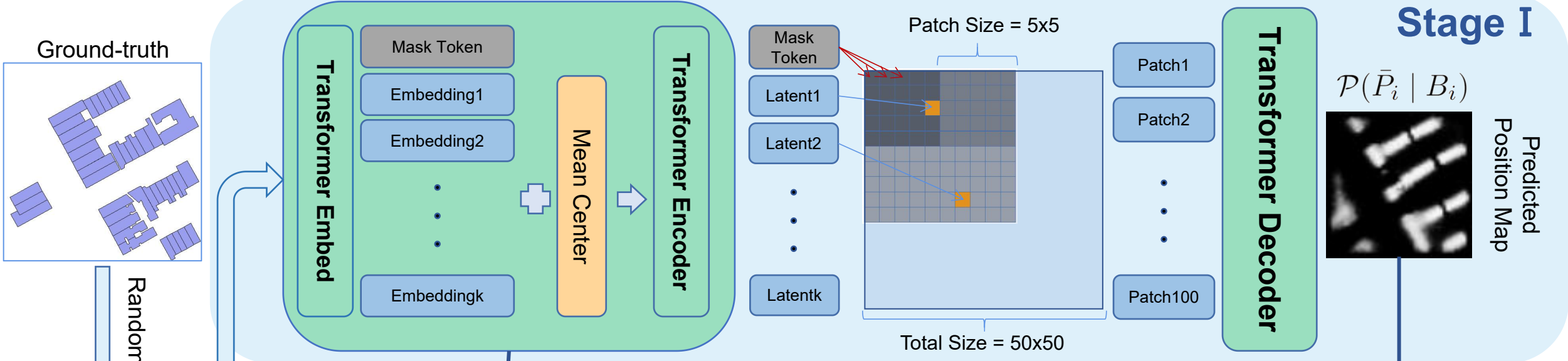


Stage I



Not share weights

Sample from the map to get the predicted position

Stage II

