part1

March 20, 2024

1 EECS 442 Homework 4: Fashion-MNIST Classification

In this part, you will implement and train Convolutional Neural Networks (ConvNets) in PyTorch to classify images. Unlike HW4 Secion 1, backpropagation is automatically inferred by PyTorch, so you only need to write code for the forward pass.

Before we start, please put your name and UMID in following format Firstname LASTNAME, #00000000 // e.g.) David FOUHEY, #12345678

Your Answer:

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1.1 Setup

```
[2]: # Run the command in the terminal if it failed on local Jupyter Notebook, □ → remove "!" before each line # !pip install torchsummary
```

```
import numpy as np
import matplotlib.pyplot as plt
from tqdm import tqdm # Displays a progress bar

import torch
from torch import nn
from torch import optim
import torch.nn.functional as F
from torchsummary import summary
from torchvision import datasets, transforms
from torch.utils.data import Dataset, Subset, DataLoader, random_split
```

```
[4]: if torch.cuda.is_available():
    print("Using the GPU. You are good to go!")
    device = 'cuda'
else:
    print("Using the CPU. Overall speed may be slowed down")
    device = 'cpu'
```

Using the GPU. You are good to go!

1.2 Loading Dataset

The dataset we use is Fashion-MNIST dataset, which is available at https://github.com/zalandoresearch/fashion-mnist and in torchvision.datasets. Fashion-MNIST has 10 classes, 60000 training+validation images (we have splitted it to have 50000 training images and 10000 validation images, but you can change the numbers), and 10000 test images.

Loading datasets...
Done!

Now, we will create the dataloder for train, val and test dataset. You are free to experiment with different batch sizes.

1.3 Model

Initialize your model and experiment with with different optimizers, parameters (such as learning rate) and number of epochs.

```
[7]: class Network(nn.Module):
    def __init__(self):
        super().__init__()
```

```
# TODO: Design your own network, define layers here.
      # Here We provide a sample of two-layer fc network from HW4 Part3.
      # Your solution, however, should contain convolutional layers.
      # Refer to PyTorch documentations of torch.nn to pick your layers.
      # (https://pytorch.org/docs/stable/nn.html)
      # Some common choices: Linear, Conv2d, ReLU, MaxPool2d, AvqPool2d,
\hookrightarrow Dropout
      # If you have many layers, use nn. Sequential() to simplify your code
# stem: 3*28*28 -> 64 * 14* 14
      self.stem = torch.nn.Sequential(torch.nn.Conv2d(1, 64, kernel_size=7,__

stride=1, padding=3),
                                   torch.nn.BatchNorm2d(64),
                                   torch.nn.MaxPool2d(kernel_size=3,_
⇔stride=2, padding=1))
      # stage1: 64 * 14 * 14 -> 64 * 14 * 14
      self.resblock1 = torch.nn.Sequential(torch.nn.Conv2d(64, 64, 1
→kernel_size=3, stride=1, padding=1),
                                        torch.nn.BatchNorm2d(64),
                                        torch.nn.ReLU(inplace=True),
                                        torch.nn.Conv2d(64, 64,
→kernel_size=3, stride=1, padding=1),
                                        torch.nn.BatchNorm2d(64))
      self.resblock2 = torch.nn.Sequential(torch.nn.Conv2d(64, 64, ...
⇒kernel size=3, stride=1, padding=1),
                                        torch.nn.BatchNorm2d(64),
                                        torch.nn.ReLU(inplace=True),
                                        torch.nn.Conv2d(64, 64,
→kernel_size=3, stride=1, padding=1),
                                        torch.nn.BatchNorm2d(64))
      # stage2: 64 * 14 * 14 -> 128 * 7 * 7
      self.resblock3 = torch.nn.Sequential(torch.nn.Conv2d(64, 128,
⇒kernel size=3, stride=2, padding=1),
                                        torch.nn.BatchNorm2d(128),
                                        torch.nn.ReLU(inplace=True),
                                        torch.nn.Conv2d(128, 128, __
→kernel_size=3, stride=1, padding=1),
```

```
torch.nn.BatchNorm2d(128))
    self.resblock4 = torch.nn.Sequential(torch.nn.Conv2d(128, 128, __
→kernel_size=3, stride=1, padding=1),
                                torch.nn.BatchNorm2d(128),
                                torch.nn.ReLU(inplace=True),
                                torch.nn.Conv2d(128, 128,
→kernel_size=3, stride=1, padding=1),
                                torch.nn.BatchNorm2d(128))
     # fc layer:
    self.pool = torch.nn.AvgPool2d(kernel_size=7)
    self.fc = torch.nn.Sequential(torch.nn.Linear(128, 512),
                           torch.nn.ReLU(inplace=True),
                           torch.nn.Linear(512, 10))
     # downsample
    self.projection = torch.nn.Sequential(torch.nn.Conv2d(64, 128,
⇔kernel_size=1, stride=2),
                                 torch.nn.BatchNorm2d(128))
     #ReLU
    self.relu = torch.nn.ReLU(inplace=True)
END OF YOUR CODE
    #
def forward(self, x):
# TODO: Design your own network, implement forward pass here
    #
# print(x.shape)
    N, C, H, W = x.shape
     # stem
    x = self.stem(x)
     # print(x.shape)
     # stage1
    x_res = torch.clone(x)
    x = self.resblock1(x)
    x += x res
    x = self.relu(x)
```

```
# print(x.shape)
     x_res = torch.clone(x)
     x = self.resblock2(x)
     x += x res
     x = self.relu(x)
      # print(x.shape)
      # stage2
     x_res = self.projection(x)
     x = self.resblock3(x)
     x += x res
     x = self.relu(x)
     # print(x.shape)
     x_res = torch.clone(x)
     x = self.resblock4(x)
     x += x res
     x = self.relu(x)
      # print(x.shape)
     # fc layer
     x = self.pool(x)
     # print(x.shape)
     x = torch.flatten(x, start_dim=1)
      # print(x.shape)
     x = self.fc(x)
     return x
 #
                           END OF YOUR CODE
     #
 model = Network().to(device)
criterion = nn.CrossEntropyLoss() # Specify the loss layer
print('Your network:')
print(summary(model, (1,28,28), device=device)) # visualize your model
# TODO: Modify the lines below to experiment with different optimizers,
                                                         #
# parameters (such as learning rate) and number of epochs.
# Set up optimization hyperparameters
learning_rate, weight_decay, num_epoch = 1e-4, 0.0, 5
```

