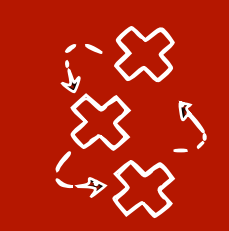


# Causal Data Science

## Lecture 10.2: Restricted models

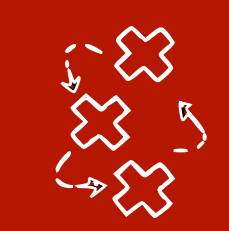
Lecturer: Sara Magliacane

UvA - Spring 2024



# Score-based causal discovery vs restricted models

- Similarly to constraint-based causal discovery, also GES returns a CPDAG
- Identification strategies are based on a known DAG
  - Add **background knowledge**
  - Add **experimental/interventional data (next week)**
  - Use advanced methods like IDA (Maathuis et al 2009) that combine the identification of each possible DAG in MEC into bounds
- Under some special assumptions, **we can recover the true causal graph:**
  - Nonlinear models with additive noise: Additive Noise Models (ANM)
  - Linear Non-Gaussian Acyclic Models (LINGAM)



# Causal discovery simplified overview

## Constraint-based causal discovery

- Conditional independence tests
- Observational data
- Output: MEC
- SGS, PC, FCI

## Score-based causal discovery

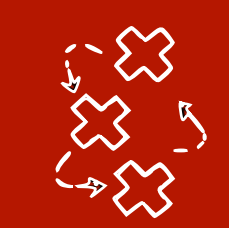
- Penalised likelihood
- Observational data
- Output: MEC
- GES, MMHC

## Restricted models

- Nonlinear additive noise, Linear Non-Gaussianity
- Observational data
- Output: DAG
- RESIT, LINGAM

## Interventional causal discovery / causal invariance

- Observational and Interventional data
- Output: parents of Y, I-MEC
- ICP, GIES, JCI

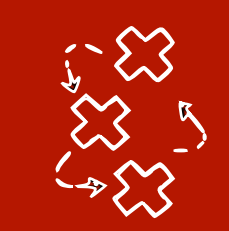


# Additive noise models (ANMs)

$$\begin{cases} X = \varepsilon_X \\ Y = f(X) + \varepsilon_Y \end{cases}$$
$$\varepsilon_X \perp\!\!\!\perp \varepsilon_Y$$

