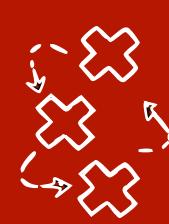


Causal Data Science

Lecture 9.1 Constraint-based causal discovery

Lecturer: Sara Magliacane

UvA - Spring 2024



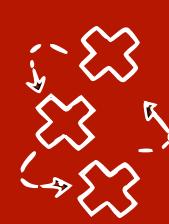
Overview on where we are in the course

1	Introduction
2	Probability recap
3	Causal graphs
4	Interventions
5	Covariate adjustment
6	Frontdoor criterion, Instrumental variables
7	Counterfactuals and potential outcomes
8	Estimating causal effects, Missing data
9	Constraint based structure learning
10	Score based structure learning
11	Advanced structure learning and transportability
12	Causality-inspired ML

Background on
causal graphs

We know the causal
graph, how do we
estimate causal effects?

What happens if the
graph is unknown?



Causal discovery simplified overview

Constraint-based causal discovery

- Conditional independence tests
- Observational data
- Output: MEC
- SGS, PC, FCI

Score-based causal discovery

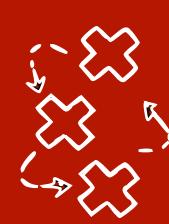
- Penalised likelihood
- Observational data
- Output: MEC
- GES, MMHC

Restricted models

- Nonlinear additive noise, Linear Non-Gaussianity
- Observational data
- Output: DAG
- RESIT, LINGAM

Interventional causal discovery / causal invariance

- Observational and Interventional data
- Output: parents of Y, I-MEC
- ICP, GIRES, JCI



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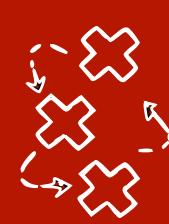
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Interventional causal discovery / causal invariance

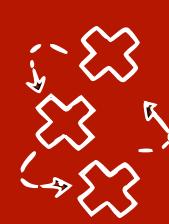
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Perfect maps - definition

- If P is Markov and faithful to G , we say that G is a **perfect map of P** .
Then, for any disjoint $A, B, C \subseteq V$:

$$A \perp_G B | C \iff X_A \perp\!\!\!\perp_P X_B | X_C$$

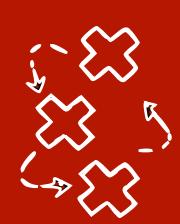


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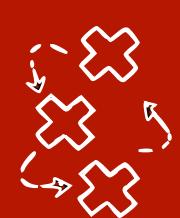
- In some special cases, the ground truth causal graph is not a perfect map of the distribution P
- We will now see an example of a faithfulness violation SCM, in which there are more conditional independences than what we would expect from the graph based on d-separations



Faithfulness violations example - cancelling paths

$$\begin{cases} X_1 = \epsilon_1 \\ X_2 = 3X_1 + \epsilon_2 \\ X_3 = X_2 - 3X_1 + \epsilon_3 \\ \epsilon_1, \epsilon_2, \epsilon_3 \sim N(0,1) \\ \epsilon_1 \perp\!\!\!\perp \epsilon_2, \epsilon_1 \perp\!\!\!\perp \epsilon_3, \epsilon_2 \perp\!\!\!\perp \epsilon_3 \end{cases}$$

$1 \xrightarrow[3]{-3} 2$
 $\downarrow \quad \downarrow 1$
 3

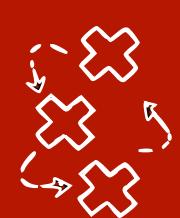


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1 ³ → 2
- 3 ↓ ↓ 1
3

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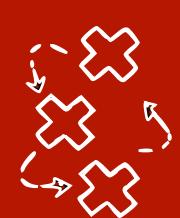


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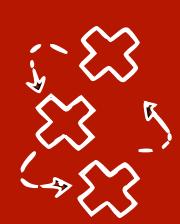


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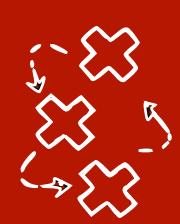
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$$\begin{matrix} & ^3 \\ 1 & \rightarrow & 2 \\ -3 & \downarrow & \downarrow 1 \\ & & 3 \end{matrix}$$

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$$X_1 \perp\!\!\!\perp X_2$$



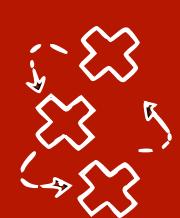
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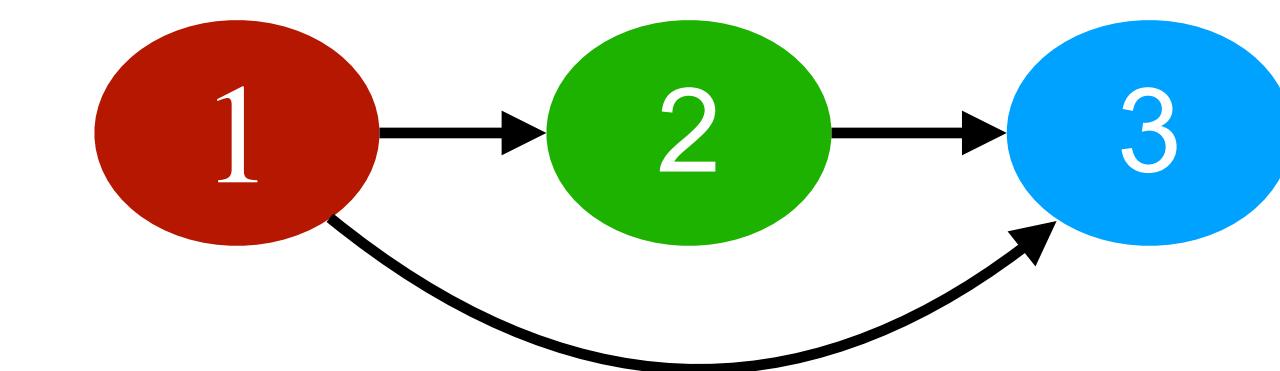
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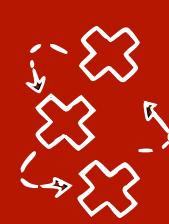
$$X_1 \perp\!\!\!\perp X_2 \quad X_2 \perp\!\!\!\perp X_3 \quad X_1 \perp\!\!\!\perp X_3$$



$$X_1 \perp_d X_2 \quad X_2 \perp_d X_3 \quad \boxed{X_1 \perp_d X_3}$$



The conditional independences don't fit the true causal graph, but they fit another one.



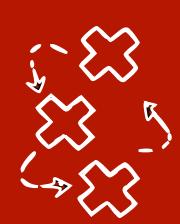
Perfect maps - non-existence

- Not every distribution p has a perfect map

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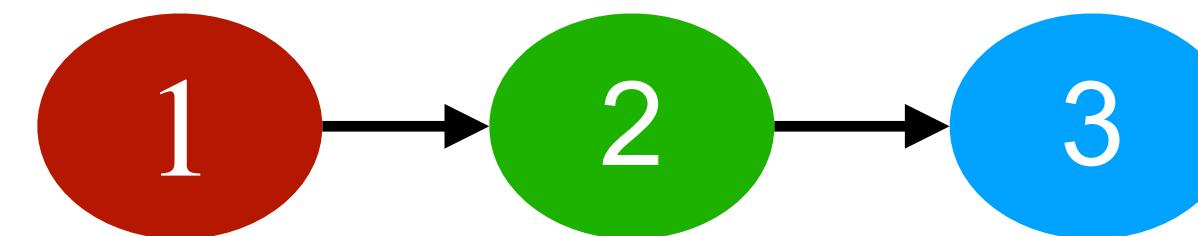
Deterministic function





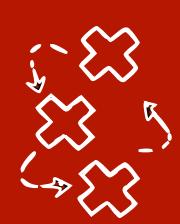
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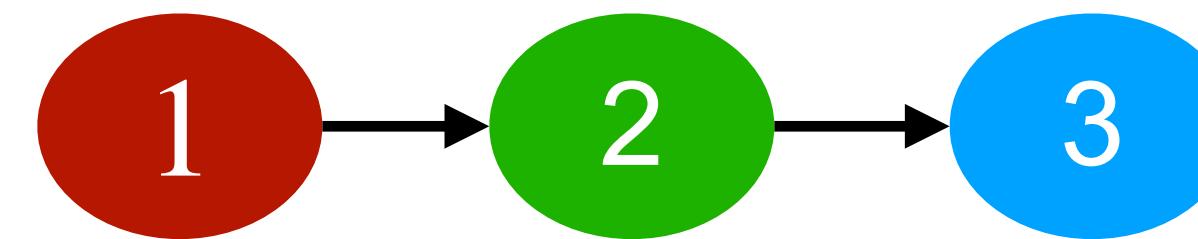
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Deterministic function

$$p(\epsilon_1 | \epsilon_1, \epsilon_1 + \epsilon_3) = p(\epsilon_1 | \epsilon_1)$$

$$\begin{cases} X_1 = \epsilon_1 \\ X_2 = \epsilon_1 \\ X_3 = \epsilon_1 + \epsilon_3 \\ \epsilon_1, \epsilon_3 \sim N(0,1) \\ \epsilon_1 \perp\!\!\!\perp \epsilon_3 \end{cases}$$

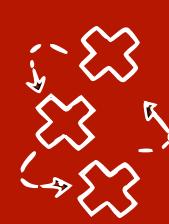
$X_1 \perp\!\!\!\perp X_2$

$X_2 \perp\!\!\!\perp X_3$

$X_1 \perp\!\!\!\perp X_3$

$X_1 \perp\!\!\!\perp X_3 | X_2$

$X_2 \perp\!\!\!\perp X_3 | X_1$



Perfect maps - existence

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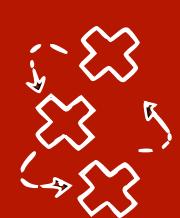
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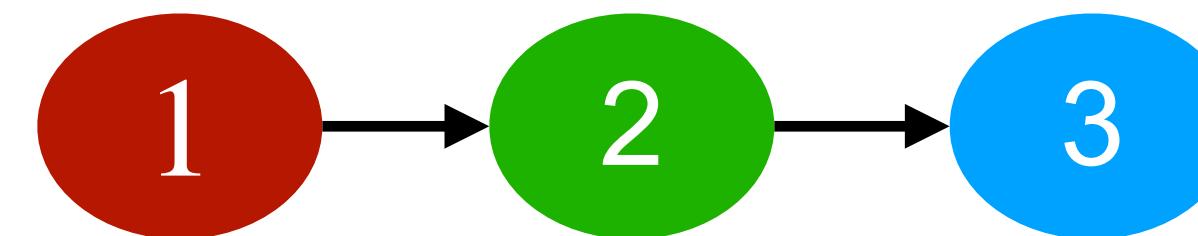
$X_2 \perp_d X_3 | X_1 ?$

$X_1 \perp\!\!\!\perp X_2$
 $X_2 \perp\!\!\!\perp X_3$
 $X_1 \perp\!\!\!\perp X_3$
 $X_1 \perp\!\!\!\perp X_3 | X_2$
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$X_2 \not\perp\!\!\!\perp X_3 | X_1$

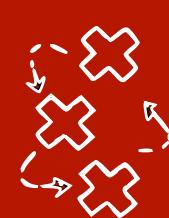
$X_1 \perp\!\!\!\perp X_2$

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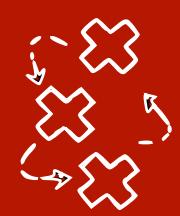
 $X_1 \perp\!\!\!\perp X_2$ $X_2 \perp\!\!\!\perp X_3$ $X_1 \perp\!\!\!\perp X_3$ $X_1 \perp\!\!\!\perp X_3 | X_2$ $X_2 \perp\!\!\!\perp X_3 | X_1$

There is a (d-connecting)
path between X_1 and X_3

X_1 and X_3 are not adjacent

X_2 and X_3 are not adjacent

This is a contradiction, there exists no Bayesian network that can represent these conditional in/dependences as d-separations perfectly!

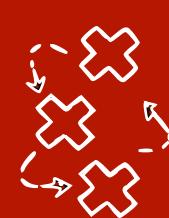


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$$A \perp_G B | C \iff X_A \perp\!\!\!\perp_P X_B | X_C$$

- In some special cases, the ground truth causal graph is not a perfect map of the distribution
 - We will now assume that there are more variables than observed. The causal graph is a perfect map of the distribution, i.e. it is Markov and faithful to P .

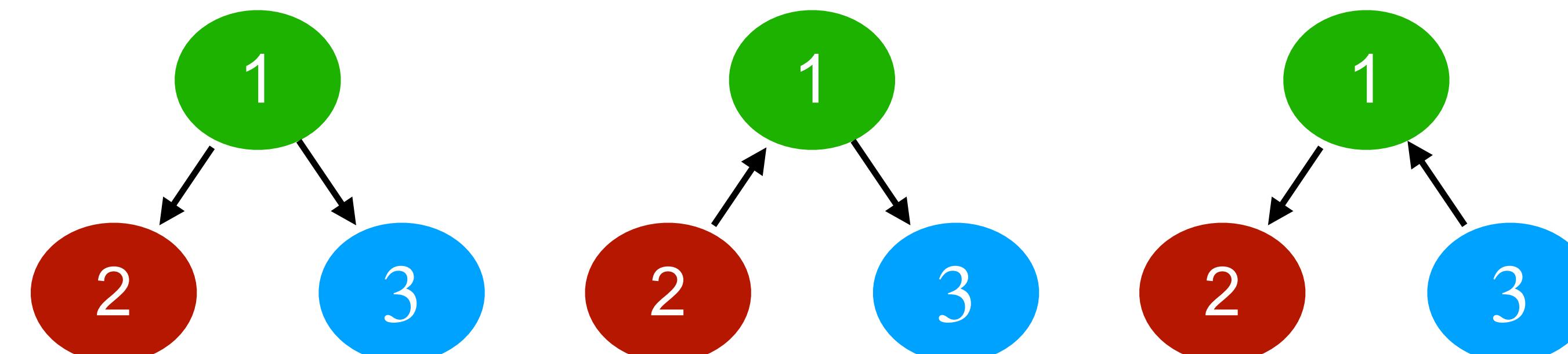


Perfect maps - Markov equivalence

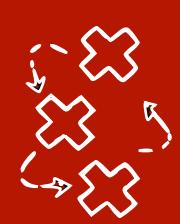
- If P is Markov and faithful to G , we say that G is a **perfect map of P** .
Then, for any disjoint $A, B, C \subseteq V$:

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- We call all DAGs with the same d-separations **Markov equivalent**
- Their set is the **Markov equivalence class (MEC)**



$$\begin{array}{ll} X_1 \perp X_2 & \\ X_1 \perp X_3 & \\ X_2 \perp X_3 & \\ X_1 \perp X_2 | X_3 & \\ X_1 \perp X_3 | X_2 & \\ X_2 \perp X_3 | X_1 & \end{array}$$



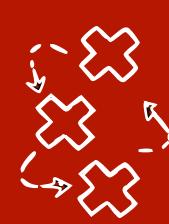
Markov equivalence example

$X \not\perp\!\!\!\perp Y$ $X \perp\!\!\!\perp Y | Z$

$X — Z — Y$

Which graphs on X, Y, Z are perfect maps of these conditional independences?

Hint: we can start by orienting this undirected graph



Markov equivalence example

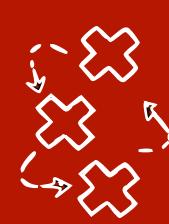
$X \not\perp\!\!\!\perp Y$ $X \perp\!\!\!\perp Y | Z$

Which graphs on X, Y, Z are perfect maps of these conditional independences?

$X - Z - Y$

$X \rightarrow Z \rightarrow Y$

$X \not\perp\!\!\!\perp Y \checkmark$
 $X \perp\!\!\!\perp Y | Z \checkmark$



Markov equivalence example

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Which graphs on X, Y, Z are perfect maps of these conditional independences?

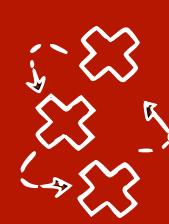
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$$X \rightarrow Z \rightarrow Y$$

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$$X \perp\!\!\!\perp Y | Z \quad \checkmark$$

$$X \leftarrow Z \leftarrow Y$$

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Markov equivalence example

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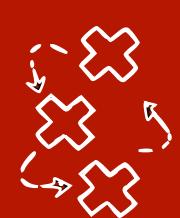
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These three graphs represent a Markov Equivalence Class



Markov equivalence example

$$X \not\perp\!\!\!\perp Y \quad X \perp\!\!\!\perp Y | Z$$

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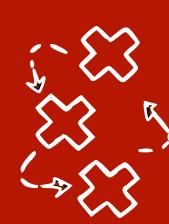
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$$X \rightarrow Z \leftarrow Y$$

$$X \perp\!\!\!\perp Y \quad \times$$

$$X \not\perp\!\!\!\perp Y | Z \quad \times$$



Markov equivalence example

$$X \not\perp\!\!\!\perp Y \quad X \perp\!\!\!\perp Y | Z$$

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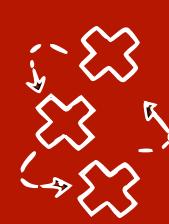
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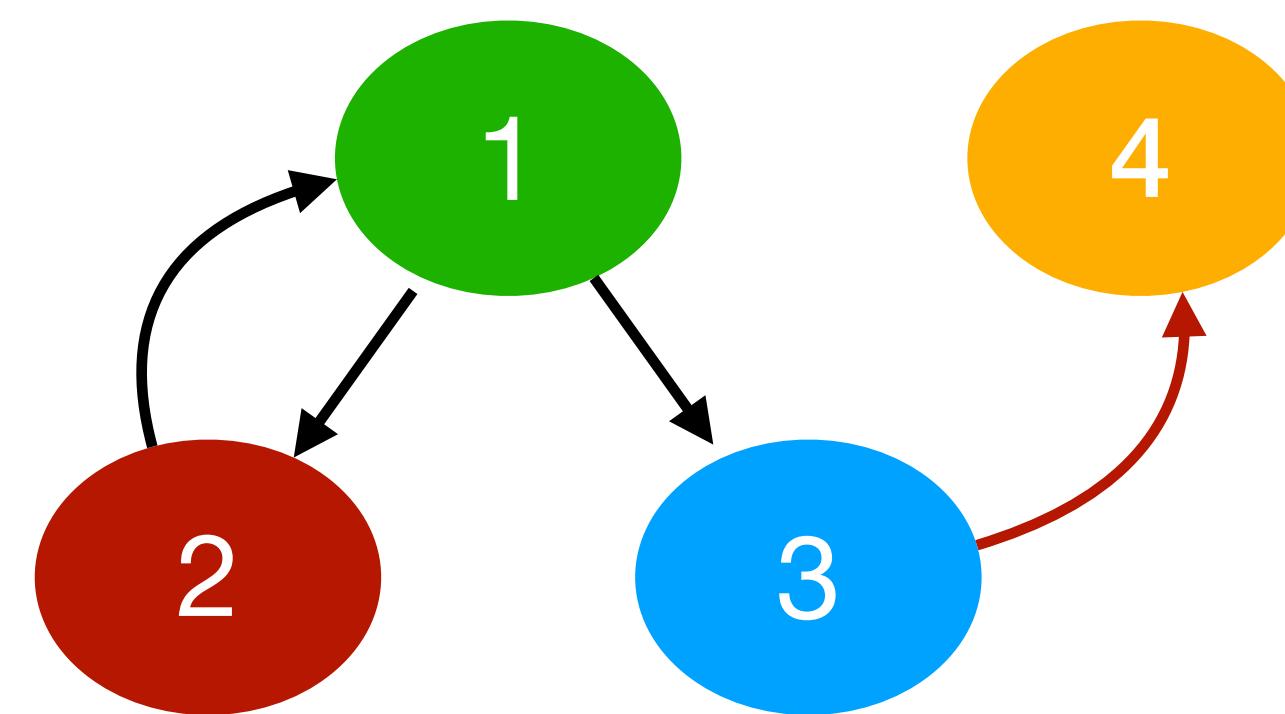
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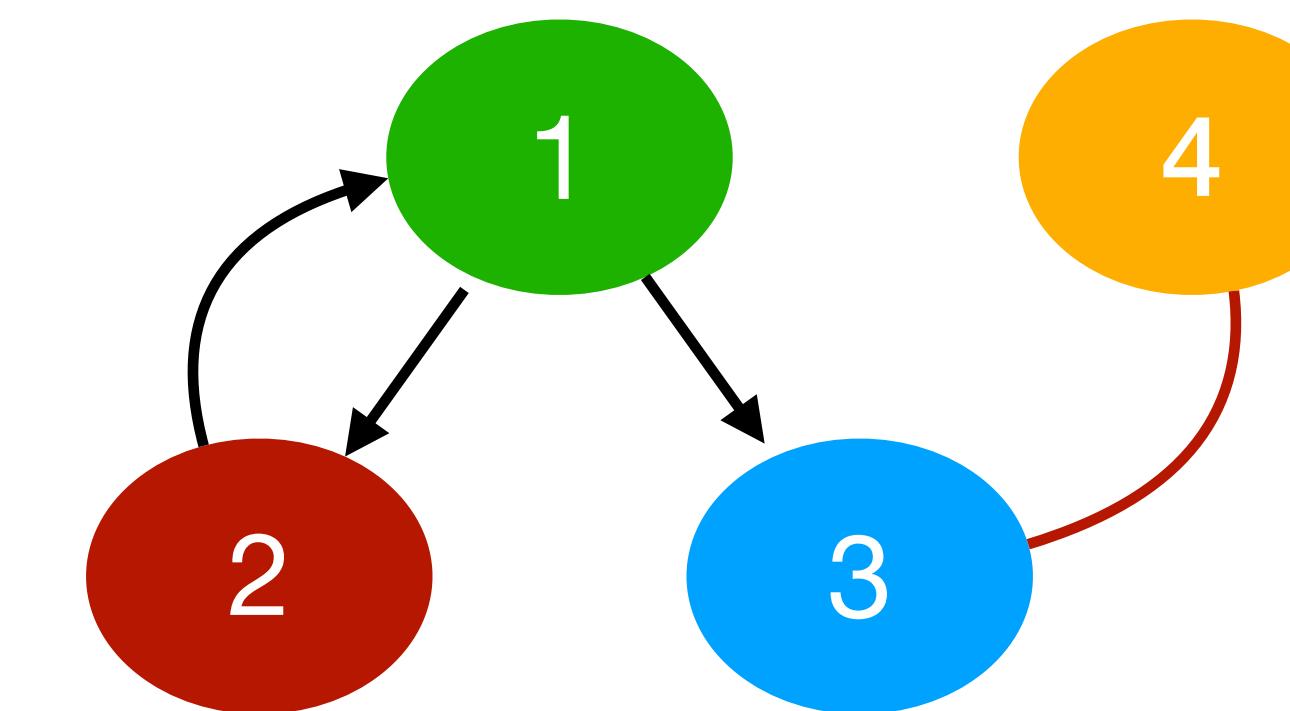


Recap from class 3: Directed graphs vs mixed graphs

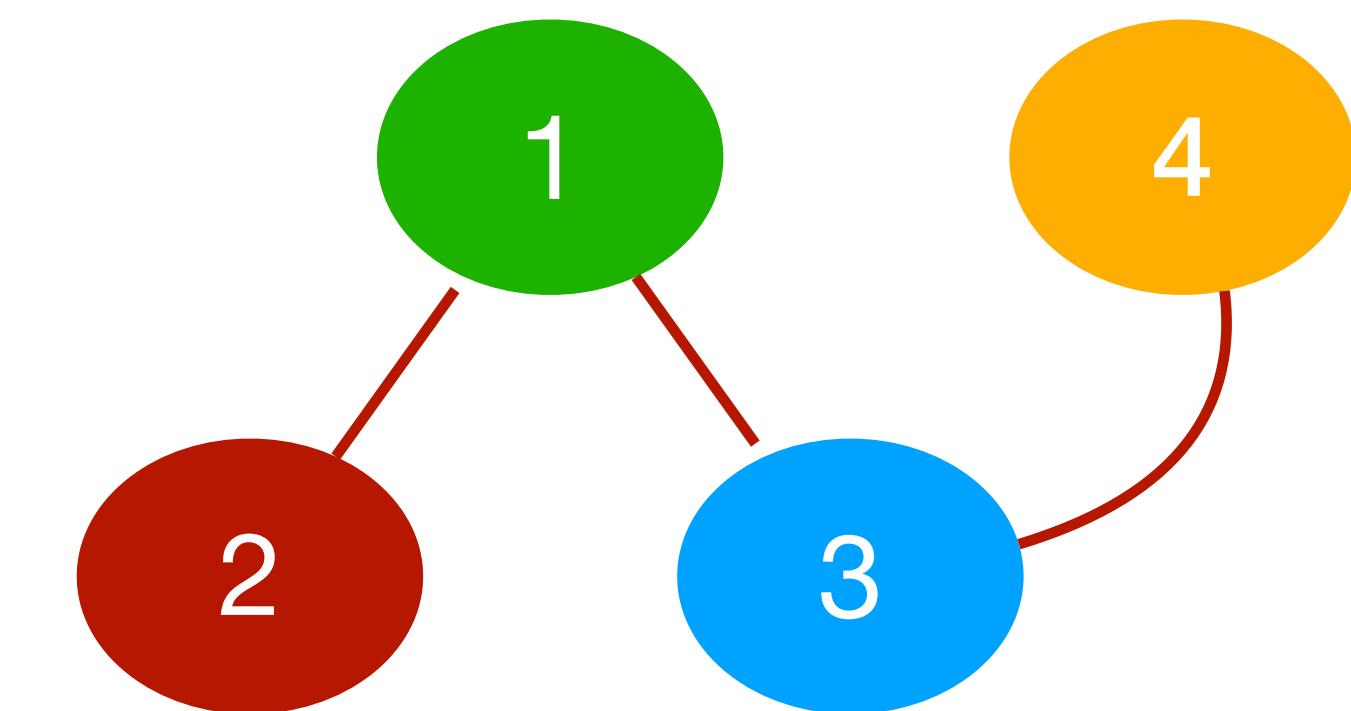
- A graph G is a tuple $G = (\mathbf{V}, \mathbf{E})$:
 - \mathbf{V} is the set of **nodes** (vertices)
 - \mathbf{E} is the set of **edges** between two nodes, i.e. $\mathbf{E} \subseteq \mathbf{V} \times \mathbf{V}$
 - If all edges are **directed** → then the graph is **directed**



