

# COEX-1

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# Overview

- 1 General
- 2 Components
- 3 Control
- 4 Exploration & Mapping
- 5 Code
- 6 Components

The goal of the robot is to map an unknown environment in a centralized multi-agent setting.

The name of the robot, COEX-1, stands for Cooperative Explorer.

The main features of the robots are,

- Following a black line
- Computing the travelled distance
- Detecting, classifying and handling intersections
- Avoiding obstacles
- Communicating with a central unit

- Arduino Nano
- Reflectance sensor array
- Sharp sensor
- Magnetic encoders
- Pololu micro metal gearmotor
- L298 dual H-bridge
- NiMH Battery 7.2V
- HC-06 Bluetooth module
- ...

# General

## Structure

## Photos

- Lorem ipsum dolor sit amet, consectetur adipiscing elit
- Aliquam blandit faucibus nisi, sit amet dapibus enim tempus eu
- Nulla commodo, erat quis gravida posuere, elit lacus lobortis est, quis porttitor odio mauris at libero
- Nam cursus est eget velit posuere pellentesque
- Vestibulum faucibus velit a augue condimentum quis convallis nulla gravida

# Blocks of Highlighted Text

## Block 1

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Integer lectus nisl, ultricies in feugiat rutrum, porttitor sit amet augue. Aliquam ut tortor mauris. Sed volutpat ante purus, quis accumsan dolor.

## Block 2

Pellentesque sed tellus purus. Class aptent taciti sociosqu ad litora torquent per conubia nostra, per inceptos himenaeos. Vestibulum quis magna at risus dictum tempor eu vitae velit.

## Block 3

Suspendisse tincidunt sagittis gravida. Curabitur condimentum, enim sed venenatis rutrum, ipsum neque consectetur orci, sed blandit justo nisi ac lacus.

## Heading

- 1 Statement
- 2 Explanation
- 3 Example

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Integer lectus nisl, ultricies in feugiat rutrum, porttitor sit amet augue. Aliquam ut tortor mauris. Sed volutpat ante purus, quis accumsan dolor.



# Table

<b>Treatments</b>	<b>Response 1</b>	<b>Response 2</b>
Treatment 1	0.0003262	0.562
Treatment 2	0.0015681	0.910
Treatment 3	0.0009271	0.296

Table: Table caption

# Theorem

## Theorem (Mass–energy equivalence)

$$E = mc^2$$

## Example (Theorem Slide Code)

```
\begin{frame}  
\frametitle{Theorem}  
\begin{theorem}[Mass--energy equivalence]  
$E = mc^2$  
\end{theorem}  
\end{frame}
```

# Figure

Uncomment the code on this slide to include your own image from the same directory as the template .TeX file.

An example of the `\cite` command to cite within the presentation:

This statement requires citation [Smith, 2012].



John Smith (2012)

Title of the publication

*Journal Name* 12(3), 45 – 678.

# The End