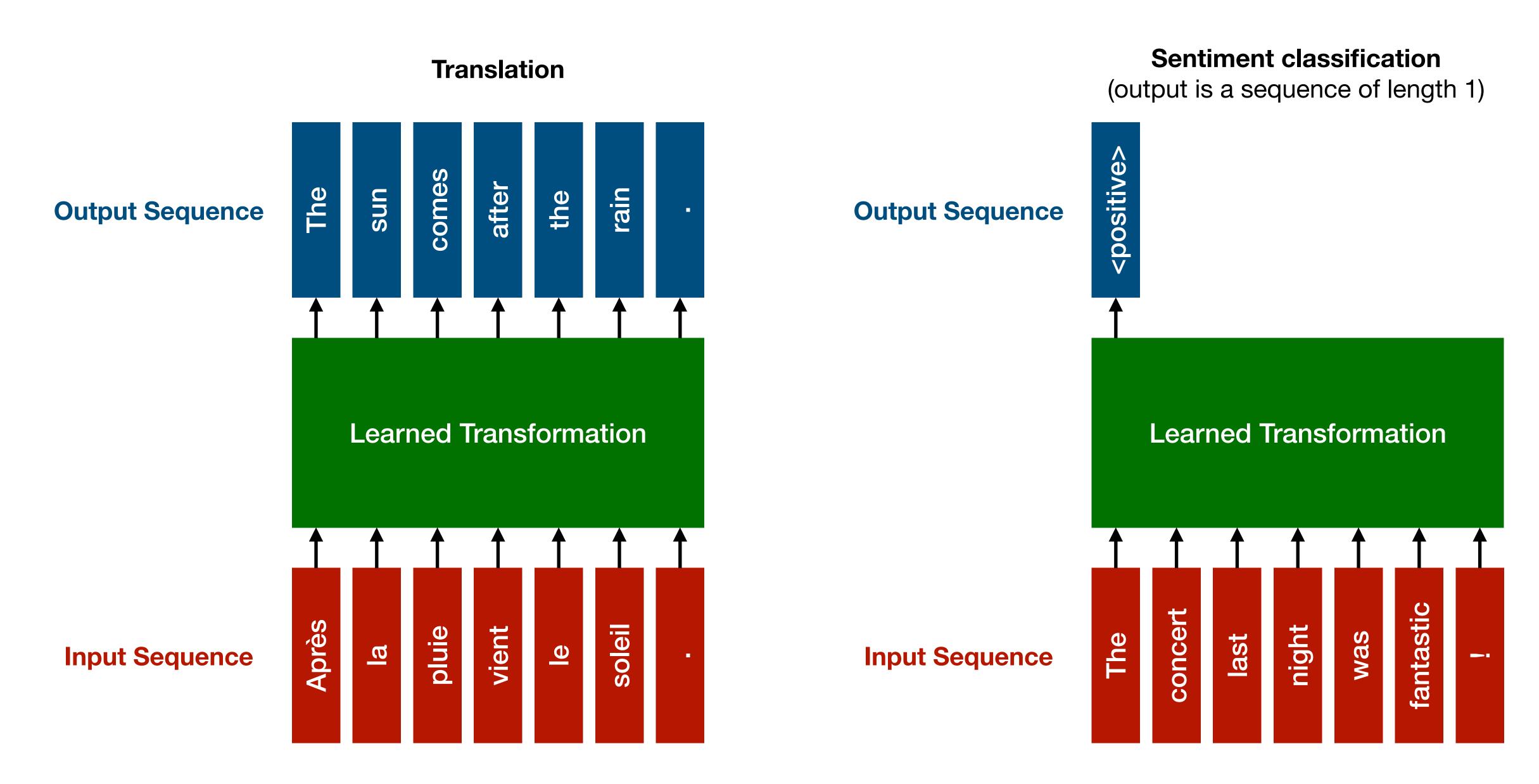
### Sequence-to-Sequence Transformations

 Many interesting problems in ML can be expressed as mapping one sequence to another

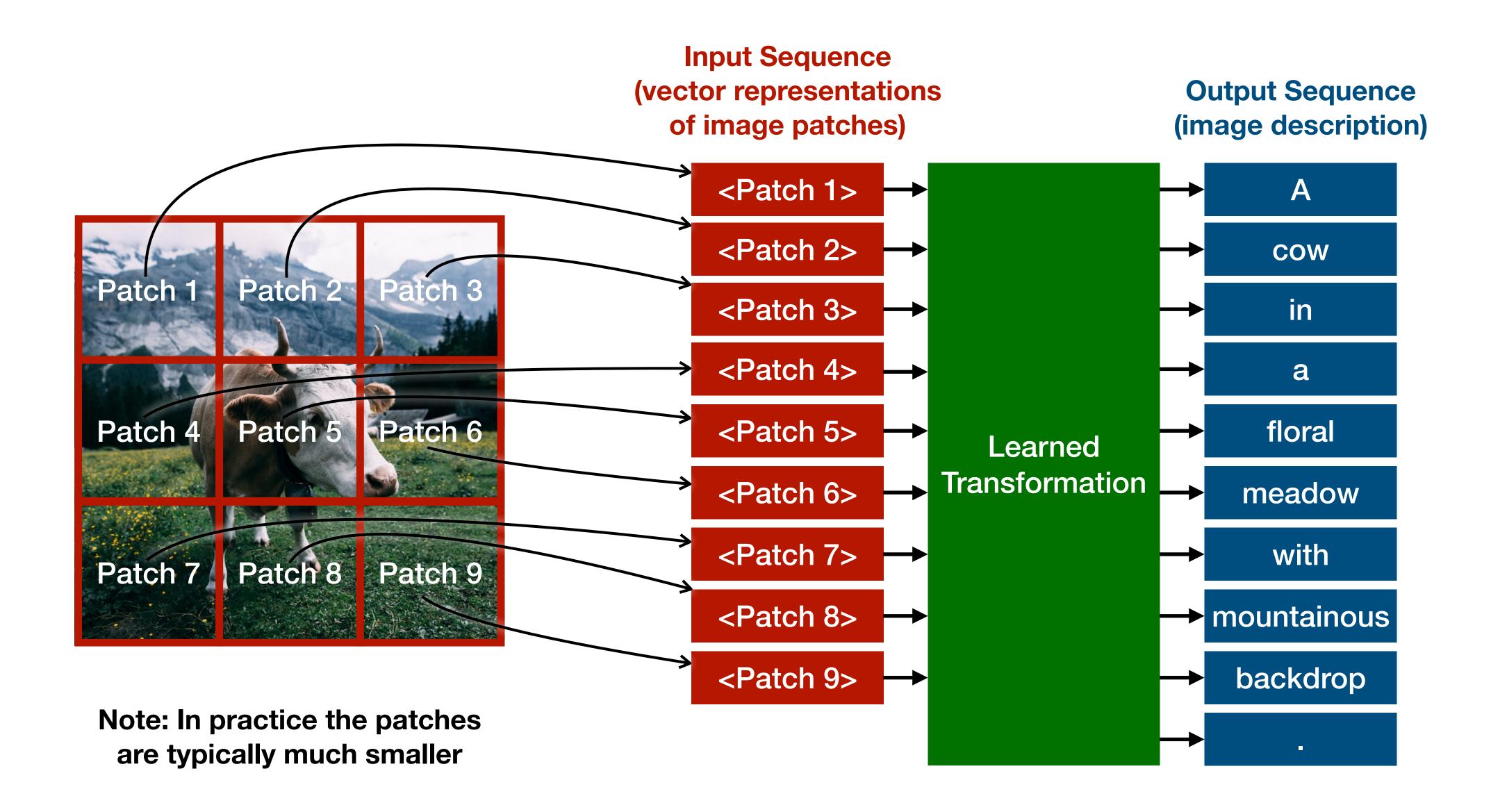
- Example: chatbots like ChatGPT
  - Input: question (word sequence)
  - Output: answer (word sequence)
- Input and output sequences can represent various types of data: words, images, speech, proteins, time series, etc.



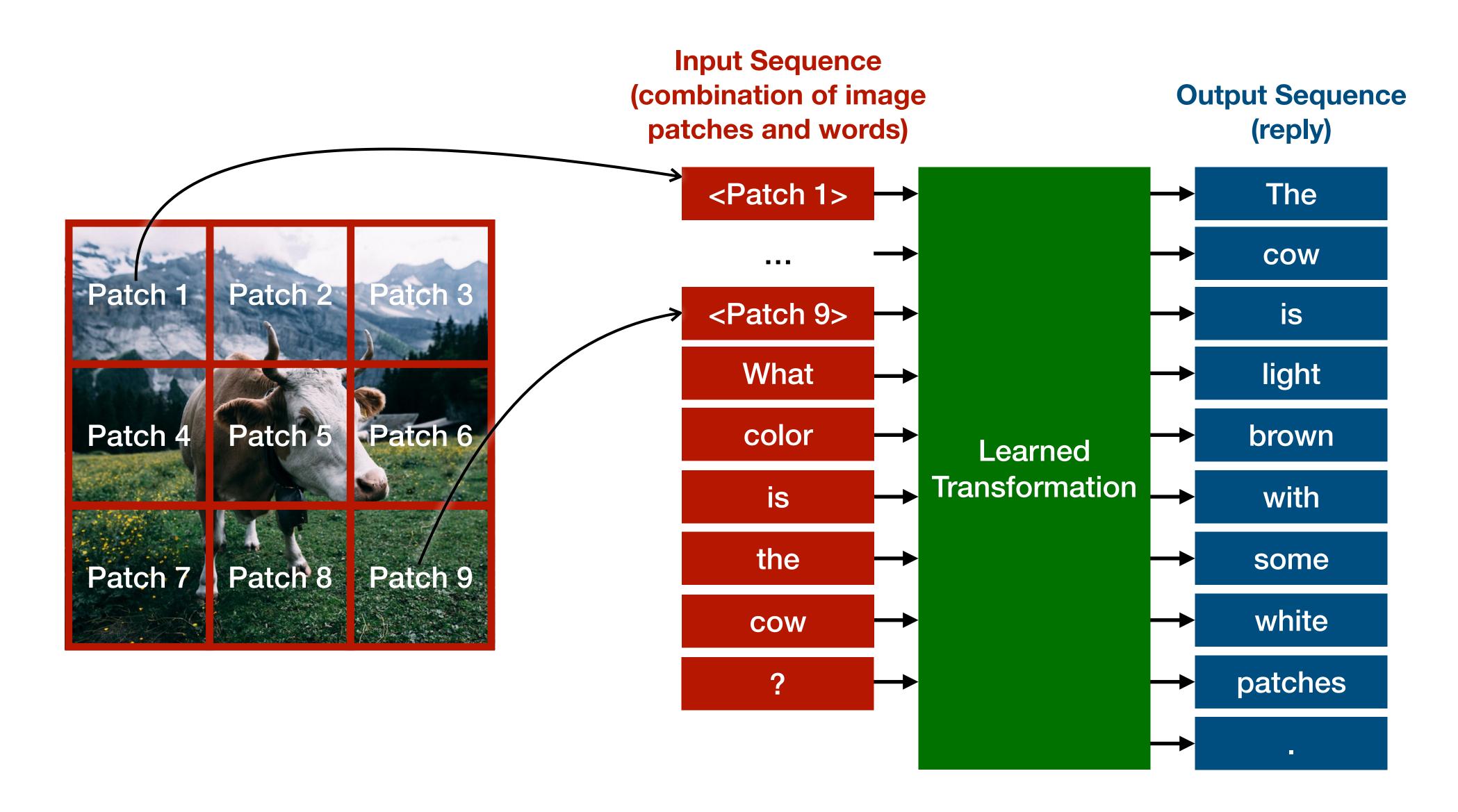
#### The sequence-to-sequence framework is very general



