

Project nr 2

Gibbs sampling

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1 Rain BBN

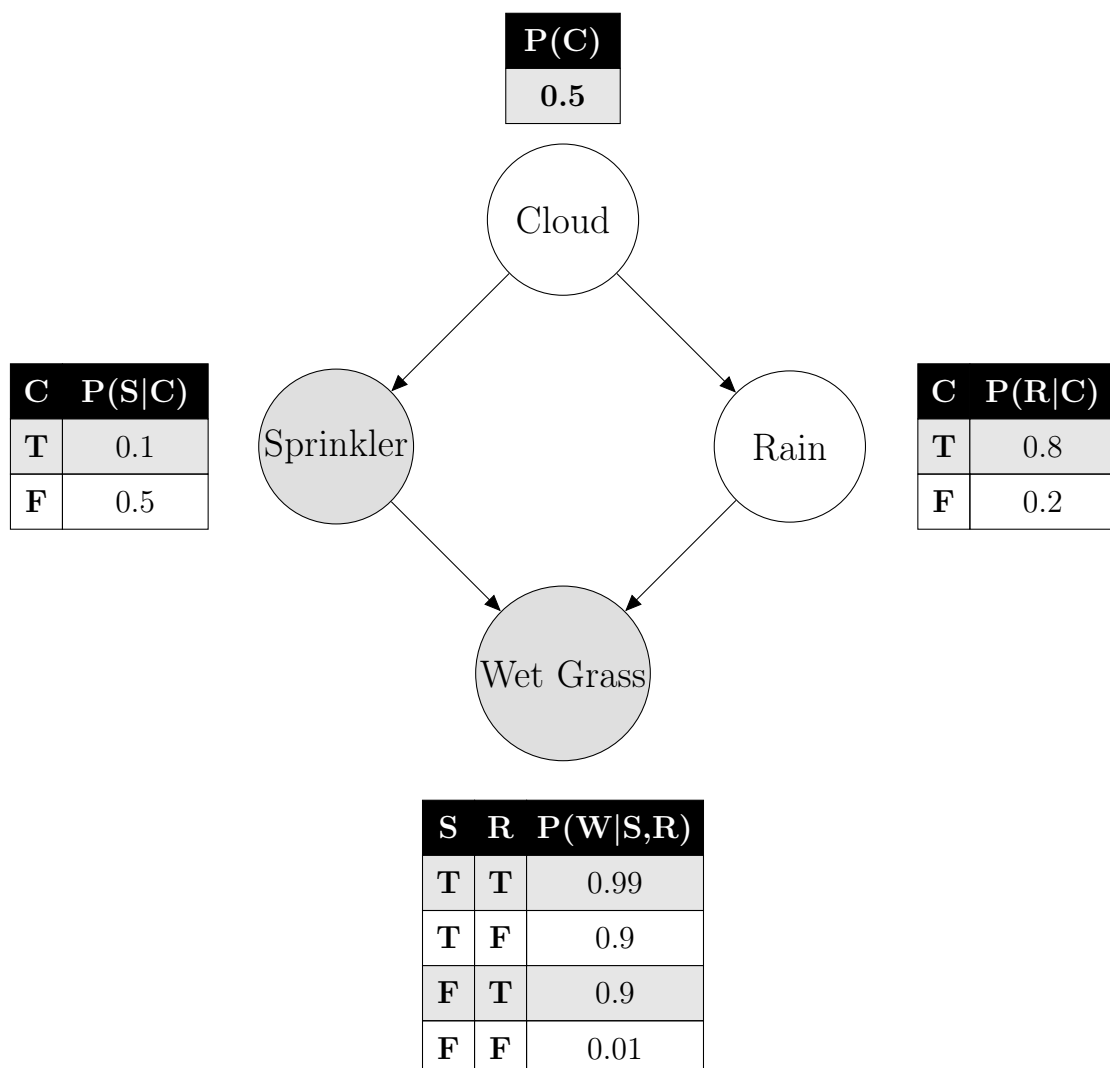


Figure 1: Bayesian diagram for rain network

Let's consider Bayesian Belief network depicted at figure 1. Each of the variables can be either True or False. Conditional dependence between them is encoded in the matrix next to each of the nodes. Right now let's do not think about which variables are observed and try to derive formula for probability of one node with respect to other variables which remain constant

1. $P(C = T | R = T, S = T, W = T)$

We can decompose local probability distribution to

$$P(C = T | R = T, S = T, W = T) \propto P(S = T | C = T)P(R = T | C = T) = 0.1 \cdot 0.8 = 0.08$$