Here  $\varepsilon_i$  are not gaussian,  
but rather uniform

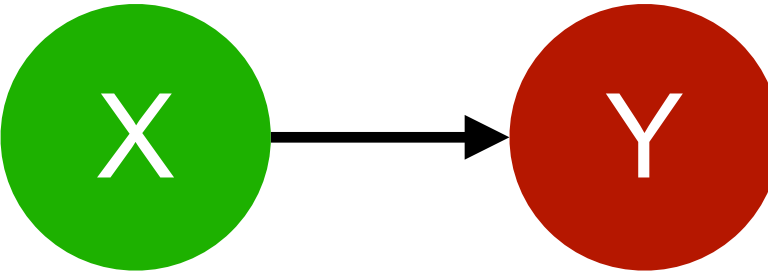




# Additive noise models (ANMs)

$$\begin{cases} X = \varepsilon_X \\ Y = f(X) + \varepsilon_Y \end{cases}$$

$\varepsilon_X \perp\!\!\!\perp \varepsilon_Y$



Here  $\varepsilon_i$  are not gaussian,  
but rather uniform

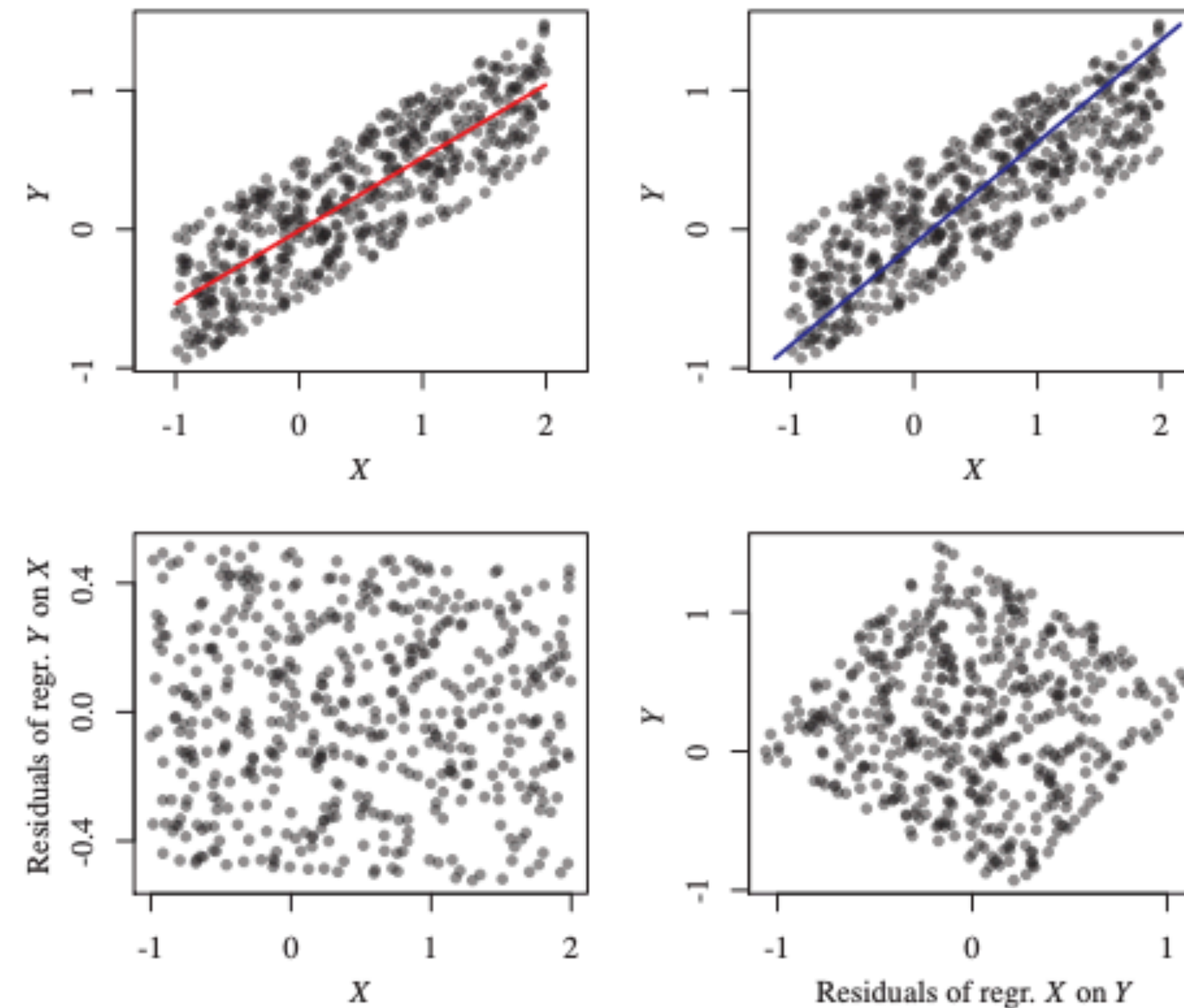
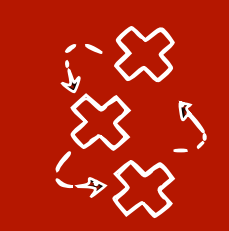


Figure 4.5: We are given a sample from the underlying distribution and perform a linear regression in the directions  $X \rightarrow Y$  (left) and  $Y \rightarrow X$  (right). The fitted functions are shown in