#### Images can also be represented as sequences



#### Sequences can be multimodal (image + text)



### Transformers

### What is a Transformer?

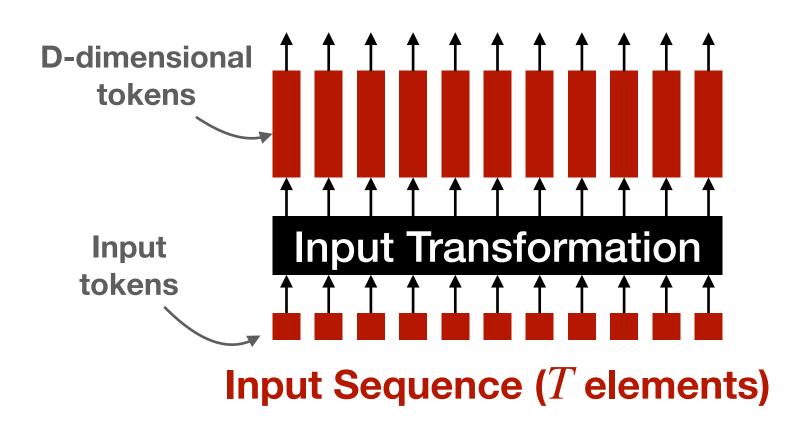
$$f: sequence \rightarrow sequence$$
 (using self-attention)

**Transformer** is a neural network f that iteratively transforms a sequence to another sequence and mixes the information between the sequence elements via **self-attention** 

#### Overview of Transformer Architecture

**Input transformation**: converts the input sequence elements into real-valued vector representations (aka **tokens**):

- maps a one-hot word vector to a real-valued vector
- extracts an image patch and flattens it into a vector

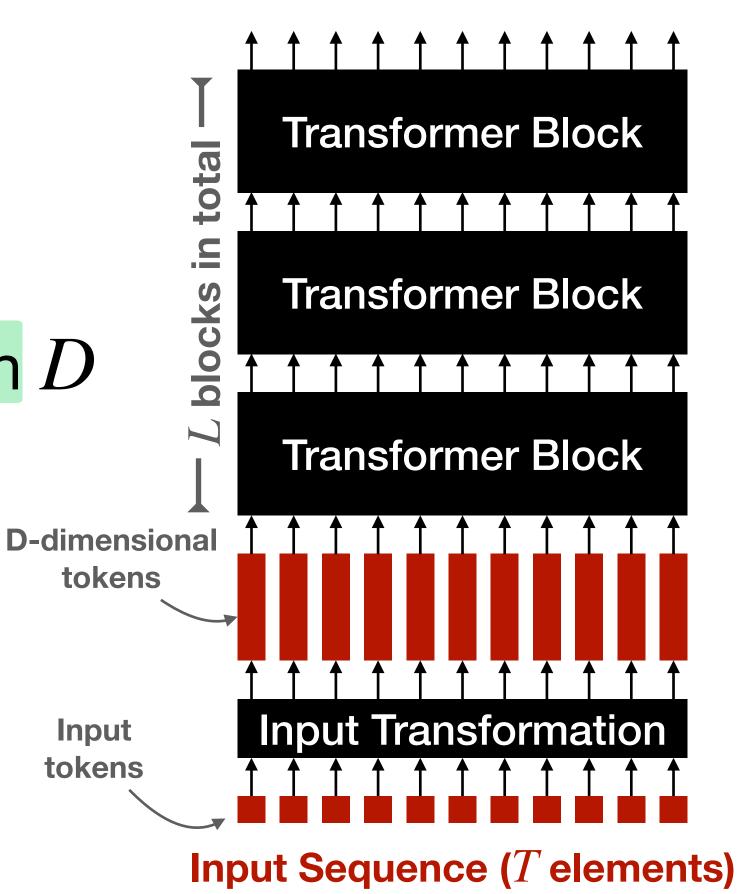


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**Transformer block**: transforms a sequence of T vectors of dimension D into a new sequence of T vectors of dimension D using **self-attention** and **MLP sub-blocks** 



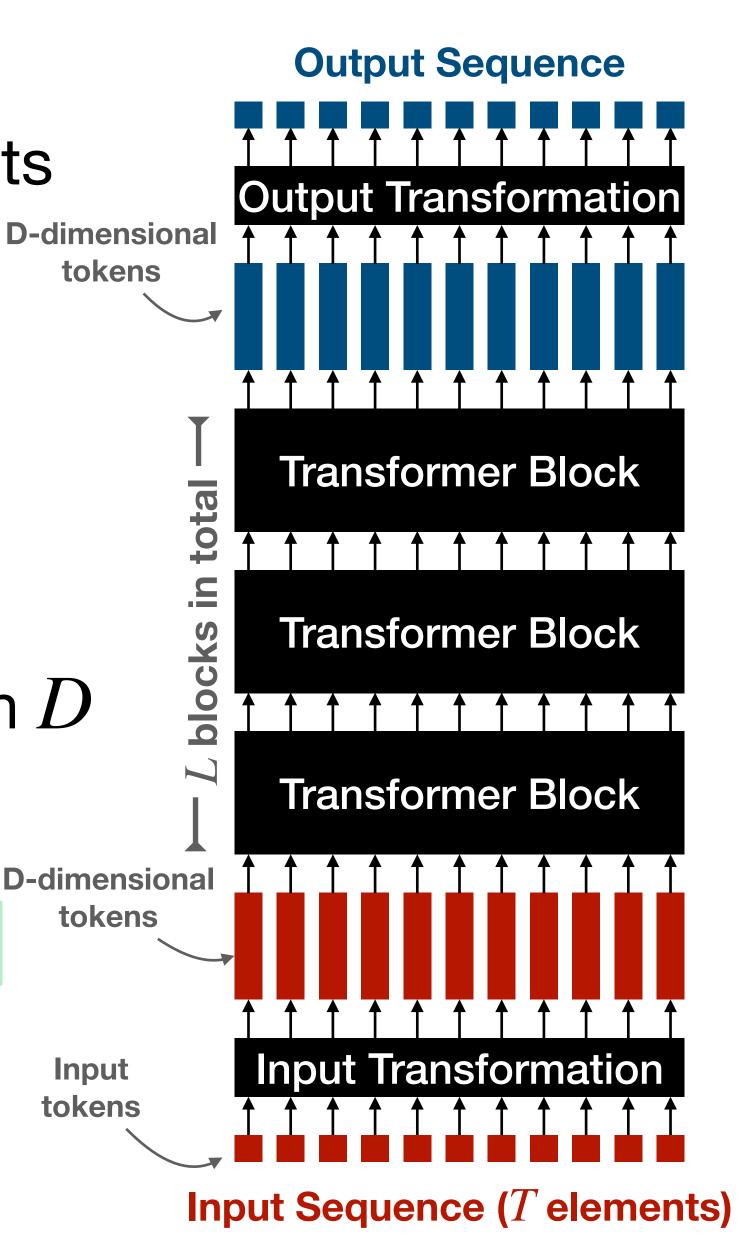
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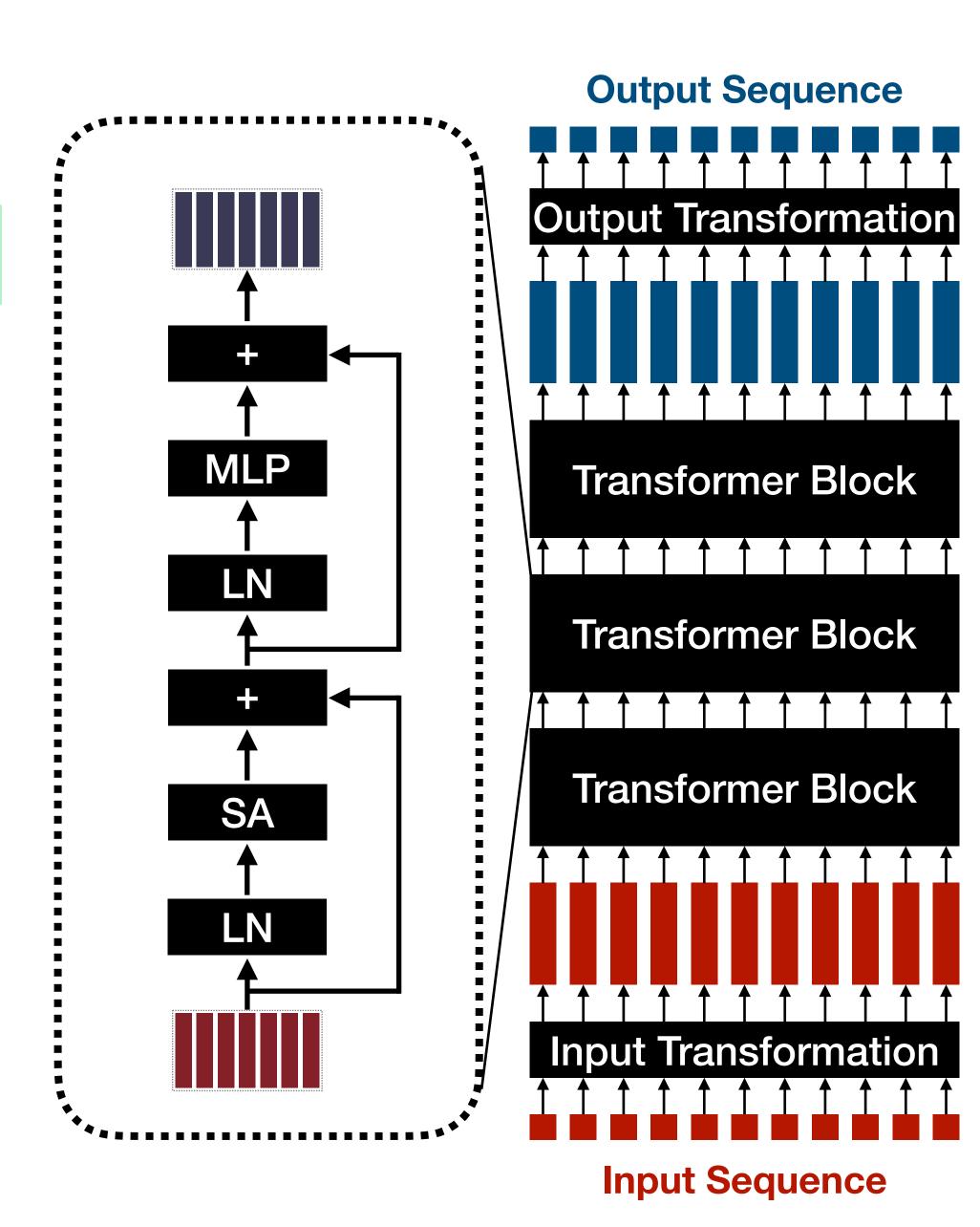
**Transformer block**: transforms a sequence of T vectors of dimension D into a new sequence of T vectors of dimension D using **self-attention** and **MLP sub-blocks** 

Output transformation: converts the vectors to the desired output format (e.g., single-element sequence for classification, multiple-element sequence of words)