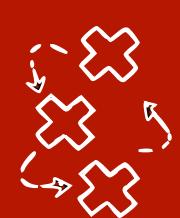
Directed graph



Mixed graph

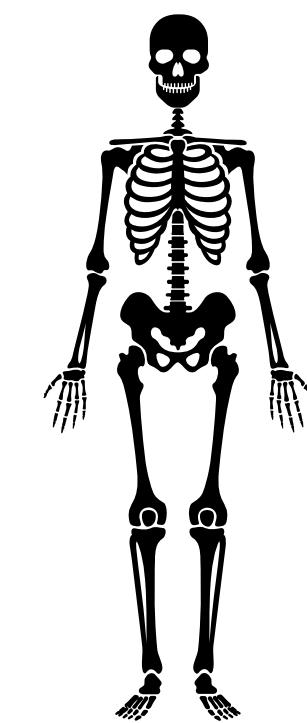
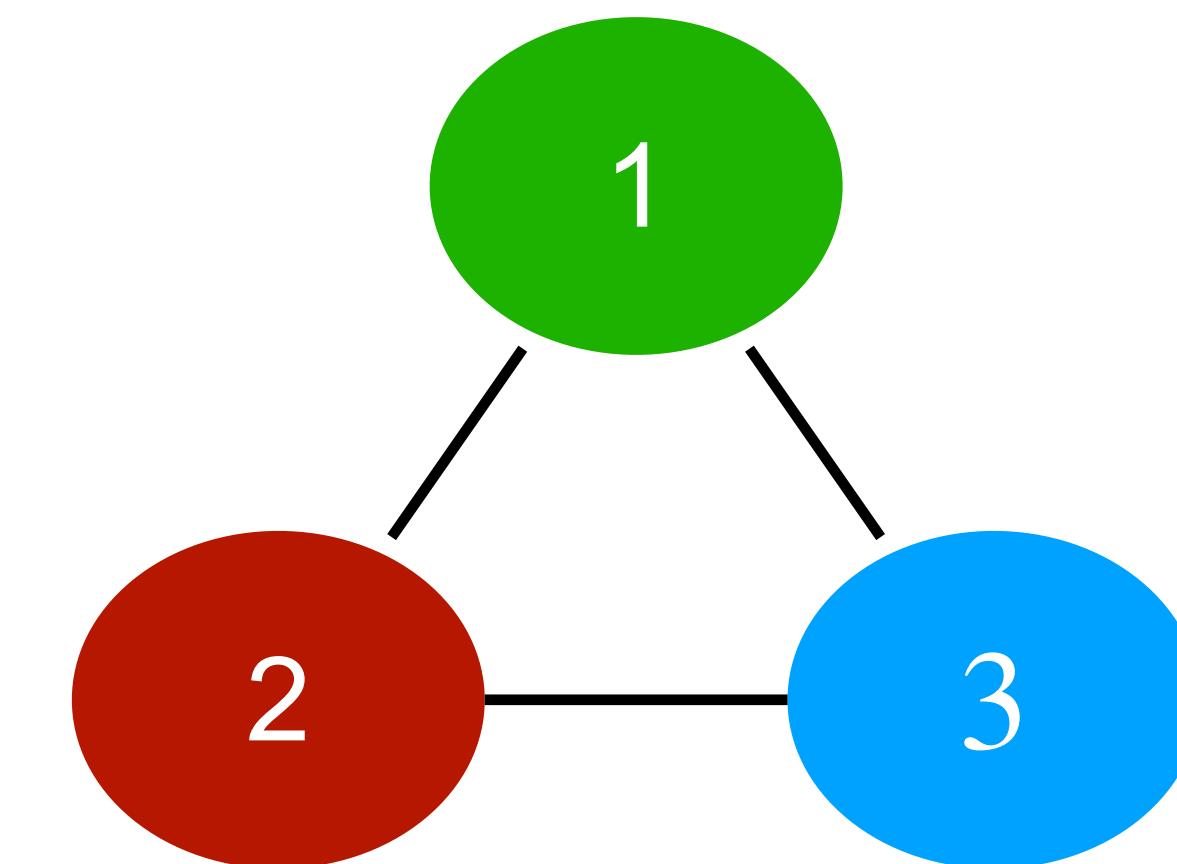
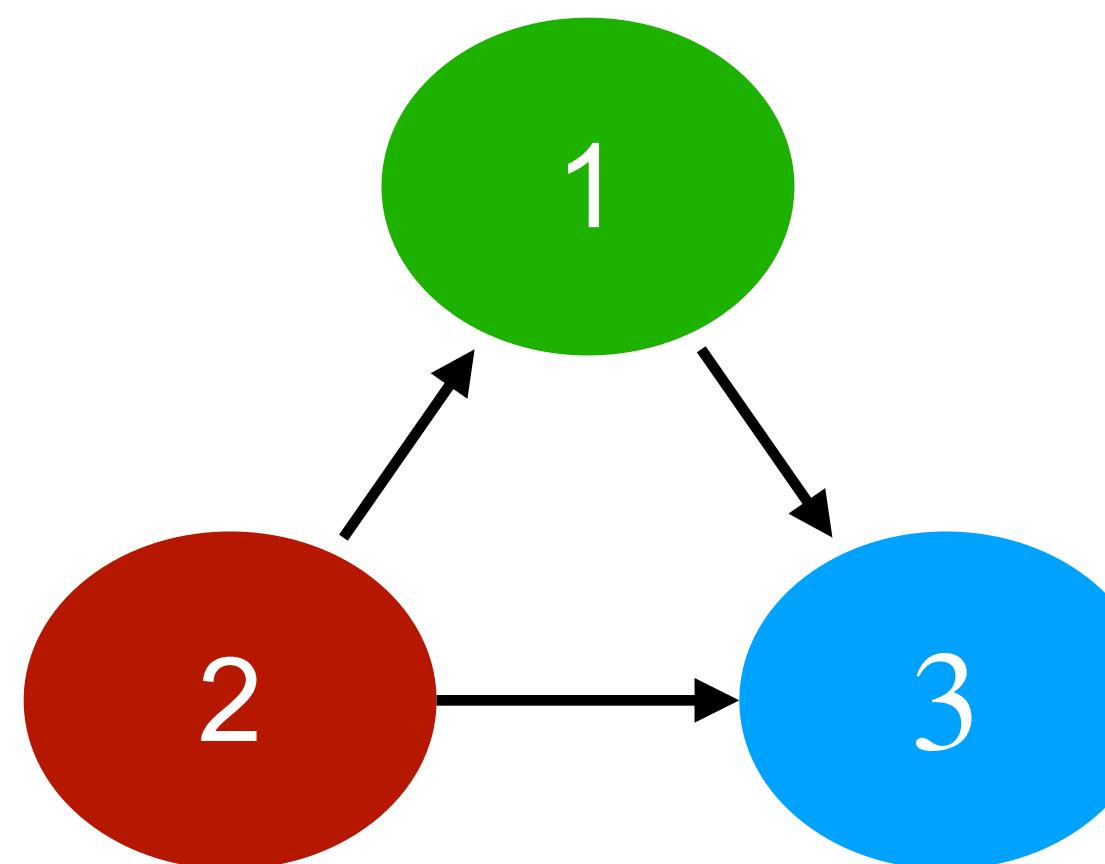


Undirected graph

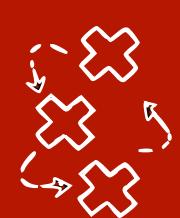


More graph terminology: skeletons

- The skeleton of a DAG $G = (V, E)$ is the undirected graph $U = (V, E')$ that has **an undirected edge** $(i, j) \in E'$ for every **directed edge** $i \rightarrow j \in E$ and no other edges

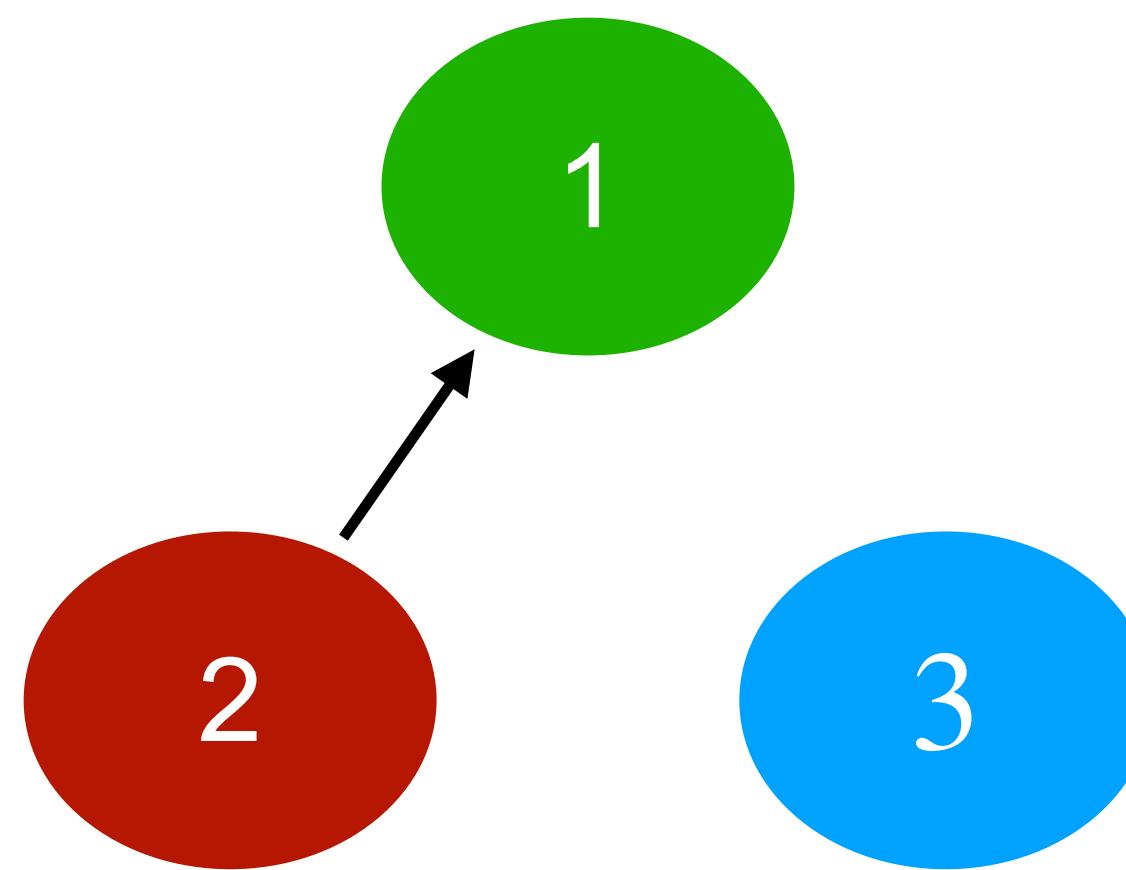


In other words a graph that is the same, but without the arrowheads

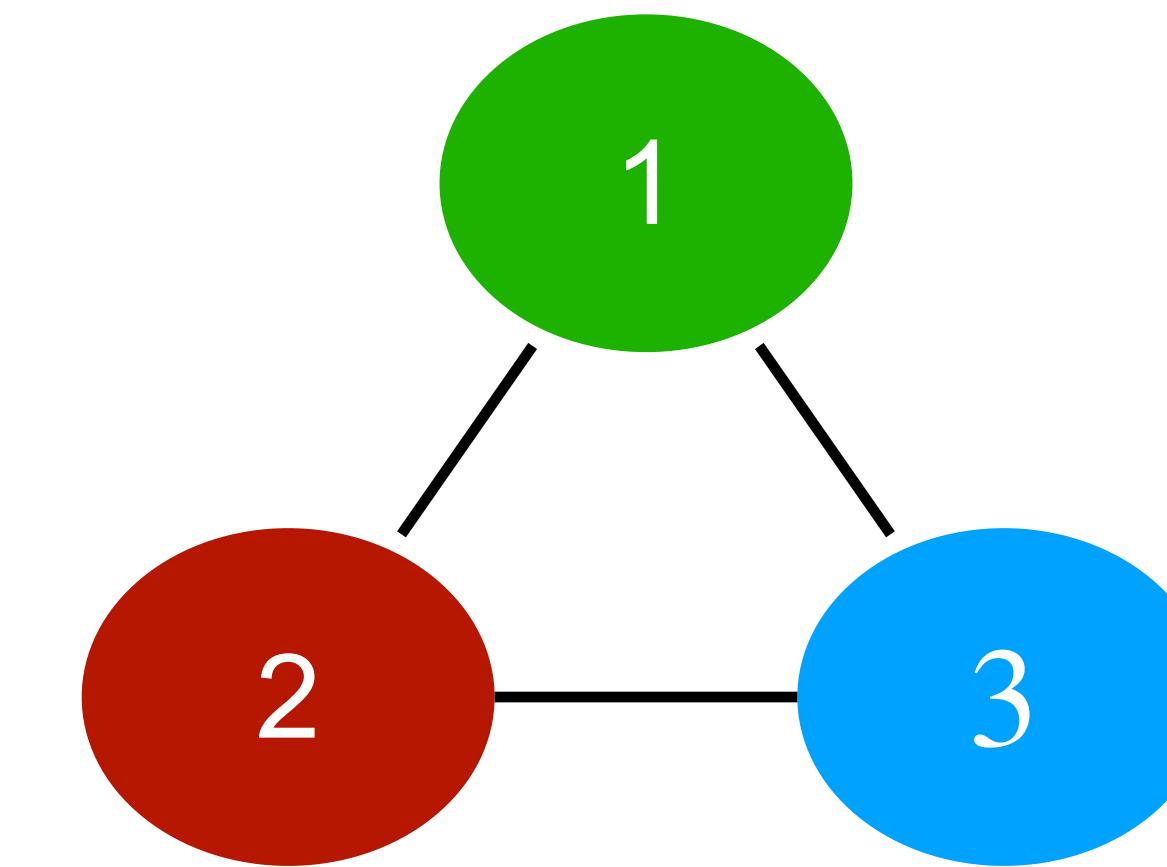


Skeleton exercise

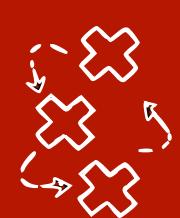
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G

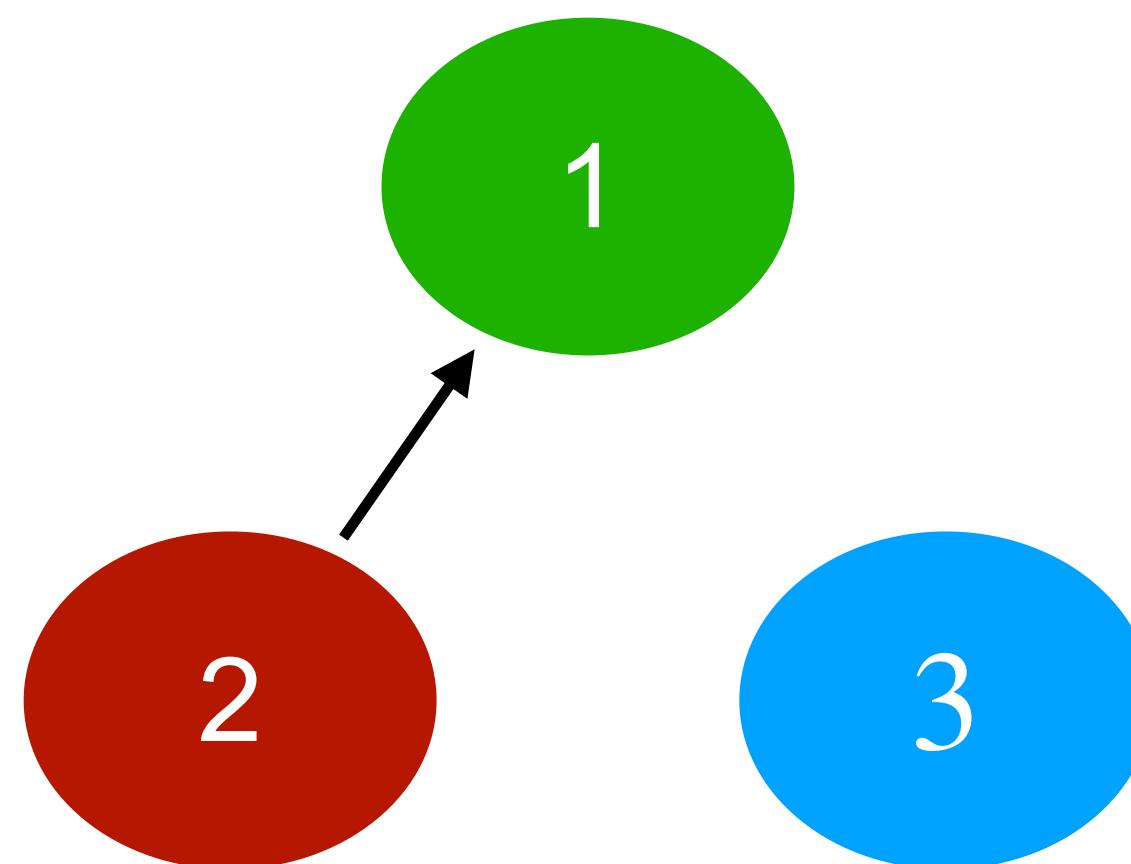


Is this the skeleton of G ?

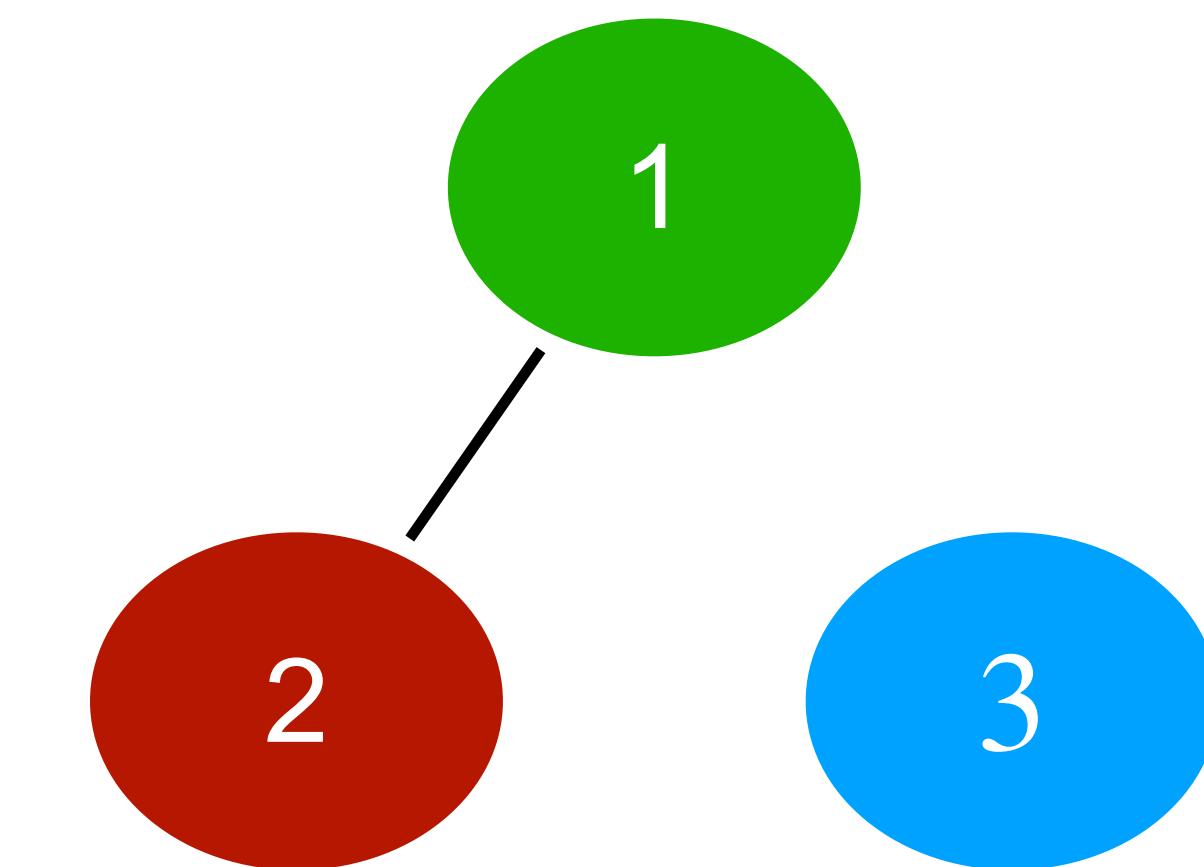
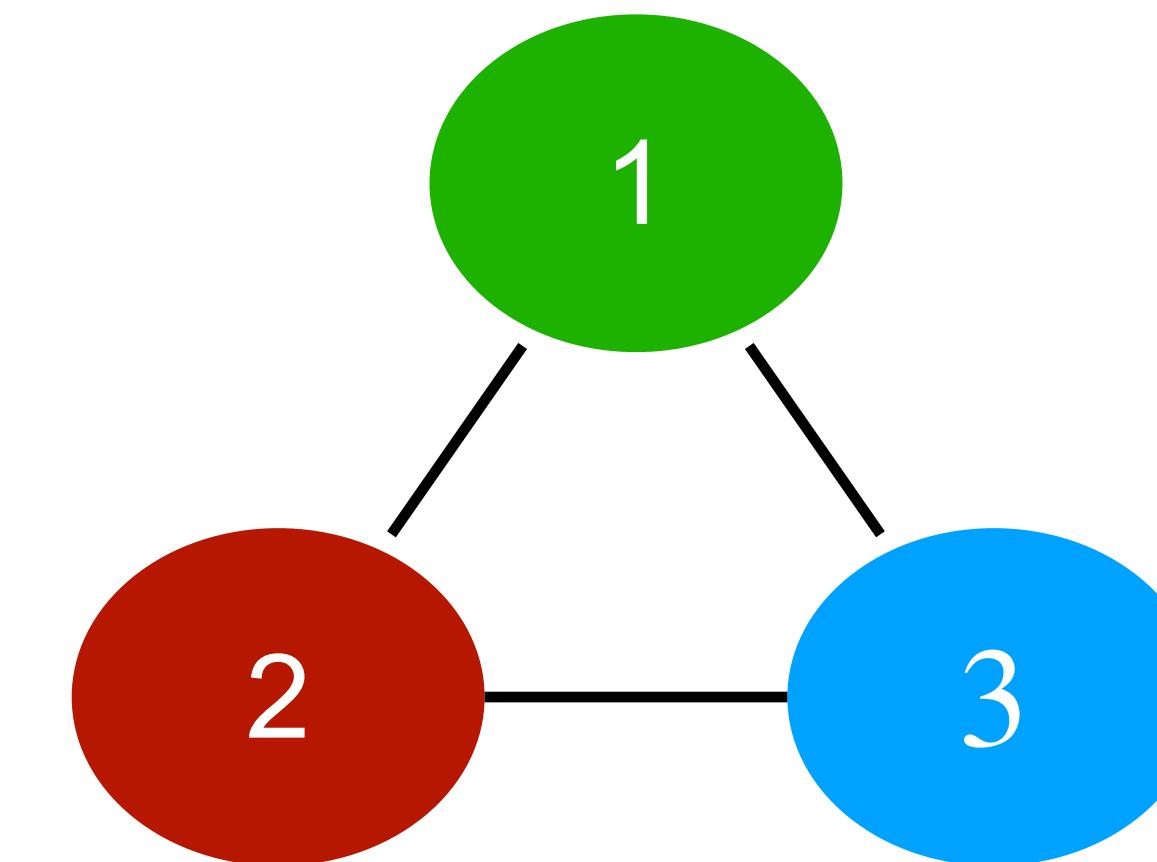


