

# Optimal stopping problem

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## 1 Baseline stopping problem

This note is based on the material from [Benjamin Moll's website](#).

### 1.1 Problem

Consider an optimal stopping problem with state variable  $(x)$  which is a diffusion process<sup>1</sup>.

$$v(x) = \max_{\tau} \mathbb{E}_0 \int_0^{\tau} e^{-\rho t} u(x_t) dt + e^{-\rho \tau} S(x_{\tau}), \quad dx_t = \mu(x_t) dt + \sigma(x_t) dW_t \quad (1)$$

This is the simplest problem from Stokey's book. One interpretation is that  $v$  is the value of a firm who may live forever.  $u$  are profits and  $x$  is the **currently realized** demand which evolves exogenously. One can close the firm and sell it at a scrap value  $S(x)$ . The problem is to choose an optimal shut-down time (stopping time)  $\tau$ . Assume  $\mu(x) < 0$  for all  $x$  to make sure that the firm shuts down eventually.

This problem can be rewritten as:

$$v(x) = \lim_{\Delta \rightarrow 0} \int_0^{\Delta} u(x) \cdot e^{-\rho t} dt + e^{-\rho \Delta} \mathbb{E}_0 \max\{v(\tilde{x}), S(\tilde{x})\} \quad (2)$$

which implies that the firm is making the discrete choice between “stopping” and “not stopping” at any point in the continuous time.

#### 1.1.1 HJB Equation

This one-dimensional optimal stopping problem, same as in [McCall \(1970\)](#), satisfies the “reservation value” property. To solve it, we need to find the “reservation demand”  $x^*$  such that the firm is indifferent between staying and exiting when the **currently realized** demand level is  $x^*$ . Since  $u(\cdot)$  is an increasing function,  $v(x)$  is increasing in the **currently realized** demand level  $x$ , the firm will stop when the demand level  $x$  falls below the reservation demand,  $x \leq x^*$ <sup>2</sup>.

### 1. Value function for firm that not stops

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<sup>1</sup>Note that the diffusion is a continuous time Markov process with **continuous sample paths**. But the Poisson arrival process,  $N_t$  = number of arrivals up to time  $t$ , is not a diffusion because its sample paths are not continuous:  $N_t$  is discontinuous at any arrival time

<sup>2</sup> $x \leq x^* \Rightarrow v(x) \leq v(x^*) = S(x^*)$

For  $x > x^*$  such that the firm does not exit, the following HJB equation<sup>3</sup> holds (see proof in the appendix)

$$\rho v(x) = u(x) + \mu(x)v'(x) + \frac{\sigma^2(x)}{2}v''(x) \quad (3)$$

Hence, for  $x$  above the exit threshold  $x^*$  we have  $v(x) \geq S(x)$ , and for  $x$  below the exit threshold  $x^*$ , we have  $v(x) = S(x)$ . Traditional methods impose “value matching” and “smooth pasting” conditions:  $v(x^*) = S(x^*)$  and  $v'(x^*) = S'(x^*)$ . We here pursue a different strategy.

## 2. HJBVI

To this end let's denote the set of  $x$  for which there is no exit by  $X$ . Then

$$\begin{aligned} x \in X : \quad & v(x) \geq S(x), \quad \rho v(x) = u(x) + \mu(x)v'(x) + \frac{\sigma^2(x)}{2}v''(x) \\ x \notin X : \quad & v(x) = S(x), \quad \rho v(x) \geq u(x) + \mu(x)v'(x) + \frac{\sigma^2(x)}{2}v''(x) \end{aligned}$$

This can also be written compactly as follows<sup>4</sup>

$$\min \left\{ \rho v(x) - u(x) - \mu(x)v'(x) - \frac{\sigma^2(x)}{2}v''(x), v(x) - S(x) \right\} = 0 \quad (4)$$

In mathematics, (4) is called a “HJB variational inequality.” See e.g. [Barles, Daher, and Romano \(1995\)](#) and [Tourin \(2013\)](#).

An alternative, and perhaps economically more intuitive way of writing this equation is

$$\rho v(x) = \max \left\{ u(x) + \mu(x)v'(x) + \frac{\sigma^2(x)}{2}v''(x), \rho S(x) \right\} \quad (5)$$

However, the HJBVI formulation (4) will be useful in the numerical solution below.

Note that rather than imposing the smooth pasting condition as is usually done in economics, this is now a result. That is, one can prove that the HJBVI (4) implies the smooth pasting condition  $v'(x^*) = S'(x^*)$ . See e.g. [Oksendal's book](#) who calls “smooth pasting” the “high contact (or smooth fit) principle.”