the top row, the corresponding residuals are shown in the bottom row. Only the direction  $X \rightarrow Y$  yields independent residuals; see also Figure 4.1.



# Linear models with additive Gaussian noise

- If we have the linear SCM

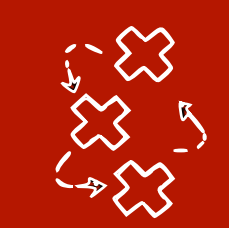
$$Y = \alpha X + \epsilon_Y \text{ such that } \epsilon_Y \perp\!\!\!\perp X$$

Then there exists a  $\beta \in \mathbb{R}$  and random variable  $\epsilon_X$  such that:

$$X = \beta Y + \epsilon_X \text{ such that } \epsilon_X \perp\!\!\!\perp Y$$

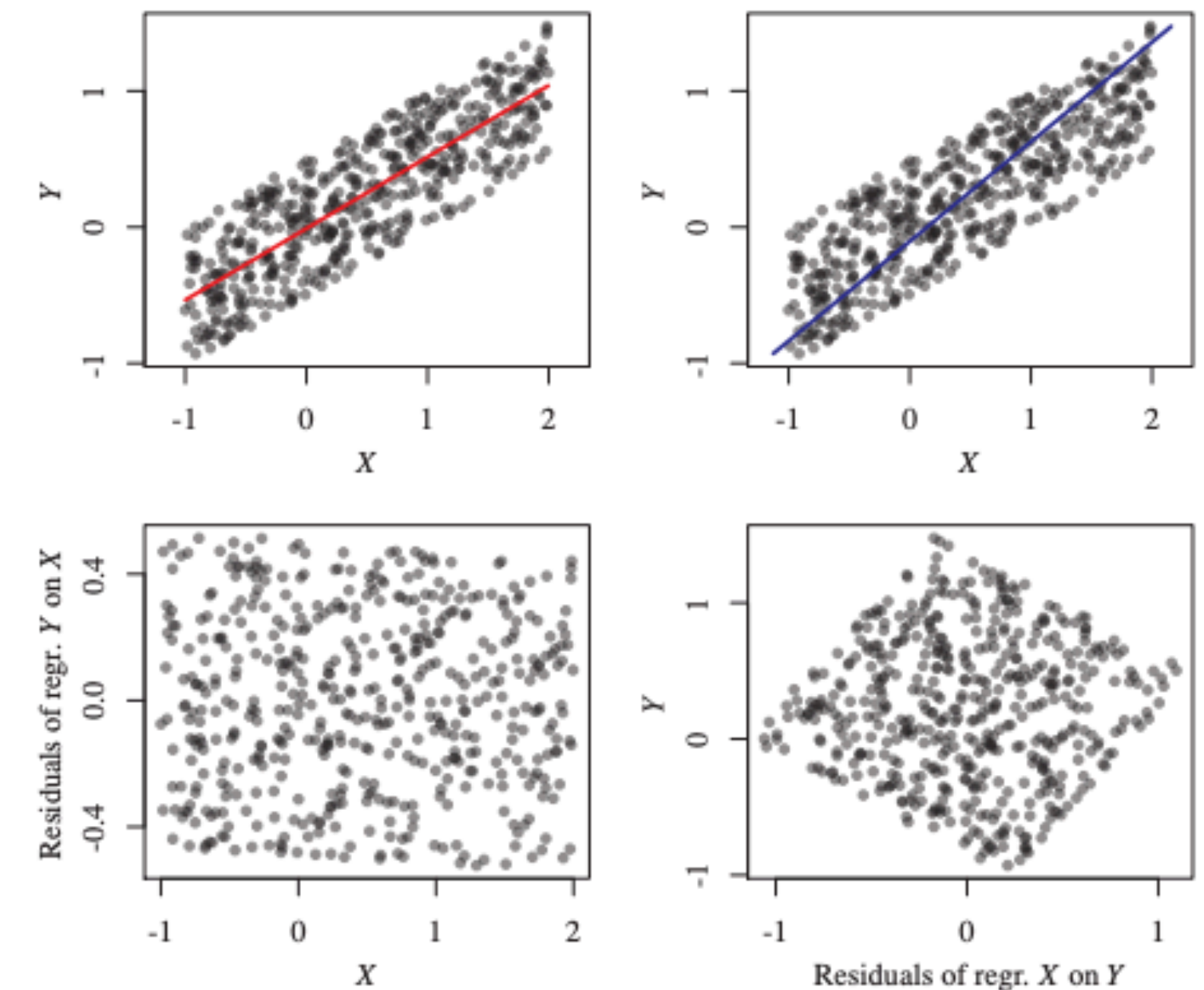
**if and only if  $\epsilon_Y$  and  $X$  are Gaussian**