Skeleton exercise

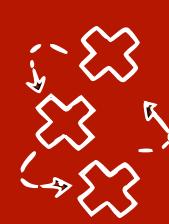
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G

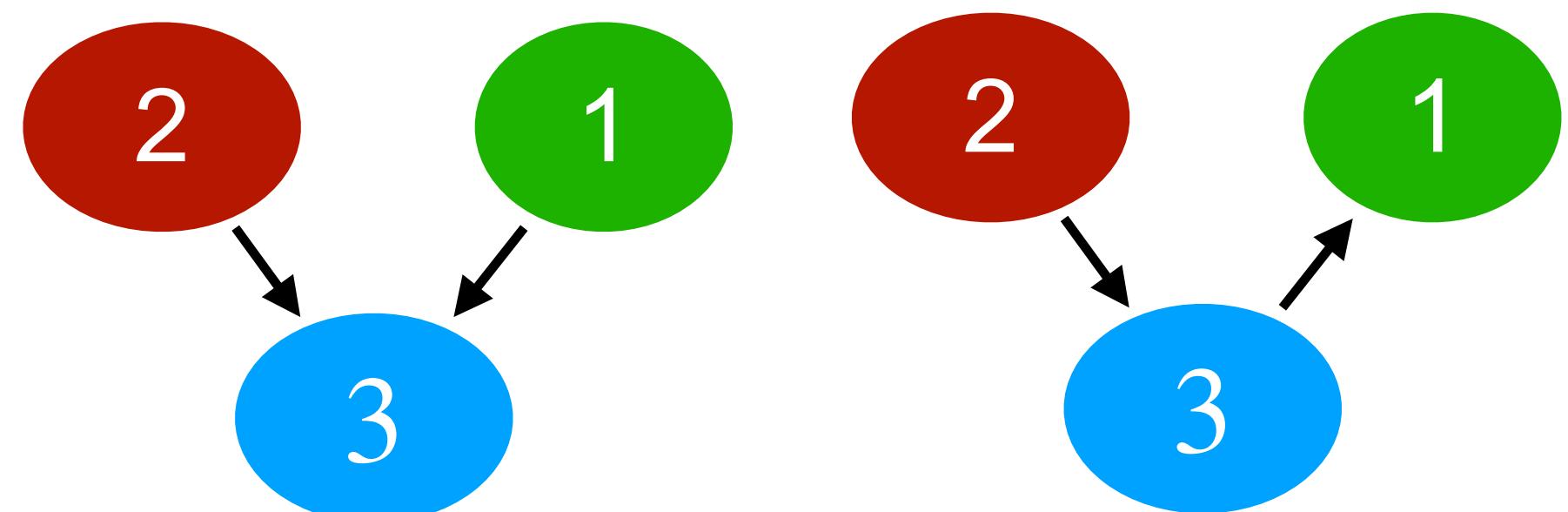


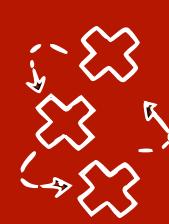
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More graph terminology: adjacent

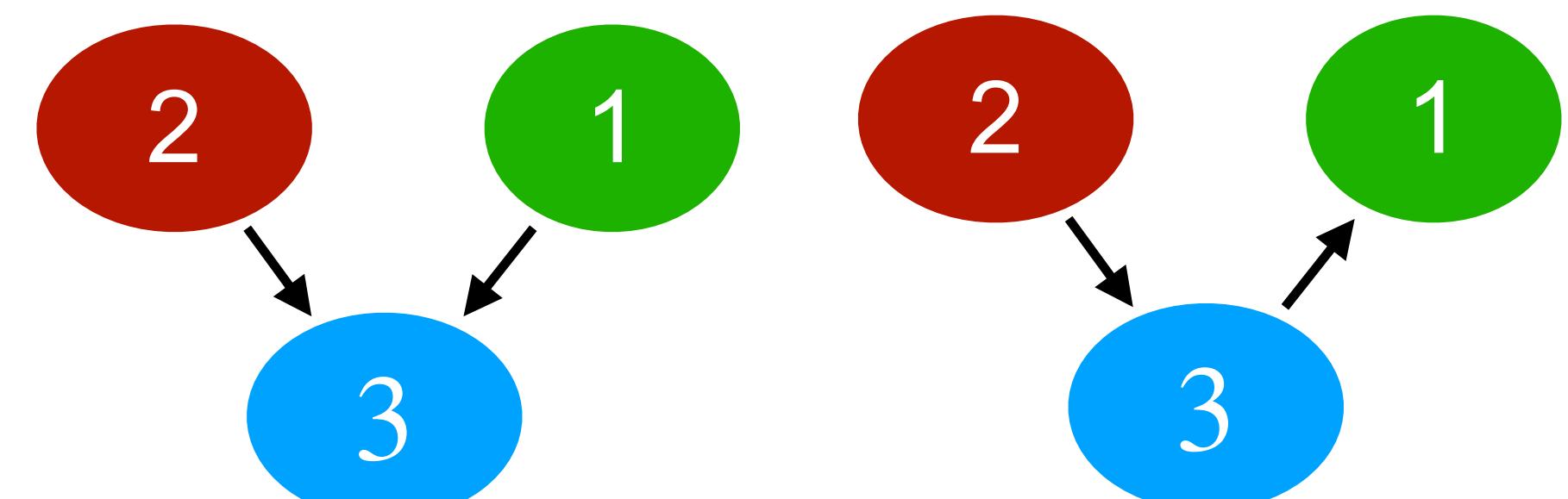
- Nodes i and j in a DAG G are **adjacent/neighbours** if $i \rightarrow j$ or $j \rightarrow i$ in G

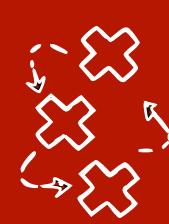




More graph terminology: adjacent

- Nodes i and j in a DAG G are **adjacent/neighbours** if $i \rightarrow j$ or $j \rightarrow i$ in G
 - I.e., they are connected by an undirected edge in the skeleton of G
 - We denote adjacency with $i - j$, while $i + j$ means non-adjacent

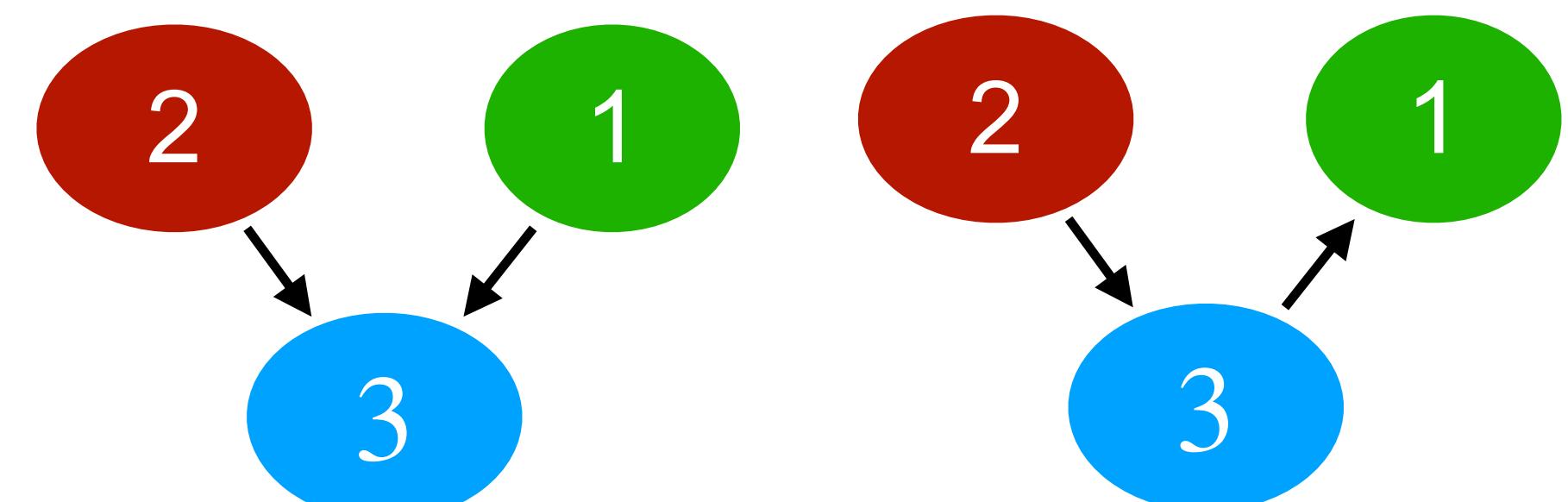


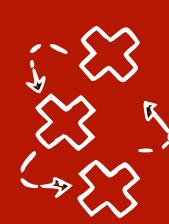


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Is 2 adjacent to 3?



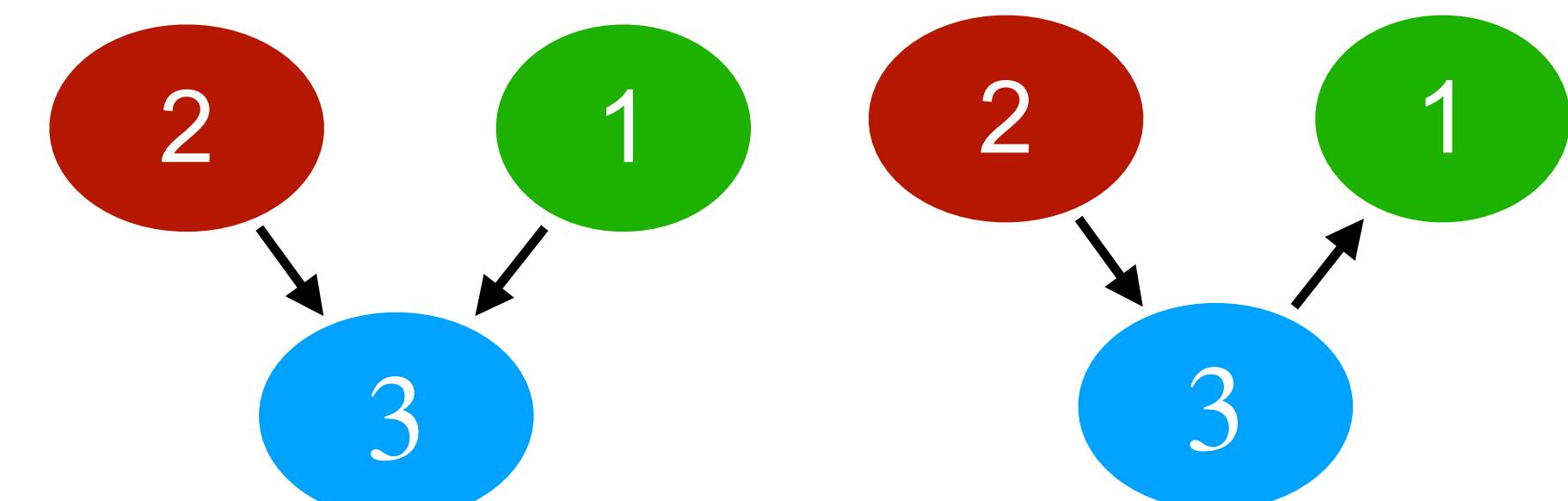


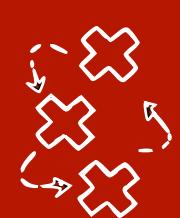
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Is 2 adjacent to 3?

Is 2 adjacent to 1?





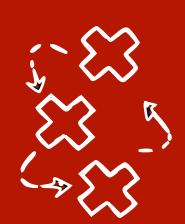
More graph terminology: v-structures/immoralities

- A triple of nodes (i, j, k) in a DAG G is a **v-structure (unshielded collider)** if

$i \rightarrow j \leftarrow k$ in G and **i is not adjacent to k**

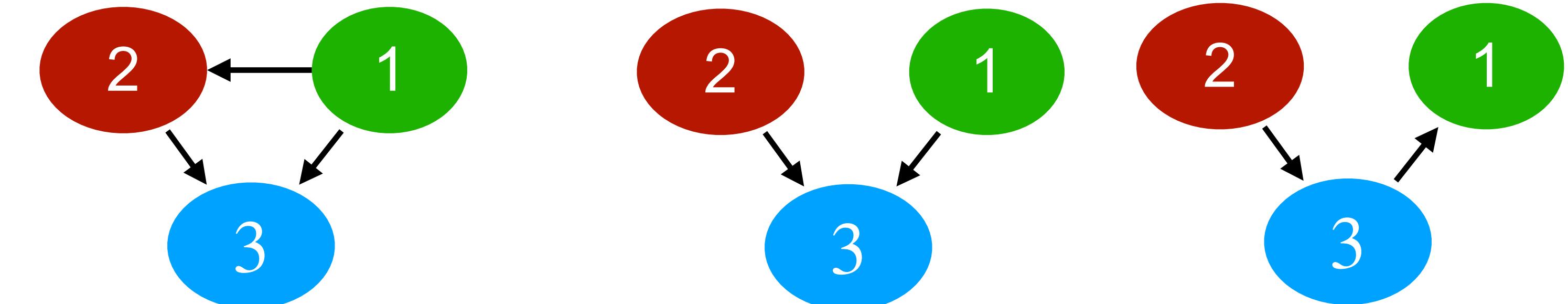
This edge is called a shield

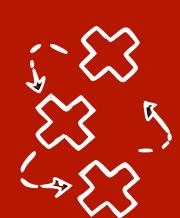
It's also called an **immorality**, because the two parents i and j who have a common child k are not “married”
(adjacent)



More graph terminology: v-structures/immoralities

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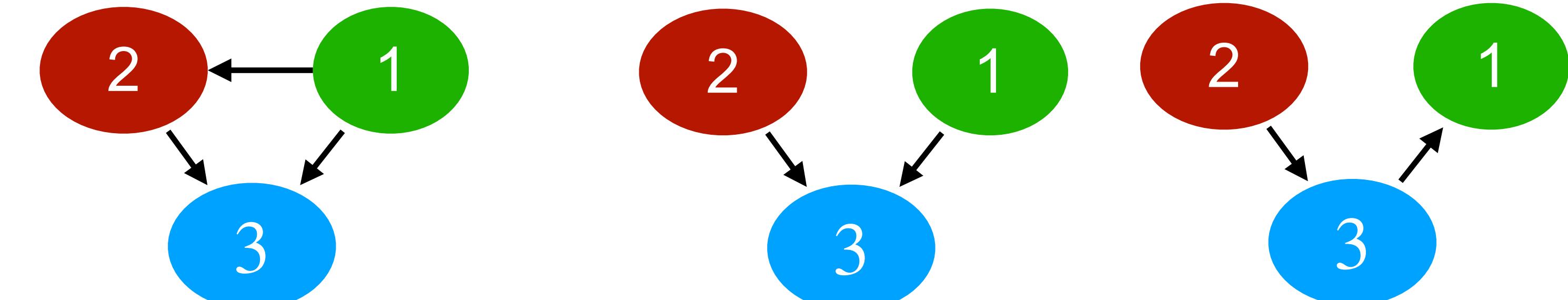


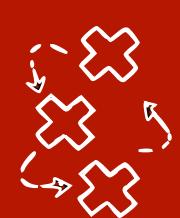


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In which graphs is 3 a collider on the path between 2 and 1?

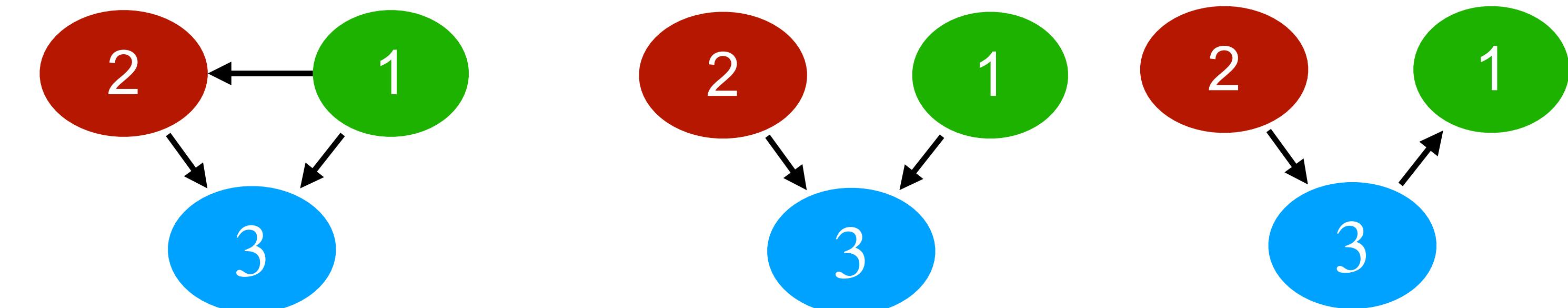


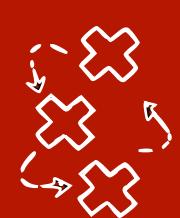


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In which graphs is 3 part of a v-structure (2,3,1)?

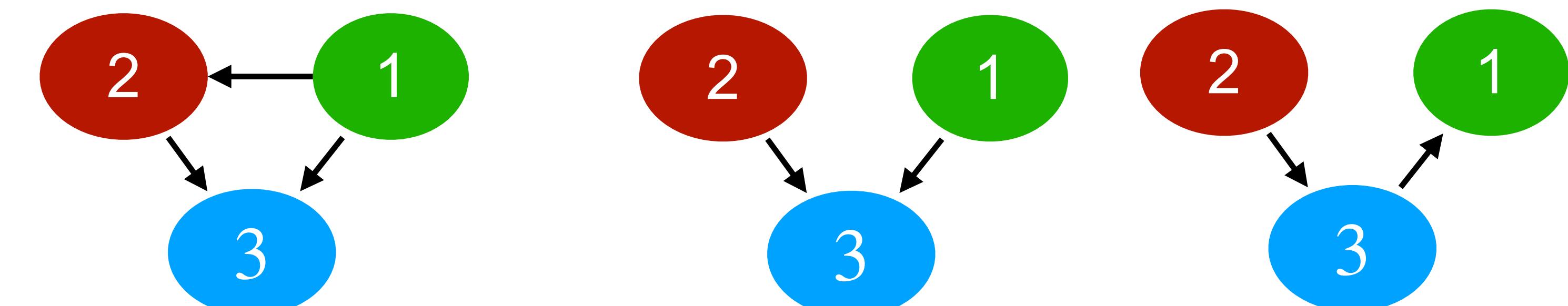


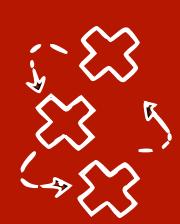


More graph terminology: unshielded triple

- A triple of nodes (i, j, k) in a DAG G is a **v-structure (unshielded collider)** if $i \rightarrow j \leftarrow k$ in G and **i is not adjacent to k** in G
- A triple of nodes (i, j, k) in a DAG G is a **an unshielded triple** if $i - j, j - k$ and **i is not adjacent to k** in G

In which graphs is $(2,3,1)$ an unshielded triple?

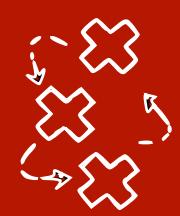




Markov equivalence class and CPDAGs

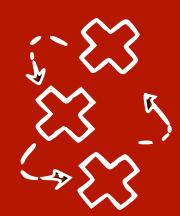
essential graphs *Summary graphs*

- (Verma and Pearl 1990) show that all DAGs in a Markov equivalence class have the **same skeleton** and the **same v-structures**



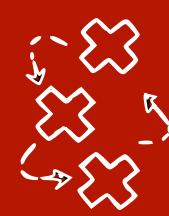
Markov equivalence class and CPDAGs

- (Verma and Pearl 1990) show that all DAGs in a Markov equivalence class have the **same skeleton** and the **same v-structures**
- We can represent the skeleton and the orientations (edge marks) all DAGs in a Markov equivalence class (MEC) have in common with a **Complete Partially Directed Acyclic Graph (CPDAG)**:



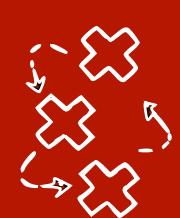
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Markov equivalence class and CPDAGs

- **Complete Partially Directed Acyclic Graph (CPDAG):**

- We have a directed edge $i \rightarrow j$ if all DAGs in the MEC have $i \rightarrow j$
- We have an undirected edge $i - j$ if some DAGs in the MEC have $i \rightarrow j$ and others have $j \rightarrow i$

$$X \rightarrow Z \rightarrow Y$$

$$\begin{array}{l} X \not\perp_d Y \checkmark \\ X \perp_d Y | Z \checkmark \end{array}$$

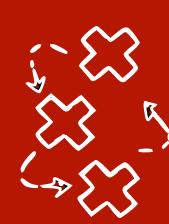
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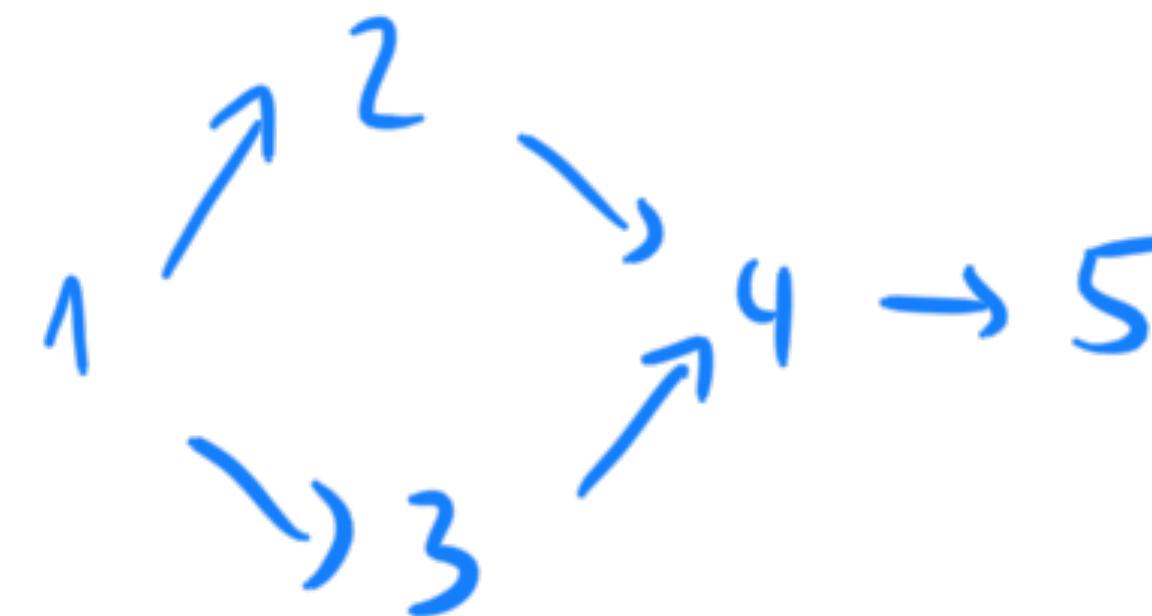
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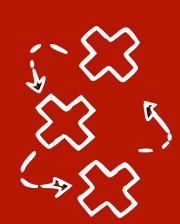


CPDAG example 2

- (Verma and Pearl 1990) show that all DAGs in a Markov equivalence class have the **same skeleton** and the **same v-structures**

