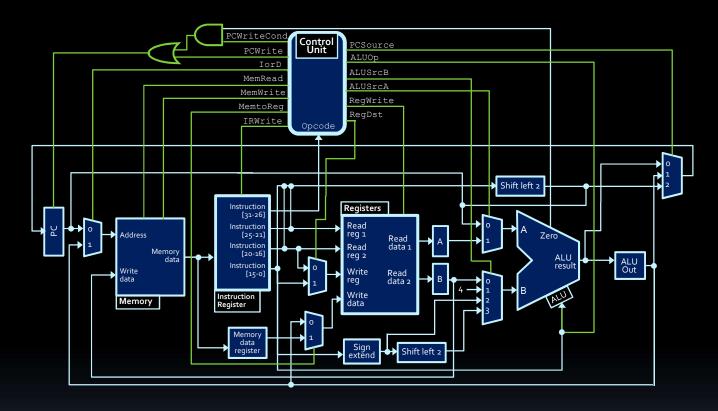
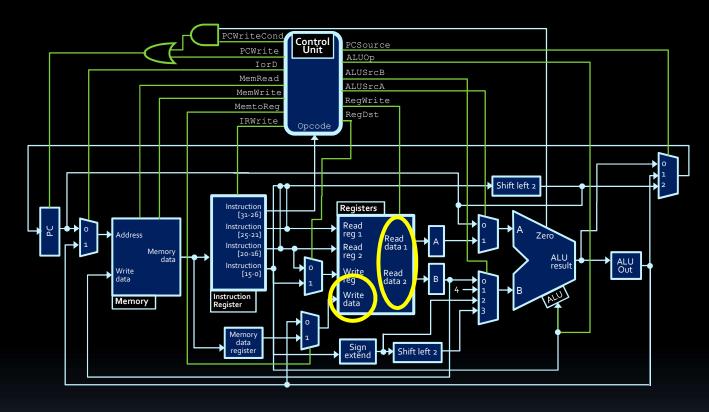
Week 9 Review



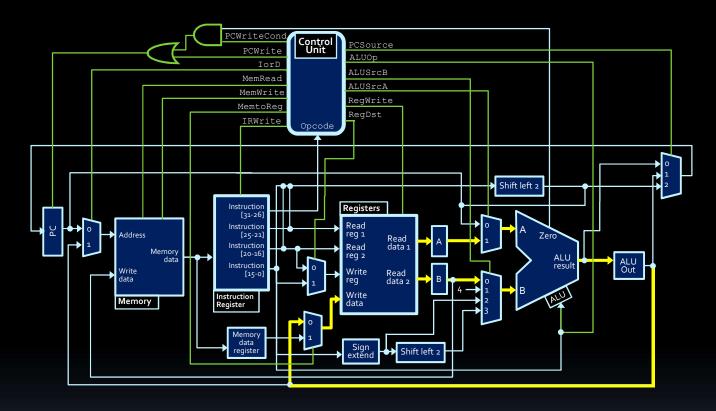
• Given the datapath above, what signals would the control unit turn on and off in order to add \$t1 to \$t2 and store the result in \$t7?

Basic approach

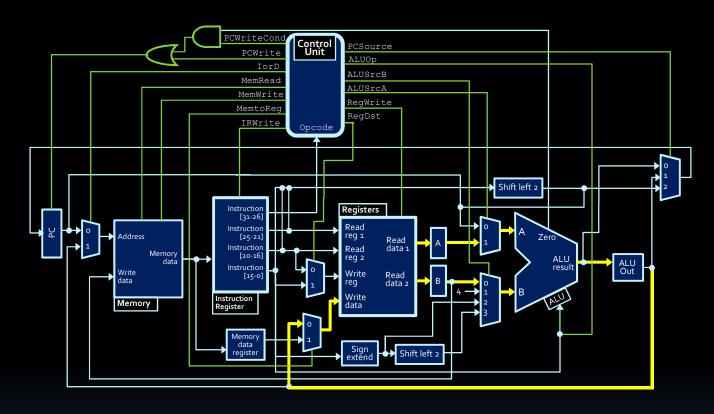
- 1. Figure out the data source(s) and destination.
- 2. Determine the path of the data.
- 3. Deduce the signal values that cause this path:
 - a) Start with Read & Write signals (at most one can be high at a time).
 - b) Then, mux signals along the data path.
 - c) Non-essential signals get an X value.