*This means we cannot  
distinguish  $X \rightarrow Y$   
or  $Y \rightarrow X$ !*

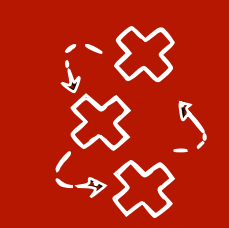


# RESIT: regression with subsequent independence test

1. Regress  $X$  on  $Y$  with (possibly nonlinear) regression and estimate  $\hat{f}_Y(X)$
2. Test if  $(Y - \hat{f}_Y(X))$  is independent of  $X$

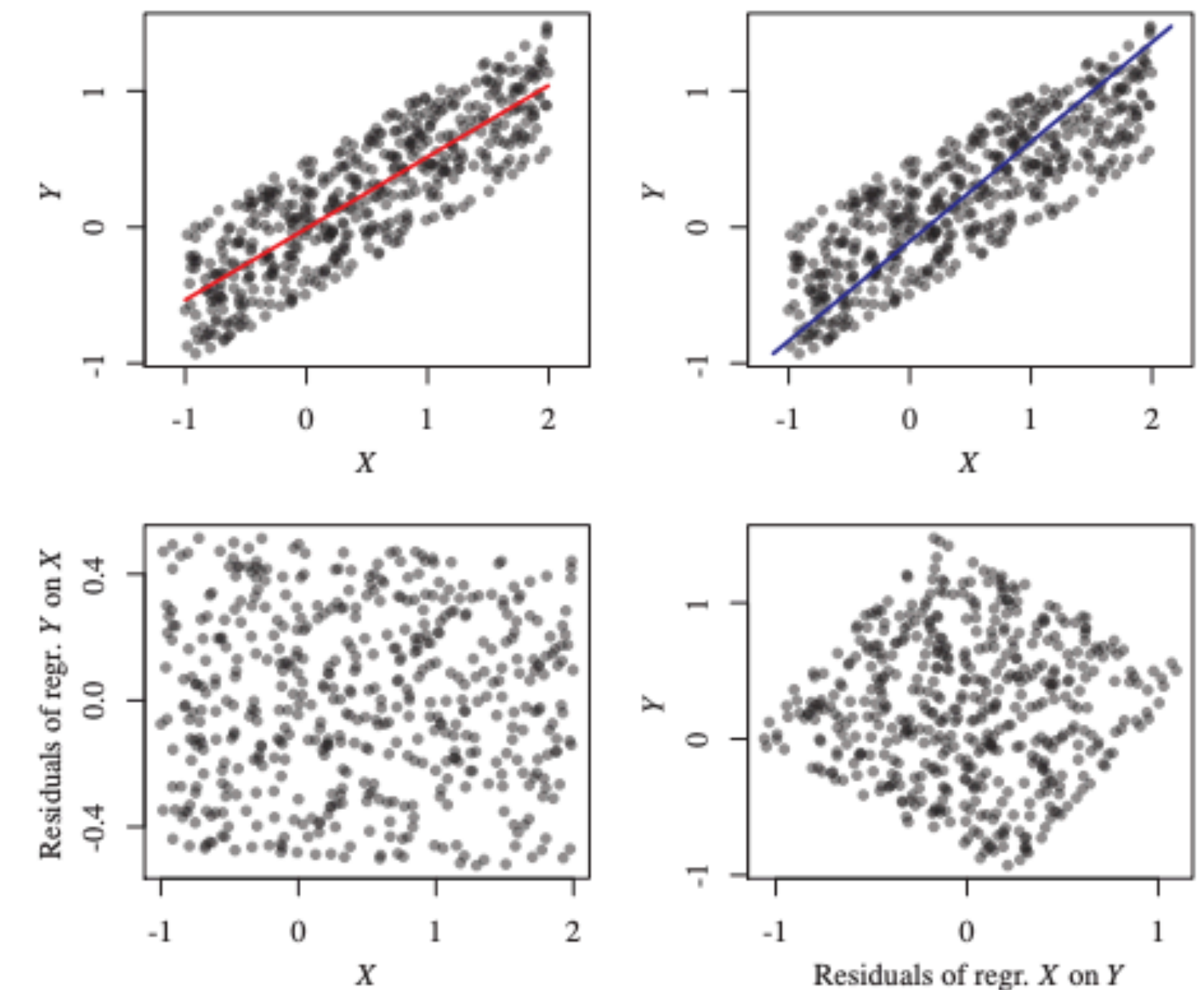






# RESIT: regression with subsequent independence test

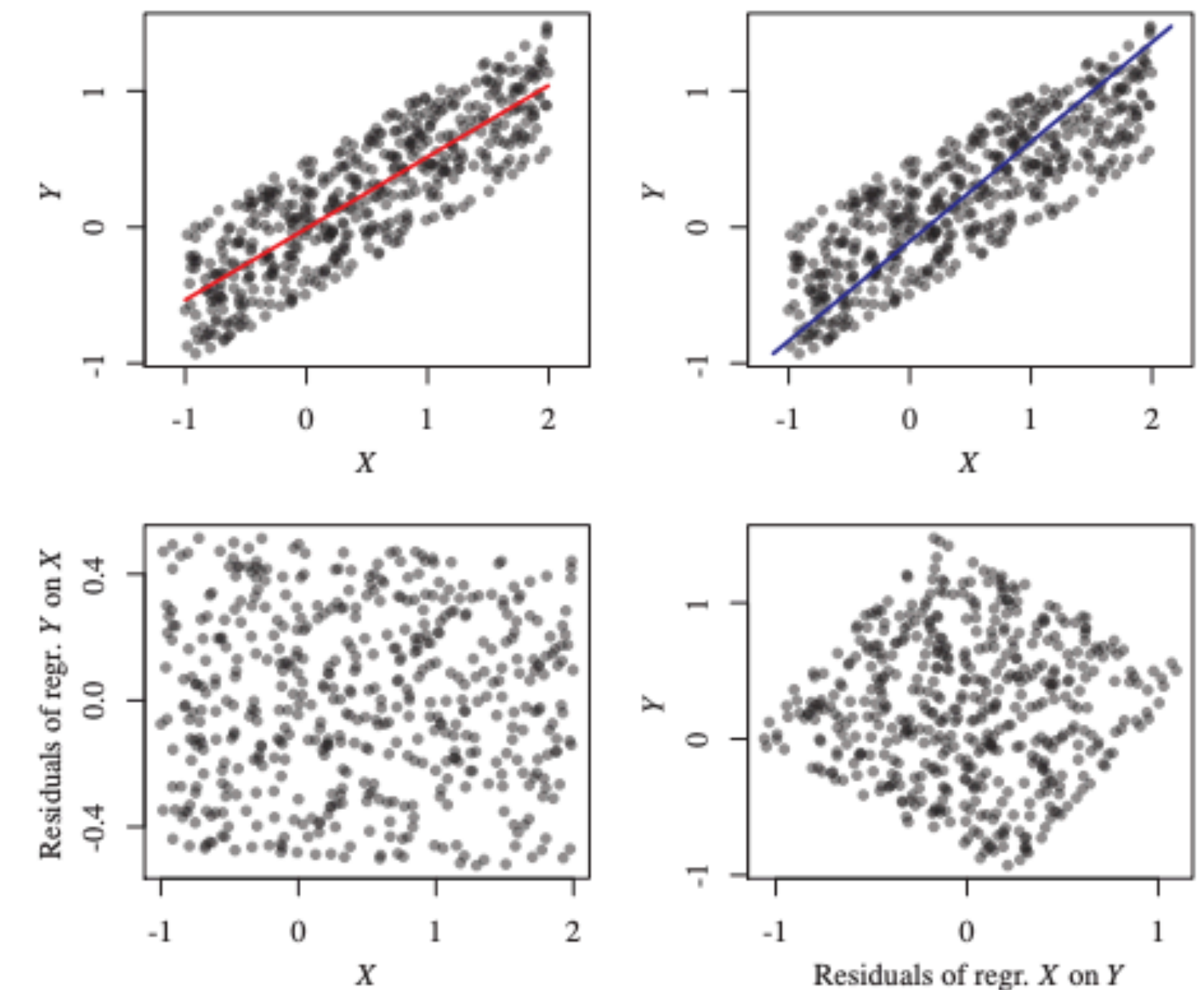
1. Regress  $X$  on  $Y$  with (possibly nonlinear) regression and estimate  $\hat{f}_Y(X)$
2. Test if  $(Y - \hat{f}_Y(X))$  is independent of  $X$
3. Regress  $Y$  on  $X$  with (possibly nonlinear) regression and estimate  $\hat{f}_X(Y)$
4. Test if  $(X - \hat{f}_X(Y))$  is independent of  $Y$