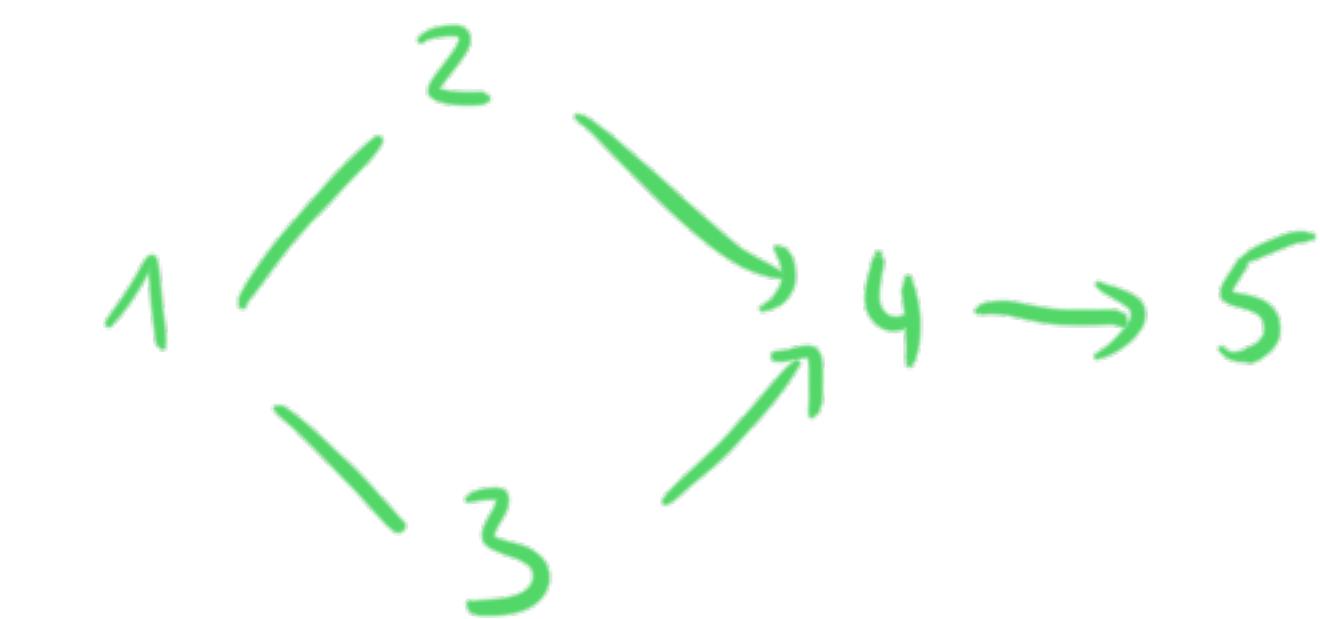
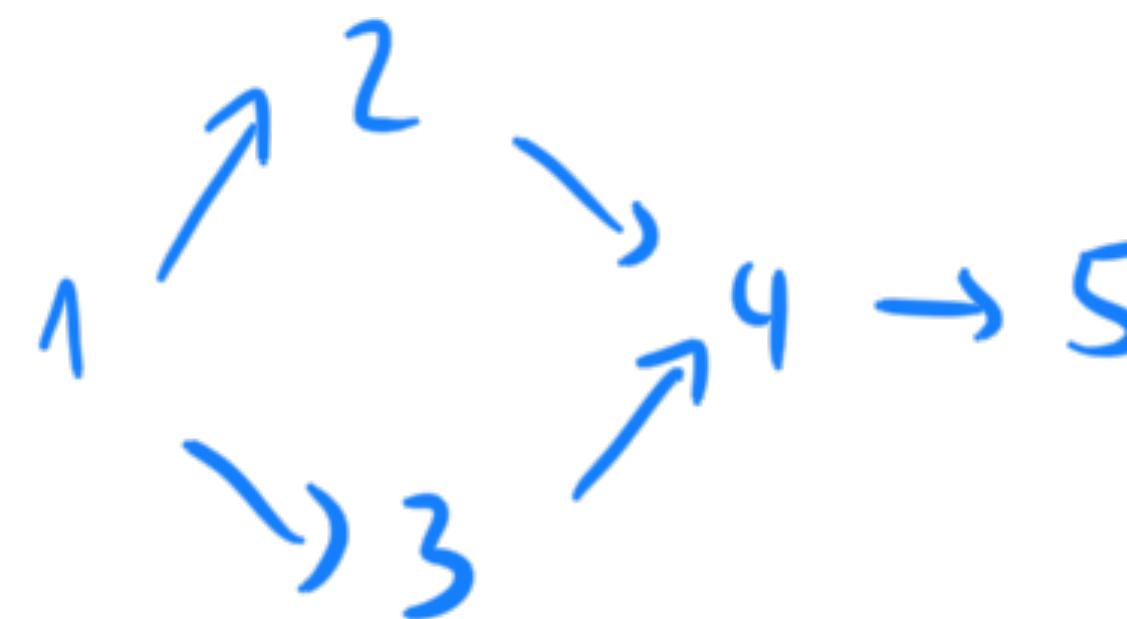


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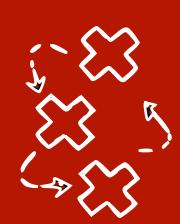


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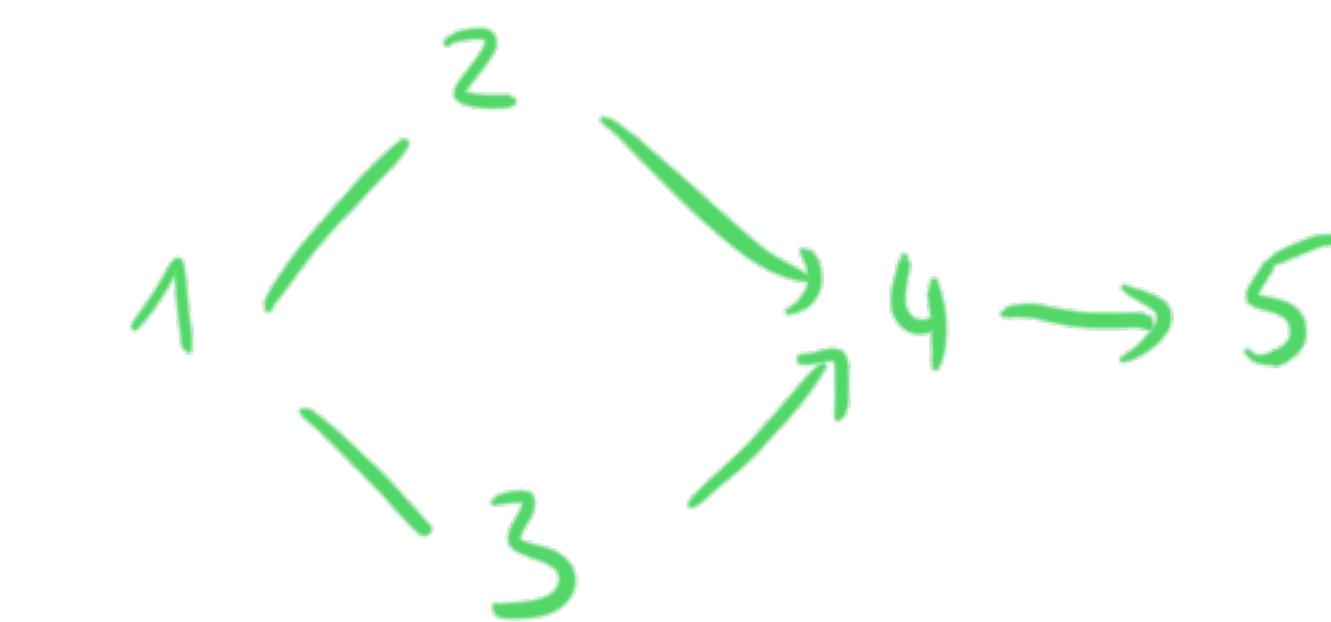


If the true graph is known we can compute
the CPDAG representing the MEC



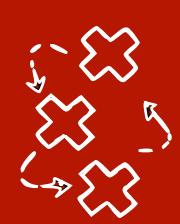
CPDAG example 2

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If the true graph is known we can compute
the CPDAG representing the MEC

What if it isn't known?!

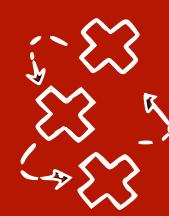


Constraint-based causal discovery

- **Idea:** we perform conditional independence tests on **observational** data and use them to constrain the possible graphs using d-separation

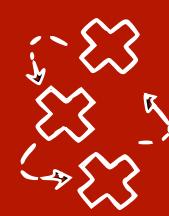
$X \not\perp\!\!\!\perp Y \quad X \perp\!\!\!\perp Y | Z$

$X - Z - Y$



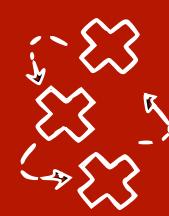
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- In general, we can narrow down the possible graphs only up to their **Markov equivalence class (MEC)**



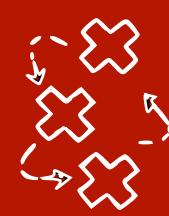
Constraint-based causal discovery

- **Idea:** we perform conditional independence tests on **observational** data and use them to constrain the possible graphs using d-separation
- In general, we can narrow down the possible graphs only up to their **Markov equivalence class (MEC)**
- The output of the algorithms we will see (e.g. SGS, PC) is a **CPDAG**, a mixed graph in which directed edges represent causal relations on which all DAGs in the MEC agree - these relations are **identifiable**



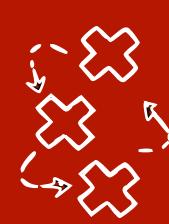
SGS algorithm (Spirtes, Glymour, Scheines)

- Assuming P is Markov and faithful to an unknown graph G
- We can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton**
 2. Determine the **v-structures**
 3. Direct as many remaining edges as possible



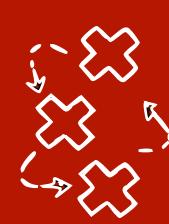
SGS algorithm (Spirtes, Glymour, Scheines)

- Assuming P is Markov and faithful to an unknown graph G
- We can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton**
 2. Determine the **v-structures** (*given the tests in the previous phase*)
 3. Direct as many remaining edges as possible
- **Note:** the directed parts of the CPDAG will agree with G , but some parts might stay undirected



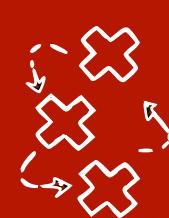
Step 1: Skeleton learning

- Given $G = (V, E)$, nodes $i, j \in V, i \neq j$ then:
 - If i is adjacent to j , they cannot be d-separated by any subset of remaining nodes (and vice-versa)



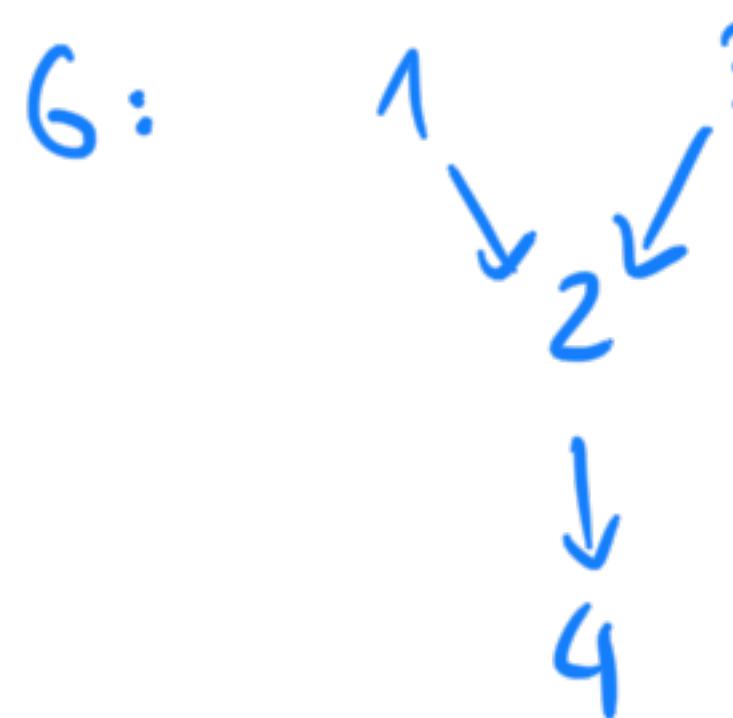
Step 1: Skeleton learning

- Given $G = (V, E)$, nodes $i, j \in V, i \neq j$ then:
 - If i is adjacent to j , they cannot be d-separated by any subset of remaining nodes (and vice-versa)
- Start with **completely connected undirected graph U**
 - For each pair $i, j \in V, i \neq j$, and for any subset $S \subseteq V \setminus \{i, j\}$
 - Check **if $X_i \perp\!\!\!\perp X_j | X_S$** for any S in data
 - If this is true, by faithfulness $i \perp\!\!\!\perp_G j | S$, so we can **remove $i - j$ in U**



Step 1: Skeleton learning - example

True causal graph



$$P: P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

Data

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

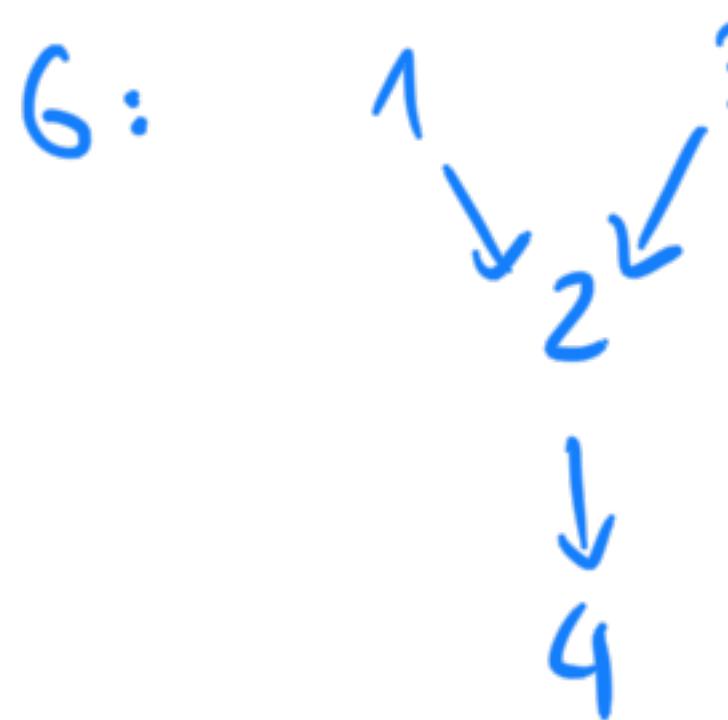
Algorithm output



For this example, we will pretend we do not know the true graph, but only the CIs that we can derive from data

Step 1: Skeleton learning - example

True causal graph



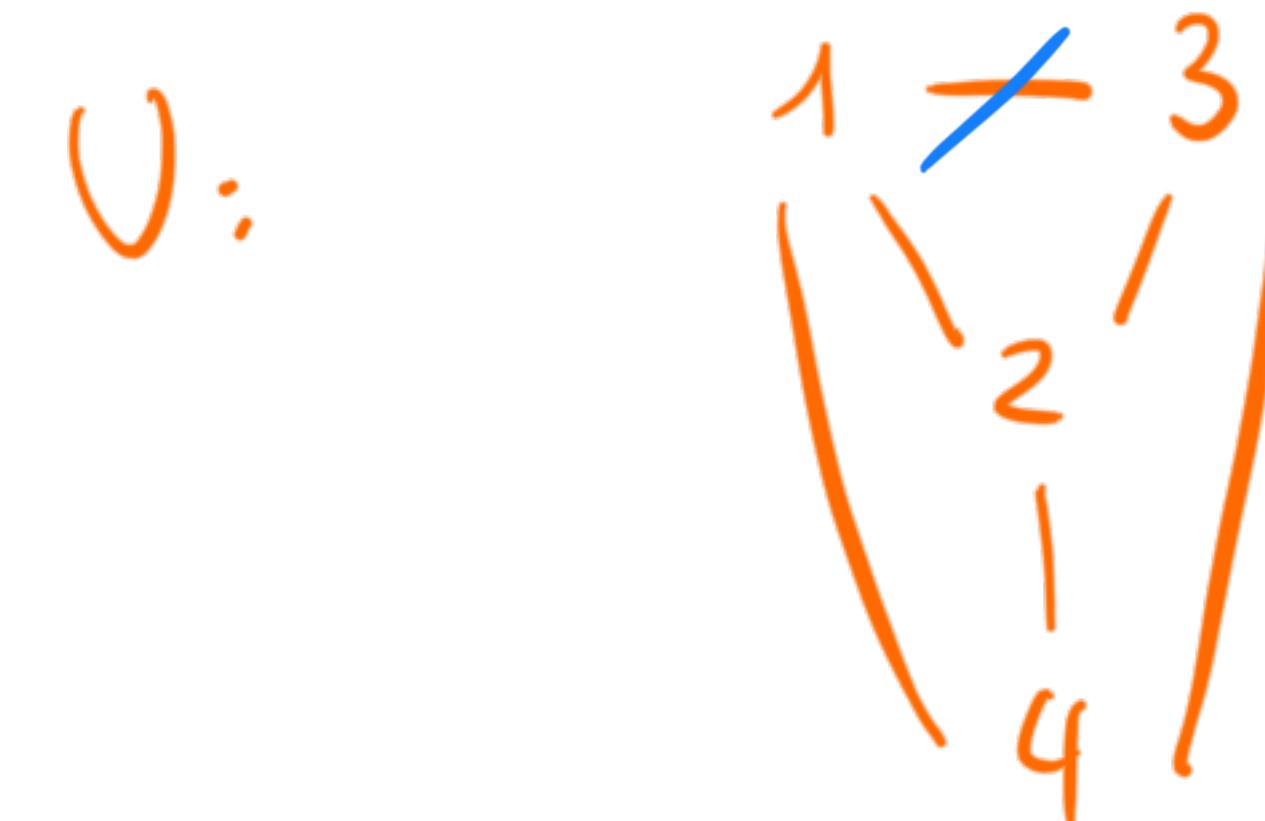
$$P: P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

Data

x_1	x_2	x_3	x_4
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1	0	0	1
0	1	0	1
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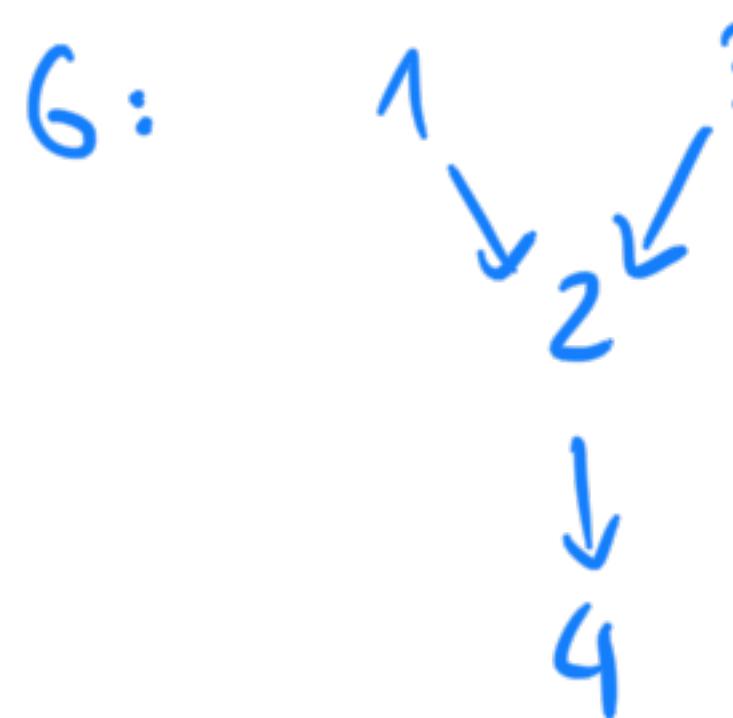
$$x_1 \perp\!\!\!\perp x_3$$

Algorithm output



Step 1: Skeleton learning - example

True causal graph



$$P: P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

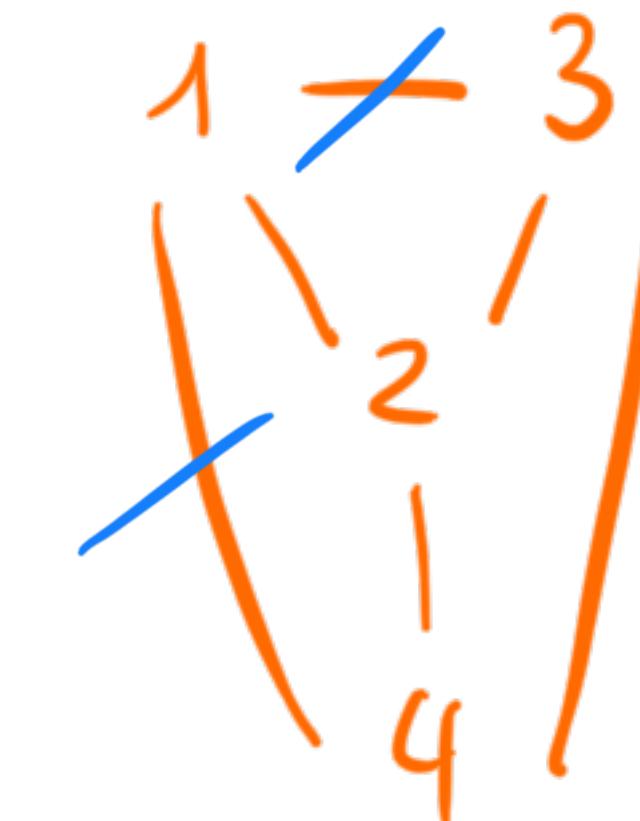
Data

1:

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

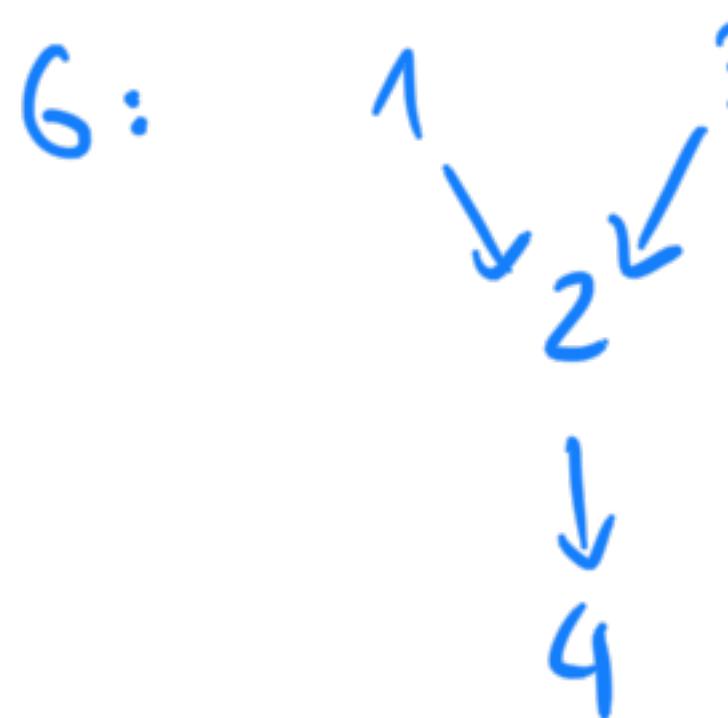
$$x_1 \perp\!\!\!\perp x_4 | x_2$$

Algorithm output



Step 1: Skeleton learning - example

True causal graph



$$P: P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

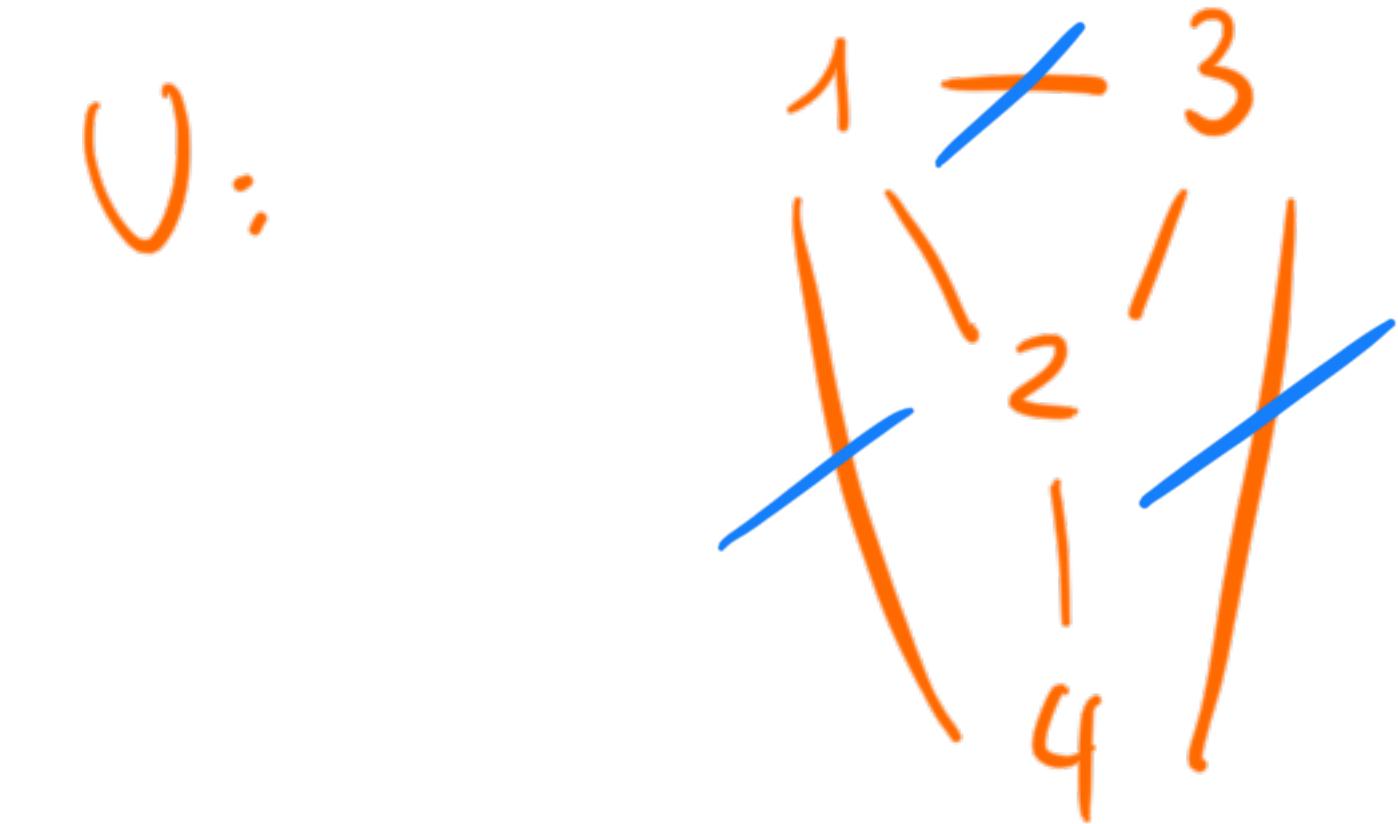
Data

True causal graph (blue) and Data (green) are grouped by a green brace.