In order to find true probability we need to compute renormalizing constant

$$P(C = F | R = T, S = T, W = T) \propto P(S = T | C = F)P(R = T | C = F) = 0.5 \cdot 0.2 = 0.10$$

. After renormalization

$$P(C = T | R = T, S = T, W = T) = \frac{0.08}{0.08 + 0.1} \approx 0.44$$

2. $P(C = T | R = F, S = T, W = T)$

As before

$$P(C = T | R = F, S = T, W = T) \propto P(S = T | C = T)P(R = F | C = T) = 0.1 \cdot 0.2 = 0.02$$

In order to find true probability we need to compute renormalizing constant

$$P(C = F | R = F, S = T, W = T) \propto P(S = T | C = F)P(R = F | C = F) = 0.5 \cdot 0.8 = 0.4$$

. After renormalization

$$P(C = T | R = F, S = T, W = T) = \frac{0.02}{0.02 + 0.4} \approx 0.047$$

3. $P(R = T | C = T, S = T, W = T)$

As before

$$P(R = T|C = T, S = T, W = T) \propto P(W = T|R = T, S = T)P(R = T|C = T) = 0.99 \cdot 0.8 = 0.792$$

In order to find true probability we need to compute renormalizing constant

$$P(R = F|C = T, S = T, W = T) \propto P(W = T|R = F, S = T)P(R = F|C = T) = 0.9 \cdot 0.2 = 0.18$$

. After renormalization

$$P(R = T|C = T, S = T, W = T) = \frac{0.792}{0.18 + 0.792} \approx 0.81$$

$$4. P(R = T|C = F, S = T, W = T)$$

As before

$$P(R = T|C = F, S = T, W = T) \propto P(W = T|R = T, S = T)P(R = T|C = F) = 0.99 \cdot 0.2 = 0.198$$

In order to find true probability we need to compute renormalizing constant

$$P(R = F|C = F, S = T, W = T) \propto P(W = T|R = F, S = T)P(R = F|C = F) = 0.9 \cdot 0.8 = 0.72$$

. After renormalization

$$P(R = T|C = F, S = T, W = T) = \frac{0.198}{0.72 + 0.198} \approx 0.22$$

Our procedure is very simple and allows us to determine marginal probability of one variable with respect to others. This simple procedure allows us to construct Gibbs sampler which uses this simple procedure to sample from our model in general case and will help to estimate what is marginal probability of $P(R = T, S = T, W = T)$.

2 Gibbs sampler

Gibbs sampler was implemented in Python programming language using NumPy. After implemen-

tation 100 samples were drawn from model. This small sample allowed to estimate that $P(R = T, S = T, W = T) \approx 0.19$. This result probably does not represent correct value as there might be a problem with convergence of our chain. Hence we need to find whether is it safe to infer from our chain.

3 Convergence Diagnostics

In order to determine whether our chain is safe to infer from two tests were performed. Firstly relative frequency of occurrence was checked and then autocorrelation test was performed. During the first $N = 50000$ samples were drawn from one chain and then relative frequency for each variable denoted as θ was calculated using

$$f(t) = \frac{1}{t} \sum_{i=1}^t \theta_i$$

allowing to present, how our estimates change across time. Results are presented on figure 2