Your network:

Layer (type)	Output Shape	Param #
Conv2d-1	[-1, 64, 28, 28]	3,200
BatchNorm2d-2	[-1, 64, 28, 28]	128
MaxPool2d-3	[-1, 64, 14, 14]	0
Conv2d-4	[-1, 64, 14, 14]	36,928
BatchNorm2d-5	[-1, 64, 14, 14]	128
ReLU-6	[-1, 64, 14, 14]	0
Conv2d-7	[-1, 64, 14, 14]	36,928
BatchNorm2d-8	[-1, 64, 14, 14]	128
ReLU-9	[-1, 64, 14, 14]	0
Conv2d-10	[-1, 64, 14, 14]	36,928
BatchNorm2d-11	[-1, 64, 14, 14]	128
ReLU-12	[-1, 64, 14, 14]	0
Conv2d-13	[-1, 64, 14, 14]	36,928
BatchNorm2d-14	[-1, 64, 14, 14]	128
ReLU-15	[-1, 64, 14, 14]	0
Conv2d-16	[-1, 128, 7, 7]	8,320
BatchNorm2d-17	[-1, 128, 7, 7]	256
Conv2d-18	[-1, 128, 7, 7]	73,856
BatchNorm2d-19	[-1, 128, 7, 7]	256
ReLU-20	[-1, 128, 7, 7]	0
Conv2d-21	[-1, 128, 7, 7]	147,584
BatchNorm2d-22	[-1, 128, 7, 7]	256
ReLU-23	[-1, 128, 7, 7]	0
Conv2d-24	[-1, 128, 7, 7]	147,584
BatchNorm2d-25	[-1, 128, 7, 7]	256
ReLU-26	[-1, 128, 7, 7]	0
Conv2d-27	[-1, 128, 7, 7]	147,584
BatchNorm2d-28	[-1, 128, 7, 7]	256
ReLU-29	[-1, 128, 7, 7]	0
AvgPool2d-30	[-1, 128, 1, 1]	0
Linear-31	[-1, 512]	66,048
ReLU-32	[-1, 512]	0
Linear-33	[-1, 10]	5,130

Total params: 748,938 Trainable params: 748,938 Non-trainable params: 0

```
Input size (MB): 0.00
Forward/backward pass size (MB): 2.69
Params size (MB): 2.86
Estimated Total Size (MB): 5.55
```