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

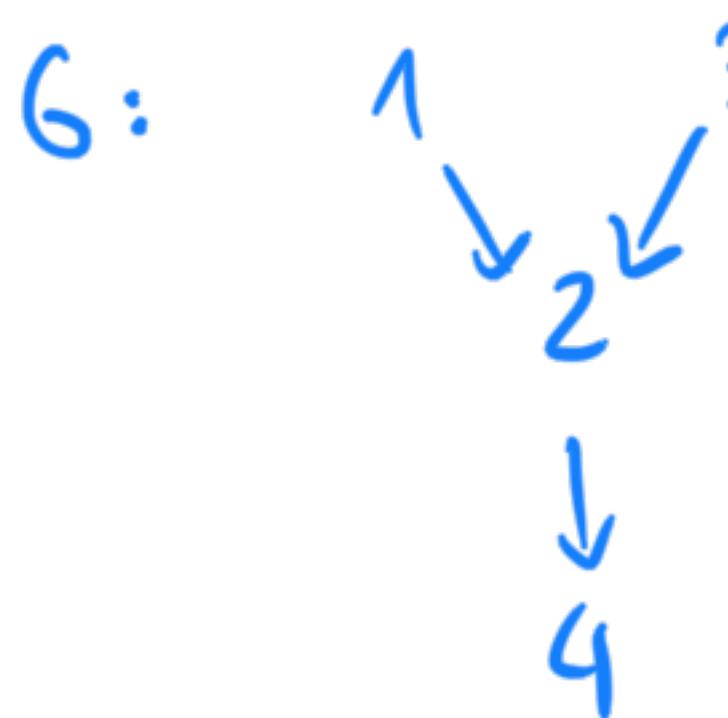
$$x_3 \perp\!\!\!\perp x_4 | x_2$$

Algorithm output



Step 1: Skeleton learning - example

True causal graph



$$P: P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

Data

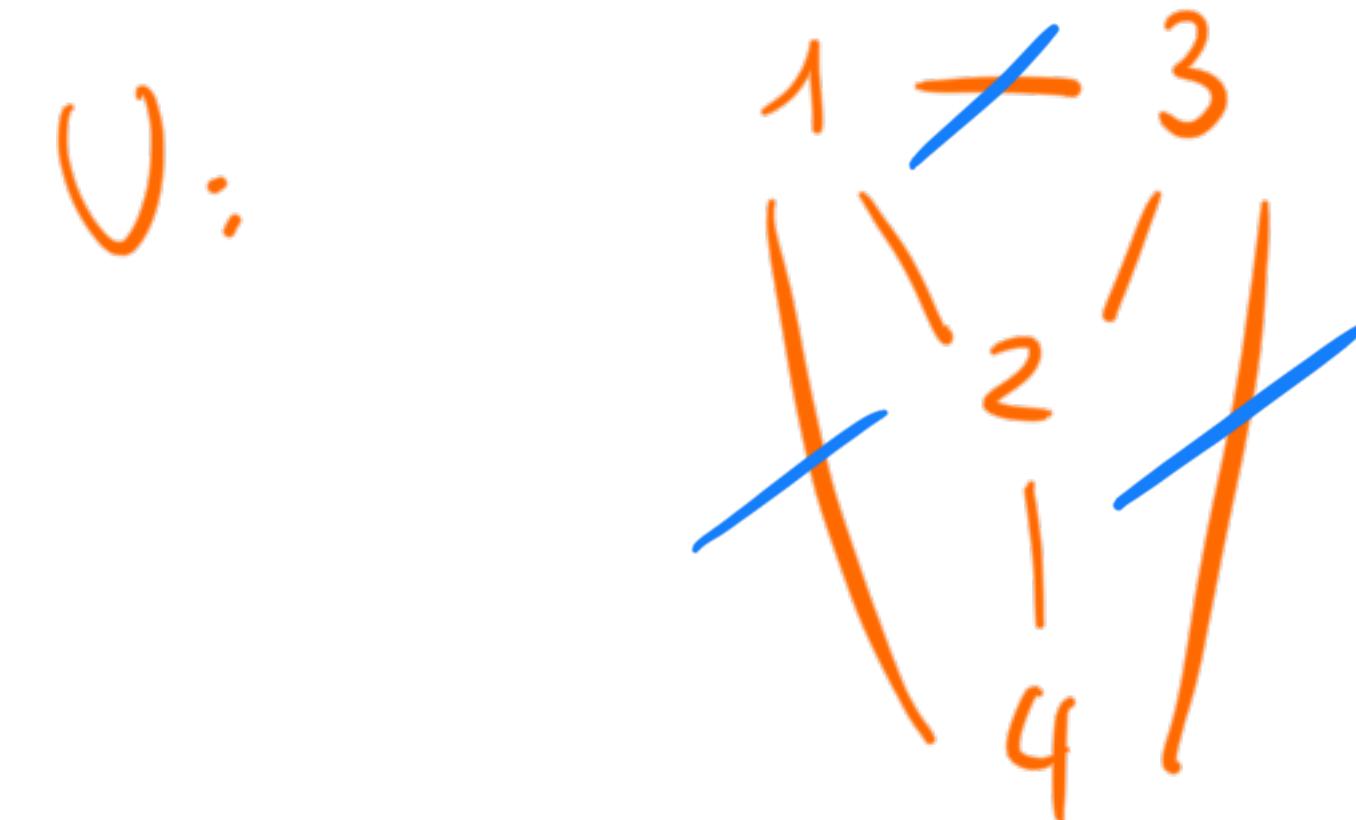
Handwritten data table:

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

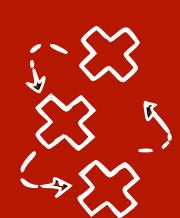
$$x_1 \perp\!\!\!\perp x_4 | x_2, x_3$$

$$x_3 \perp\!\!\!\perp x_4 | x_2, x_1$$

Algorithm output

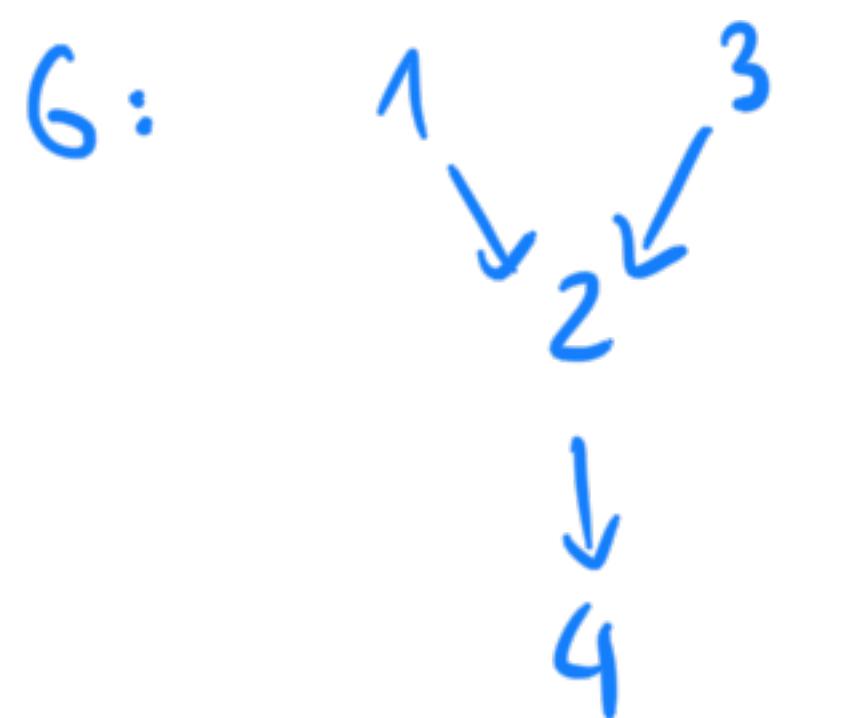


Nothing changes, we can stop



Step 1: Skeleton learning - example

True causal graph

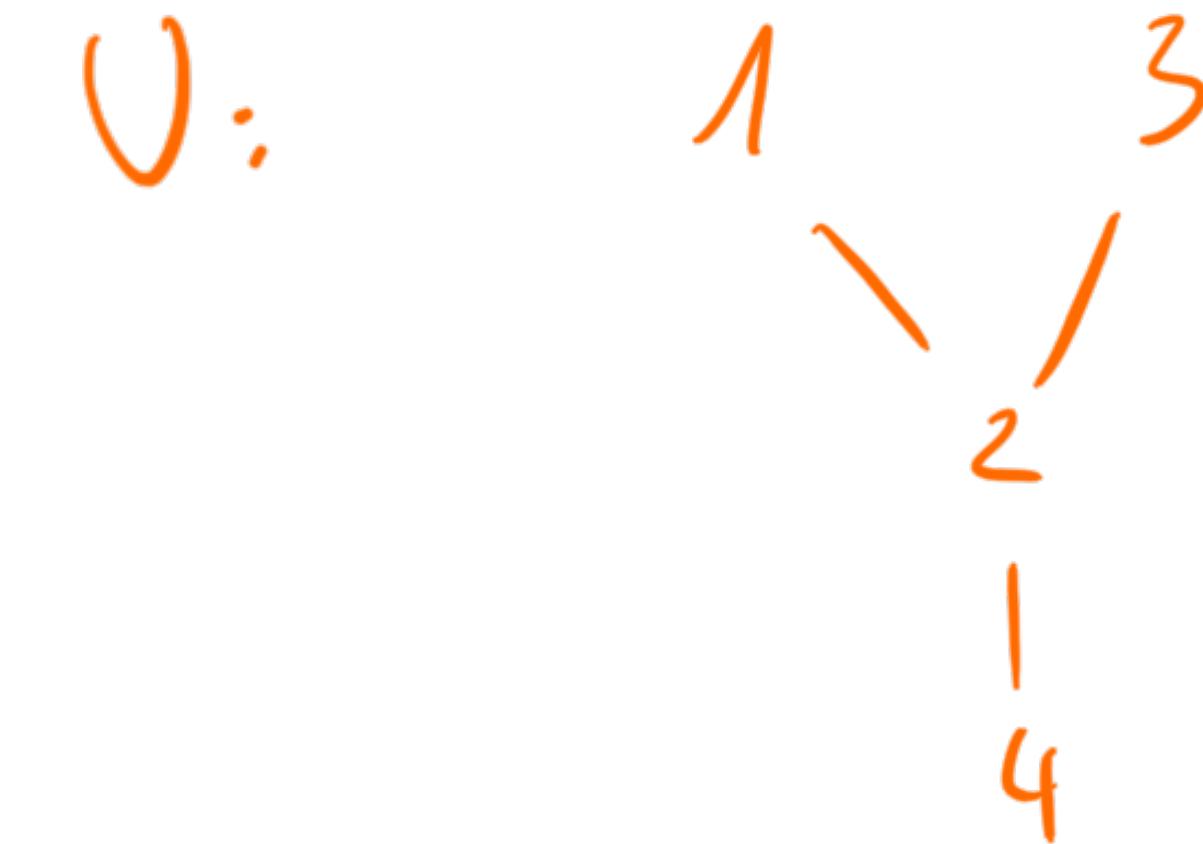


P: $P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$

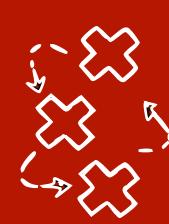
Data

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

Algorithm output

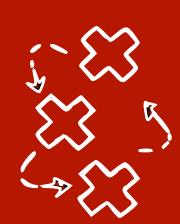


Step 1 finds the correct skeleton



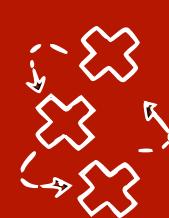
SGS algorithm (Spirtes, Glymour, Scheines)

- Assuming P is Markov and faithful to an unknown graph G
- We can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton**
 2. Determine the **v-structures** (*given the tests in the previous phase*)
 3. Direct as many remaining edges as possible
- **Note:** the directed parts of the CPDAG will agree with G , but some parts might stay undirected



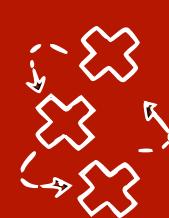
Step 2: Determine v-structures

- A triple of nodes (i, j, k) in a DAG G is a **an unshielded triple** if $i - j, j - k$ and **i is not adjacent to k** , i.e. $i \perp k$, in G



Step 2: Determine v-structures

- A triple of nodes (i, j, k) in a DAG G is a **an unshielded triple** if $i - j, j - k$ and i **is not adjacent to k**, i.e. $i \perp\!\!\!\perp k$, in G
1. Start from the skeleton U from previous step
 2. For each unshielded triple (i, j, k) in U , i.e. $i - j, j - k$ **and** $i \perp\!\!\!\perp k$ in U
 - For all $S \subseteq V \setminus \{i, j, k\}$ check if $X_i \not\perp\!\!\!\perp X_k | X_j \cup X_S$ in data
 - If this is true, $i \rightarrow j \leftarrow k$ **is a v-structure**

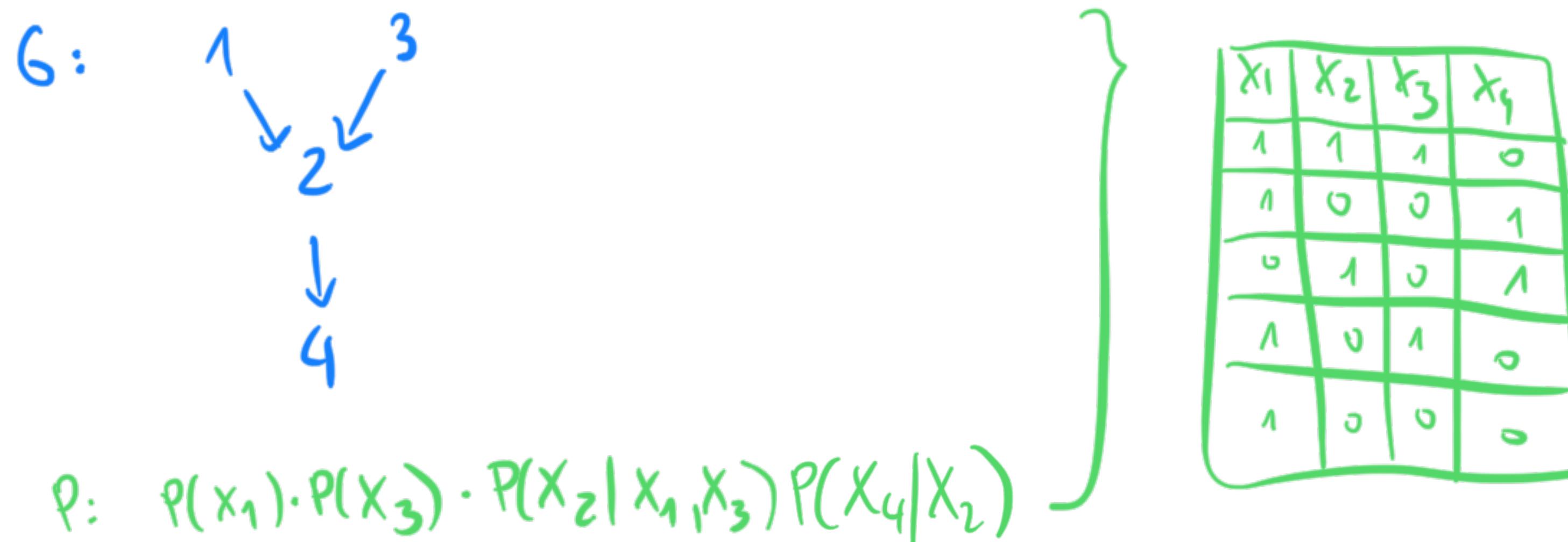


Step 2: Determine v-structures

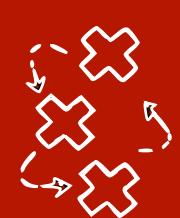
- A triple of nodes (i, j, k) in a DAG G is a **an unshielded triple** if $i - j, j - k$ and i is not adjacent to k , i.e. $i \perp\!\!\!\perp k$ in G
- Keep in mind:** for unshielded triples (i, j, k) we check if X_i, X_j are always dependent given any conditioning set containing X_j

 1. Start from the skeleton U from previous slide
 2. For each unshielded triple (i, j, k) in U , i.e. $i - j, j - k$ and $i \perp\!\!\!\perp k$ in U
 - For all $S \subseteq V \setminus \{i, j, k\}$ check if $X_i \not\perp\!\!\!\perp X_k | X_j \cup X_S$ in data
 - If this is true, $i \rightarrow j \leftarrow k$ is a **v-structure**

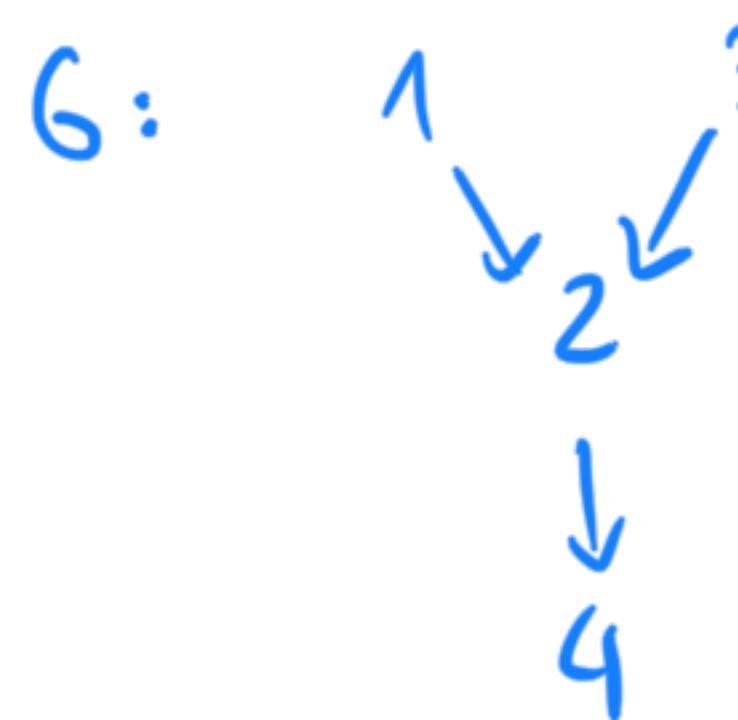
Step 2: Determine v-structures - example



x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0



Step 2: Determine v-structures - example



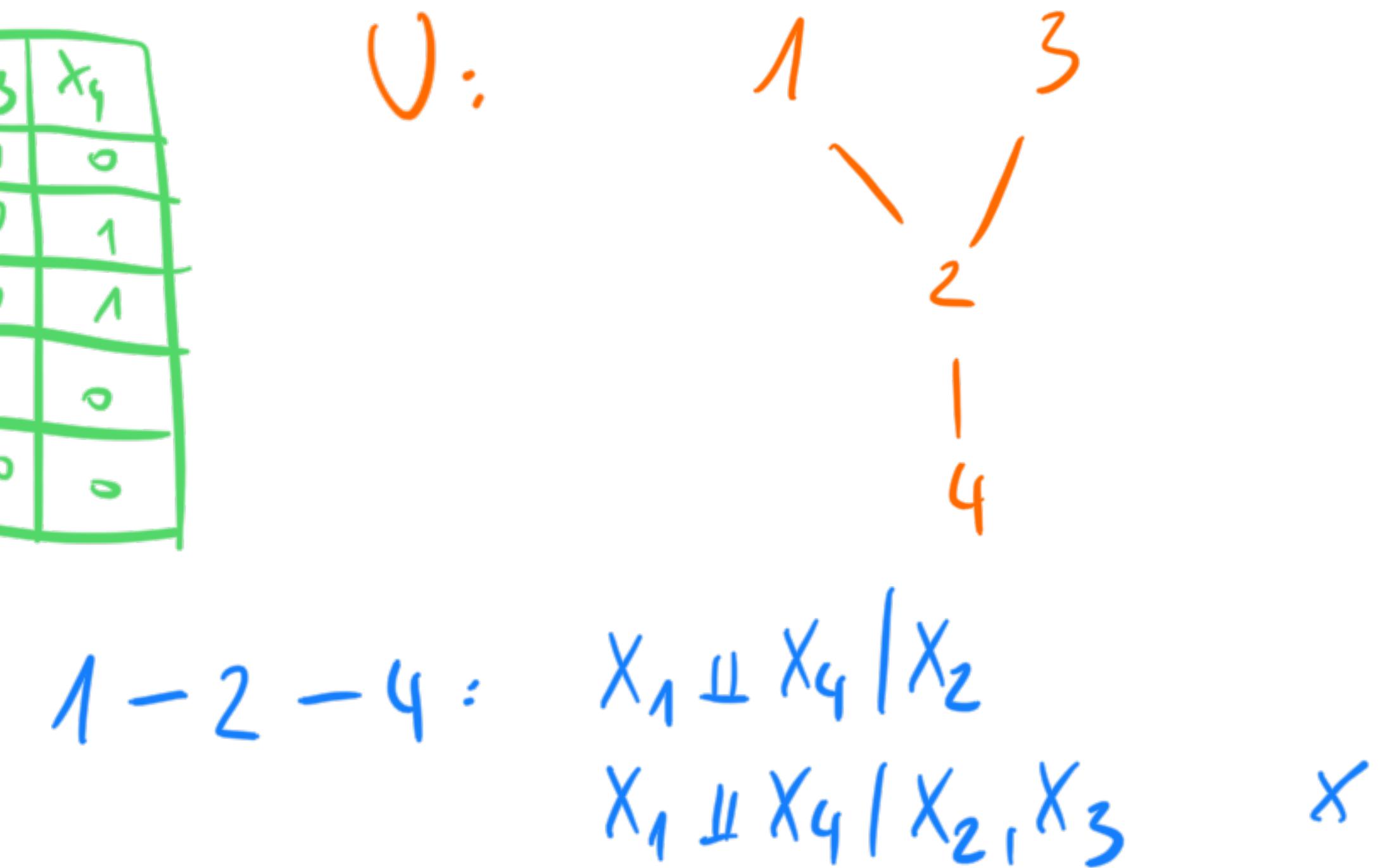
$$\rho: \rho(x_1) \cdot \rho(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

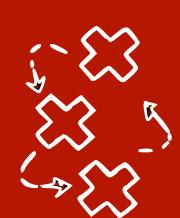
We can reuse
the CIs from
phase 1

- $X_1 \perp\!\!\!\perp X_3$
- $X_1 \perp\!\!\!\perp X_4 | X_2$
- $X_3 \perp\!\!\!\perp X_4 | X_2$
- $X_1 \perp\!\!\!\perp X_4 | X_2, X_3$
- $X_3 \perp\!\!\!\perp X_4 | X_2, X_1$