### Transformer Block

- Self-Attention (SA): mixes information between tokens
- Multi-Layer Perceptron (MLP): mixes information within each token
- Other standard components:
  - Skip connections are widely used
  - Layer normalization (LN) is usually placed at the start of a residual branch



# Input Transformations

## Text Token Embeddings

**Tokenization**: split the input text into a sequence of *input tokens* (typically word fragments + some special symbols) according to some predefined tokenizer procedure:

- Text: "<User:>Transformers are awesome!"
- Tokens: [<User token>, "Trans", "form", "ers\_", "are\_", "awe", "some", "!"]
- Token IDs: [0, 5124, 1029, 645, 3001, 6931, 7330, 10] (each token corresponds to some number  $i \in \{1, ..., N_{vocab}\}$ )

**Token embedding**: maps each token ID  $i \in \{1, ..., N_{vocab}\}$  into a real-valued vector  $\mathbf{w}_i \in \mathbb{R}^D$ :

- Token embeddings:  $[w_0, w_{5124}, w_{1029}, w_{645}, w_{3001}, w_{6931}, w_{7330}, w_{10}]$

$$\begin{bmatrix} w_0^\mathsf{T} \\ w_{5124}^\mathsf{T} \\ \vdots \\ w_{10}^\mathsf{T} \end{bmatrix} \in \mathbb{R}^{T \times L}$$

### Text Token Embeddings - Learning

• The matrix 
$$\mathbf{W}_{\text{emb}} = \begin{bmatrix} \mathbf{w}_1^{\mathsf{T}} \\ \vdots \\ \mathbf{w}_{N_{vocab}}^{\mathsf{T}} \end{bmatrix} \in \mathbb{R}^{N_{vocab} \times D}$$
 is learned via backpropagation, along

with all other transformer parameters

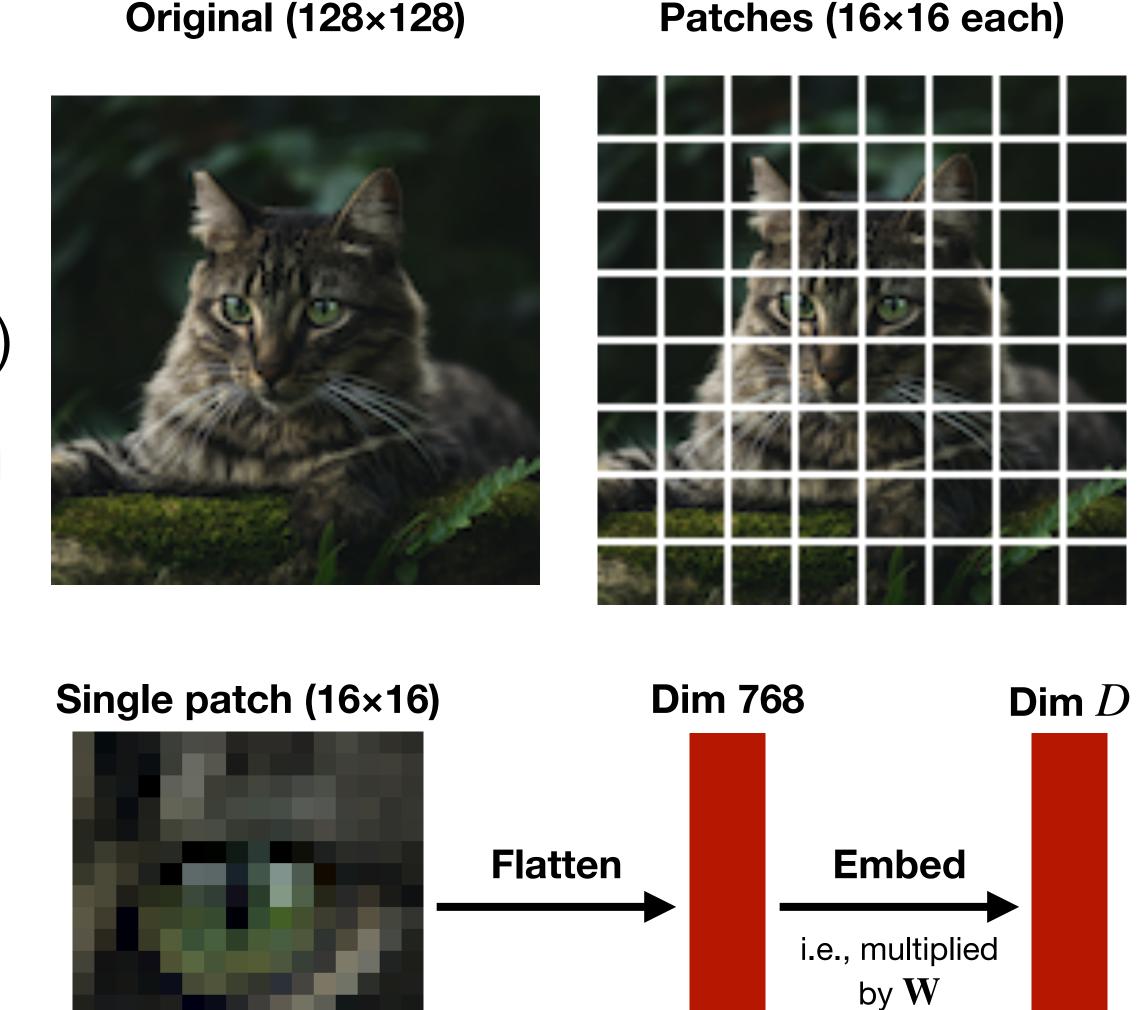
• This can be seen as a matrix multiplication:

$$\mathbf{X} = \begin{bmatrix} \mathbf{e}_{i_1}^{\mathsf{T}} \\ \vdots \\ \mathbf{e}_{i_T}^{\mathsf{T}} \end{bmatrix} \mathbf{W}_{\mathsf{emb}} \quad (\mathsf{since} \ \mathbf{e}_{i}^{\mathsf{T}} \mathbf{W}_{\mathsf{emb}} = (\mathbf{W}_{\mathsf{emb}})_{i,:} = \mathbf{w}_{i}^{\mathsf{T}})$$

The tokenizer procedure is typically fixed in advance and not learned

# Image Patch Embeddings

- Divide image into patches of a given size (typical choice: 16 × 16 pixels each)
- Flatten each patch into a vector of size  $16 \cdot 16 \cdot 3 = 768$  (height\*width\*color channels)
- Multiply each resulting vector by an embedding matrix  $\mathbf{W}_{\text{emb}} \in \mathbb{R}^{D \times 768}$  which is shared for all inputs
- Learn  $W_{\text{emb}}$  through backpropagation, along with all other transformer parameters
- The whole input sequence of T embedded patches leads to an input matrix  $X \in \mathbb{R}^{T \times D}$



### Self-attention

### What is Self-attention?

 $A: tokens \rightarrow tokens$ 

(using a weighted average)

Reminder: a token is simply a real-valued vector

Self-attention is a function that transforms a sequence of tokens to a new sequence of tokens using a learned input-dependent weighted average

## Self-Attention

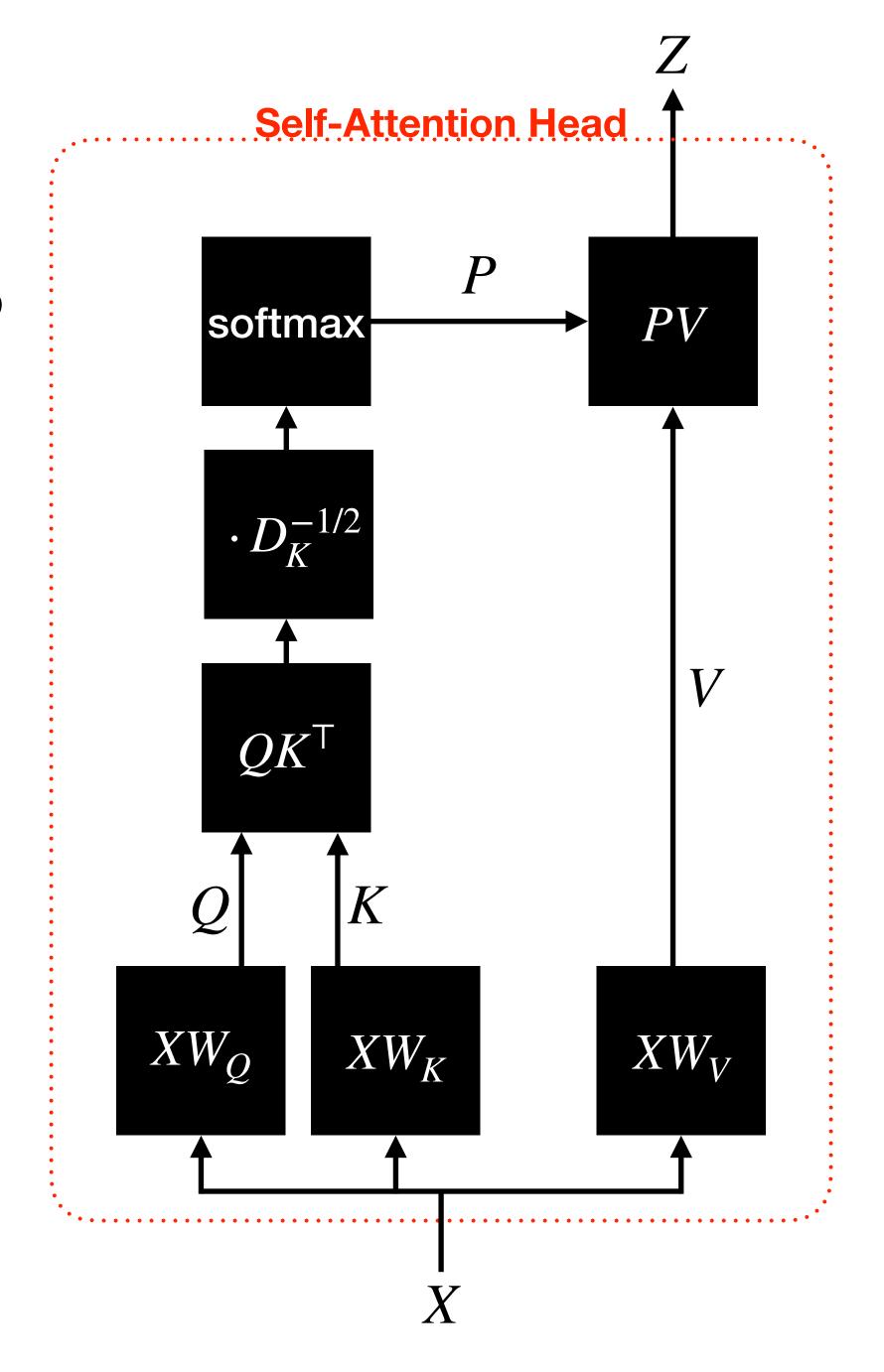
Define K, Q, V from the **same** input sequence  $X \in \mathbb{R}^{T \times D}$ 

- Keys:  $K = XW_K \in \mathbb{R}^{T \times D_K}$
- Queries:  $Q = XW_Q \in \mathbb{R}^{T \times D_K}$
- Values:  $V = XW_V \in \mathbb{R}^{T \times D_V}$
- $ightharpoonup W_K$ ,  $W_Q \in \mathbb{R}^{T imes D_K}$ ,  $W_V \in \mathbb{R}^{T imes D_V}$  are parameters