## 1.2 Finite Difference Method

### 1.2.1 Solving as Linear Complementarity Problem (LCP)

This is inspired by [Huang and Pang \(1998\)](#) who realize the connection between the HJB for American options and LCP.

Without the exit option, we would have HJB (3) which is discretized as

$$\rho v_i^n = u_i + \mu_i (v_i^n)' + \frac{\sigma_i^2}{2} (v_i^n)''$$

or in matrix form

$$\rho v = u + \mathbf{A}v$$

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<sup>3</sup>By including  $\mu(x)$  and  $\sigma(x)$  in the value function, this condition states that if the currently realized demand level satisfies this condition, the  $x_t$  will never be too low for firm to stay.

<sup>4</sup>To see this take any two functions  $f(x)$  and  $g(x)$  and consider the following statement: for all  $x$  either  $f(x) \geq 0, g(x) = 0$  or  $f(x) = 0, g(x) \geq 0$ . This statement can be written compactly as  $\min\{f(x), g(x)\} = 0$  for all  $x$ .

Instead, now  $v$  solves the variational inequality (4). The discretized analogue is:

$$\min\{\rho v - u - \mathbf{A}v, v - S\} = 0$$

Equivalently

$$(v - S)'(\rho v - u - \mathbf{A}v) = 0$$

$$v \geq S$$

$$\rho v - u - \mathbf{A}v \geq 0$$

Note that the second and third equations imply that the first equation actually has to hold element-wise.

Let's denote the "excess value"  $z = v - S$  and  $\mathbf{B} = \rho\mathbf{I} - \mathbf{A}$ . Then the second equation is  $z \geq 0$  and the third equation is

$$\mathbf{B}z + q \geq 0$$

where  $q = -u + \mathbf{B}S$ . Summarizing

$$z'(\mathbf{B}z + q) = 0$$

$$z \geq 0$$

$$\mathbf{B}z + q \geq 0$$

This is the standard form for LCPs problem, see details in [Wikipedia](#), so it can solve it with an LCP solver.

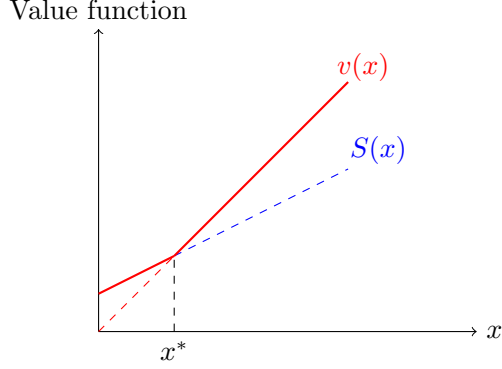
## References

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- Huang, J., & Pang, J. S. (1998). Option pricing and linear complementarity. *Journal of Computational Finance*, 2, 31-60.
- McCall, J. J. (1970). Economics of information and job search. *The Quarterly Journal of Economics*, 84(1), 113-126.

## Appendix

### HJB for firm that never stops:

The “reservation value” property implies that  $v(x) = S(x)$  for  $x \leq x^*$ . A simple illustration would be:



Therefore, for a very short period  $\Delta$  such that  $x_t = x > x^*, t \in [0, \Delta]$ , the value function (2) can be rewritten as

$$\begin{aligned} v(x) &= \int_0^\Delta u(x) \cdot e^{-\rho t} dt + e^{-\rho \Delta} \cdot \mathbb{E}_0[v(x_\Delta)] \\ &= u(x) \cdot \Delta + \frac{\mathbb{E}_0[v(x_\Delta)]}{1 + \rho \Delta} \\ \rho v(x) &= u(x) + \frac{\mathbb{E}_0[v(x_\Delta) - v(x)]}{\Delta} \\ &= u(x) + \mathbb{E}_0\left(\frac{dv(x)}{dt}\right) \end{aligned}$$

The second equality is obtained from  $e^{-x} \approx \frac{1}{1+x}$  for  $x \rightarrow 0$ . By *Ito's Lemma*<sup>5</sup>, we know that

$$\begin{aligned} dv(x_t) &= v_x \cdot d(x_t) + \frac{1}{2} v_{xx} d(x_t)^2 \\ &= v'(x_t) (\mu(x_t) dt + \sigma(x_t) dW_t) + \frac{1}{2} v''(x_t) (\mu(x_t) dt + \sigma(x_t) dW_t)^2 \end{aligned}$$

Because  $dW_t^2 = dt$ ,  $\mathbb{E}(W_t) = dt^2 = 0$ , the HJB writes

$$\rho v(x) = u(x) + v'(x)\mu(x) + \frac{\sigma^2(x)}{2} v''(x), x > x^*$$

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<sup>5</sup>Since  $v(\cdot)$  is time invariant,  $\frac{dv}{dt} = 0$