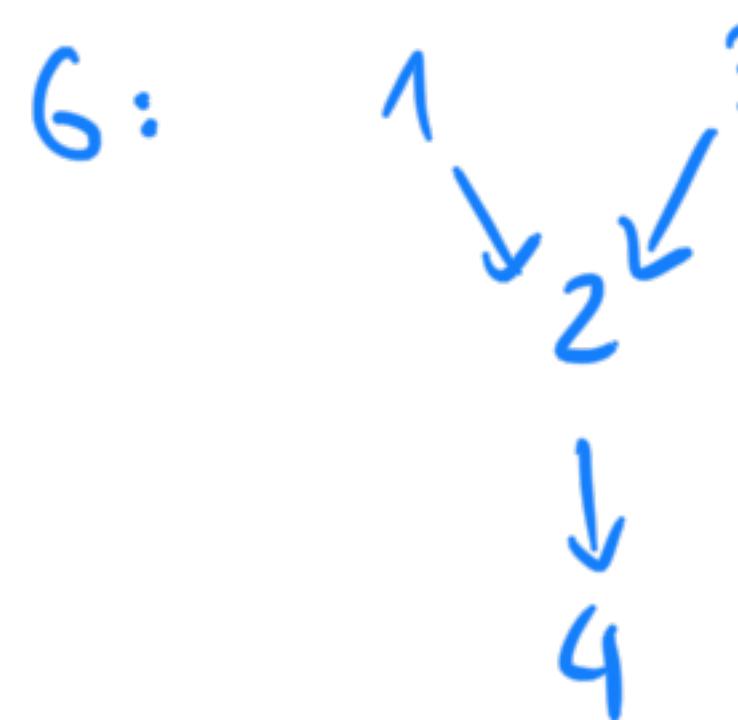
}

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0





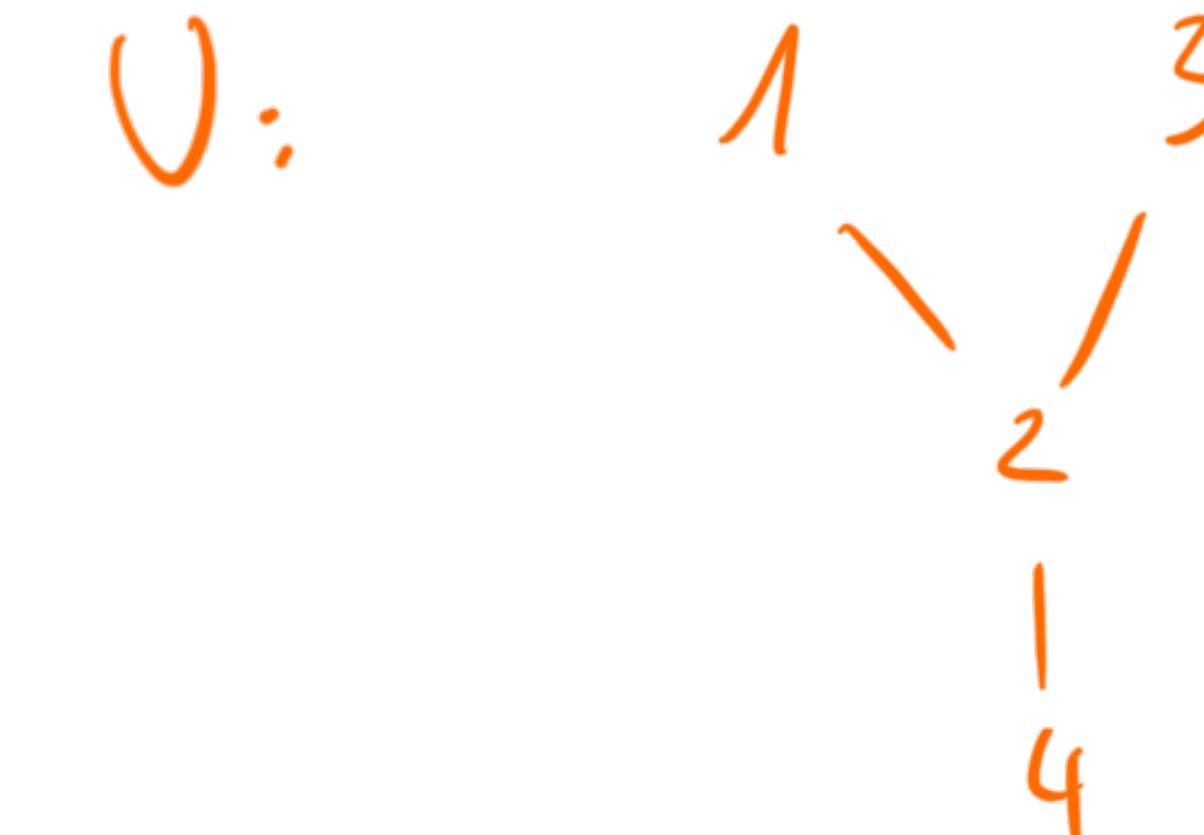
Step 2: Determine v-structures - example



$$\rho: \rho(x_1) \cdot \rho(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

}()

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0



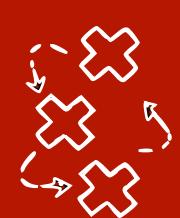
We can reuse
the CIs from
phase 1

- $X_1 \perp\!\!\!\perp X_3$
- $X_1 \perp\!\!\!\perp X_4 | X_2$
- $X_3 \perp\!\!\!\perp X_4 | X_2$
- $X_1 \perp\!\!\!\perp X_4 | X_2, X_3$
- $X_3 \perp\!\!\!\perp X_4 | X_2, X_1$

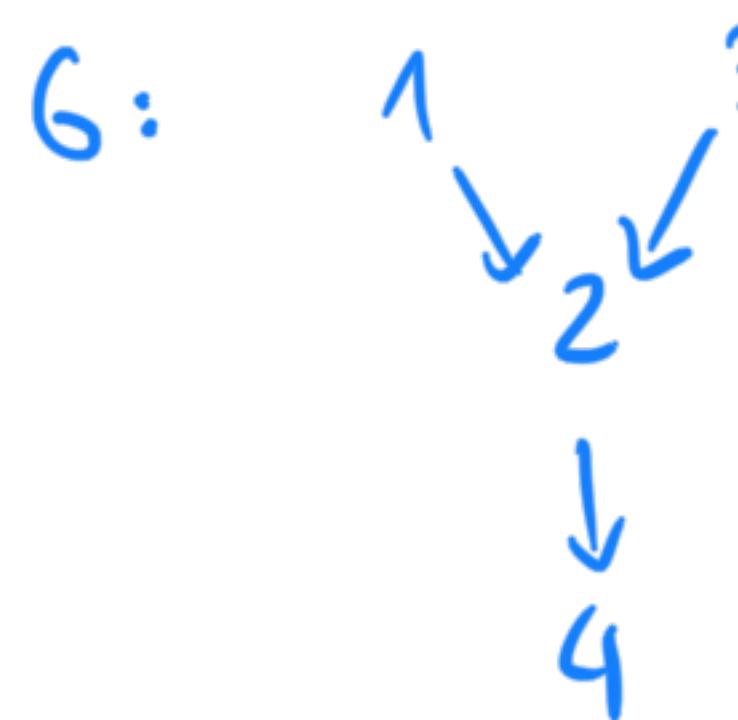
3-2-4

- $X_3 \perp\!\!\!\perp X_4 | X_2$
- $X_3 \perp\!\!\!\perp X_4 | X_2, X_1$

X



Step 2: Determine v-structures - example



$$\rho: \rho(x_1) \cdot \rho(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

We can reuse
the CIs from
phase 1

$X_1 \perp\!\!\!\perp X_3$
 $X_1 \perp\!\!\!\perp X_4 | X_2$
 $X_3 \perp\!\!\!\perp X_4 | X_2$
 $X_1 \perp\!\!\!\perp X_4 | X_2, X_3$
 $X_3 \perp\!\!\!\perp X_4 | X_2, X_1$

$X_1 \perp\!\!\!\perp X_3$ has $Z = \emptyset$, so it does
not contain X_2 and we ignore it

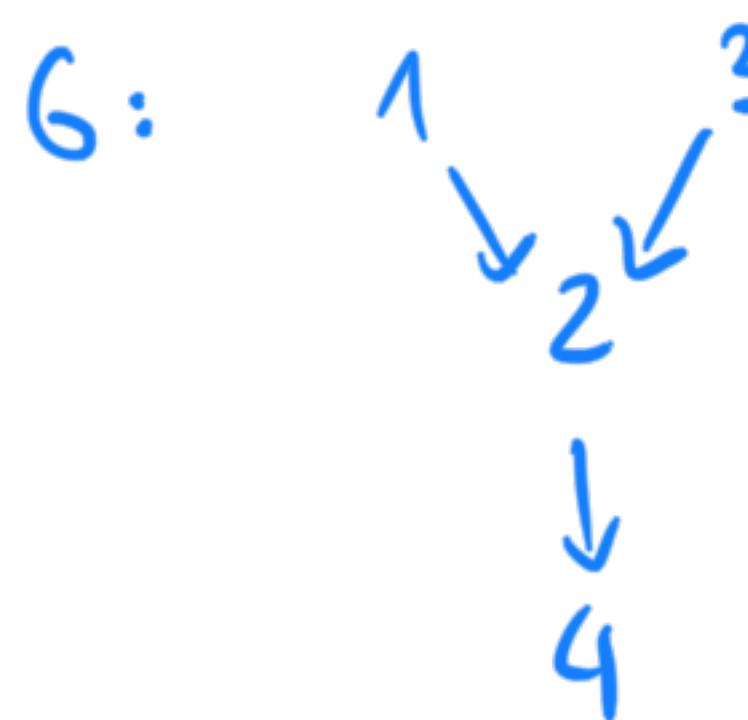
}

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0



$\cancel{X_1 \perp\!\!\!\perp X_3 | X_2}$ ✓
 $\cancel{X_1 \perp\!\!\!\perp X_3 | X_2, X_4}$ ✓

Step 2: Determine v-structures - example



$$P: P(x_1) \cdot P(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

}

x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

1 - 2 - 3

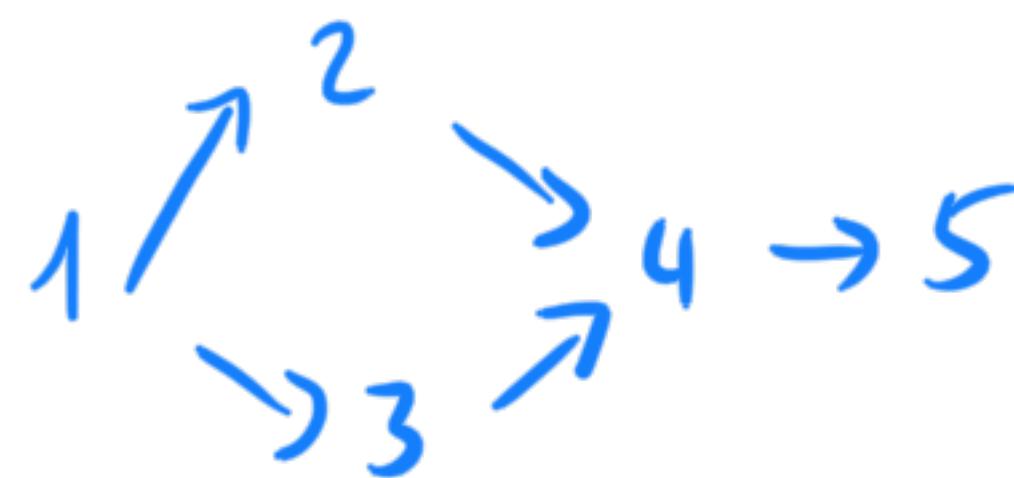
U:



$x_1 \not\perp\!\!\!\perp x_3 | x_2$ ✓

$x_1 \not\perp\!\!\!\perp x_3 | x_2, x_4$ ✓

Step 2: Determine v-structures - example 2



$X_1 \perp\!\!\!\perp X_4 | X_2, X_3$

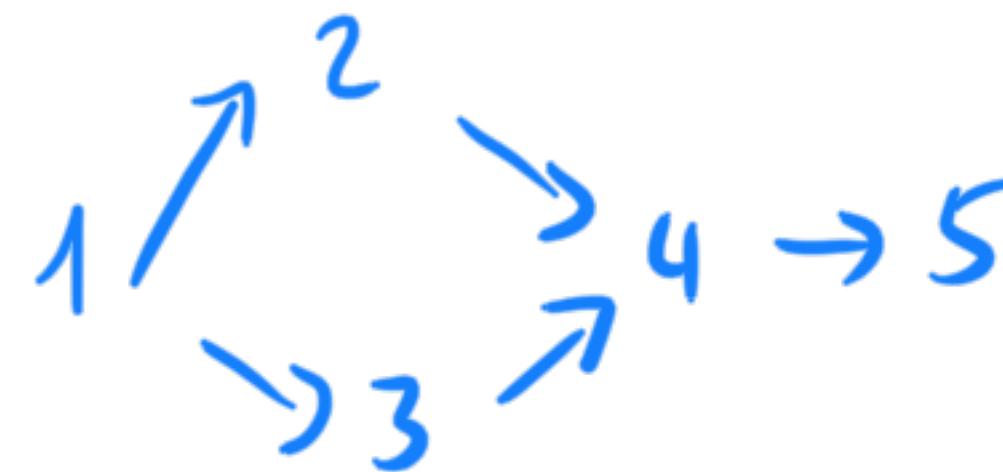
$X_2 \perp\!\!\!\perp X_3 | X_1$

$X_3 \perp\!\!\!\perp X_5 | X_4$

$X_2 \perp\!\!\!\perp X_5 | X_4$

$X_1 \perp\!\!\!\perp X_5 | X_4$

Step 2: Determine v-structures - example 2



$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3$$

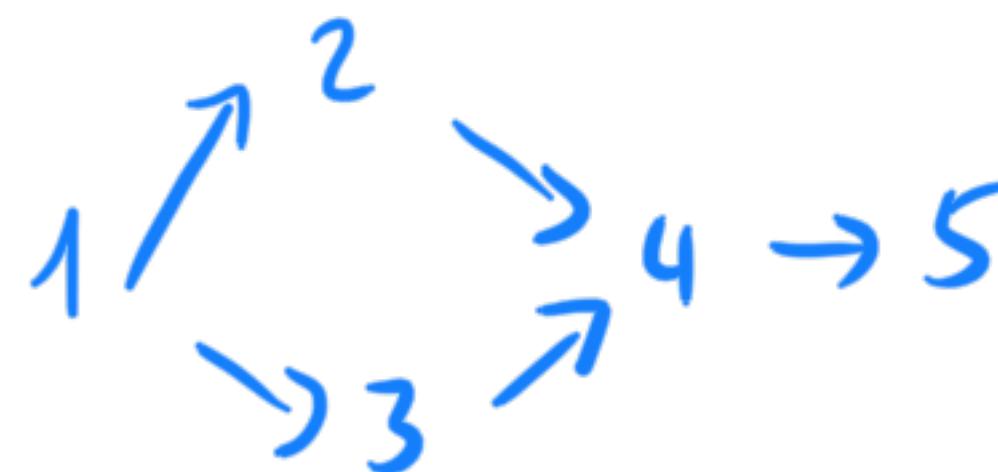
$$X_2 \perp\!\!\!\perp X_3 \mid X_1$$

$$X_3 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_2 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_1 \perp\!\!\!\perp X_5 \mid X_4$$

Step 2: Determine v-structures - example 2



$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3$$

$$X_2 \perp\!\!\!\perp X_3 \mid X_1$$

$$X_3 \perp\!\!\!\perp X_5 \mid X_4$$

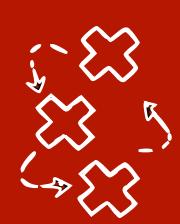
$$X_2 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_1 \perp\!\!\!\perp X_5 \mid X_4$$

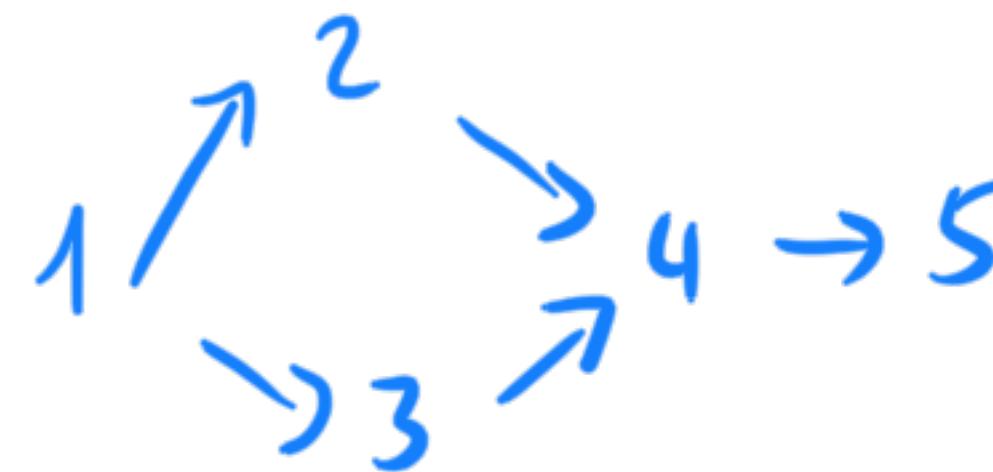
1-2-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_2$$

$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3 \quad \times$$



Step 2: Determine v-structures - example 2



$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3$$

$$X_2 \perp\!\!\!\perp X_3 \mid X_1$$

$$X_3 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_2 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_1 \perp\!\!\!\perp X_5 \mid X_4$$

1-2-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_2$$

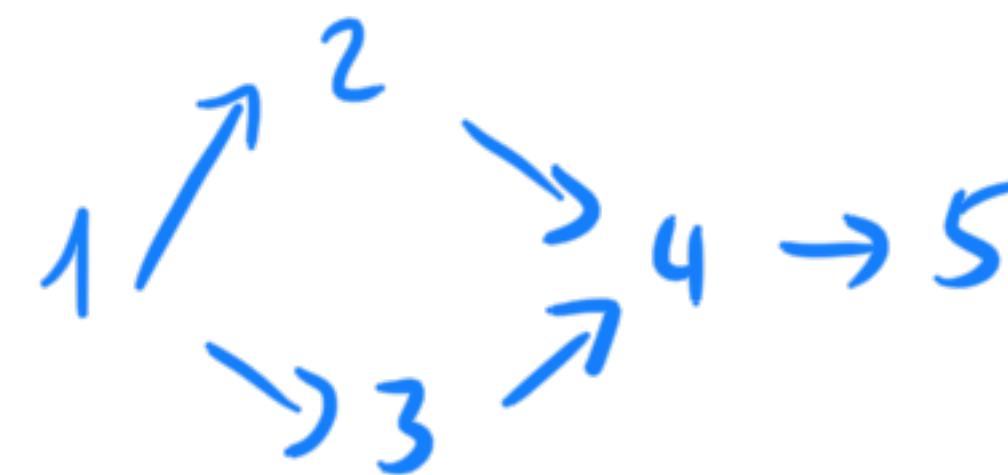
$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3 \quad \times$$

1-3-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_3$$

$$X_1 \perp\!\!\!\perp X_4 \mid X_3, X_2$$

Step 2: Determine v-structures - example 2



$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3$$

$$X_2 \perp\!\!\!\perp X_3 \mid X_1$$

$$X_3 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_2 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_1 \perp\!\!\!\perp X_5 \mid X_4$$

1-2-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_2$$

$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3 \quad \times$$

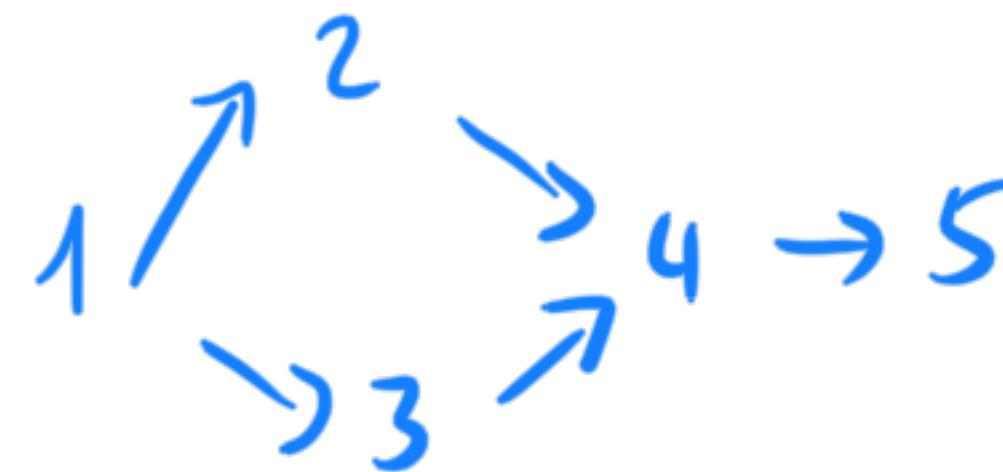
1-3-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_3$$

$$X_1 \perp\!\!\!\perp X_4 \mid X_3, X_2$$

3-1-2: $X_3 \perp\!\!\!\perp X_2 \mid X_1 \quad \times$

Step 2: Determine v-structures - example 2



$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3$$

$$X_2 \perp\!\!\!\perp X_3 \mid X_1$$

$$X_3 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_2 \perp\!\!\!\perp X_5 \mid X_4$$

$$X_1 \perp\!\!\!\perp X_5 \mid X_4$$

1-2-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_2$$

$$X_1 \perp\!\!\!\perp X_4 \mid X_2, X_3$$

1-3-4

$$X_1 \not\perp\!\!\!\perp X_4 \mid X_3$$

$$X_1 \perp\!\!\!\perp X_4 \mid X_3, X_2$$

3-1-2:

$$X_3 \perp\!\!\!\perp X_2 \mid X_1 \quad \times$$

2-4-5:

$$X_2 \perp\!\!\!\perp X_5 \mid X_4 \quad \times$$

Step 2: Determine v-structures - example 2



$$\begin{aligned} X_1 \perp\!\!\!\perp X_4 | X_2, X_3 \\ X_2 \perp\!\!\!\perp X_3 | X_1 \\ \textcolor{blue}{X_3 \perp\!\!\!\perp X_5 | X_4} \end{aligned}$$

$$\begin{aligned} X_2 \perp\!\!\!\perp X_5 | X_4 \\ X_1 \perp\!\!\!\perp X_5 | X_4 \end{aligned}$$

1-2-4

$$\begin{aligned} X_1 \not\perp\!\!\!\not\perp X_4 | X_2 \\ X_1 \perp\!\!\!\perp X_4 | X_2, X_3 \end{aligned}$$

1-3-4

$$\begin{aligned} X_1 \not\perp\!\!\!\not\perp X_4 | X_3 \\ X_1 \perp\!\!\!\perp X_4 | X_3, X_2 \end{aligned}$$

