ECSE 597: Circuit Simulations and Modeling Assignment 3, October 3, 2019

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Chebychev Filter 1

MATLAB code listings will be presented at the end of the document. Figures 1 and 2 below show the magnitude and angular response of the Chebychev filter.

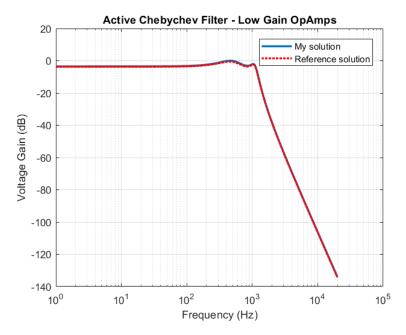


Figure 1: Magnitude Response of the Chebychev Filter

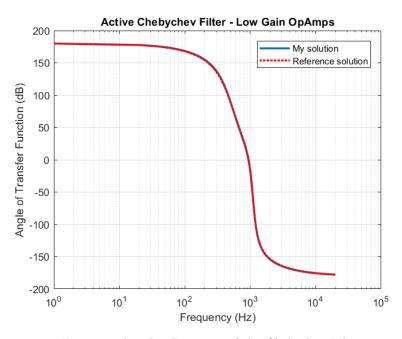


Figure 2: Angular Response of the Chebychev Filter

2 Large Gain Chebychev Filter

Figures 3 and 4 below show the magnitude and angular response of the large gain Chebychev filter.

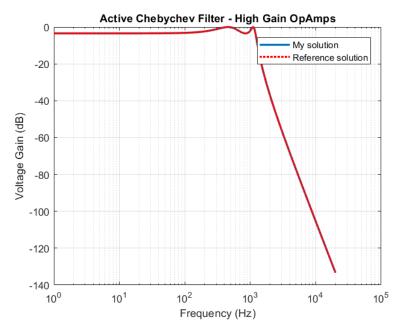


Figure 3: Magnitude Response of the Large Gain Chebychev Filter

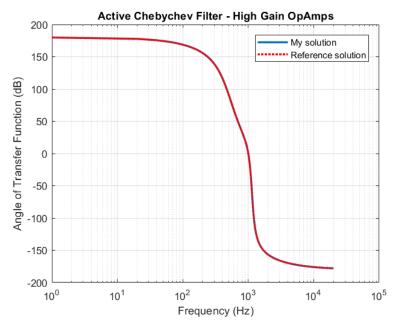


Figure 4: Angular Response of the Large Gain Chebychev Filter

3 Circuit 4 Test Bench

Figures 5 and 6 below show the magnitude and angular response of the Circuit 4 Test Bench.

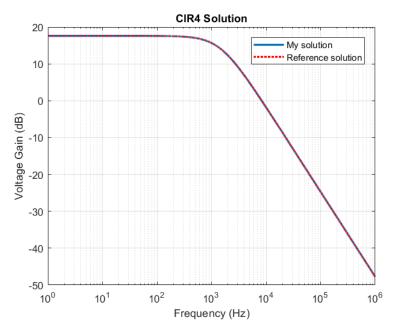


Figure 5: Magnitude Response of the Circuit 4 Test Bench

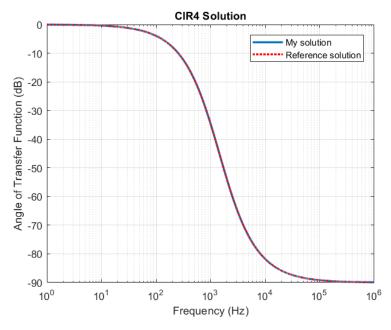


Figure 6: Angular Response of the Circuit 4 Test Bench

4 LC Filter 1 Test Bench

Figures 7 and 8 below show the magnitude and angular response of the LC Filter 1 Test Bench.

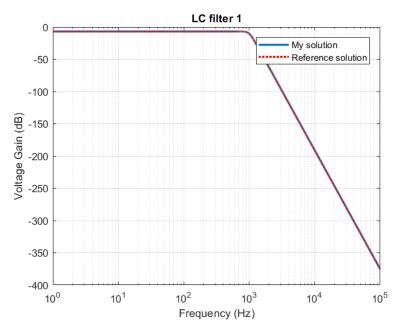


Figure 7: Magnitude Response of the LC Filter 1 Test Bench

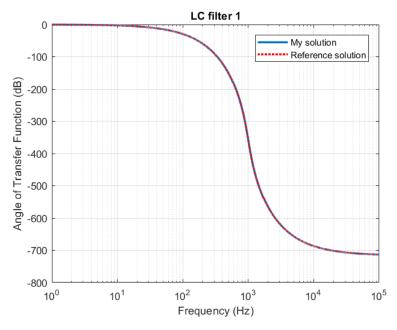


Figure 8: Angular Response of the LC Filter 1 Test Bench

5 LC Filter 2 Test Bench

Figures 9 and 10 below show the magnitude and angular response of the LC Filter 2 Test Bench.

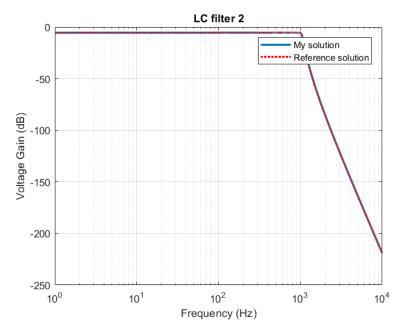


Figure 9: Magnitude Response of the LC Filter 2 Test Bench

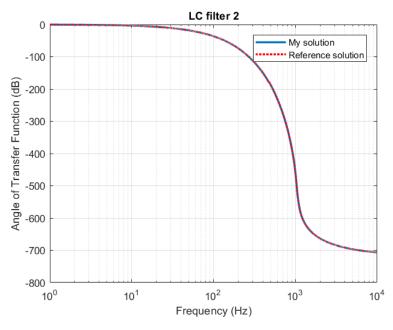


Figure 10: Angular Response of the LC Filter 2 Test Bench

6 LC Filter 3 Test Bench

Figures ?? and 12 below show the magnitude and angular response of the LC Filter 3 Test Bench.