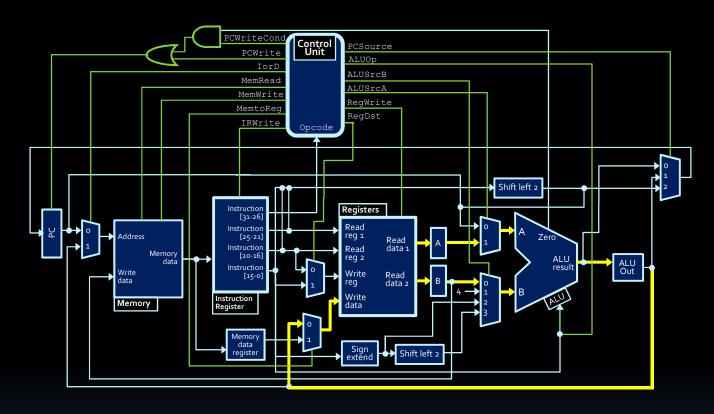
- Step #1: Data source and destination
 - Data starts in register block.
 - Data goes to register block.



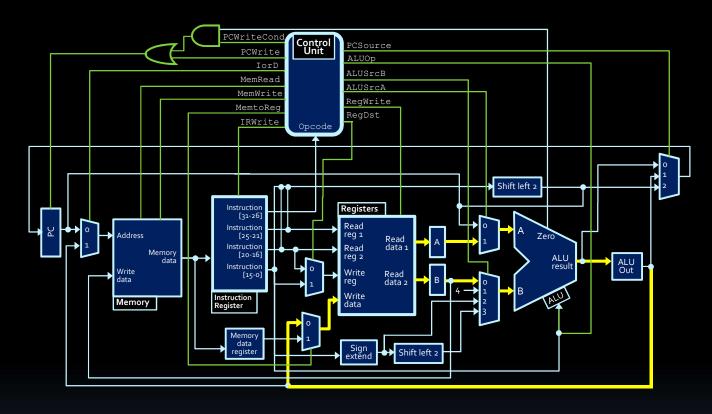
- Step #2: Determine the path of the data
 - Data needs to go through the ALU before heading back into the register file.



- Step #3a: Read & Write signals
 - Only RegWrite needs to be high.
 - PCWrite, PCWriteCond, MemRead, MemWrite, IRWrite would be low.



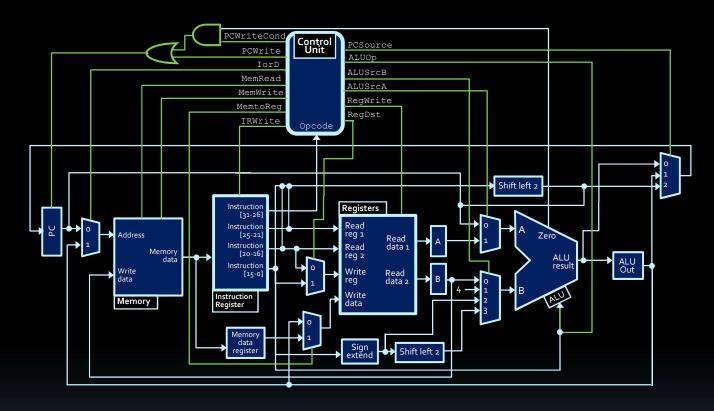
- Step #3b: Data path signals
 - Muxes before ALU: ALUSTCA → 1, ALUSTCB → 00.
 - ALUOp → 001 (Add)
 - Mux before registers: MemToReg > 0