3-1-2:

$$X_3 \perp\!\!\!\perp X_2 | X_1 \quad \times$$

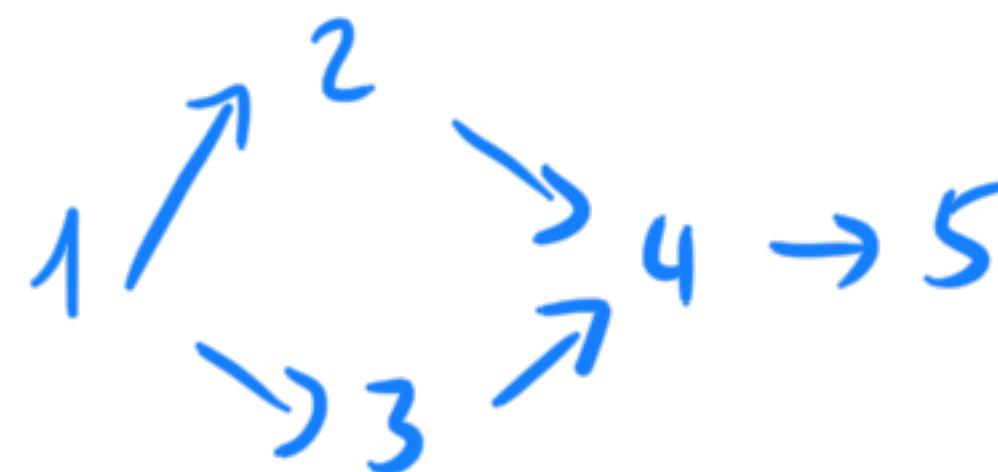
2-4-5:

$$X_2 \perp\!\!\!\perp X_5 | X_4 \quad \times$$

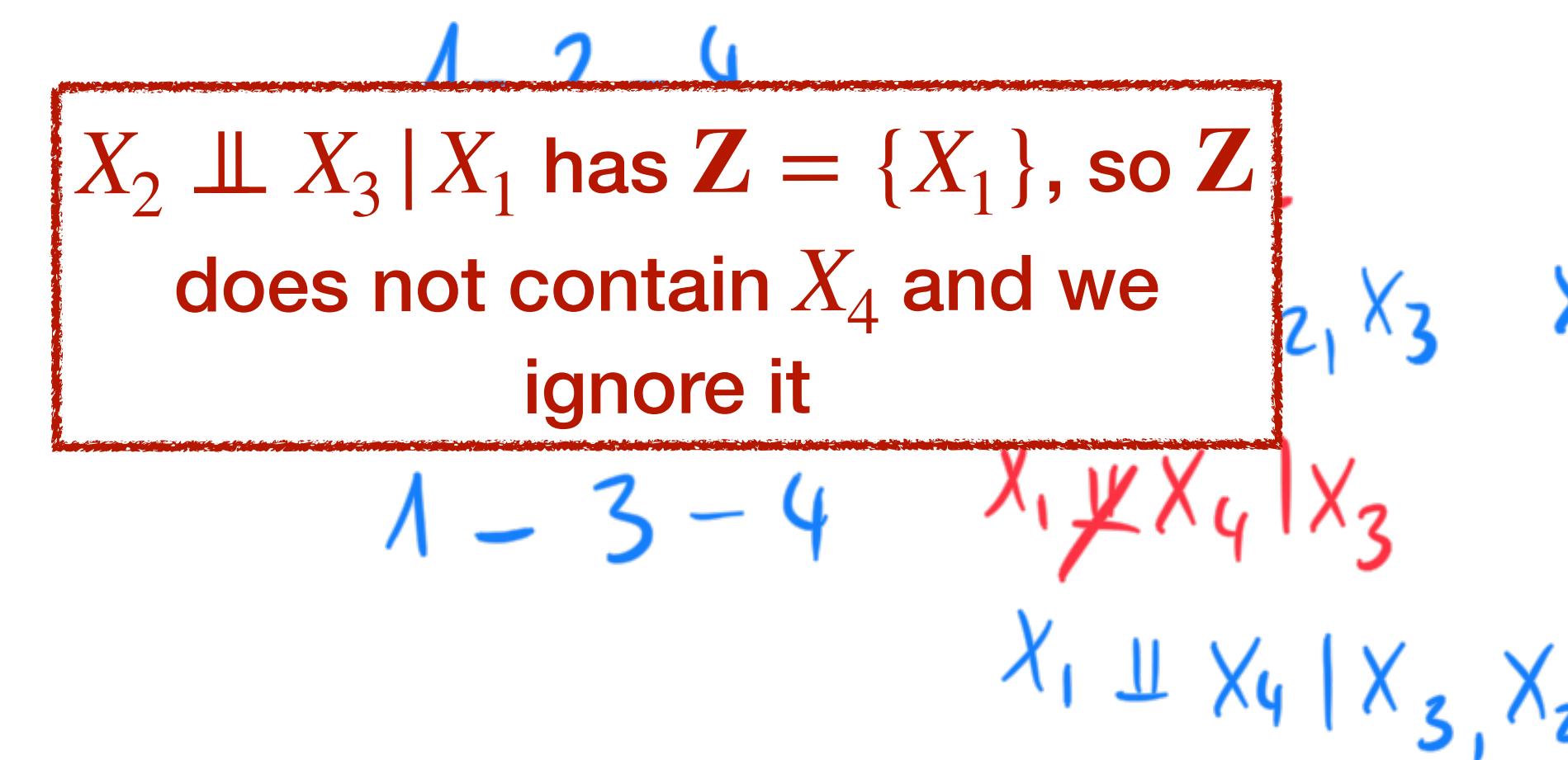
3-4-5:

$$X_3 \perp\!\!\!\perp X_5 | X_4 \quad \times$$

Step 2: Determine v-structures - example 2



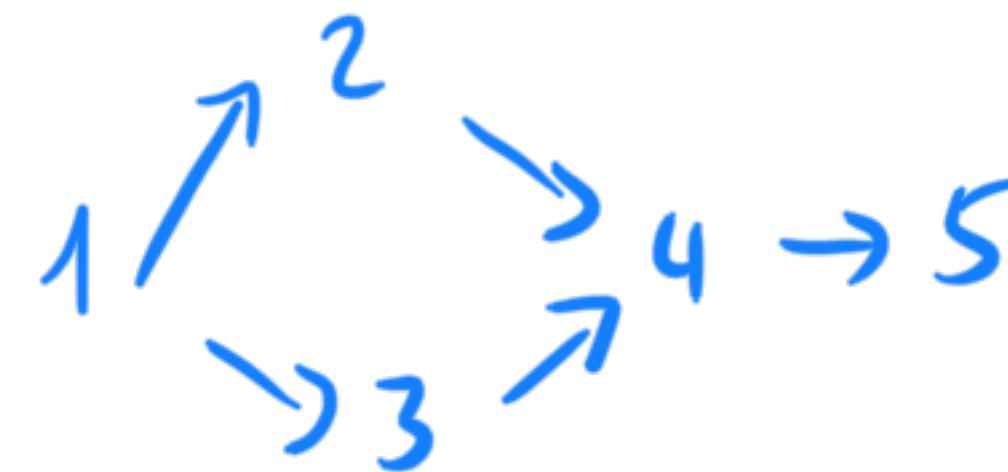
$X_1 \perp\!\!\!\perp X_4 | X_2, X_3$
 $X_2 \perp\!\!\!\perp X_3 | X_1$
 $X_3 \perp\!\!\!\perp X_5 | X_4$
 $X_2 \perp\!\!\!\perp X_5 | X_4$
 $X_1 \perp\!\!\!\perp X_5 | X_4$



3-1-2: $X_3 \perp\!\!\!\perp X_2 | X_1$ \times
 2-4-5: $X_2 \perp\!\!\!\perp X_5 | X_4$ \times
 3-4-5: $X_3 \perp\!\!\!\perp X_5 | X_4$ \times

 2-4-3 $X_2 \not\perp\!\!\!\perp X_3 | X_4$ $X_2 \not\perp\!\!\!\perp X_3 | X_4, X_1$
 $X_2 \not\perp\!\!\!\perp X_3 | X_4, X_1, X_5$ $X_2 \not\perp\!\!\!\perp X_3 | X_4, X_5$

Step 2: Determine v-structures - example 2



$X_1 \perp\!\!\!\perp X_4 | X_2, X_3$
 $X_2 \perp\!\!\!\perp X_3 | X_1$
 $X_3 \perp\!\!\!\perp X_5 | X_4$
 $X_2 \perp\!\!\!\perp X_5 | X_4$
 $X_1 \perp\!\!\!\perp X_5 | X_4$

1-2-4

$X_1 \not\perp\!\!\!\perp X_4 | X_2$
 $X_1 \perp\!\!\!\perp X_4 | X_2, X_3$

3-1-2: $X_3 \perp\!\!\!\perp X_2 | X_1$ \times

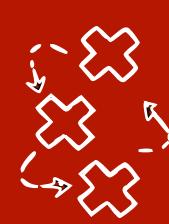
1-3-4

$X_1 \not\perp\!\!\!\perp X_4 | X_3$
 $X_1 \perp\!\!\!\perp X_4 | X_3, X_2$

2-4-5: $X_2 \perp\!\!\!\perp X_5 | X_4$ \times

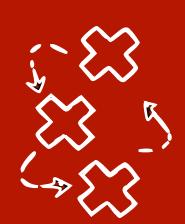
3-4-5: $X_3 \perp\!\!\!\perp X_5 | X_4$ \times

$X_2 \not\perp\!\!\!\perp X_3 | X_4, X_1$
 $X_2 \not\perp\!\!\!\perp X_3 | X_4, X_1, X_5$



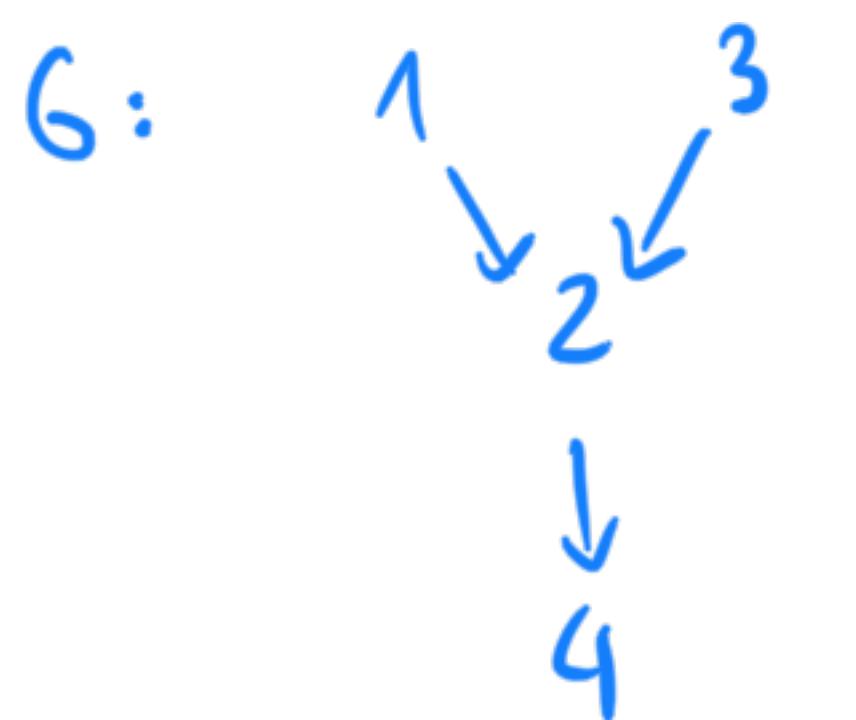
SGS algorithm (Spirtes, Glymour, Scheines)

- Assuming P is Markov and faithful to an unknown graph G
- We can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton**
 2. Determine the **v-structures** (*given the tests in the previous phase*)
 3. Direct as many remaining edges as possible
- **Note:** the directed parts of the CPDAG will agree with G , but some parts might stay undirected



Step 3: Direct as many edges as possible - example

- Cannot create cycles or new v-structures
- Some of the edges can be oriented to disallow these situations to happen



$$\rho: \rho(x_1) \cdot \rho(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

}

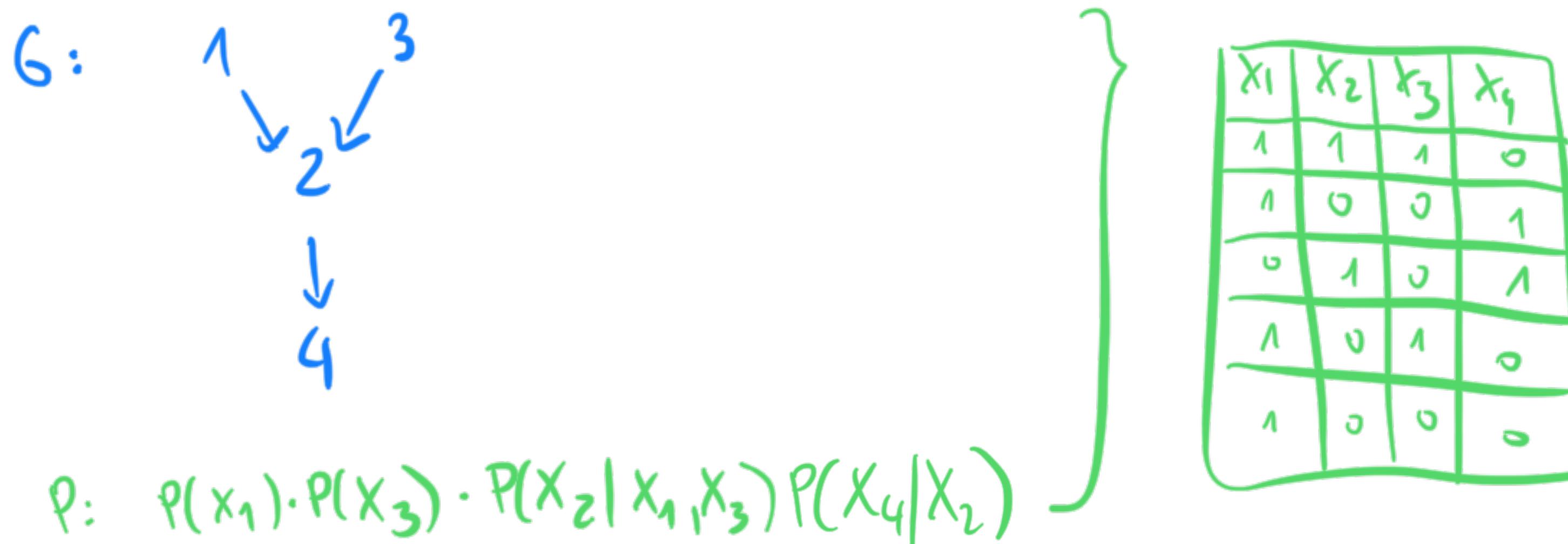
x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0

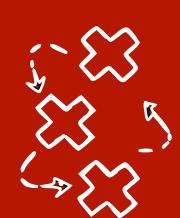
U:



Step 3: Direct as many edges as possible - example

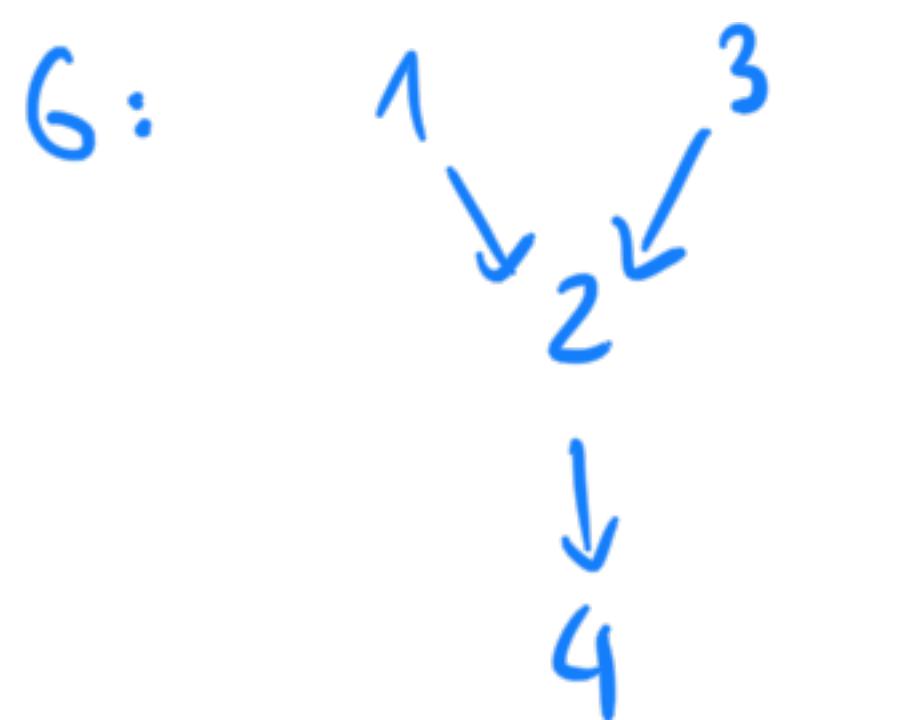
- Cannot create cycles or new v-structures
- Some of the edges can be oriented to disallow these situations to happen





Step 3: Direct as many edges as possible - example

- Cannot create cycles or new v-structures
- Some of the edges can be oriented to disallow these situations to happen

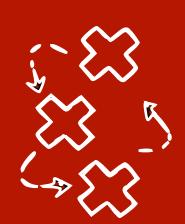


$$\rho: \rho(x_1) \cdot \rho(x_3) \cdot P(x_2 | x_1, x_3) P(x_4 | x_2)$$

CPDAG:

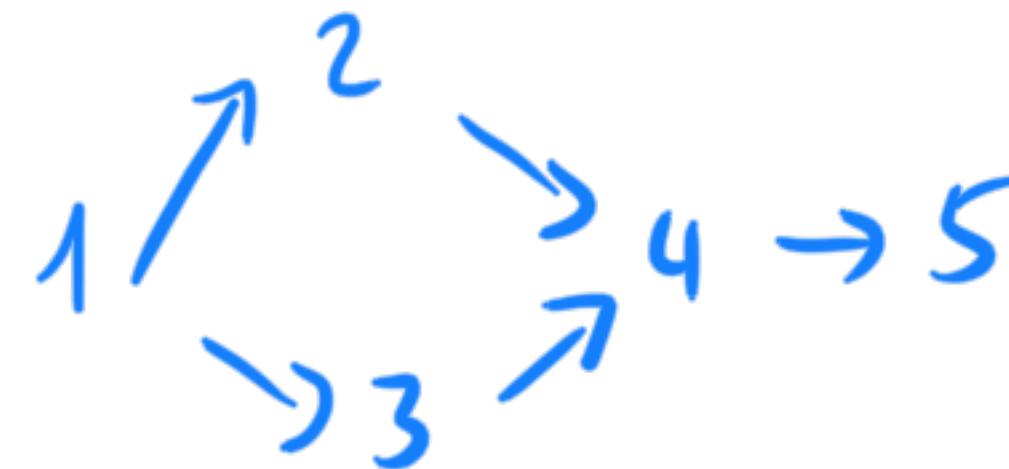
x_1	x_2	x_3	x_4
1	1	1	0
1	0	0	1
0	1	0	1
1	0	1	0
1	0	0	0





Step 3: Direct as many edges as possible - example

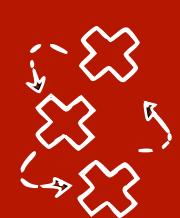
- Cannot create cycles or new v-structures
- Some of the edges can be oriented to disallow these situations to happen



Step 3: Direct as many edges as possible - example

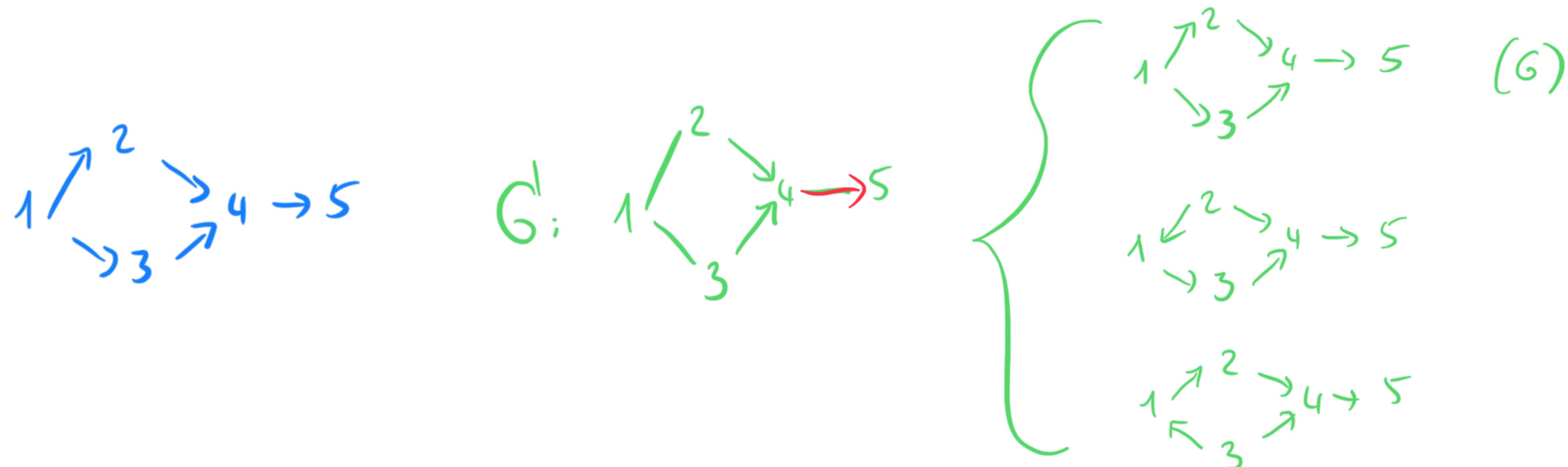
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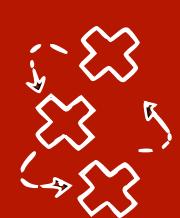




Step 3: Direct as many edges as possible - example

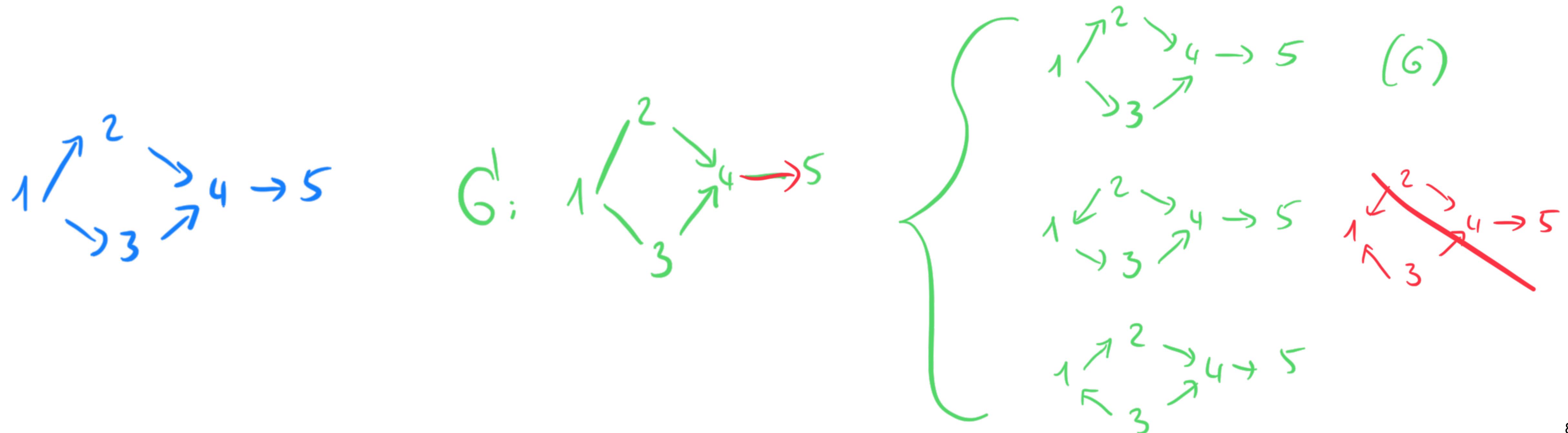
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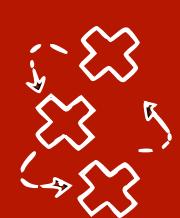




Step 3: Direct as many edges as possible - example

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- Some of the edges can be oriented to disallow these situations to happen





Step 3: Meek's rules (1995)

Sound and complete rules for additional orientations (also with added background knowledge)

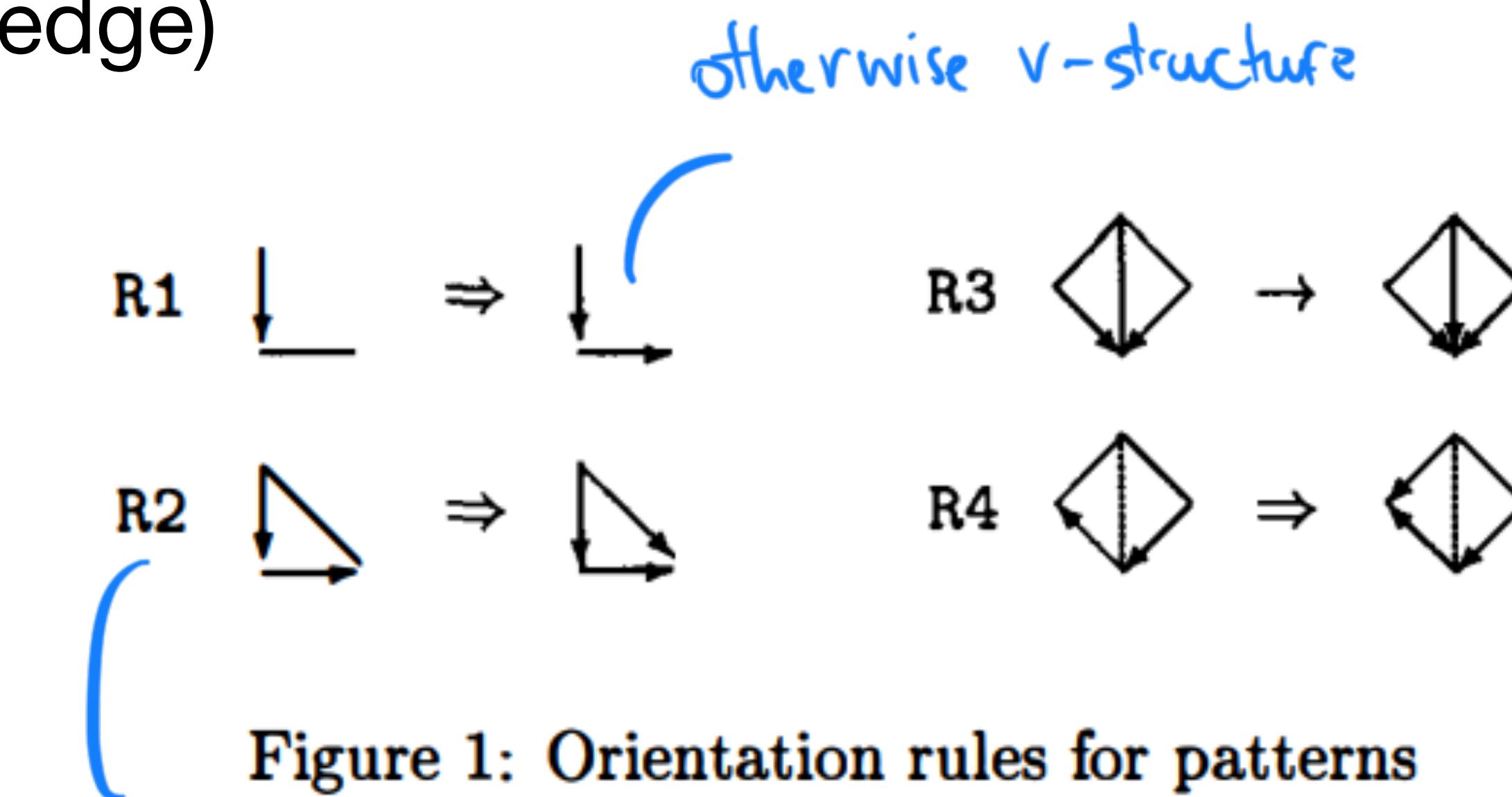
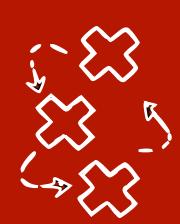