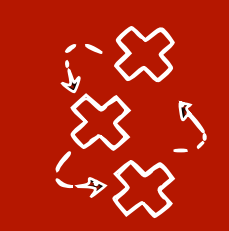




# RESIT: regression with subsequent independence test

1. Regress  $X$  on  $Y$  with (possibly nonlinear) regression and estimate  $\hat{f}_Y(X)$
2. Test if  $(Y - \hat{f}_Y(X))$  is independent of  $X$
3. Regress  $Y$  on  $X$  with (possibly nonlinear) regression and estimate  $\hat{f}_X(Y)$
4. Test if  $(X - \hat{f}_X(Y))$  is independent of  $Y$
5. If independence is rejected in only one direction, the other **independent** direction is **causal**





# Extensions

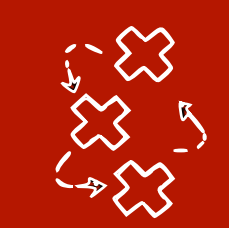
$$\begin{cases} X = \varepsilon_x \\ Y = f(X) + \varepsilon_y \end{cases}$$

$\varepsilon_x \perp\!\!\!\perp \varepsilon_y$

$$\begin{cases} X = \varepsilon_x \\ Y = g(f(X) + \varepsilon_y) \end{cases}$$

POST-LINEAR

For more details check Chapter 4 in the book: [http://web.math.ku.dk/~peters/jonas\\_files/ElementsOfCausalInference.pdf](http://web.math.ku.dk/~peters/jonas_files/ElementsOfCausalInference.pdf)

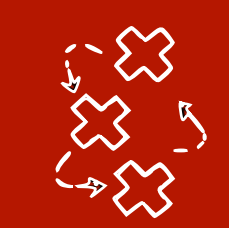


# Linear Non Gaussian Acyclic Models (LINGAM)

- We can write a linear SCM in matrix notation:

$$X = \mathbf{B}X + \varepsilon \text{ with } \mathbf{B} \in \mathbb{R}^{p \times p}, X \in \mathbb{R}^p, \varepsilon \in \mathbb{R}^p$$

- For Gaussian noise, we cannot distinguish the direction, but **for non-Gaussian noises we can**
  - Assume they are mean zero non Gaussian with positive variance
  - **We don't need faithfulness!** (So it can work on cancelling paths, etc)



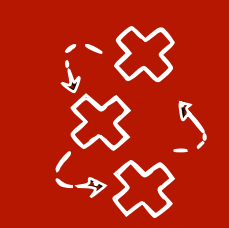
# Linear Non Gaussian Acyclic Models (LINGAM)

"position"

- For a DAG  $G$ , a bijective function  $\pi : \{1, \dots, p\} \rightarrow \{1, \dots, p\}$  is a (not necessarily unique) **causal ordering** if, for all  $i, j \in \{1, \dots, p\}$ :

$$\pi(i) < \pi(j) \text{ if } j \in \text{Desc}(i)$$





# Linear Non Gaussian Acyclic Models (LINGAM)

"position"

- For a DAG  $G$ , a bijective function  $\pi : \{1, \dots, p\} \rightarrow \{1, \dots, p\}$  is a (not necessarily unique) **causal ordering** if, for all  $i, j \in \{1, \dots, p\}$ :

$$\pi(i) < \pi(j) \text{ if } j \in \text{Desc}(i)$$

$$1 \rightarrow 2 \rightarrow 3$$

$$\pi(1) = 1$$

$$\pi(2) = 2$$

$$\pi(3) = 3$$

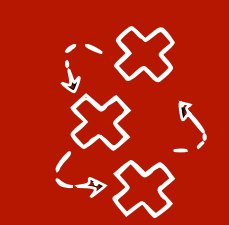
$$3 \rightarrow 2 \rightarrow 1$$

$$\pi(3) = 1$$

$$\pi(2) = 2$$

$$\pi(1) = 3$$

BECAUSE ACYCLICITY AT LEAST  
ONE CAUSAL ORDERING EXISTS.



# Linear Non Gaussian Acyclic Models (LINGAM)

"position"

- For a DAG  $G$ , a bijective function  $\pi : \{1, \dots, p\} \rightarrow \{1, \dots, p\}$  is a (not necessarily unique) **causal ordering** if, for all  $i, j \in \{1, \dots, p\}$ :