The output of self-attention is then given by:

$$Z = \operatorname{softmax} \left( \frac{QK^{\mathsf{T}}}{\sqrt{D_K}} \right) V$$

- ⇒ softmax(·) is applied row-wise
- ightharpoonup Quadratic computational complexity  $O(T^2)$



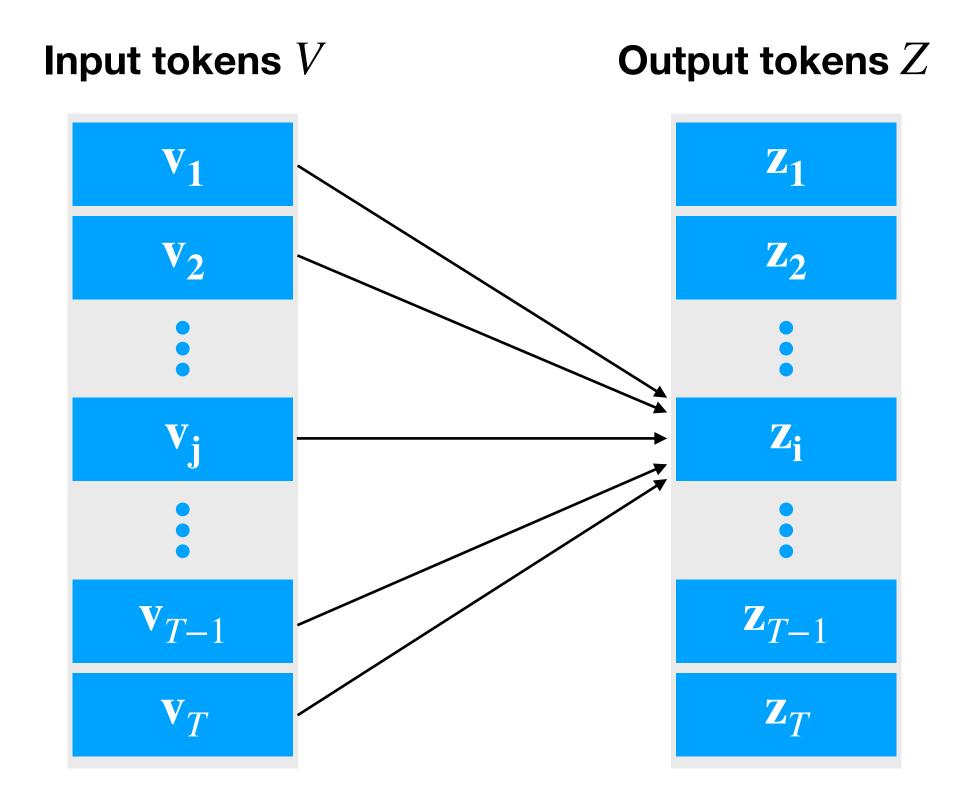
# Attention as a Weighted Average

- T input and output tokens:  $V \in \mathbb{R}^{T \times D_V}, Z \in \mathbb{R}^{T \times D}$
- Outputs are a weighted average of the inputs:

$$\mathbf{z_i} = \sum_{j=1}^{T} p_{i,j} \mathbf{v_j} \quad \text{or in matrix form } Z = PV$$

- Weighting coefficients  $P \in [0,1]^{T \times T}$  form valid probability distributions over the input tokens:

**Notation:** throughout this lecture, the j-th rows of V and Z are denoted by  $\mathbf{v}_i$  and  $\mathbf{z}_i$ 

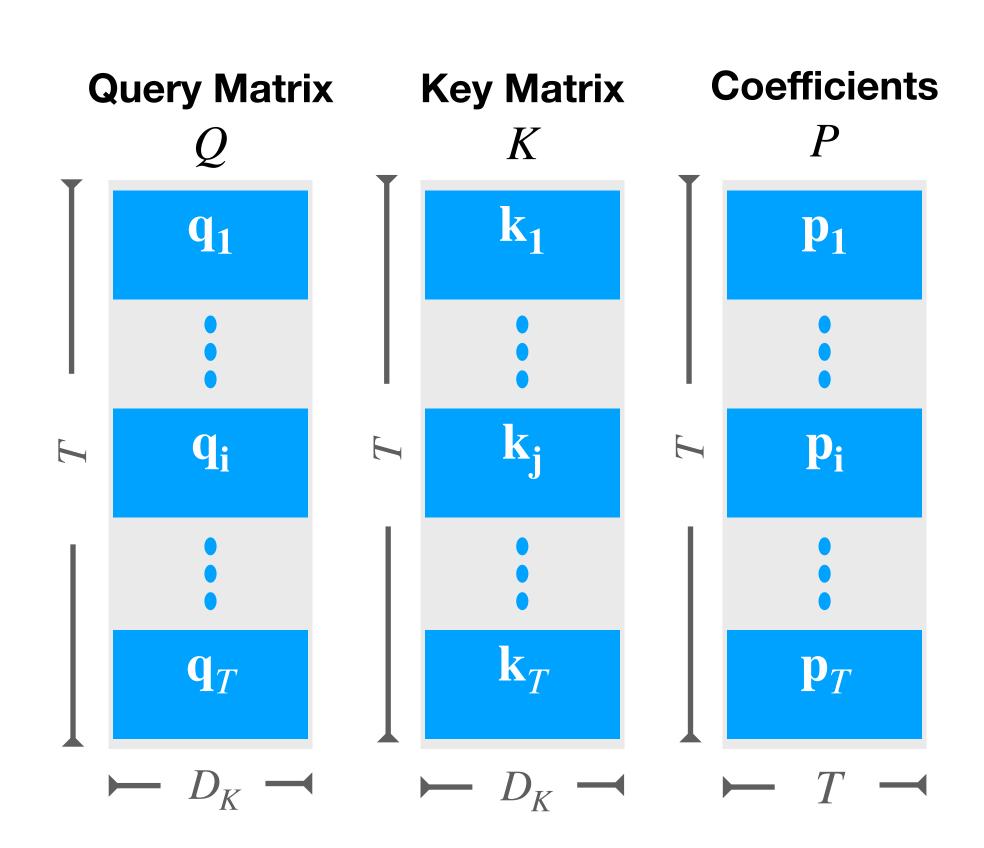


# The Weighting Coefficients P

- Query tokens  $Q \in \mathbb{R}^{T \times D_K}$  (one query per output token)
- **Key tokens**  $K \in \mathbb{R}^{T \times D_K}$  (one key per input token)
- Determine weight  $p_{i,j}$  based on how similar  $\mathbf{q}_i$  and  $\mathbf{k}_j$  are
  - Use inner product to obtain raw similarity scores
  - Normalize with softmax (scaled the temperature by  $\sqrt{D_K}$ ) to obtain a probability distribution
- This can be expressed as:

Element-wise: 
$$p_{i,j} = \frac{\exp\left(\mathbf{q}_{i} \mathbf{k}_{j}^{\top} / \sqrt{D_{K}}\right)}{\sum_{t=1}^{T} \exp\left(\mathbf{q}_{i} \mathbf{k}_{t}^{\top} / \sqrt{D_{K}}\right)}$$

**Matrix form:** 
$$P = \operatorname{softmax} \left( \frac{QK^{\mathsf{T}}}{\sqrt{D_K}} \right)$$
 The softmax is applied on each row *independently*



#### Computation complexity:

$$O(T \times T)$$

# The Weighting Coefficients P

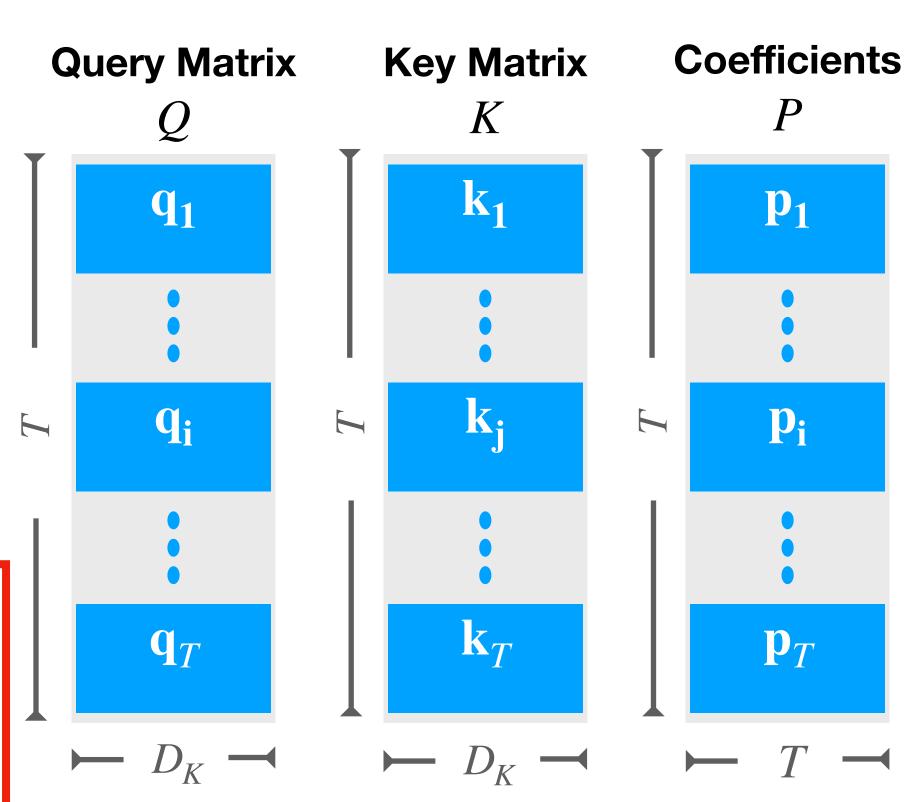
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  - Use inner product to obtain raw similarity scores
  - Normalize with softmax (scaled the temperature by  $\sqrt{D_{\it K}}$ ) to obtain a probability distribution

In some applications, causal masking is used:

Sum until position 
$$i$$
:  $p_{i,j} = \frac{\exp\left(\mathbf{q}_i \mathbf{k}_j^{\top} / \sqrt{D_K}\right)}{\sum_{t=1}^{i} \exp\left(\mathbf{q}_i \mathbf{k}_t^{\top} / \sqrt{D_K}\right)}$  for  $j \leq i$  and  $p_{i,j} = 0$  otherwise

Mask before softmax: 
$$P = \operatorname{softmax} \left( \frac{M}{\sqrt{D_K}} \right)$$

where  $M \in \mathbb{R}^{T \times T}$  is the matrix  $M_{ij} = -\infty$  for j > i and  $M_{i,j} = 0$  otherwise