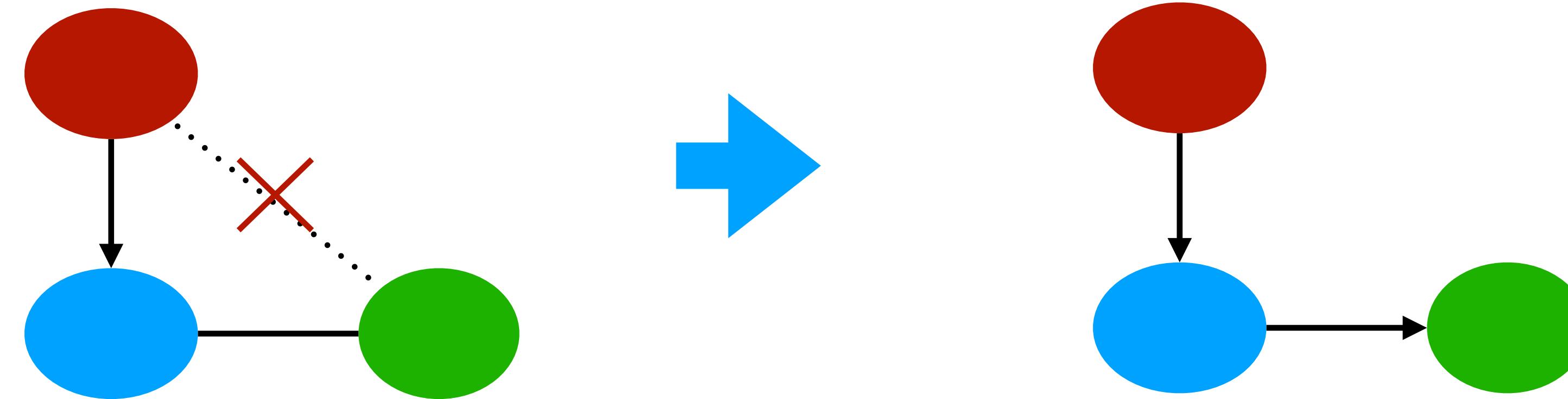
Figure 1: Orientation rules for patterns

otherwise cycle

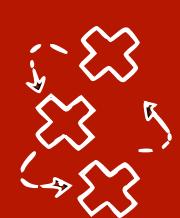


Step 3: Meek's rules (1995) - Rule 1

Sound and complete rules for additional orientations (also with added background knowledge)

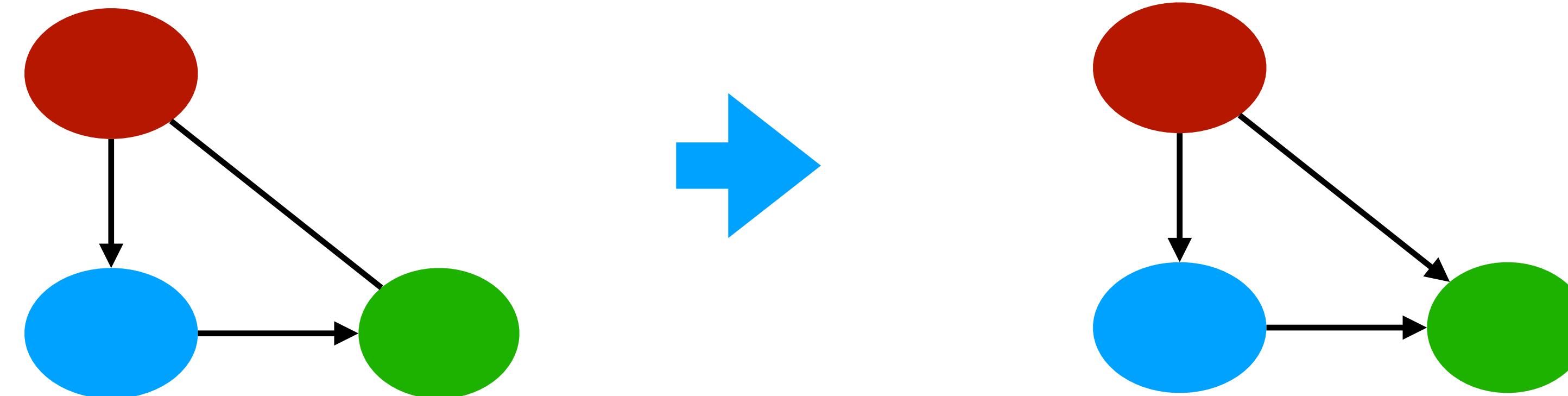


Otherwise v-structure

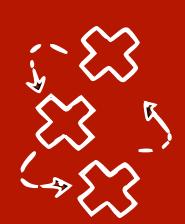


Step 3: Meek's rules (1995) - Rule 2

Sound and complete rules for additional orientations (also with added background knowledge)

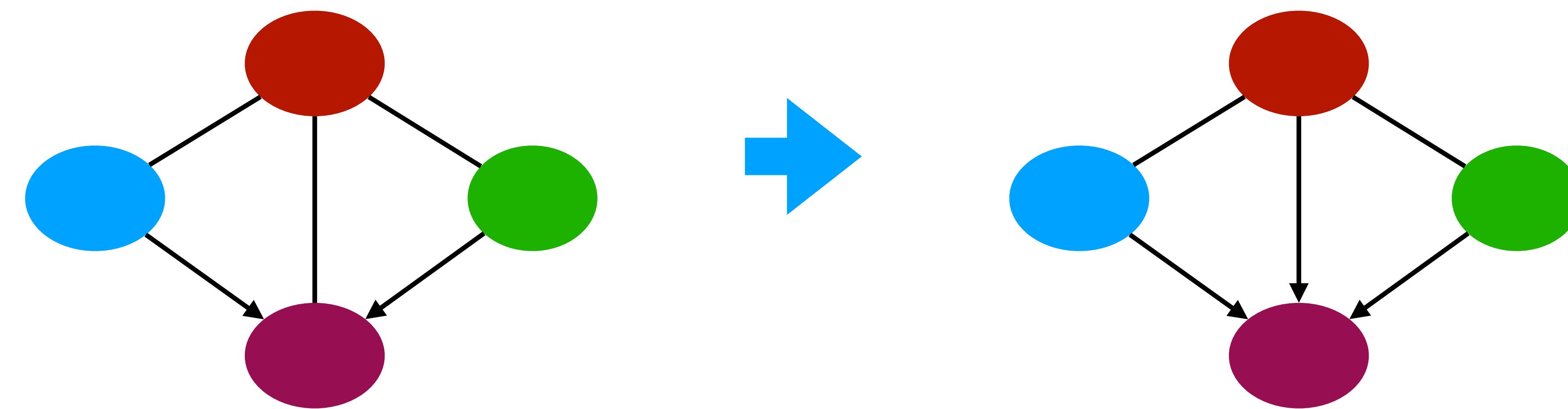


Otherwise cycle



Step 3: Meek's rules (1995) - Rule 3

Sound and complete rules for additional orientations (also with added background knowledge)



Otherwise cycle or v-structure

Canvas exercise - SGS algorithm

 $X_1 \perp\!\!\!\perp X_4$
 $X_2 \perp\!\!\!\perp X_4$
 $X_1 \perp\!\!\!\perp X_3 | X_2$
 $X_1 \perp\!\!\!\perp X_4 | X_2$
 $X_2 \perp\!\!\!\perp X_4 | X_1$
 $X_1 \perp\!\!\!\perp X_4 | X_3, X_2$

1) skeleton

 $1 - 2 - 3 - 4$

 $1 - 4 - 3 - 2$

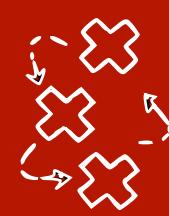

2) unshielded triples

3) v- structures?

4) additional orientations?

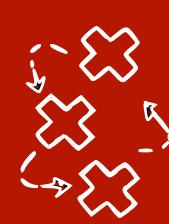
5) fully oriented (PODA6)?

6) 1 and 2?



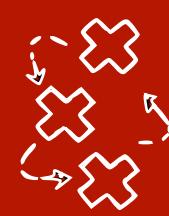
SGS algorithm (Spirtes, Glymour, Scheines)

- Assuming P is Markov and faithful to an unknown graph G
- We can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton**
 2. Determine the **v-structures** (*given the tests in the previous phase*)
 3. Direct as many remaining edges as possible
- **Computationally inefficient:** potentially $O(2^p)$ tests
 - Even if we reuse the test results from skeleton phase in other phases



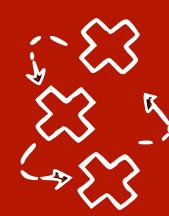
PC algorithm (Peter Spirtes, Clark Glymour)

- Assuming P is Markov and faithful to an unknown graph G
- We can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton in an optimised way**
 2. Determine the **v-structures** (*given the results in the previous phase*)
 3. Direct as many remaining edges as possible



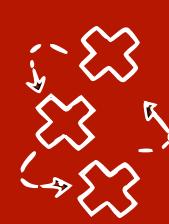
PC algorithm skeleton learning

- If i is not adjacent to j , then they can be d-separated by $\text{Pa}(i)$ or $\text{Pa}(j)$
- Determine the **skeleton in an optimised way**
 - Since we do not know the parents we will use the nodes that are adjacent, $\text{Adj}(i)$ or $\text{Adj}(j)$ in U at a given iteration (*superset*)



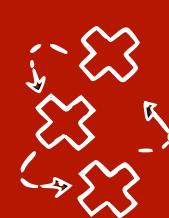
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1. Start with **completely connected undirected graph U**



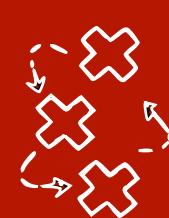
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1. Start with **completely connected undirected graph U**
 2. For $k = 0, 1, 2, \dots, p - 2$
 - If $i - j$ in U and there exists a set $S \subseteq \text{Adj}(i) \setminus \{j\}$ of size at least k



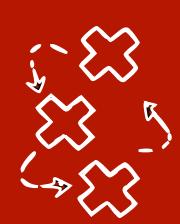
PC algorithm skeleton learning

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1. Start with **completely connected undirected graph U**
 2. For $k = 0, 1, 2, \dots, p - 2$
 - If $i - j$ in U and there exists a set $S \subseteq \text{Adj}(i) \setminus \{j\}$ of size at least k
 - If holds $X_i \perp\!\!\!\perp X_j | S$, then **remove $i - j$ in U** (and add S to $\text{SepSet}(i, j)$)



PC algorithm skeleton learning

- If i is not adjacent to j , then they can be d-separated by $\text{Pa}(i)$ or $\text{Pa}(j)$
 - Determine the **skeleton** in an optimal way
 - Since we do not know the parents of i and j we start with a superset of adjacent, $\text{Adj}(i)$ or $\text{Adj}(j)$ in U at a given iteration (superset)
- SepSet(i, j)** is the separating set of X_i and X_j where we store the results of the conditional independence tests
1. Start with **completely connected**
 2. For $k = 0, 1, 2, \dots, p - 2$
 - If $i - j$ in U and there exists a set $S \subseteq \text{Adj}(i) \setminus \{j\}$ of size at least k such that $X_i \perp\!\!\!\perp X_j | S$, then remove $i - j$ in U (and add S to SepSet(i, j))
- We stop when there are no more untested sets of size k in the adjacencies of any variable

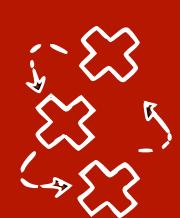


PC algorithm skeleton example

SepSet(1,3)= \emptyset

$K = \emptyset \quad X_1 \perp\!\!\!\perp X_3 :$
 $X_1 \not\perp\!\!\!\perp X_2; X_3 \not\perp\!\!\!\perp X_2; X_1 \not\perp\!\!\!\perp X_4; X_3 \not\perp\!\!\!\perp X_4$





PC algorithm skeleton example

SepSet(1,3)= \emptyset

SepSet(3,4)={1,2}

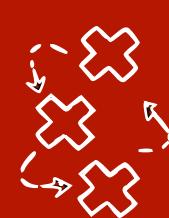
$K=0 \quad X_1 \perp\!\!\!\perp X_3 : \quad K=1$

$X_1 \not\perp\!\!\!\perp X_2; X_3 \not\perp\!\!\!\perp X_2; X_1 \not\perp\!\!\!\perp X_4; X_3 \not\perp\!\!\!\perp X_4$

$K=2$

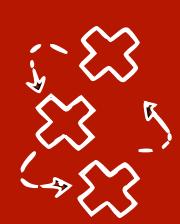
$X_3 \perp\!\!\!\perp X_4 | X_2 X_1$





PC algorithm determine v-structures

- A triple of nodes (i, j, k) in a DAG G is a **an unshielded triple** if $i - j, j - k$ and i is not adjacent to k , i.e. $i \perp\!\!\!\perp k$, in G
1. Start from the skeleton U from previous step
 2. For each unshielded triple (i, j, k) in U , i.e. $i - j, j - k$ and $i \perp\!\!\!\perp k$ in U
 - Check if $j \notin \text{SepSet}(i, k)$
 - If this is true, $i \rightarrow j \leftarrow k$ is a **v-structure**



PC algorithm skeleton example

$$K=0 \quad X_1 \perp\!\!\!\perp X_3$$

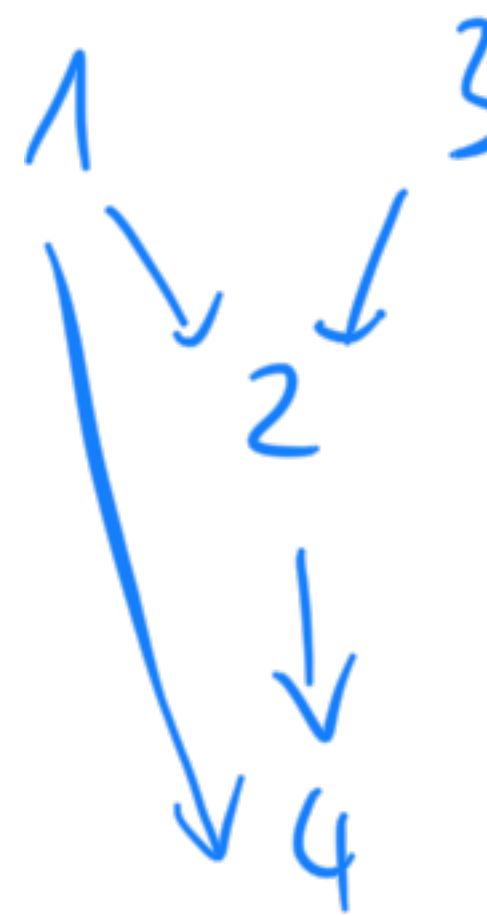
$$K=1$$

$$K=2 \quad X_3 \perp\!\!\!\perp X_4 \mid X_2, X_1$$

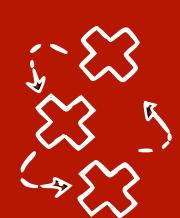
$$1-2-3 \quad X_1 \not\perp\!\!\!\perp X_3 \mid X_2$$

$$X_1 \not\perp\!\!\!\perp X_3 \mid X_2, X_4$$

V-structure



$2 \notin \text{SepSet}(1,3) = \emptyset$



PC algorithm skeleton example

$K=0 \quad X_1 \perp\!\!\!\perp X_3$

$K=1$

$X_3 \perp\!\!\!\perp X_4 \mid X_2, X_1$

1-2-3

$X_1 \not\perp\!\!\!\perp X_3 \mid X_2$
 $X_1 \not\perp\!\!\!\perp X_3 \mid X_2, X_4$
V-structure

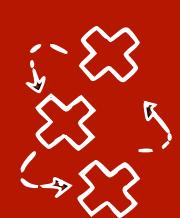
3-2-4 $X_3 \perp\!\!\!\perp X_4 \mid X_2, X_1$

Note: 1-4-2 is NOT a v-structure
(1 is adjacent to 2)



$1 \in \text{SepSet}(3,4)=\{1,2\}$

$2 \notin \text{SepSet}(1,3)=\emptyset$



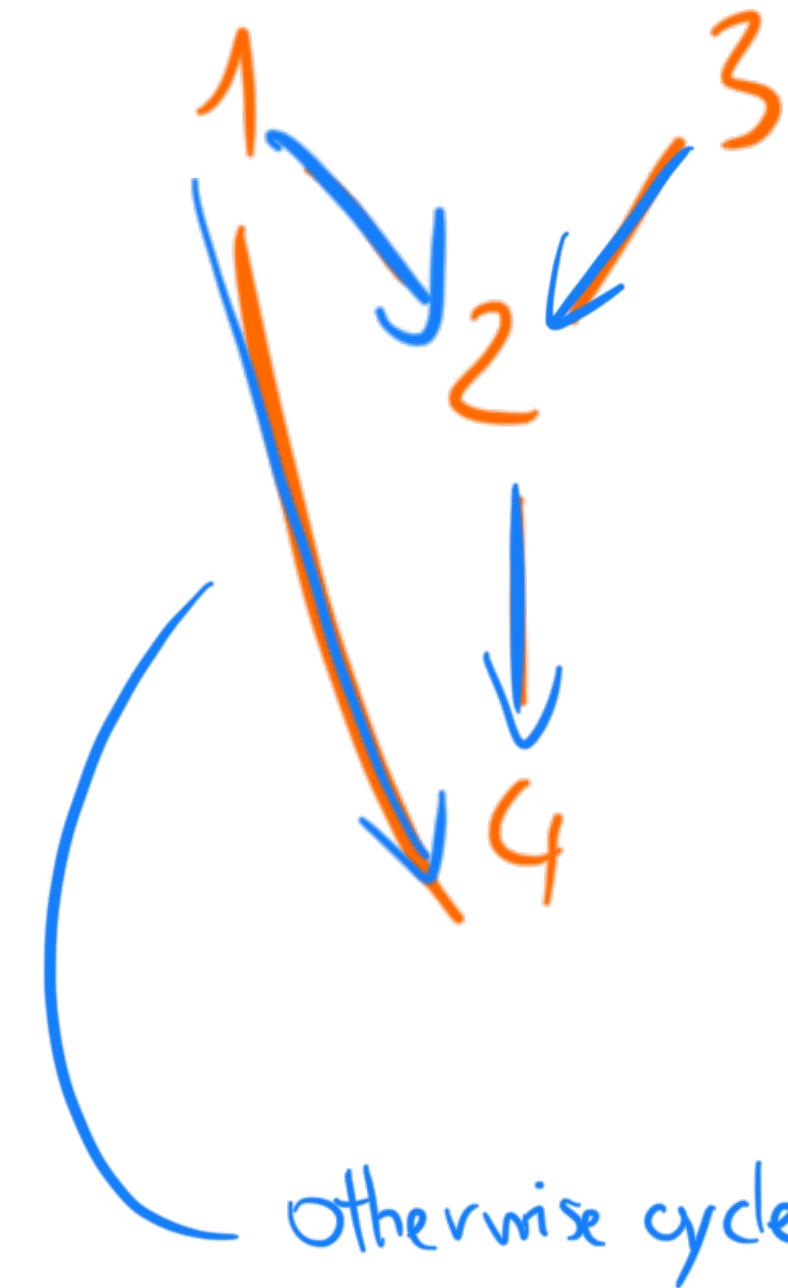
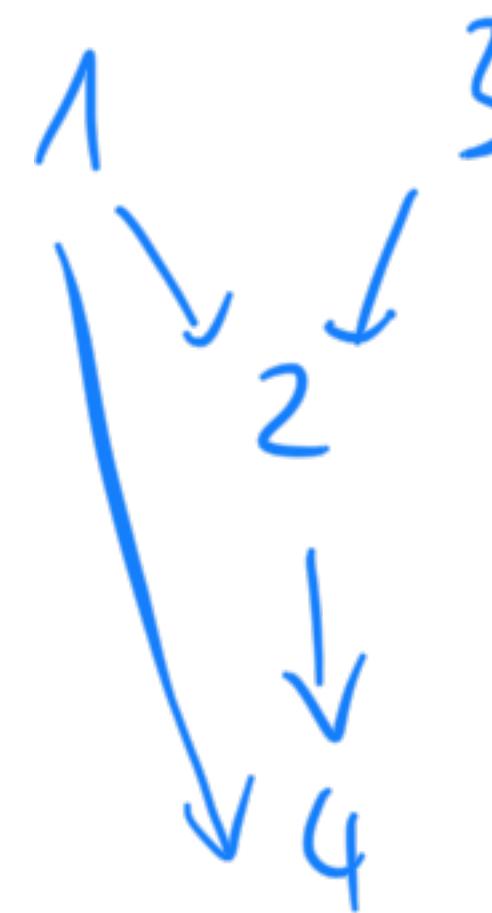
PC algorithm skeleton example

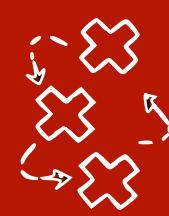
$k=0 \quad X_1 \perp\!\!\!\perp X_3$

$k=2 \quad X_3 \perp\!\!\!\perp X_4 \mid X_2, X_1$

$2 \notin \text{SepSet}(1,3)=\emptyset$

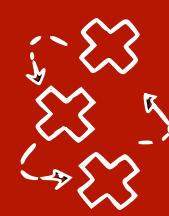
$1 \in \text{SepSet}(3,4)=\{1,2\}$





SGS vs PC

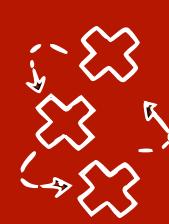
- **SGS:** we can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton**
 2. Determine the **v-structures**
 3. Direct as many remaining edges as possible
- **PC:** we can estimate a CPDAG from samples of P in three steps:
 1. Determine the **skeleton in an optimised way**
 2. Determine the **v-structures in an optimised way**
 3. Direct as many remaining edges as possible



PC algorithm - when does it fail?

- If the conditional independence tests give the wrong result
 - Too few samples
 - A very weak dependence
 - Wrong parametric assumption (e.g. partial correlation on nonlinear data)

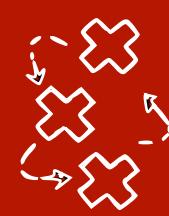
If you're curious, you can see here some variants (like conservative PC) that try to circumvent the problem by doing more tests <https://rdrr.io/cran/pcalg/man/pc.html>



PC algorithm - when does it fail?

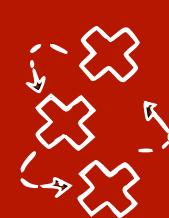
- If the conditional independence tests give the wrong result
 - Too few samples
 - A very weak dependence
 - Wrong parametric assumption (e.g. partial correlation on nonlinear data)
- If there are unmeasured confounders or selection bias
 - For example Chocolate - Nobel prizes





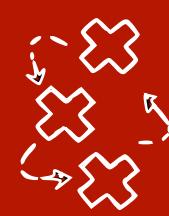
PC algorithm - when does it fail?

- If the conditional independence tests give the wrong result
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 - Wrong parametric assumption (e.g. partial correlation on nonlinear data)
- If there are unmeasured confounders or selection bias (**causal sufficiency**)
- More advanced algorithms like Fast Causal Inference (FCI)
 - Chapter 6 in [SGS] Causation Prediction and Search
 - https://www.researchgate.net/publication/242448131_Causation_Prediction_and_Search



PC algorithm - when does it fail?

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- If there are unmeasured confounders or selection bias (**causal sufficiency**)
Main advantage of constraint-based methods
 - More advanced algorithms like Fast Causal Inference (FCI)
 - Chapter 6 in [SGS] Causation Prediction and Search
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Next class:

Constraint-based causal discovery

- Conditional independence tests
- Observational data
- Output: MEC
- SGS, PC, FCI

Score-based causal discovery

- Penalised likelihood
- Observational data
- Output: MEC
- GES, MMHC

Restricted models

- Nonlinear additive noise, Linear Non-Gaussianity
- Observational data
- Output: DAG
- RESIT, LINGAM

Interventional causal discovery / causal invariance

- Observational and Interventional data
- Output: parents of Y, I-MEC
- ICP, GIES, JCI