$$\pi(i) < \pi(j) \text{ if } j \in \text{Desc}(i)$$

$$1 \rightarrow 2 \rightarrow 3$$

$$\pi(1) = 1$$

$$\pi(2) = 2$$

$$\pi(3) = 3$$

$$3 \rightarrow 2 \rightarrow 1$$

$$\pi(3) = 1$$

$$\pi(2) = 2$$

$$\pi(1) = 3$$



$$\pi(1) = 1$$

$$\pi(2) = 2$$

$$\pi(3) = 3$$

$$\pi(1) = 1$$

$$\pi(2) = 3$$

$$\pi(3) = 2$$

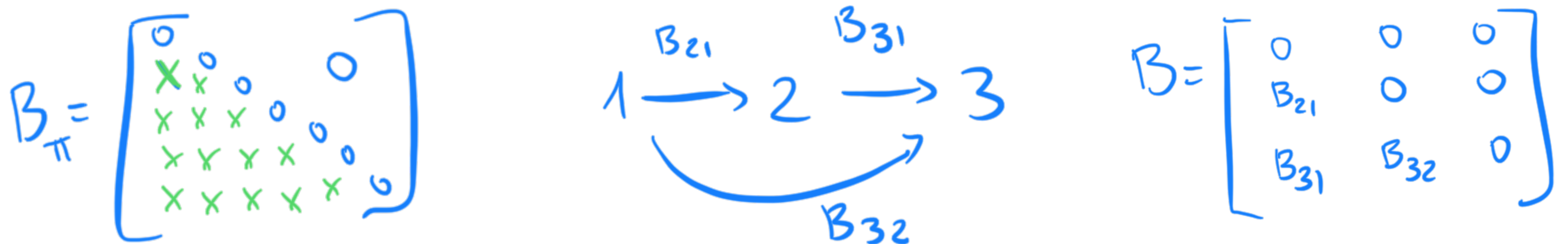
BECAUSE ACYCLICITY AT LEAST  
ONE CAUSAL ORDERING EXISTS.

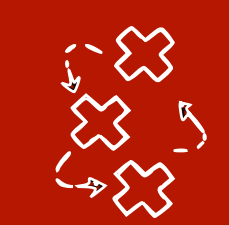
# Linear Non Gaussian Acyclic Models (LINGAM)

- We can write a linear SCM in matrix notation:

$$X = \mathbf{B}X + \varepsilon \text{ with } \mathbf{B} \in \mathbb{R}^{p \times p}, X \in \mathbb{R}^p, \varepsilon \in \mathbb{R}^p$$

- Because of acyclicity we can show that we can rewrite  $\mathbf{B}$  as **strictly lower triangular** by **permuting the variables using a causal ordering**





# Linear Non Gaussian Acyclic Models (LINGAM)

- We can write a linear SCM in matrix notation:

$$X = \mathbf{B}X + \varepsilon \text{ with } \mathbf{B} \in \mathbb{R}^{p \times p}, X \in \mathbb{R}^p, \varepsilon \in \mathbb{R}^p$$

- Because of acyclicity we can show that we can rewrite  $\mathbf{B}$  as **strictly lower triangular** by **permuting the variables using a causal ordering**

Diagram illustrating a causal ordering (permutation)  $\pi$  for a linear SCM. The causal ordering is shown as  $3 \rightarrow 1 \rightarrow 2$ , indicating that variable 3 is a parent of variable 1, and variable 1 is a parent of variable 2. The permutation  $\pi$  maps the original indices to the new order:  $\pi(3) = 1$ ,  $\pi(1) = 2$ , and  $\pi(2) = 3$ .

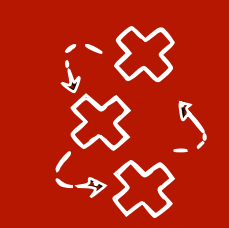
The matrix  $\mathbf{B}$  is shown in green, representing the original coefficients:

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & B_{13} \\ B_{21} & 0 & B_{23} \\ 0 & 0 & 0 \end{bmatrix}$$

The matrix  $\mathbf{B}_\pi$  is shown in red, representing the coefficients after permuting the variables according to the causal ordering  $\pi$ . The columns are labeled  $x_3$ ,  $x_1$ , and  $x_2$  from left to right, and the rows are labeled  $x_3$ ,  $x_1$ , and  $x_2$  from top to bottom:

$$\mathbf{B}_\pi = \begin{bmatrix} 0 & 0 & 0 \\ B_{13} & 0 & 0 \\ B_{23} & B_{21} & 0 \end{bmatrix}$$