None

Run the cell below to start your training, we expect you to achieve over 85% on the test set. A valid solution that meet the requirement take no more than 10 minutes on normal PC Intel core CPU setting. If your solution takes too long to train, try to simplify your model or reduce the number of epochs.

```
[8]: %%time
    def train(model, trainloader, valloader, num_epoch=10): # Train the model
        print("Start training...")
        trn_loss_hist = []
        trn_acc_hist = []
        val_acc_hist = []
        model.train() # Set the model to training mode
        for i in range(num_epoch):
            running_loss = []
            print('-----' % (i+1))
            for batch, label in tqdm(trainloader):
                batch = batch.to(device)
                label = label.to(device)
                optimizer.zero_grad() # Clear gradients from the previous iteration
                # This will call Network.forward() that you implement
                pred = model(batch)
                loss = criterion(pred, label) # Calculate the loss
                running_loss.append(loss.item())
                loss.backward() # Backprop gradients to all tensors in the network
                optimizer.step() # Update trainable weights
            print("\n Epoch {} loss:{}".format(i+1, np.mean(running_loss)))
            # Keep track of training loss, accuracy, and validation loss
            trn_loss_hist.append(np.mean(running_loss))
            trn_acc_hist.append(evaluate(model, trainloader))
            print("\n Evaluate on validation set...")
            val_acc_hist.append(evaluate(model, valloader))
        print("Done!")
        return trn_loss_hist, trn_acc_hist, val_acc_hist
    def evaluate(model, loader): # Evaluate accuracy on validation / test set
        model.eval() # Set the model to evaluation mode
        correct = 0
        with torch.no_grad(): # Do not calculate grident to speed up computation
            for batch, label in tqdm(loader):
```

```
batch = batch.to(device)
          label = label.to(device)
         pred = model(batch)
          correct += (torch.argmax(pred, dim=1) == label).sum().item()
      acc = correct/len(loader.dataset)
      print("\n Evaluation accuracy: {}".format(acc))
      return acc
trn_loss_hist, trn_acc_hist, val_acc_hist = train(model, trainloader,
                                        valloader, num_epoch)
# TODO: Note down the evaluation accuracy on test set
print("\n Evaluate on test set")
evaluate(model, testloader)
#5: 64, 1e-4, 0.95, 5: 0.7843
#6: 64, 1e-4, 0.98, 5: 0.7851
#7: 64, 1e-4, 0.00, 5: 0.8917
Start training...
-----Epoch = 1-----
           0%|
59.46it/s]
Epoch 1 loss:0.5725756988424779
100%|
        | 782/782 [00:07<00:00, 99.74it/s]
Evaluation accuracy: 0.83086
Evaluate on validation set...
100%|
        | 157/157 [00:01<00:00, 96.58it/s]
Evaluation accuracy: 0.8212
-----Epoch = 2-----
100%|
        | 782/782 [00:12<00:00, 61.51it/s]
Epoch 2 loss:0.38106703539105025
100%
        | 782/782 [00:07<00:00, 101.50it/s]
Evaluation accuracy: 0.89394
```

Evaluate on validation set...

100% | 157/157 [00:01<00:00, 98.84it/s]

Evaluation accuracy: 0.8852

-----Epoch = 3-----

100%| | 782/782 [00:12<00:00, 61.09it/s]

Epoch 3 loss:0.31754977807707496

100%| | 782/782 [00:07<00:00, 102.77it/s]

Evaluation accuracy: 0.89466

Evaluate on validation set...

100% | 157/157 [00:01<00:00, 97.87it/s]

Evaluation accuracy: 0.8833

-----Epoch = 4-----

100%| | 782/782 [00:12<00:00, 61.65it/s]

Epoch 4 loss:0.2882935323983507

100%| | 782/782 [00:07<00:00, 101.61it/s]

Evaluation accuracy: 0.89676

Evaluate on validation set...

100% | 157/157 [00:01<00:00, 101.90it/s]

Evaluation accuracy: 0.8843

-----Epoch = 5-----

100%| | 782/782 [00:12<00:00, 61.54it/s]

Epoch 5 loss:0.2685324148086788

100%| | 782/782 [00:07<00:00, 99.73it/s]

Evaluation accuracy: 0.9109

Evaluate on validation set...

```
100% | 157/157 [00:01<00:00, 101.33it/s]

Evaluation accuracy: 0.8966

Done!

Evaluate on test set

100% | 157/157 [00:01<00:00, 103.19it/s]

Evaluation accuracy: 0.8917

CPU times: user 1min 54s, sys: 512 ms, total: 1min 54s

Wall time: 1min 52s
```

[8]: 0.8917

Once your training is complete, run the cell below to visualize the training and validation accuracies across iterations.

```
# TODO: Submit the accuracy plot
   # visualize the training / validation accuracies
   x = np.arange(num_epoch)
   # train/val accuracies for MiniVGG
   plt.figure()
   plt.plot(x, trn_acc_hist)
   plt.plot(x, val_acc_hist)
   plt.legend(['Training', 'Validation'])
   plt.xticks(x)
   plt.xlabel('Epoch')
   plt.ylabel('Accuracy')
   plt.title('fashion MNIST Classification')
   plt.gcf().set_size_inches(10, 5)
   plt.savefig('part1.png', dpi=300)
   plt.show()
```

