

Avaliação 01 de Álgebra Linear

[M] In Exercises 41 and 42, use as many columns of A as possible to construct a matrix B with the property that the equation $B\mathbf{x} = \mathbf{0}$ has only the trivial solution. Solve $B\mathbf{x} = \mathbf{0}$ to verify your work.

$$41. A = \begin{bmatrix} 3 & -4 & 10 & 7 & -4 \\ -5 & -3 & -7 & -11 & 15 \\ 4 & 3 & 5 & 2 & 1 \\ 8 & -7 & 23 & 4 & 15 \end{bmatrix}$$

$$42. A = \begin{bmatrix} 12 & 10 & -6 & 8 & 4 & -14 \\ -7 & -6 & 4 & -5 & -7 & 9 \\ 9 & 9 & -9 & 9 & 9 & -18 \\ -4 & -3 & -1 & 0 & -8 & 1 \\ 8 & 7 & -5 & 6 & 1 & -11 \end{bmatrix}$$

43. [M] With A and B as in Exercise 41, select a column \mathbf{v} of A that was not used in the construction of B and determine if \mathbf{v} is in the set spanned by the columns of B . (Describe your calculations.)
44. [M] Repeat Exercise 43 with the matrices A and B from Exercise 42. Then give an explanation for what you discover, assuming that B was constructed as specified.

[M] In Exercises 37 and 38, the given matrix determines a linear transformation T . Find all \mathbf{x} such that $T(\mathbf{x}) = \mathbf{0}$.

$$37. \begin{bmatrix} 2 & 3 & 5 & -5 \\ -7 & 7 & 0 & 0 \\ -3 & 4 & 1 & 3 \\ -9 & 3 & -6 & -4 \end{bmatrix} \quad 38. \begin{bmatrix} 3 & 4 & -7 & 0 \\ 5 & -8 & 7 & 4 \\ 6 & -8 & 6 & 4 \\ 9 & -7 & -2 & 0 \end{bmatrix}$$

$$39. \text{ [M] Let } \mathbf{b} = \begin{bmatrix} 8 \\ 7 \\ 5 \\ -3 \end{bmatrix} \text{ and let } A \text{ be the matrix in Exercise 37.}$$

Is \mathbf{b} in the range of the transformation $\mathbf{x} \mapsto A\mathbf{x}$? If so, find an \mathbf{x} whose image under the transformation is \mathbf{b} .

$$40. \text{ [M] Let } \mathbf{b} = \begin{bmatrix} 4 \\ -4 \\ -4 \\ -7 \end{bmatrix} \text{ and let } A \text{ be the matrix in Exercise 38.}$$

Is \mathbf{b} in the range of the transformation $\mathbf{x} \mapsto A\mathbf{x}$? If so, find an \mathbf{x} whose image under the transformation is \mathbf{b} .

[M] In Exercises 37–40, let T be the linear transformation whose standard matrix is given. In Exercises 37 and 38, decide if T is a one-to-one mapping. In Exercises 39 and 40, decide if T maps \mathbb{R}^5 onto \mathbb{R}^5 . Justify your answers.

$$37. \begin{bmatrix} -5 & 6 & -5 & -6 \\ 8 & 3 & -3 & 8 \\ 2 & 9 & 5 & -12 \\ -3 & 2 & 7 & -12 \end{bmatrix}$$

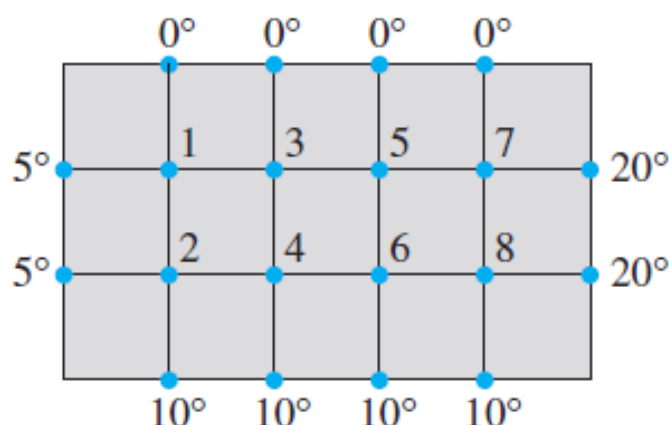
$$38. \begin{bmatrix} 7 & 5 & 9 & -9 \\ 5 & 6 & 4 & -4 \\ 4 & 8 & 0 & 7 \\ -6 & -6 & 6 & 5 \end{bmatrix}$$

$$39. \begin{bmatrix} 4 & -7 & 3 & 7 & 5 \\ 6 & -8 & 5 & 12 & -8 \\ -7 & 10 & -8 & -9 & 14 \\ 3 & -5 & 4 & 2 & -6 \\ -5 & 6 & -6 & -7 & 3 \end{bmatrix}$$

$$40. \begin{bmatrix} 9 & 43 & 5 & 6 & -1 \\ 14 & 15 & -7 & -5 & 4 \\ -8 & -6 & 12 & -5 & -9 \\ -5 & -6 & -4 & 9 & 8 \\ 13 & 14 & 15 & 3 & 11 \end{bmatrix}$$