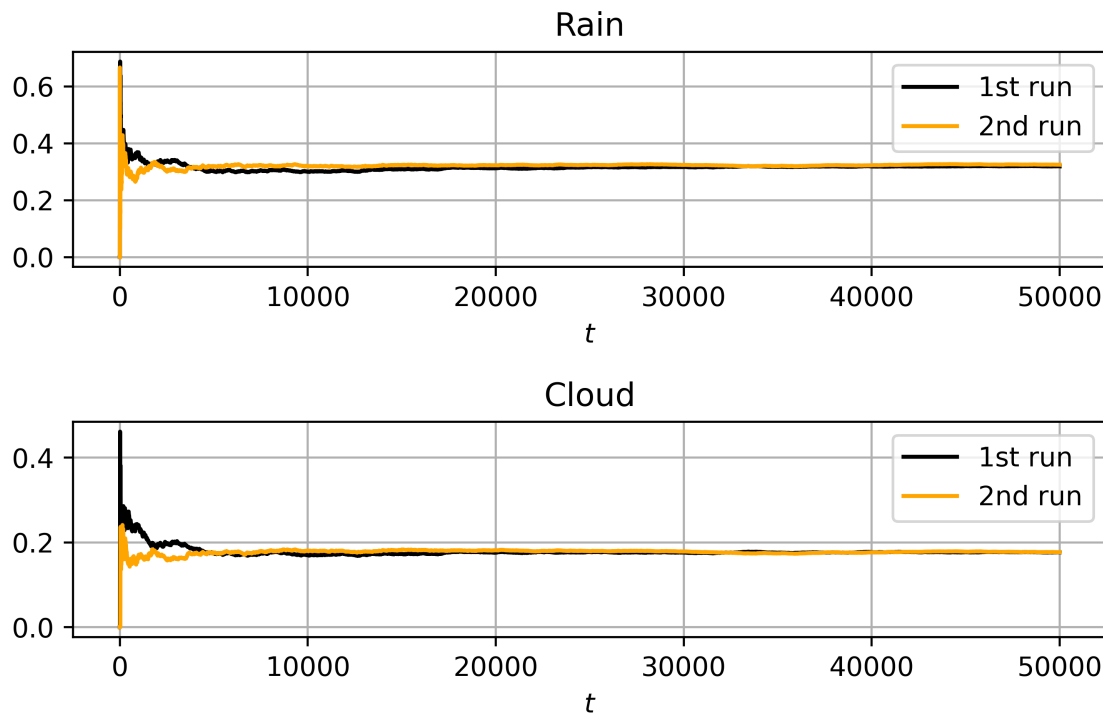


Figure 2: Relative frequency f of parameter against position in chain t for Rain variable and Cloud variable

We can see, that around $t \approx 10000$ our chain is beginning to stabilize and from this point onward our estimates do not change. What needs to be emphasized is the huge bump at the beginning of our sequence. This behaviour suggests our chain is very noisy at the beginning and we should not infer from the

first 100 samples only. Second test was based on the lagged autocorrelation function. Firstly we can introduce lagged sequence $\theta_t^l = \theta_{t+l}$. Due to finite length of our chain last l elements of original chain are discarded in this calculation. We can then introduce Pearson correlation coefficient $P(l)$ using equation

$$P(l) = \frac{\sum_{i=0}^n (\theta_i - \hat{\theta})(\theta_i^l - \hat{\theta}^l)}{\sqrt{\sum_{i=0}^n (\theta_i^2 - (\hat{\theta})^2)} \sqrt{\sum_{i=0}^n ((\theta_i^l)^2 - (\hat{\theta}^l)^2)}}$$

where $\hat{\theta}$ is mean value of θ while n is effective length of our sample equal to $n = N - l$ (as we discard last l draws). Values of our coefficient for $l \in \langle 0, 100 \rangle$ were computed and plotted on figure 3.

