## 3. Line Intersections (Redux)

Now, suppose you are given a set L of n line segments in the plane, but the endpoints of the segment lie on the unit circle (e.g. defined by the equation  $x^2 + y^2 = 1$ ), and all 2n endpoints are distinct. Give an algorithm to compute the largest subset of L in which no pair of segments intersects. To obtain full marks your algorithm should run in time  $O(n^3)^1$ .

## **Solution**

We solve this problem by way of dynamic programming. There are several ways to do it — one is to give a memoized recursive dynamic programming algorithm which fixes a line and recurses on the "areas" of the circle which remain, such as in the minimum-weight triangulation algorithm. This gives an  $O(n^3)$  running time, and the implementation is very similar to that of the minimum-weight triangulation algorithm. A modification of this algorithm runs in time  $O(n^2)$ , which we will present here.

We use  $\ell_1,\ell_2,\ldots,\ell_n$  to denote the n line segments in L. As stated, these line segments all have distinct endpoints and all of the endpoints of the lines lie on the unit circle. Let P be the set of all endpoints of the lines in L. Let  $p_1$  be one of the endpoints of  $\ell_1$  and re-label  $p_1$  with the integer 1. Then, label the rest of the points with integers in increasing order by starting at  $p_1$  and moving clockwise around the circle. After this relabeling we will have  $P = \{1, 2, \ldots, 2n\}$ , and each line  $\ell$  in the input can be identified as a pair of endpoints in P. For an example of such an ordering see Figure 2.

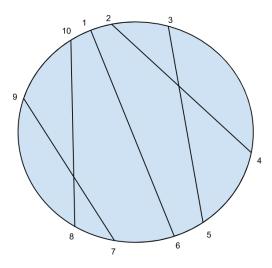


Figure 2: A circle ordering of the line endpoints

Using this new definition of the endpoints we can easily determine if two lines intersect. (From here on, whenever we consider a line  $\ell$  from the input, we will implicitly assume it is defined by a pair of integers from P in increasing order. So the line in Figure 2 with endpoints 1 and 6 will always be written as  $\ell = (1,6)$ , not (6,1).) For suppose that  $\ell_1 = (i,j)$ ,  $\ell_2 = (k,l)$ , and assume without loss of generality that i < k. Then  $\ell_1$  and  $\ell_2$  intersect if and only if i < k < j < l — to convince yourself of this, choose two lines in Figure 2 and test it out.

Before we give the recursive definition, first suppose that i, j are two integers with  $1 \le i < j \le 2n$ . We define the subset of lines  $L_{ij} \subseteq L$  as follows: a line  $\ell = (a, b)$  is in  $L_{ij}$  if  $i \le a < b \le j$ . For example, in Figure 2, the set  $L_{16}$  contains the lines (1, 6), (2, 4), and (3, 5). More generally the set  $L_{ij}$  consists of all lines from the input with both endpoints "between" i and j. Note that  $L_{1,2n} = L$ .

 $<sup>\</sup>overline{O(n^3)}$  is not the best running time possible for this problem. I will offer a bonus (up to 5%) for anyone who can beat the  $O(n^3)$  algorithm.

We are ready to give the recursive definition used by the algorithm. We make an  $n \times n$  array D and for each  $1 \le i \le j \le 2n$  we set

D[i,j] := the maximum number of non-intersecting line segments in the set  $L_{ij}$ .

By our comment above, the maximum number of non-intersecting line segments in the circle will be stored in D[1, 2n].

For the base cases of the recursive definition, for each  $i \leq 2n-1$  we set

$$D[i, i+1] = \begin{cases} 1 & \text{if } (i, i+1) \text{ is a line in the input} \\ 0 & \text{otherwise} \end{cases}$$

and also D[i, i] = 0.

As for the recursive definition, we set

$$D[i,j] := \max \begin{cases} D[i+1,j-1]+1 & \text{if } (i,j) \text{ is a line in the input} \\ D[i+1,k-1]+D[k+1,j]+1 & \text{if } (i,k) \text{ is a line in the input and } i < k < j \\ D[i,k-1]+D[k+1,j-1]+1 & \text{if } (k,j) \text{ is a line in the input and } i < k < j \\ D[i+1,j-1] & \text{otherwise} \end{cases}$$

We will prove this recursive definition is correct by induction over j-i. If j-i=0 then j=i and  $L_{i,i}=\emptyset$ , since all of the lines in the input have distinct endpoints. If j-i=1, then j=i+1, and either  $L_{i,i+1}=\emptyset$  if (i,i+1) is not a line in the input, or  $L_{i,i+1}=\{(i,i+1)\}$  if (i,i+1) is a line in the input. Both of these cases are covered correctly by the base cases of D above. Assume that D[i,j] is correctly defined for all j-i< m, and we will prove that it is correctly defined when j-i=m.