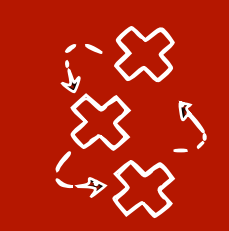


# Linear Non Gaussian Acyclic Models (LINGAM)

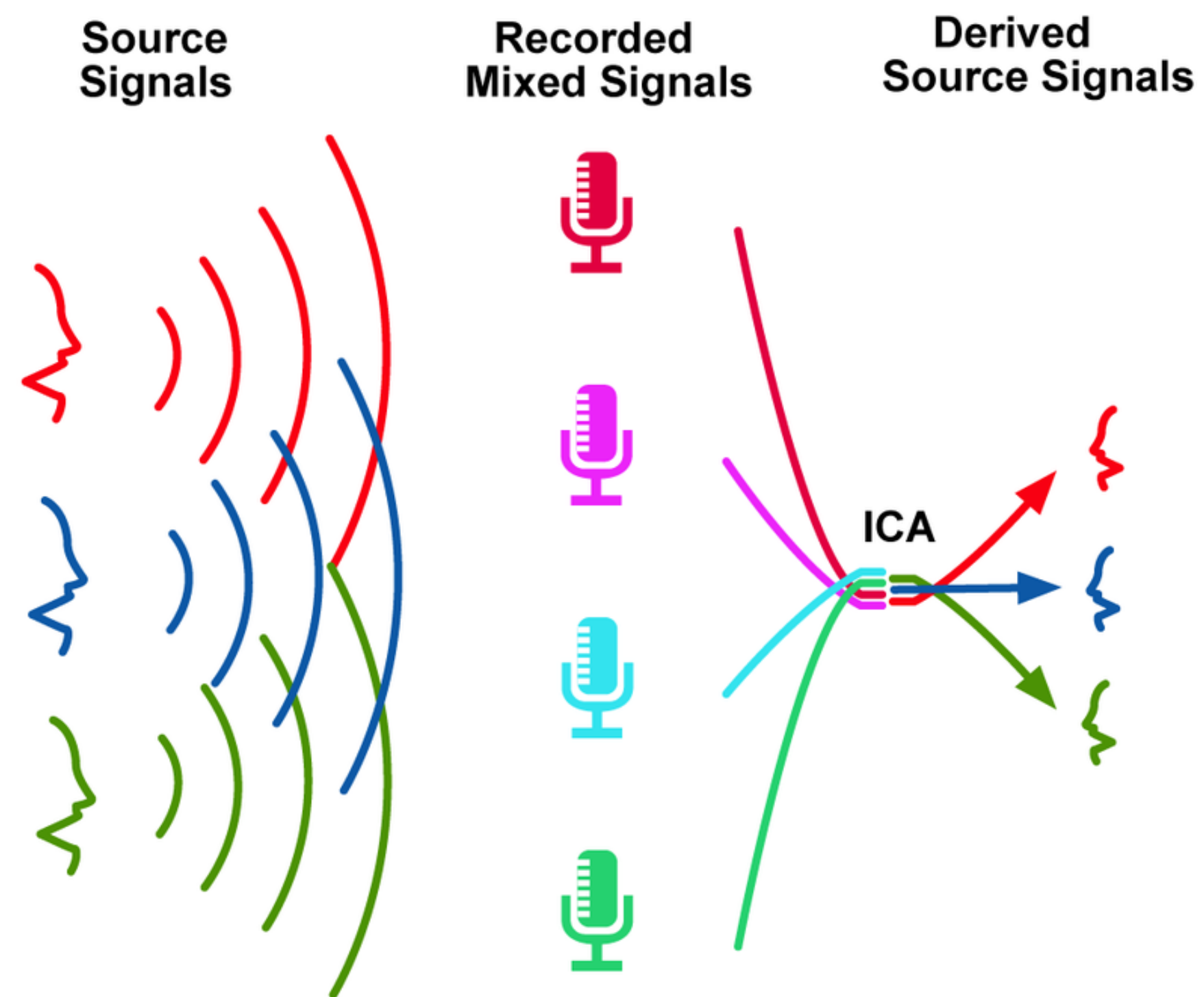
- We can write a linear SCM in matrix notation:

$$X = \mathbf{B}X + \varepsilon \text{ with } \mathbf{B} \in \mathbb{R}^{p \times p}, X \in \mathbb{R}^p, \varepsilon \in \mathbb{R}^p$$

- Because of acyclicity we can show that we can rewrite  $\mathbf{B}$  as **strictly lower triangular** by **permuting the variables using a causal ordering**
- **Goal:** estimate  $\mathbf{B}$  from data (which also identifies the DAG)
- ICA-LINGAM, DirectLINGAM (and many others)