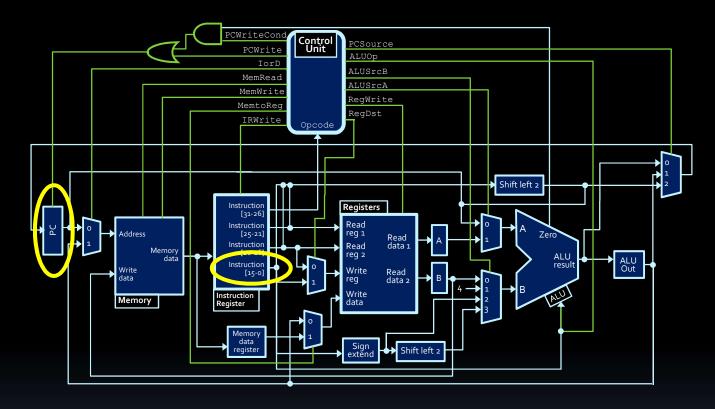
- Step #3c: Non-essential signals
 - No writing to PC: PCSource \rightarrow X.
 - No reading from memory: $IorD \rightarrow X$.

- PCWrite = 0
- PCWriteCond = X
- IorD = X
- MemRead = 0
- MemWrite = 0
- MemToReg = 0
- IRWrite = 0
- PCSource = X
- ALUOp = 001

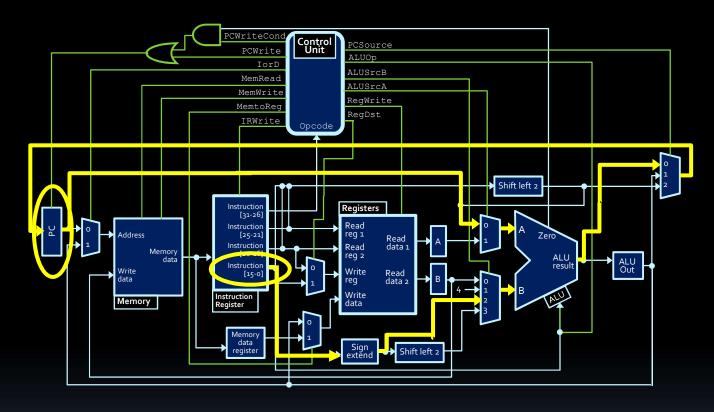
- \blacksquare ALUSTCA = 1
- ALUSTCB = 00
 - RegWrite = 1
 - RegDst = 1
 - Note: RegDst rule
 - high for 3-register operations
 - low for 2-register operations



• Given the datapath above, what signals would the control unit turn on and off in order to add 100 to the program counter?



- Step #1: Source and destination.
 - Program counter is both source and destination.
 - Immediate value from instruction is other source.

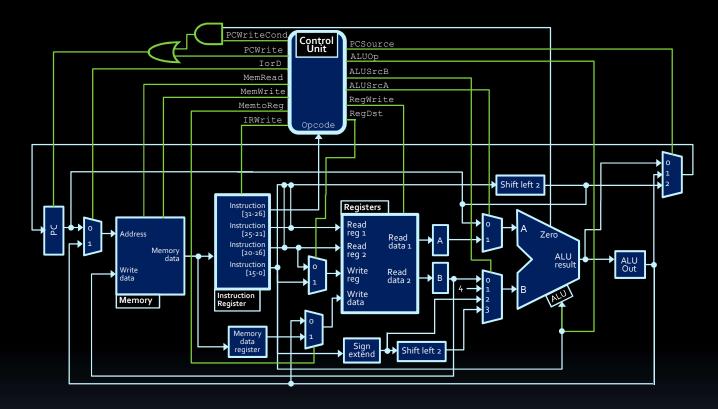


Step #2: Path between source and destination.