Let  $O_{ij}$  be the largest set of non-intersecting lines in  $L_{ij}$ . We want to prove that  $D[i,j] = |O_{ij}|$ . There are several cases:

Case 1: (i, j) is a line in  $O_{ij}$ 

In this case, then (i,j) cannot intersect with any other line in  $L_{ij}$  since every other line  $\ell=(k_1,k_2)$  in  $L_{ij}$  satisfies  $i < k_1$  and  $k_2 < j$  by the distinctness of the endpoints. Thus,  $O_{ij} = O_{i+1,j-1} \cup \{(i,j)\}$ , and so  $|O_{ij}| = D[i+1,j-1]+1$  by the inductive hypothesis.

Case 2: (i, k) is a line in  $O_{ij}$  with  $k \neq j$ .

In this case we must have i < k < j. The rest of the lines in  $O_{ij}$  must therefore have endpoints between i and k and between k and j. This implies that

$$O_{ij} = O_{i+1,k-1} \cup O_{k+1,j} \cup \{(i,k)\},\$$

and so  $O_{ij} = D[i+1,k-1] + D[k+1,j] + 1$  by the inductive hypothesis.

Case 3: (k, j) is a line in  $O_{ij}$  with  $k \neq i$ .

This is identical to Case 2, except now we have

$$O_{ij} = O_{i+1,k-1} \cup O_{k+1,j} \cup \{(i,k)\}.$$

By the inductive hypothesis this implies that  $|O_{ij}| = D[i+1, k-1] + D[k+1, j] + 1$ .

Case 4: There are no lines in  $O_{ij}$  with endpoint i or j.

In this this, all of the lines  $\ell = (k_1, k_2)$  in  $O_{ij}$  must satisfy  $i < k_1$  and  $k_2 < j$ . This means that  $O_{ij} = O_{i+1,j-1}$ , and so the inductive hypothesis implies that  $O_{ij} = D[i+1,j-1]$ .

We can therefore express  $|O_{ij}|$  as the maximum of all of these four cases. This gives us exactly the expression for D[i,j] given above, and so  $D[i,j] = |O_{ij}|$ . The proof is complete.

Finally, we give an algorithm (Algorithm 3) implementing our recurrence. Note that finding such an ordering of the endpoints P as we defined it above can be determined in linear time by fixing one of the endpoints arbitrarily, and then doing a clockwise sweep of the circle in polar coordinates. We will therefore assume that the endpoints will be given in this manner.

Algorithm 3 runs in  $O(n^2)$  time, owing to the doubly-nested for-loop.

## **Algorithm 3:** Circle Intersection

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Input: A list of n lines in the unit circle L, each line with distinct endpoints, and a circular ordering P of the
       2n endpoints.
Output: The largest set of non-intersecting lines in L.
/\star~D is the semantic array, S is an array helping us building the
    optimal solution, and M is a helper array storing line endpoints
let D be an n \times n array, initialized to all 0s;
let S be a n \times n array, initialized to all \emptysets;
let M be a 2n \times 1 array, initialized to all 0s;
for each line (i, j) \in L do
   if j = i + 1 then
       D[i, i+1] = 1;
       S[i, i+1] = \{(i, i+1)\};
   else
       M[i] = j;
       M[j] = i;
   end
end
for gap = 2, 3, ..., 2n - 1 do
   for i = 1, 2, ..., 2n - gap do
       j := i + gap;
       t_1 = t_2 = t_3 = 0;
       S_1 = S_2 = S_3 = \emptyset;
       if M[i] = j then
           t_1 = D[i+1, j-1] + 1;
           S_1 = S[i+1, j-1] \cup \{(i, j)\};
           t_1 = D[i+1, j-1];
           S_1 = S[i+1, j-1];
       if M[i] = k and i < k < j then
           t_2 = D[i+1, k-1] + D[k+1, j] + 1;
           S_2 = S[i+1, k-1] \cup D[k+1, j] \cup \{(i, k)\}
       end
       if M[j] = k and i < k < j then
           t_3 = D[i, k-1] + D[k+1, j-1] + 1;
          S_3 = S[i, k-1] \cup D[k+1, j-1] \cup \{(k, j)\}
       end
       D[i, j] = \max_{i=1,2,3} \{t_i\};
       index = \arg\max_{i=1,2,3} \{t_i\};
       S[i,j] = S_{index};
   end
```

end

return S[1,2n]