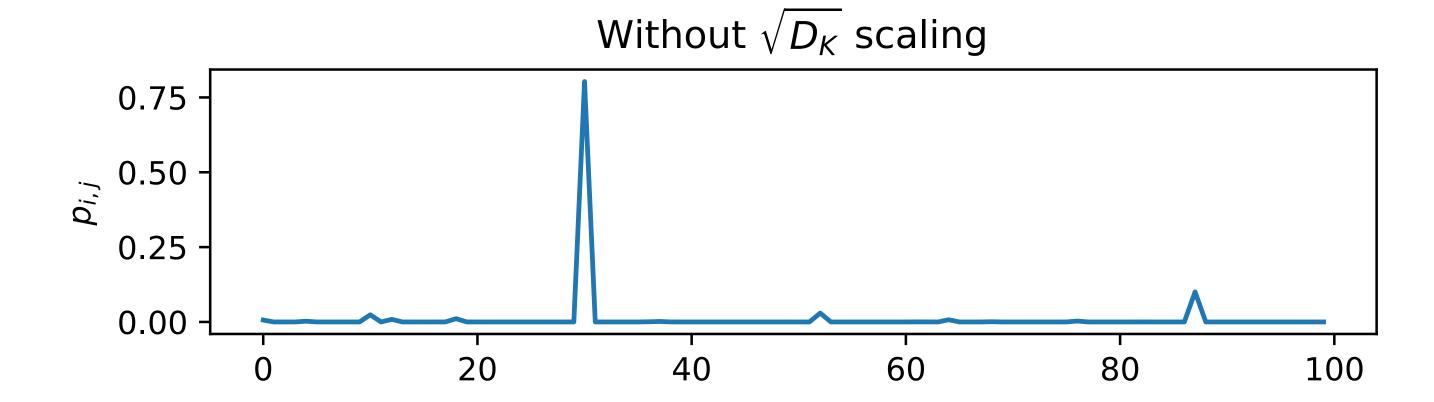
#### Computation complexity:

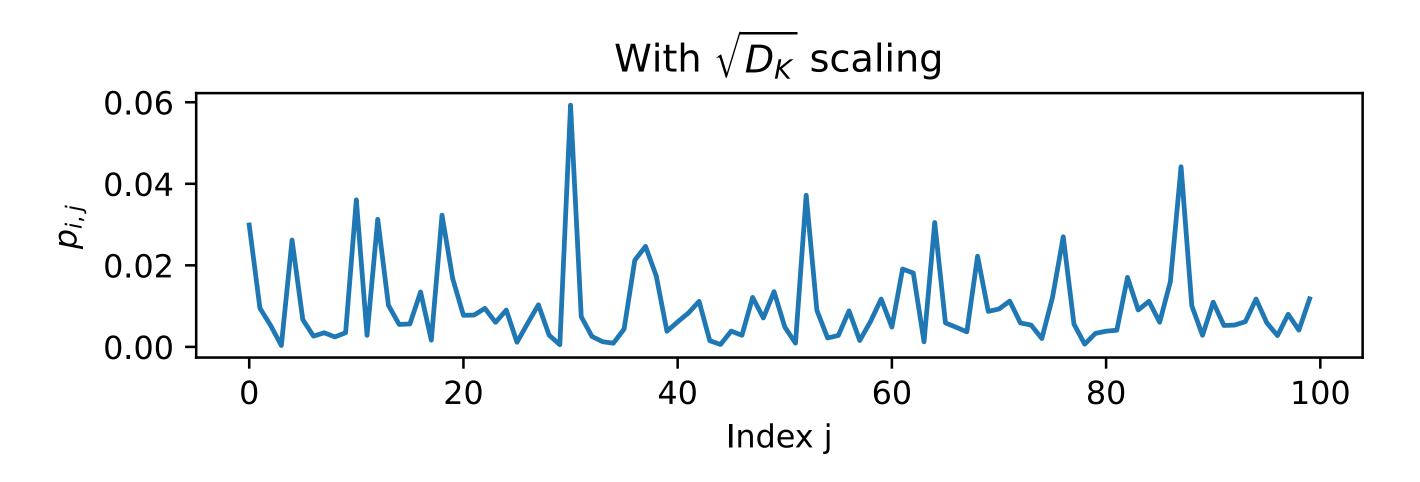
$$O(T \times T)$$

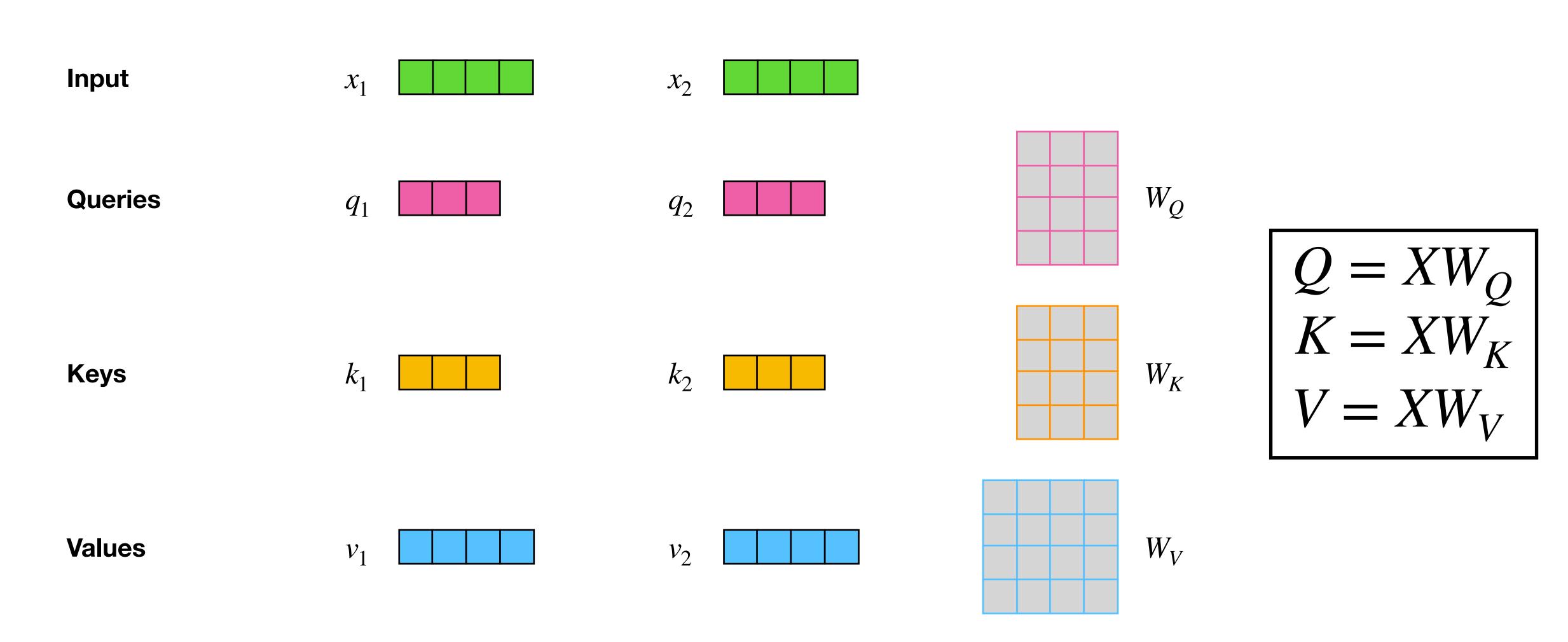
# Why Use the $1/\sqrt{D_K}$ Scaling?

$$P = \operatorname{softmax} \left( \frac{QK^{\top}}{\sqrt{D_K}} \right)$$

- Without scaling: sharp distribution of the attention weights  $p_{i,j}$  at random initialization
- The model takes much more time to adjust from the initial peak due to vanishing gradients
- The  $1/\sqrt{D_K}$  scaling ensures uniformity at initialization and faster convergence







Multiplying the input by the Q/K/V weight matrices, we create a query, a key and a value projection of each input of the input sequence

Input

Queries

Keys

**Values** 

 $c_1$ 

 $q_1$ 

 $k_1$ 

 $v_1$ 

 $x_2$ 

 $q_2$ 

 $k_2$ 

 $v_2$ 

Step 1: create query, key and value vectors for each input token

$$Q = XW_Q$$

$$K = XW_K$$

$$V = XW_V$$

Input

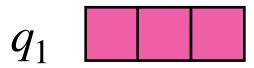
**Queries** 

Keys

**Values** 

Score





$$k_1$$

$$v_1$$

$$q_1 k_1^{\mathsf{T}} = 102$$

$$x_2$$

$$q_2$$

$$k_2$$

$$v_2$$

$$q_1 k_2^{\mathsf{T}} = 99$$

Step 2: calculate the scores by taking scalar product of the query and key vectors

$$QK^{\mathsf{T}} = XW_{Q}W_{K}^{\mathsf{T}}X^{\mathsf{T}}$$

Input

**Queries** 

Keys

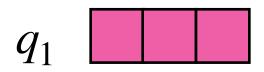
**Values** 

Score

Divide by  $\sqrt{D_K}$ 

**Softmax** 

$$x_1$$



$$k_1$$

$$v_1$$

$$q_1 k_1^{\mathsf{T}} = 102$$

$$\frac{q_1 k_1^{\mathsf{T}}}{\sqrt{D_K}} = 58.9$$

$$p_{1,1} = 0.85$$

$$x_2$$

$$q_2$$

$$\mathcal{K}_2$$

$$v_2$$

$$q_1 k_2^{\mathsf{T}} = 99$$

$$\frac{q_1 k_2^{\mathsf{T}}}{\sqrt{D_K}} = 57.2$$

$$p_{1,2} = 0.15$$

Step 3: divide the scores by 
$$\sqrt{D_K}$$

**Step 4: Compute the softmax of these values** 

$$P = \operatorname{softmax} \left( \frac{QK^{\top}}{\sqrt{D_K}} \right)$$

Input

**Queries** 

Keys

**Values** 

Score

Divide by  $\sqrt{D_K}$ 

**Softmax** 

Softmax\*Value

Sum





$$k_1$$

$$v_1$$

$$q_1 k_1^{\mathsf{T}} = 102$$

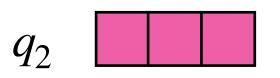
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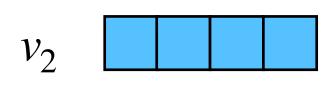
$$p_{1,1}v_1$$

$$z_1$$

$$x_2$$



$$k_2$$



$$q_1 k_2^{\mathsf{T}} = 99$$

$$\frac{q_1 k_2^{\mathsf{T}}}{\sqrt{D_K}} = 57.2$$

$$p_{1,2} = 0.15$$

$$p_{1,2}v_2$$

$$z_2$$

Step 5: Multiply each value vector

by the softmax score

Step 6: Sum up the weighted value vectors

Input

**Queries** 

Keys

**Values** 

Score

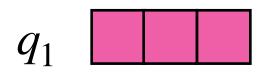
Divide by  $\sqrt{D_K}$ 

**Softmax** 

Softmax\*Value

Sum

$$x_1$$



$$k_1$$

$$v_1$$

$$q_1 k_1^{\mathsf{T}} = 102$$

$$\frac{q_1 k_1^{\mathsf{T}}}{\sqrt{D_K}} = 58.9$$

$$p_{1,1} = 0.85$$

$$p_{1,1}v_1$$

$$z_1$$

$$x_2$$

$$q_2$$

$$k_2$$

$$v_2$$

$$q_1 k_2^{\mathsf{T}} = 99$$

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$$p_{1,2} = 0.15$$

$$p_{1,2}v_2$$

$$\frac{q_1 k_2^{\mathsf{T}}}{\sqrt{D_K}} = 57.2$$
 
$$p_{1,2} = 0.15$$
 
$$Z = \mathsf{softmax} \left( \frac{X W_Q W_K^{\mathsf{T}} X^{\mathsf{T}}}{\sqrt{D_K}} \right) X W_V$$