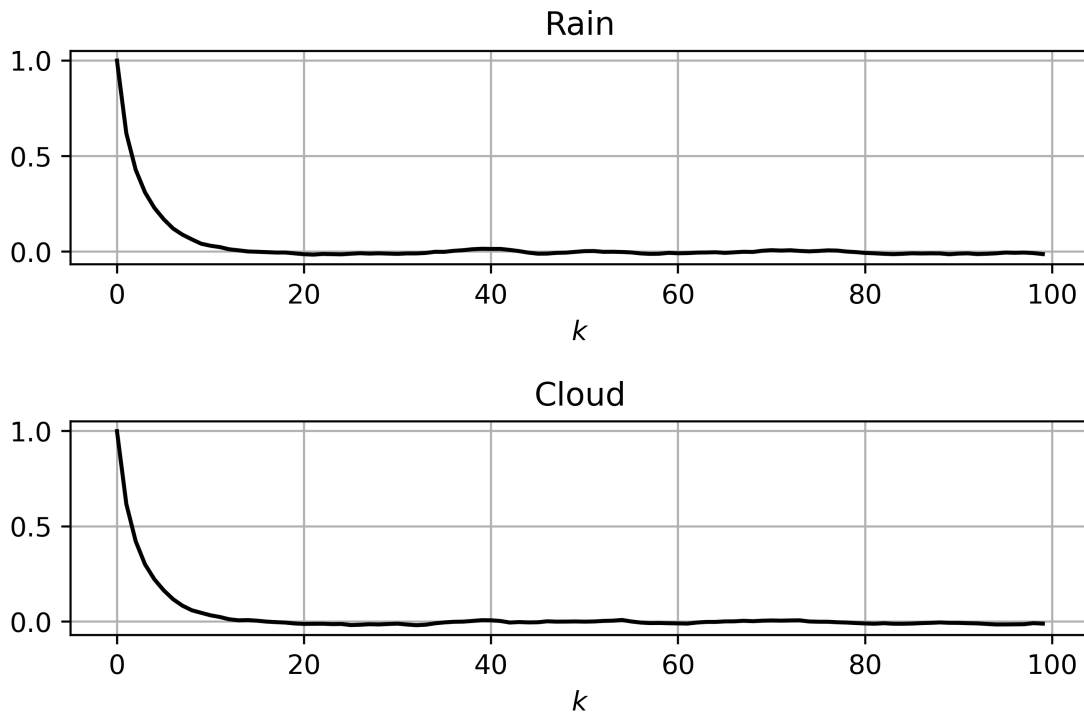


Figure 3: Corelation coefficients $P(l)$ of parameter against lag l for Rain variable and Cloud variable

We can see, that for $l > 20$ autocorrelation is neglectable so suggested thinning out should be around this value (in final model we will use $l = 50$).

3.1 Final model

After determining suitable parameters in previous section final sampling took place with burnin $N_b = 10000$ and thinning out $l = 50$. Based on MCMC estimation $P(R = T, S = T, W = T) \approx 0.30$ was obtained. Now we can compare this result with exact one. In order to calculate analytically value of

probability we will follow procedure from first section. We can write

$$P(R = T|S = T, W = T) \propto P(R = T|C = T)P(W = T|R = T, S = T)P(S = T|C = T) + \\ + P(R = T|C = F)P(W = T|R = T, S = T)P(S = T|C = F) = 0.8 \cdot 0.99 \cdot 0.1 + 0.2 \cdot 0.99 \cdot 0.5 = 0.1782$$

. On the other hand

$$P(R = F|S = T, W = T) \propto P(R = F|C = T)P(W = T|R = F, S = T)P(S = T|C = T) + \\ + P(R = F|C = F)P(W = T|R = F, S = T)P(S = T|C = F) = 0.2 \cdot 0.9 \cdot 0.1 + 0.8 \cdot 0.9 \cdot 0.5 = 0.378$$

. Combining both results we get

$$P(R = T|S = T, W = T) = \frac{0.1782}{0.1782 + 0.378} \approx 0.32$$

. We can hence see that our result is just little of from the exact value. Moreover we can see that our estimation is much better then one based on first 100 samples which do not have anything in common with exact result.

3.2 Gelman-Rubin Test

Finally in order to find whether chain have reached convergence Gelman-Rubin test was implemented. In order to test for convergence following procedure was followed. M runs of same MCMC model was performed. For each chain mean and variance were calculated

$$\hat{\theta}^m = \frac{1}{M} \sum_{i=1}^N \theta_i^m \quad (1)$$

$$\sigma_m^2 = \frac{1}{N-1} \sum_{i=0}^N (\theta_i^m - \hat{\theta}^m)^2 \quad (2)$$

. Those parameters characterize each of the chains individually. Then we define mean of all chains

$$\hat{\theta} = \frac{1}{M} \sum_{m=1}^M \hat{\theta}^m$$

and variance of means across common mean

$$B = \frac{N}{M-1} \sum_{m=1}^M (\hat{\theta}^m - \hat{\theta})^2$$

. At the end we can introduce average variance of all chains

$$W = \frac{1}{M} \sum_{m=1}^M \sigma_m^2$$

together with estimator

$$\hat{V} = \frac{N-1}{N} W + \frac{M+1}{MN} B$$

. Under hypothesis that we reached convergence \hat{V} is unbiased estimator of true variance. On the other hande in this scenario also W should be unbiased estimator of variance. Hence we can introduce value $R = \sqrt{\frac{(3+d)\hat{V}}{(1+d)W}}$ which should be 1 in the case of convergence. d parameter is estimation of number of degrees of freedom and can be obtained using method of moments $d = \frac{2\hat{V}}{Var(V)}$. Rubin Gelman test was performed using $M = 40$ and statistics R were calculated for both final sampler as the first one. For 100 samples with no burnout and thinning out statistics for Rain and Cloud node were $R_{rain} \approx 1.02$ and $R_{cloud} \approx 1.03$ respectively. For final parameters with $N = 100$, burnin $N_b = 10000$ and thinning out $l = 50$ statistic had value $R_{rain} \approx 1.0004$ and $R_{cloud} \approx 1.002$ so we can clearly see we improved in the convergence and first sample was certainly biased and should not be used to infer parameters.