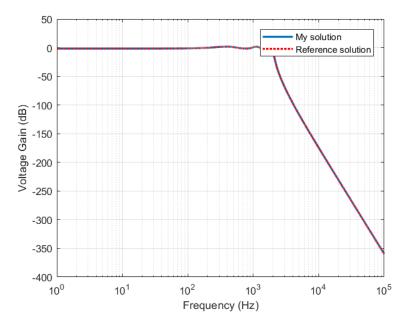


Figure 11: Magnitude Response of the LC Filter 3 Test Bench

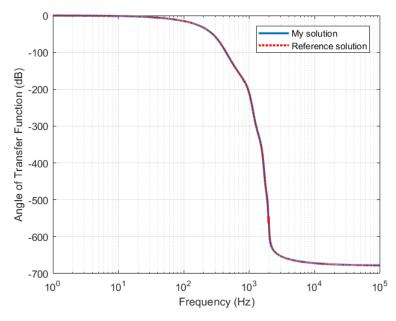


Figure 12: Angular Response of the LC Filter 3 Test Bench

A Code Listings

35 36

37

end

Listing 1: MATLAB Function to Compute the Frequency Response (fsolve.m). function r = fsolve(fpoints, out)% fsolve(fpoints ,out) % Obtain frequency domain response 3 % global variables G C b % Inputs: fpoints is a vector containing the fequency points at which to compute the response in Hz 6 out is the output node % Outputs: r is a vector containing the value of of the response at the points fpoint 9 10 global G C b 11 12 r = zeros(1, size(fpoints, 2)); 13 14 for i = 1:size(fpoints, 2) 15 $X = (G + 2 * pi * fpoints(i) * 1j * C) \setminus b;$ 16 r(1, i) = X(out);17 18 end end 19 Listing 2: MATLAB Function to Generate Inductance Matrices (ind.m). function ind(n1,n2,val) % ind(n1,n2,val) % Add stamp for inductor to the global circuit representation 3 % Inductor connected between n1 and n2 % The indjuctance is val in Henry 5 % global G 6 % global C % global b % Date: 9 10 % defind global variables 11 12 global G global b 13 global C 14 15 % Add additional entries to G, C, and b matrices. 16 17 G(end + 1, :) = 0;G(:, end + 1) = 0;18 C(end + 1, :) = 0;19 20 C(:, end + 1) = 0;21 b(end + 1) = 0;22 % Modify the G matrix. 23 if n1 ~= 0 24 G(end, n1) = 1;25 G(n1, end) = 1;end 27 28 **if n2** ~= 0 29 G(end, n2) = -1;30 G(n2, end) = -1;31 32 33 % Modify the C matrix.34 C(end, end) = -val;

Listing 3: MATLAB Function to Generate VCCS Matrices (vccs.m).

```
1
    function vccs(nd1,nd2,ni1,ni2,val)
2
         % \ vccs(nd1,nd2,ni1,ni2,val)
         % Add stamp for voltage controlled current source
3
        \% to the global circuit representation
4
         % ni1 and ni2 are the controlling voltage nodes
         % the controlled current source is between nd1 and nd2
6
        \% The controlled current (from nd1 to nd2) is val*(Vni1-Vni2)
8
9
        global G
10
11
        if nd1 ~= 0
12
            if ni1 ~= 0
13
                 G(nd1, ni1) = G(nd1, ni1) + val;
14
15
             end
            if ni2 ~= 0
16
                 G(nd1, ni2) = G(nd1, ni2) - val;
17
18
            end
        end
19
20
         if nd2 ~= 0
21
            if ni1 ~= 0
22
23
                 G(nd2, ni1) = G(nd2, ni1) - val;
24
            if ni2 ~= 0
25
                 G(nd2, ni2) = G(nd2, ni2) + val;
26
27
         end
28
    end
```

Listing 4: MATLAB Function to Generate VCVS Matrices (vccs.m).

```
function vcvs(nd1,nd2,ni1,ni2,val)
        % vcvs(nd1,nd2,ni1,ni2,val)
         % Add stamp for a voltage controlled voltage source
3
         % to the global circuit representation
4
         % val is the gain of the vcvs
        % ni1 and ni2 are the controlling voltage nodes
6
         \mbox{\%} nd1 and nd2 are the controlled voltage nodes
        % The relation of the nodal voltages at nd1, nd2, ni1, ni2 is:
        % Vnd1 - Vnd2 = val*(Vni1 - Vni2)
9
10
11
        global G
12
13
        global b
        global C
14
16
         % Extend the matrices.
        G(end + 1, :) = 0;
17
18
        G(:, end + 1) = 0;
        b(end + 1) = 0;
19
        C(end + 1, :) = 0;
20
        C(:, end + 1) = 0;
22
         if nd1 ~= 0
23
             G(nd1, end) = 1;
24
             G(end, nd1) = 1;
25
26
        end
27
        if nd2 ~= 0
28
             G(nd2, end) = -1;
29
             G(end, nd2) = -1;
30
31
         end
32
         if ni1 ~= 0
33
34
             G(end, ni1) = -val;
         end
35
        if ni2 ~= 0
36
            G(end, ni2) = val;
```