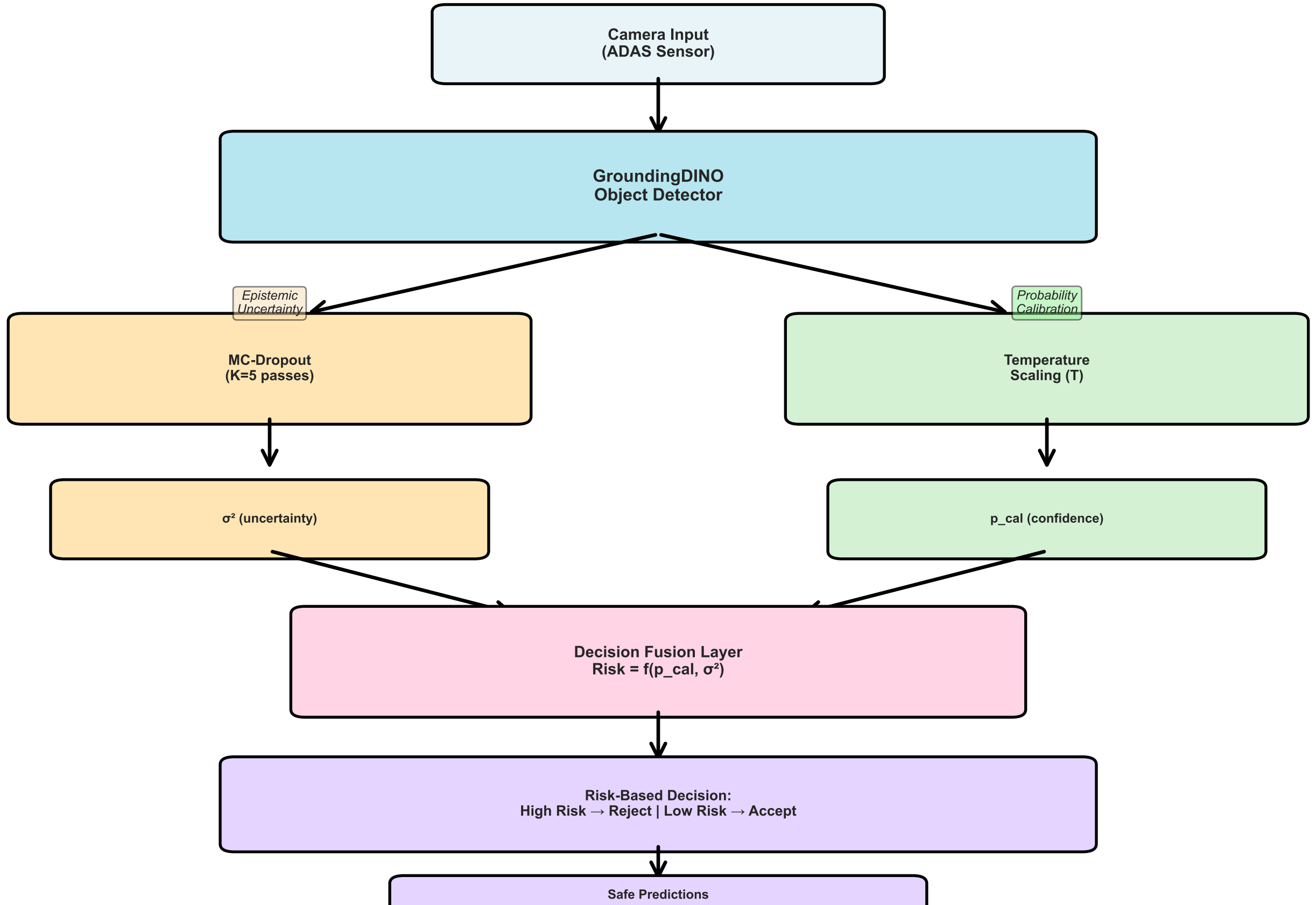Figure 9. Decision-level fusion of uncertainty-calibrated detections for ADAS perception.