### Multi-Head Self-Attention

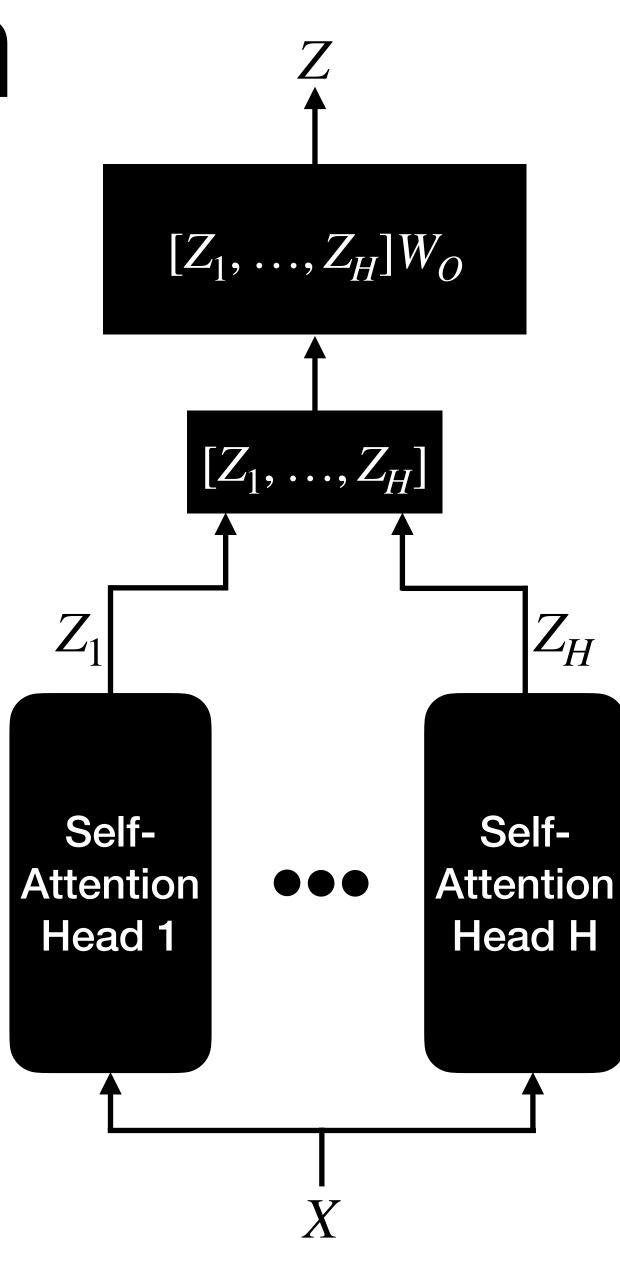
- It is desirable to have multiple attention patterns per layer, similar to having multiple convolutions in a convolutional layer
  - → Run *H* Self-Attention "heads" in parallel
- The output of head h is given by:

$$Z_h = \operatorname{softmax} \left( \frac{XW_{Q,h}W_{K,h}^{\top}X^{\top}}{\sqrt{D_K}} \right) XW_{V,h}$$
 
$$W_{V,h} \in \mathbb{R}^{D \times D_V}, W_{K,h} \in \mathbb{R}^{D \times D_K}, W_{O,h} \in \mathbb{R}^{D \times D_K}$$

 The final output is obtained by concatenating head-outputs and applying a linear transformation

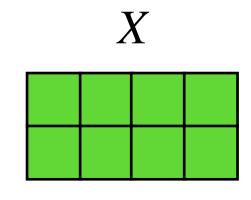
$$Z = [Z_1, \dots, Z_H]W_O$$

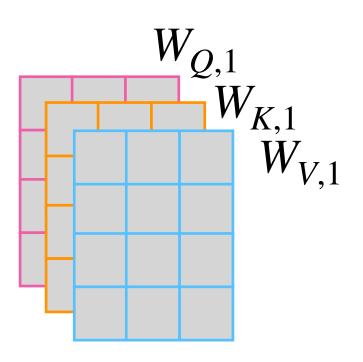
where  $W_O \in \mathbb{R}^{HD_V \times D}$  is learned via backpropagation

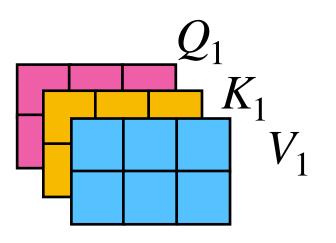


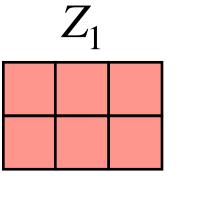
# Multi-Head Self-Attention: recap

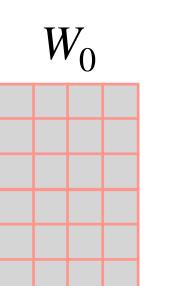
- 1) Input
- 2) Split into H heads We multiply X by weight matrices
- 3) Calculate attention using the resulting  $Q_h, K_h, V_h$  matrices
- 4) Concatenate the resulting matrices  $Z_h$ and multiply by  $W_0$  to obtain the final output Z of the self-attention layer

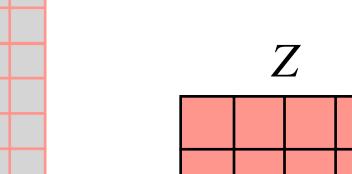


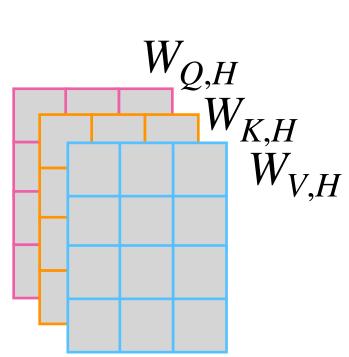


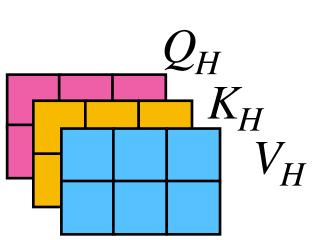


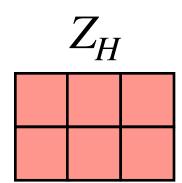












### Positional information

#### Attention does not account for the order of input

For a permutation matrix  $R \in \{0,1\}^{T \times T}$  we have:

$$\begin{split} Z_R &= \operatorname{softmax} \left( \frac{RXW_Q W_K^\top X^\top R^\top}{\sqrt{D_K}} \right) RXW_V & \text{Permute every X in original formula} \\ &= R\operatorname{softmax} \left( \frac{XW_Q W_K^\top X^\top R^\top}{\sqrt{D_K}} \right) RXW_V & \text{Since softmax is computed row-wise} \\ &= R\operatorname{softmax} \left( \frac{XW_Q W_K^\top X^\top}{\sqrt{D_K}} \right) R^\top RXW_V & \text{Reordering the terms in the softmax sum does not affect the output} \\ &= RPR^{-1}RXW_V & \text{For a permutation matrix: transpose=inverse} \\ &= RPXW_V \end{split}$$

Which is equivalent to a permutation of the original output Z = PV

#### Positional Information in Transformers

- In practice, the input order matters:
   "She prefers cats to dogs" ≠ "She prefers dogs to cats"
- Solution: incorporate a positional encoding in the network which is a function from the position to a feature vector pos :  $\{1,...,T\} \to \mathbb{R}^D$
- The most basic choice is to add a positional embedding  $W_{\text{pos}}$  corresponding to each token's position t to the input embedding.  $W_{\text{pos}} \in \mathbb{R}^{T \times D}$  is learned via backpropagation along with the other parameters:

$$\mathbf{X} = \begin{bmatrix} \mathbf{e}_{i_1}^{\mathsf{T}} \\ \vdots \\ \mathbf{e}_{i_T}^{\mathsf{T}} \end{bmatrix} \mathbf{W}_{\mathsf{emb}} + \begin{bmatrix} \mathbf{e}_1^{\mathsf{T}} \\ \vdots \\ \mathbf{e}_T^{\mathsf{T}} \end{bmatrix} \mathbf{W}_{\mathsf{pos}}$$

Numerous hand-crafted positional encodings exist (active area of research!)

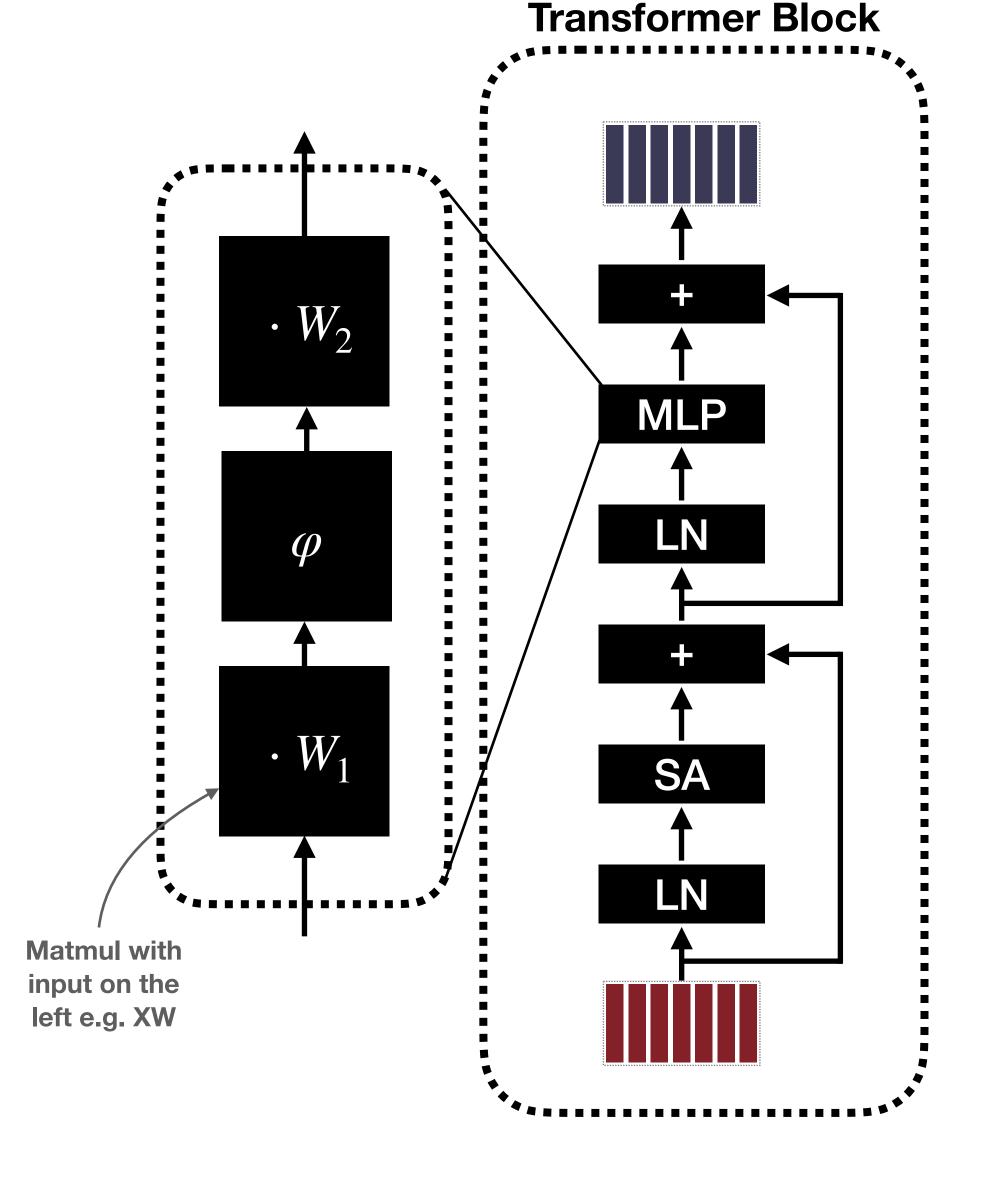
### MLP

### Mixing Information within Tokens

- MLP mixes information within each token
- Apply the same transformation to each token independently:

$$MLP(X) = \varphi(XW_1)W_2$$

- Matrices  $W_1, W_2 \in \mathbb{R}^{D \times D}$  learned via backprop
- Non-linearity  $\varphi$  in between (e.g., ReLU or GeLU)
- The model may also include learned bias terms