36. [M] Write the command(s) that will create a 5×6 matrix with random entries. In what range of numbers do the entries lie? Tell how to create a 4×4 matrix with random integer entries between -9 and 9 . [Hint: If x is a random number such that $0 < x < 1$, then $-9.5 < 19(x - .5) < 9.5$.]
37. [M] Construct random 4×4 matrices A and B to test whether $AB = BA$. The best way to do this is to compute $AB - BA$ and check whether this difference is the zero matrix. Then test $AB - BA$ for three more pairs of random 4×4 matrices. Report your conclusions.
38. [M] Construct a random 5×5 matrix A and test whether $(A + I)(A - I) = A^2 - I$. The best way to do this is to compute $(A + I)(A - I) - (A^2 - I)$ and verify that this difference is the zero matrix. Do this for three random matrices. Then test $(A + B)(A - B) = A^2 - B^2$ the same way for three pairs of random 4×4 matrices. Report your conclusions.

31. [M] Consider the heat plate in the following figure (refer to Exercise 33 in Section 1.1).



The solution to the steady-state heat flow problem for this plate is approximated by the solution to the equation $A\mathbf{x} = \mathbf{b}$, where $\mathbf{b} = (5, 15, 0, 10, 0, 10, 20, 30)$ and

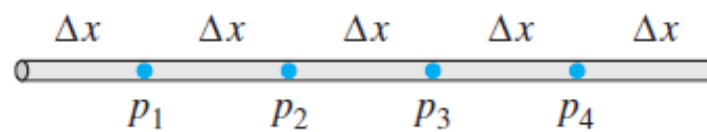
$$A = \begin{bmatrix} 4 & -1 & -1 & & & & & \\ -1 & 4 & 0 & -1 & & & & \\ -1 & 0 & 4 & -1 & -1 & & & \\ & -1 & -1 & 4 & 0 & -1 & & \\ & & -1 & 0 & 4 & -1 & -1 & \\ & & & -1 & -1 & 4 & 0 & -1 \\ & & & & -1 & 0 & 4 & -1 \\ & & & & & -1 & -1 & 4 \end{bmatrix}$$

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The missing entries in A are zeros. The nonzero entries of A lie within a band along the main diagonal. Such *band matrices* occur in a variety of applications and often are extremely large (with thousands of rows and columns but relatively narrow bands).

- Use the method in Example 2 to construct an LU factorization of A , and note that both factors are band matrices (with two nonzero diagonals below or above the main diagonal). Compute $LU - A$ to check your work.

- b. Use the LU factorization to solve $A\mathbf{x} = \mathbf{b}$.
 - c. Obtain A^{-1} and note that A^{-1} is a dense matrix with no band structure. When A is large, L and U can be stored in much less space than A^{-1} . This fact is another reason for preferring the LU factorization of A to A^{-1} itself.
32. [M] The band matrix A shown below can be used to estimate the unsteady conduction of heat in a rod when the temperatures at points p_1, \dots, p_4 on the rod change with time.²



The constant C in the matrix depends on the physical nature of the rod, the distance Δx between the points on the rod, and the length of time Δt between successive temperature measurements. Suppose that for $k = 0, 1, 2, \dots$, a vector \mathbf{t}_k in \mathbb{R}^4 lists the temperatures at time $k\Delta t$. If the two ends of the rod are maintained at 0° , then the temperature vectors satisfy the equation $A\mathbf{t}_{k+1} = \mathbf{t}_k$ ($k = 0, 1, \dots$), where

$$A = \begin{bmatrix} (1 + 2C) & -C & & \\ -C & (1 + 2C) & -C & \\ & -C & (1 + 2C) & -C \\ & & -C & (1 + 2C) \end{bmatrix}$$

- a. Find the LU factorization of A when $C = 1$. A matrix such as A with three nonzero diagonals is called a *tridiagonal matrix*. The L and U factors are *bidiagonal matrices*.
- b. Suppose $C = 1$ and $\mathbf{t}_0 = (10, 15, 15, 10)^T$. Use the LU factorization of A to find the temperature distributions $\mathbf{t}_1, \mathbf{t}_2, \mathbf{t}_3$, and \mathbf{t}_4 .