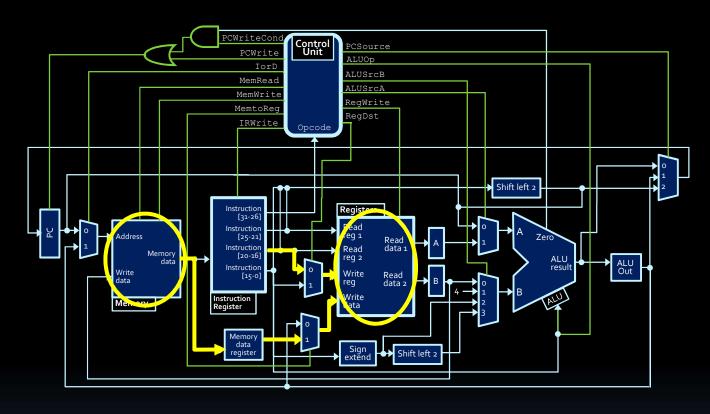
- Read / Write signals:
 - PCWrite high, all others low.
 - PCWriteCond is X, when PCWrite is high.
- Datapath signals:
 - \bullet ALUSrcA \rightarrow 0
 - ALUSrcB → 2 (100 is an immediate value; needs to come from the instruction)
 - □ PCSource → 0
- Non-essential signals:
 - IorD, MemToReg, RegDst

- PCWrite = 1
- PCWriteCond = X
- \blacksquare IorD = X
- MemRead = 0
- MemWrite = 0
- MemToReg = X
- IRWrite = 0

- PCSource = 0
- ALUOp = 001
- ALUSrcA = 0
- ALUSrcB = 10
- RegWrite = 0
- RegDst = X



• Given the datapath above, what signals would the control unit turn on and off in order to load a memory value into \$t0?



- Loading a memory value into \$t0
 - Step #1: Determine source and destination.
 - Step #2: Path between source and destination.
- Note: This assumes that the address of this memory location has already been sent to the memory unit as part of a previous instruction.

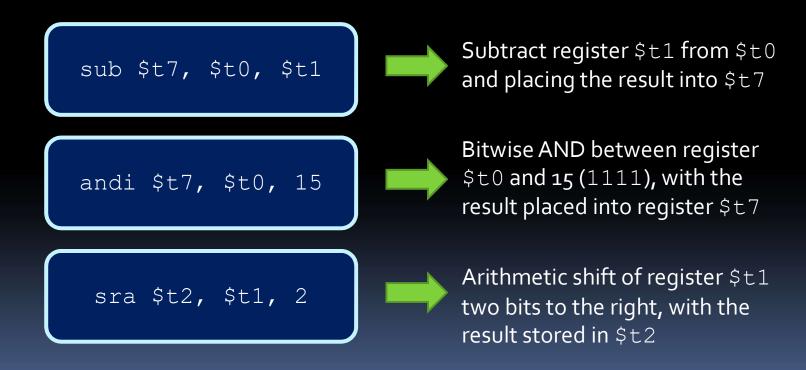
- Read / Write signals:
 - RegWrite and MemRead high, all others low.
- Datapath signals:
 - MemToReg → 1
 - RegDst → 0
- Non-essential signals:
 - IorD, PCSource, AluSrcA, AluSrcB

- PCWrite = 0
- PCWriteCond = 0
- \blacksquare IorD = X
- MemRead = 1
- MemWrite = 0
- MemToReg = 1
- IRWrite = 0

- PCSource = X
- \blacksquare ALUOp = XXX
- ALUSrcA = X
- ALUSTCB = XX
- RegWrite = 1
- RegDst = 0

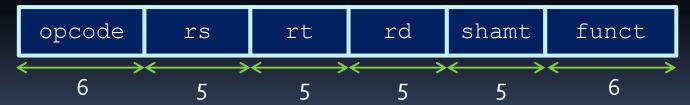
Note: The highlighted signals will have values if you choose to extend the hold of the memory address for the duration of the load operation.

• What are the following assembly language instructions doing?



How do you translate the following assembly language instruction into machine code?

R-type instruction!



add \$t7, \$t0, \$t1

- Step #1: The opcode
 - Arithmetic operations start with six 0's, and have the function identifier at the end.

000000 sssss ttttt ddddd XXXXX 100000

- Step #2: The register values
 - Remember that \$t0 does not translate to register 0
 - The temporary registers start at register 8, so \Rightarrow 8, \Rightarrow 9 and \Rightarrow 15

000000 01000 01001 01111 XXXXX 100000