# Independent Component Analysis (ICA)

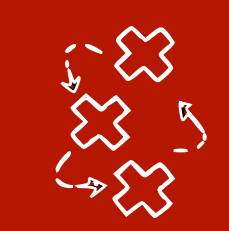


$$X = AS$$

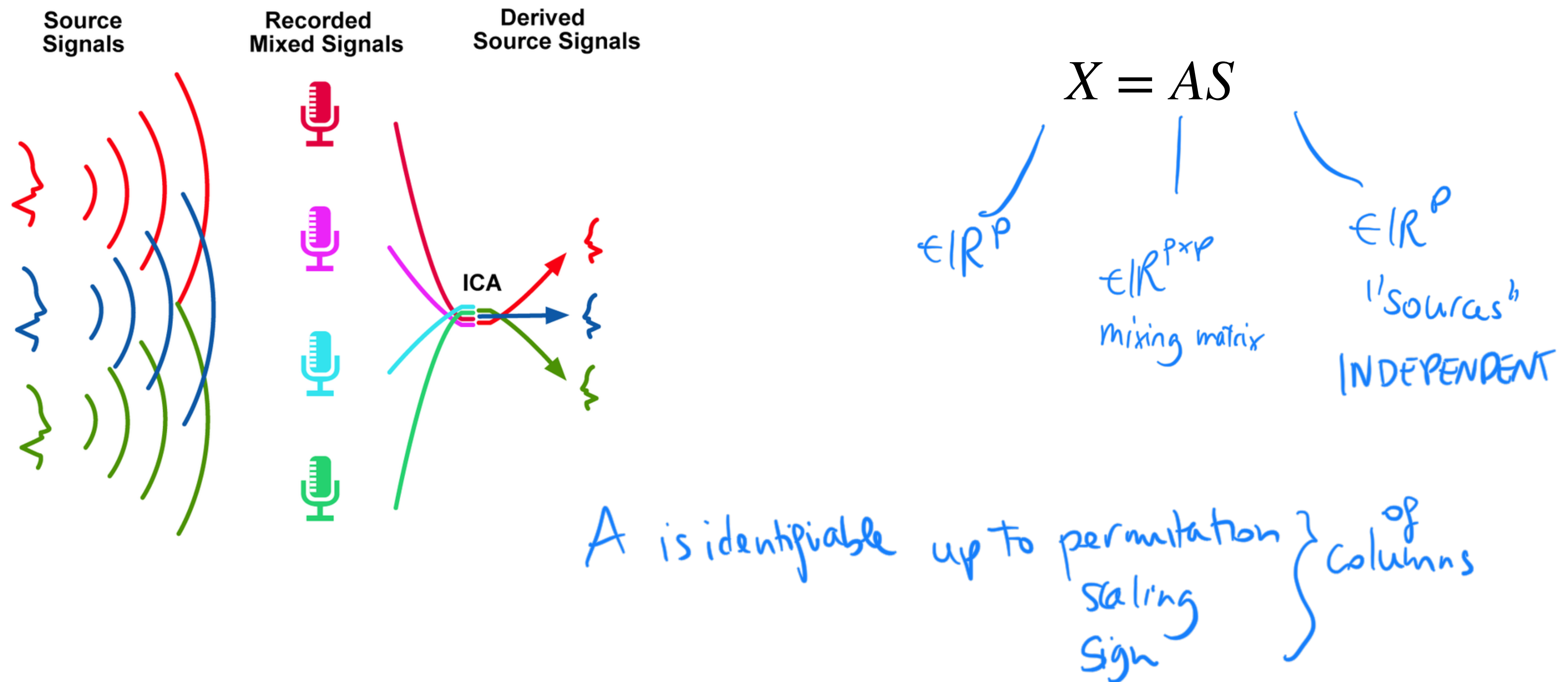
$\in \mathbb{R}^p$

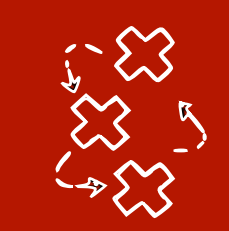
$\in \mathbb{R}^{p \times p}$   
mixing matrix

$\in \mathbb{R}^p$   
"sources"  
INDEPENDENT



# Independent Component Analysis (ICA)

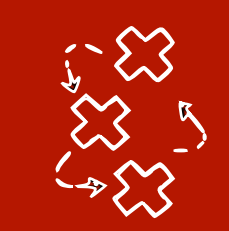




# ICA-LINGAM

- A linear SCM  $X = \mathbf{B}X + \varepsilon$  can be rewritten as  $(I - \mathbf{B})X = \varepsilon$  and  $X = (I - \mathbf{B})^{-1}\varepsilon$





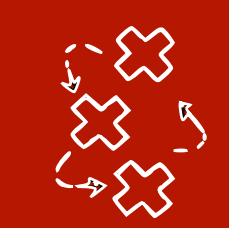
# ICA-LINGAM

- A linear SCM  $X = \mathbf{B}X + \varepsilon$  can be rewritten as  $(I - \mathbf{B})X = \varepsilon$  and

$$X = (I - \mathbf{B})^{-1} \varepsilon$$

mixing matrix  
 $A$

Sources  $S$



# ICA-LINGAM

- A linear SCM  $X = \mathbf{B}X + \varepsilon$  can be rewritten as  $(I - \mathbf{B})X = \varepsilon$  and

$$X = (I - \mathbf{B})^{-1} \varepsilon$$

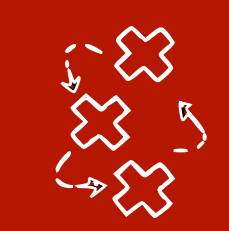
mixing matrix  
 $A$

Sources  $S$

LINGAM: independent non Gaussian

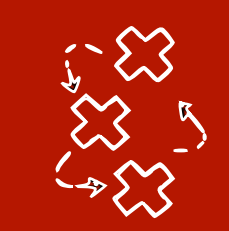
$\equiv$  ICA

up to permutation, scaling...



# ICA-LINGAM

1. Given dataset  $D = \{x_{\mathbf{V}}^1, x_{\mathbf{V}}^2, \dots, x_{\mathbf{V}}^n\}$  use ICA to estimate  $W = A^{-1} = (I - \mathbf{B})$
2. Find **unique permutation** of rows of  $W$  such that  $\tilde{W}$  does not have zeros on diagonal
3. Divide each row in  $\tilde{W}$  by its diagonal element (so we get all 1 on the diagonal)
4. Compute  $\hat{\mathbf{B}} = I - \tilde{W}$
5. Find **causal ordering** described by the permutation matrix  $P$  by making  $\tilde{\mathbf{B}} = P\hat{\mathbf{B}}P^T$  as close as possible to strictly lower triangular



# Next week: using interventional data

- All of the methods we saw until now use only **observational data**
- For restricted models this works well, since if the assumptions they make are true, then they can recover the true causal graph
- For score-based and constraint-based models, there are more advanced methods that can also use interventional data
  - For example for GES there is GIES
- If we don't know the targets of the interventions -> Joint Causal Inference