## Mixing Information within Tokens

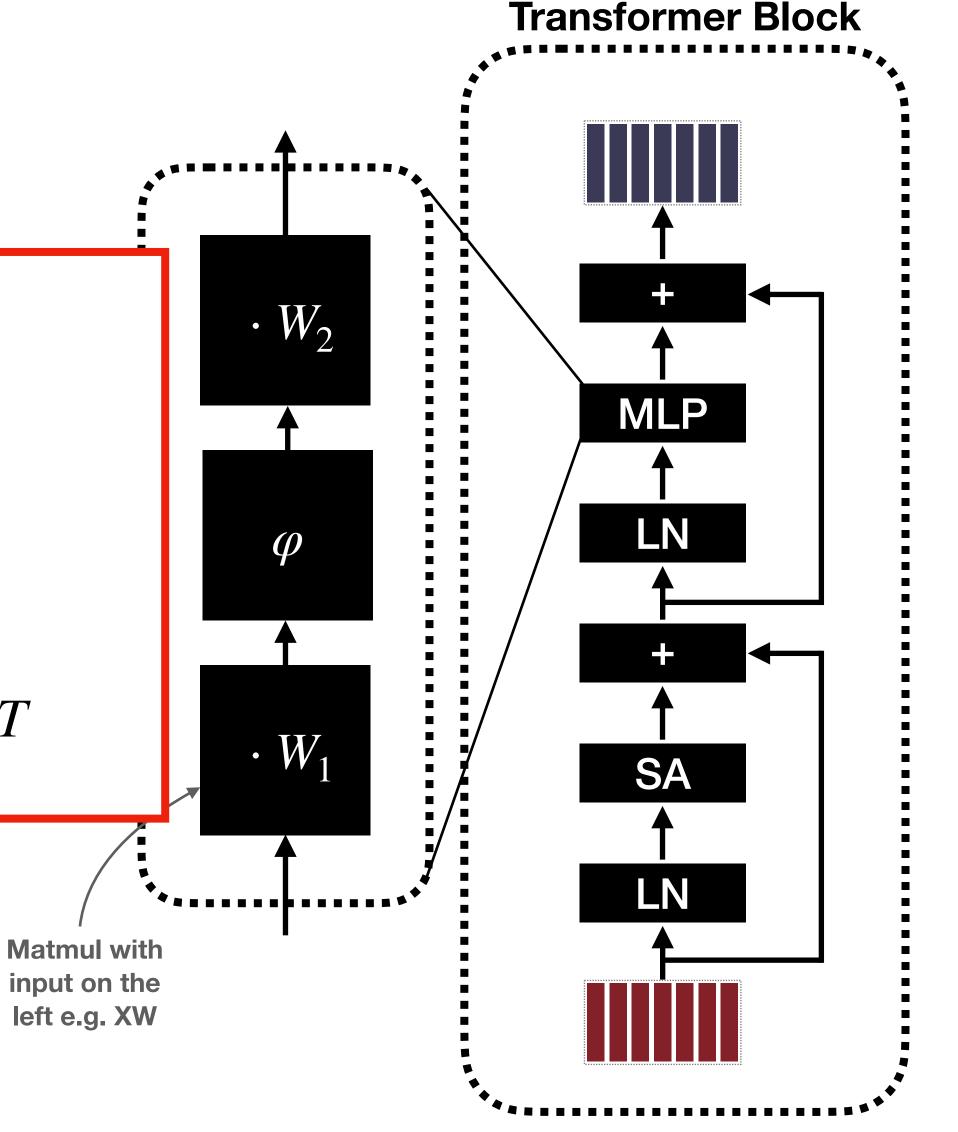
• MLP mixes information within each token

#### The same MLP is applied to each token:

$$MLP(X) = \varphi(XW_1)W_2$$

$$MLP(x_i) = \varphi(x_iW_1)W_2$$
, for each token  $x_1, ..., x_T$ 

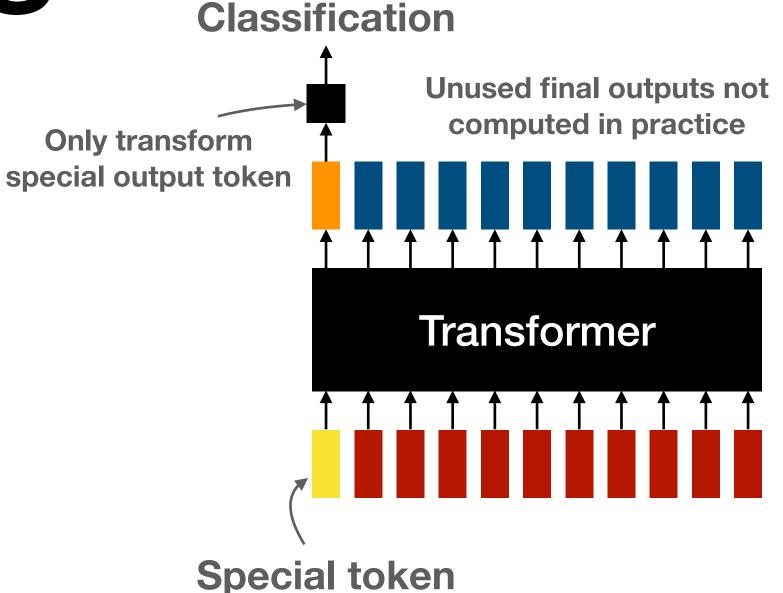
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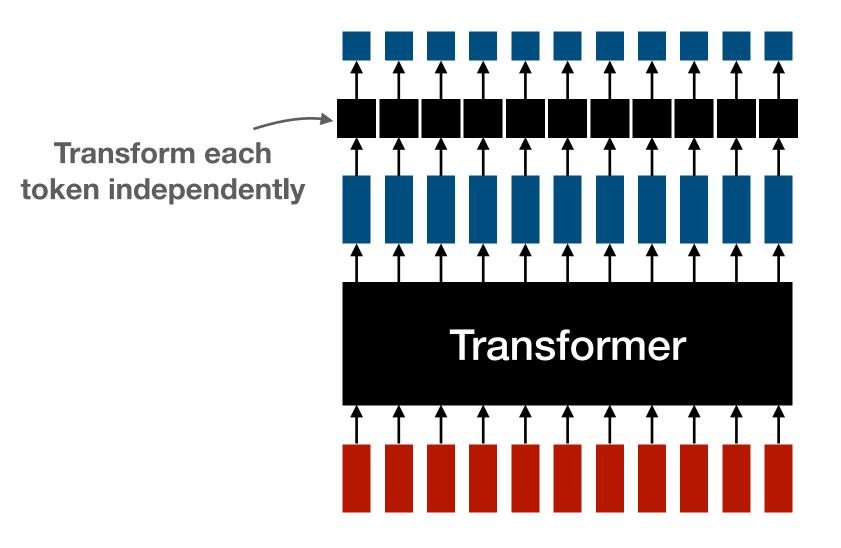


# Output Transformations

# Output Transformations

- We obtain the output from the final transformer block
- Output transformation is typically simple: linear transformation or a small MLP
- The specifics are highly dependent on the task:
  - Single output (e.g., sequence-level classification): apply an output transformation to a special task-specific input token or to the average of all tokens
  - Multiple outputs (e.g., per-token classification): apply an output transformation to each token independently

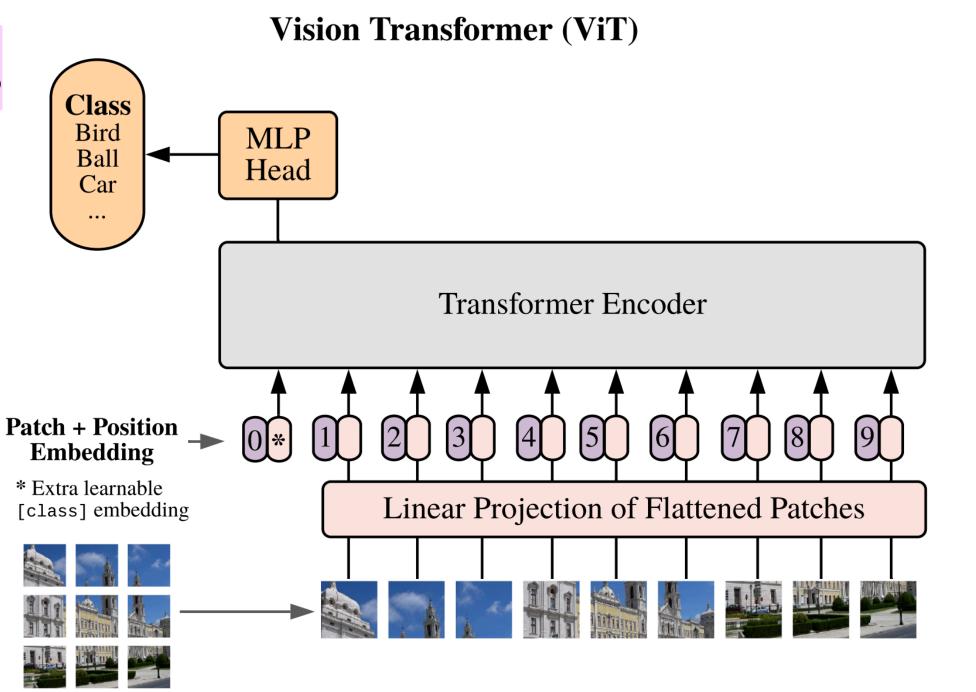


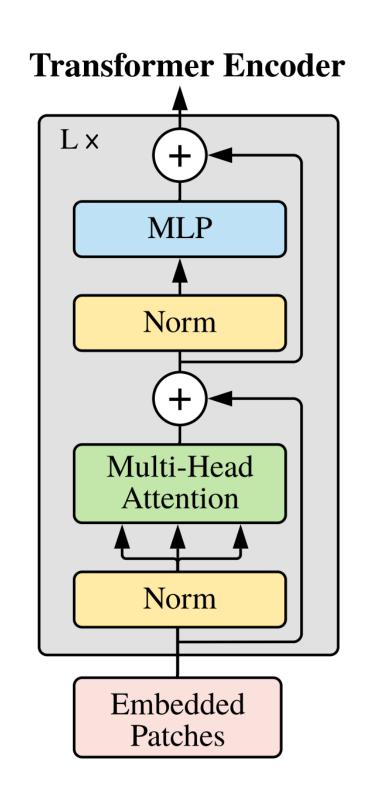


# Putting the pieces together: Vision Transformers

#### Vision Transformer Architecture

- Simple architecture: number of features D is constant across all layers. There is no use of padding, pooling, or strides.
- Self-attention is more general than convolution and can express it
- The receptive field is the whole image after just one self-attention layer
- ViTs require more data than CNNs due to their reduced inductive bias in extracting local features
- However, ViTs become competitive with CNNs after large-scale pretraining

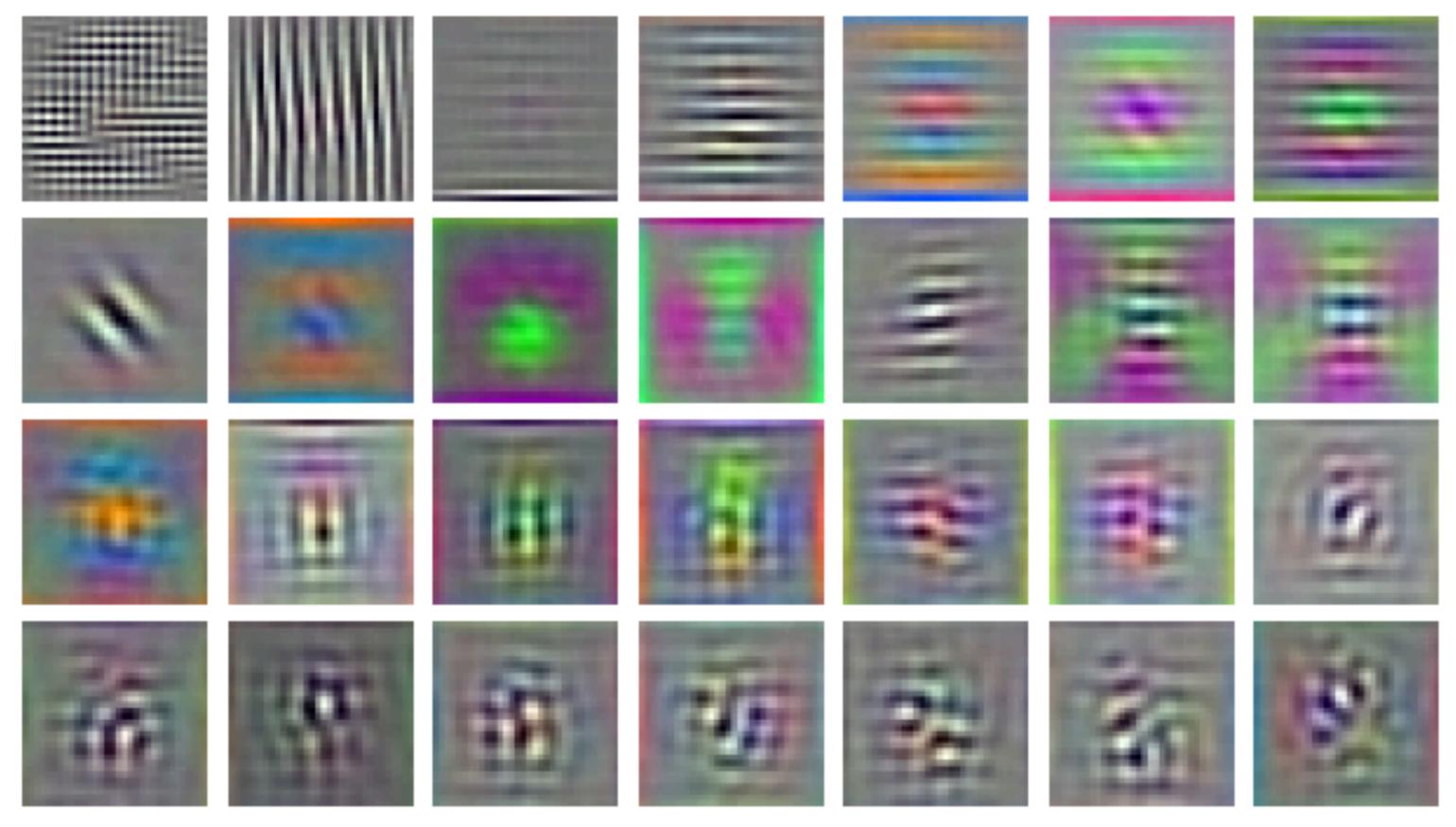




$$\begin{aligned} \mathbf{z}_0 &= [\mathbf{x}_{\text{class}}; \ \mathbf{x}_p^1 \mathbf{E}; \ \mathbf{x}_p^2 \mathbf{E}; \cdots; \ \mathbf{x}_p^N \mathbf{E}] + \mathbf{E}_{pos}, & \mathbf{E} \in \mathbb{R}^{(P^2 \cdot C) \times D}, \ \mathbf{E}_{pos} \in \mathbb{R}^{(N+1) \times D} \\ \mathbf{z}'_{\ell} &= \text{MSA}(\text{LN}(\mathbf{z}_{\ell-1})) + \mathbf{z}_{\ell-1}, & \ell = 1 \dots L \\ \mathbf{z}_{\ell} &= \text{MLP}(\text{LN}(\mathbf{z}'_{\ell})) + \mathbf{z}'_{\ell}, & \ell = 1 \dots L \\ \mathbf{y} &= \text{LN}(\mathbf{z}_L^0) \end{aligned}$$

Source: An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale (ICLR 2020)

### What do ViTs learn: embedding layer



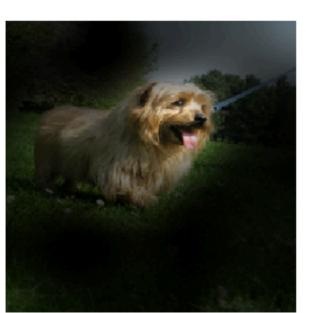
The first 28 principal components of the embedding layer applied on patches **Source**: An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale (ICLR 2020)

• The embedding layer: edge/color detectors similar to first-layer convolutions

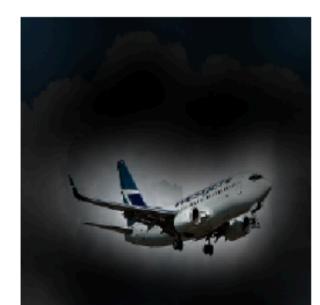
#### What do ViTs learn: attention

- The input-dependent attention weights can be visualized and manually inspected
- We show here one particular method known as <u>Attention Rollout</u>: where the attention weights are averaged across all heads and the resulting weight matrices of all layers are multiplied together
- This accounts for the mixing of attention across tokens through all layers
- In many cases, the model attends to image regions that are semantically relevant for classification











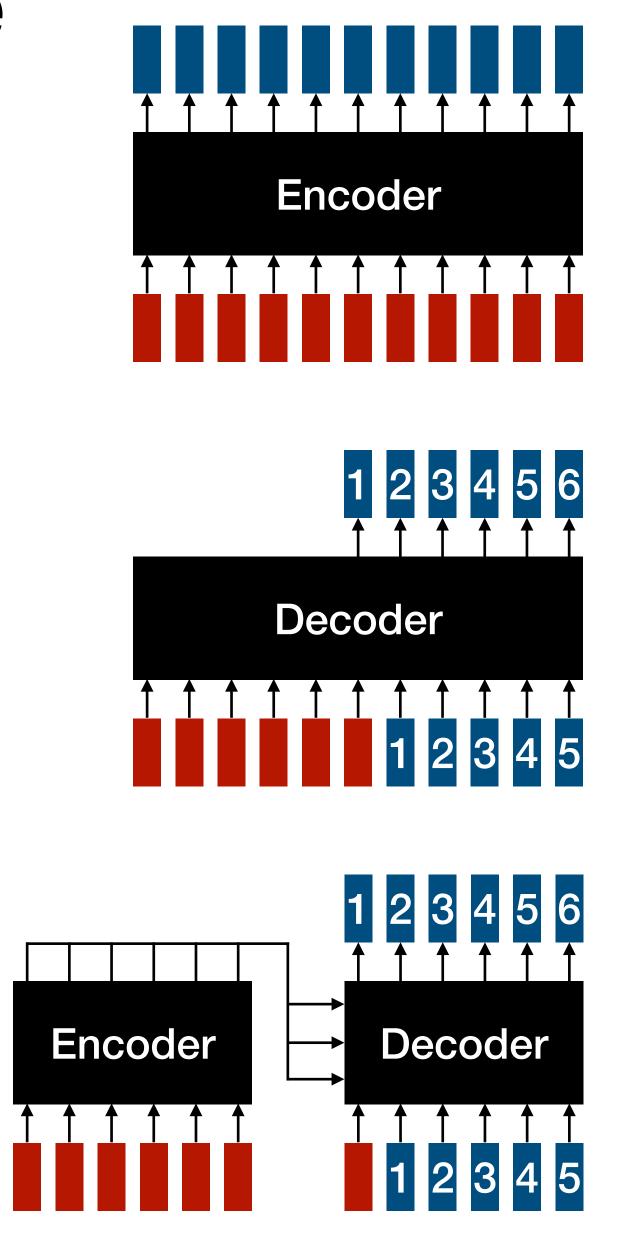


**Source**: An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale (ICLR 2020)

# The Big Picture and Takeaways

# The transformer architecture can be used in different ways

- Encoders (e.g., classification):
  - They produce a fixed output size and process all inputs simultaneously
- Decoders (e.g., ChatGPT):
  - Auto-regressively sample the next token as  $x_{t+1} \sim softmax(f(x_1, ..., x_t))$  and use it as new input token
  - Capable of generating responses of arbitrary length
- Encoder-decoder (e.g., translation):
  - First encode the whole input (e.g., in one language) and then decode to token by token (e.g., in a different language)



# Transformers: Big Picture

- Everything can be seen as a token, hence transformers are applicable across any modality
- CNNs can also be used for text processing, but transformers excel at capturing long-range dependencies (as an example, the latest GPT-4 model can process up to 128k input tokens, equivalent to ~300 pages of text).
- Self-attention scales quadratically with sequence length, making it computationally expensive for large volumes of text or numerous patches—active area of research
- However, self-attention is highly parallelizable, which is advantageous for multi-GPU or multi-node training setups
- Transformers are now the preferred method for both text and vision applications
- Emergent abilities at scale: few-shot learning (aka in-context learning from a few example) and zero-short learning (e.g., you can ask ChatGPT any question without prior training on the task)

# Recap

- Transformers iteratively map sequences to sequences using the self-attention mechanism
- The whole architecture is remarkably simple:
  - Self-attention blocks mix the information between tokens
  - MLP blocks mix the information within each token
- Transformers excel at modeling long-range dependencies
- Different architectures are possible (e.g., ChatGPT is decoder-only, but neural translation typically employs an encoder-decoder)
- Transformers have become a universal architecture for almost any type of data modality; they perform exceptionally well when given enough pretraining data

#### Additional Resources

If you want to learn more about attention and transformers:

- The Illustrated Transformer: <a href="https://jalammar.github.io/illustrated-transformer/">https://jalammar.github.io/illustrated-transformer/</a> (a good step-by-step guide with detailed illustrations)
- The blog of Lilian Weng (OpenAI): <a href="https://lilianweng.github.io/posts/2018-06-24-attention/">https://lilianweng.github.io/posts/2018-06-24-attention/</a> (from 2018 but covers well the history of the attention mechanism and its different versions)
- CS231n: Deep Learning for Computer Vision (Stanford): <a href="http://sca231n.stanford.edu/slides/2023/lecture-9.pdf">http://sca231n.stanford.edu/slides/2023/lecture-9.pdf</a> (more on positional encodings, masked self-attention, general attention, discussion of recurrent neural networks)
- Minimal implementation of GPT-2: <a href="https://github.com/karpathy/nanoGPT/">https://github.com/karpathy/nanoGPT/</a> (some things are just clearer in code)