| 1 | NO:DATE: | | | | | | |
|---------------|---|--|--|--|--|--|--|
| | | | | | | | |
| | $y=e^{\alpha}$ $sin^2\theta + (0s^2\theta = 1)$ $sin(A+B) = sinA(0sB + (0sA)sinB$ | | | | | | |
| | $y = e^{x}$ $\sin^{2}\theta + (0s^{2}\theta = 1)$ $\sin(A+B) = \sin A(0s B + (0s A sin B)$ $\frac{dy}{dx} = e^{x}$ $\tan^{2}\theta + 1 = se(^{2}\theta)$ $(0s(A+B) = (0sA (0sB - sin A sin B)$ | | | | | | |
| | $\int \frac{1}{\lambda} dx = \ln x + C$ $\sin 2A = 2 \sin A \cos A$ | | | | | | |
| | $\int \frac{f(X)}{f_1(X)} dX \qquad \frac{dX}{q}(2JMX) = co2(X) \qquad co2 5 H = co25 H - 2JM_5 H$ | | | | | | |
| | $= \ln(f(x)) + C \qquad \frac{d}{dx}(\tan x) = \frac{1}{(0!^2(x))} = \sec^2(x) \qquad = 1 - 2\sin^2 A$ | | | | | | |
| | Il = 180 0 | | | | | | |
| - 1 | Area of sector: \frac{1}{2}8r = \frac{1}{2}8r^2 . approximate CHANGE in y \Rightarrow Sy = \frac{dy}{dx} \times SX | | | | | | |
| | · approximate VALUE of y => Ynew=Yord + &y | | | | | | |
| | $y = mx + C$ $\frac{dy}{dx} \approx \frac{Sy}{Sx}$ • approximate PERCENTAGE ERROR / CHANGE of y $m = \frac{y - y_1}{x - x_1} = \frac{y_1 S_C}{run}$ $Sy = \frac{dy}{dx} \times Sx$ $\Rightarrow \frac{Sy}{y} = \frac{dy}{dx} \times \frac{Sx}{y}$ | | | | | | |
| <u> </u> | $y-y_1=m(x-x_1)$ | | | | | | |
| | mix m2=-1 tangent gradient x normal gradient =-1 | | | | | | |
| | $d = J(\chi_1 - \chi_2)^2 + (y_1 + y_2)^2 $ (AS \rightarrow menu $\rightarrow 4 \rightarrow 9 \rightarrow$ tangent line $(\chi^2 + \chi_1, \chi_1)$ | | | | | | |
| | A -> normal line (x2+2, x12) | | | | | | |
| x + x x y x + | (OST [C(X)]; revenue [R(X)]; profit [P(X)] | | | | | | |
| - V | P(x) = R(x) - C(x) area under curve | | | | | | |
| | marginal cost $\begin{bmatrix} \frac{dC}{dx} \end{bmatrix}$ average cost $\begin{bmatrix} \frac{C(X)}{X} \end{bmatrix}$ \Rightarrow if graph area falls | | | | | | |
| | marginal revenue [dx] average revenue [R(x)] below x-axis, add | | | | | | |
| | marginal posit [dx] average posit [p(x)] modulus "11" | | | | | | |
| | | | | | | | |
| | Displacement total change $\frac{d}{dx} \int_{a}^{x} f(t) dt = f(x)$ Sat $\int_{a}^{b} \frac{dv}{dt} = \int_{a}^{b} \frac{dv}{dt}$ $\int_{a}^{b} \frac{dv}{dt} = \int_{a}^{b} \frac{dv}{dt}$ | | | | | | |
| | | | | | | | |
| 1 | velocity rate of change | | | | | | |
| | $\int_{5}^{2} f(x) dx = -\int_{2}^{5} f(x) dx$ | | | | | | |
| | Acceleration Special formulas: $\int_{a}^{a} f(x) dx = 0$ | | | | | | |
| | 7) $\int f'(x) e^{f(x)} dx = e^{f(x)} + C$ | | | | | | |
| , 8 11 2 | Distance ii) $\int f'(x) [f(x)]^n dx = \frac{[f(x)]^{n+1}}{n+1} + C$ average change find $\int \frac{f'(x)}{f(x)} dx = \ln(f(x)) + C$ = $\frac{\text{total change}}{\text{fime}}$ | | | | | | |
| | | | | | | | |
| | speed $x = \sqrt{\frac{1}{x}} dx = \ln(x) + C$ | | | | | | |
| * 1, | f(b)-f(a) | | | | | | |
| 10 m | t=0 when particle at rest constant acceleration b-a | | | | | | |
| | x changing direction = \uparrow velocity $\int_{0}^{b} f'(x) dx = f(b) - f(a)$ | | | | | | |

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|--|---|---|---|--------------------------|--|---|--|
| type | shape | f'(X) | f"(X) | stationary point | turning point | | |
| maximum | max | | f"(X) < 0 | A | , & | | |
| | | f1(x)=0 3 x = 0 | ** tu(x) < 0 | ✓ | ✓ | | |
| | | | sub a | | ran altija | | |
| minimum | | 1 .1 - " | fu(X) > 0 | 8 77 A | | 5 | |
| | | f((X)=0 => X = b | * f"(x) >0 | V | 1 √ 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | | |
| | พ้าท | | 1 sub b | | | | |
| Honzontal | H.POI | | f"(X) = 0 | | | | |
| point of | * | f(1)=0; x=C | tu(()=0 | ✓ | × | | |
| Inflection | 2.7 | | Comment is | | (* (* 5) | | |
| Oblique | 0.P01 | t'(x)>0 / t'(x) <0 | $f''(\chi) = 0$ | | | | |
| Point of | 1 | BUT never = 0 | L> x = 6 | × | × | ~ | |
| Inflection | f,(x)<0 f,(x)>0 | | · · · · · · · · · · · · · · · · · · · | | A. 1. 131 | $\gamma iii \cdot \frac{d}{dx} (ini+(x))$ | |
| | Optimisation | x 4 7 + 2 - 2 | s. We get the | Logarithms | x Indices: | $=\frac{f(\chi)}{f(\chi)}$ | |
| | | | function | an=x ; 109 | | | |
| find variables x optimized function an=x; loga(x)=n relationship function loga(xy) = loga(x) + loga(y) | | | | | | + 10(1a(4) | |
| | | A points $(f'(x) = 0)$ | | | = 10ga(x) - | 0 0 | |
| 1.5 | | f"(x) >0 ⇒ min ; | | 0.0 | • | | |
| | Ju 3 3 | | | | | | |
| | | al max / min | $iv. \log_{\mathbf{x}}(\mathbf{y}) = \frac{\log_{\mathbf{a}}(\mathbf{y})}{\log_{\mathbf{a}}(\mathbf{x})}$ | | | | |
| | V 100 (12 5 0 5 100 (02 5) | | | | | 2 | |
| | f(x) = | $\int_{a}^{c} f(x) dx =$ | : A1+(-A2) | vi. log _e (x) | | | |
| | Ai | J | = h ₁ - h ₂ | VII. dx (logal | | P ₀ | |
| | Area = displacement Area = Velocity | | | | | าดนา | |
| | In f(x) dx + Ic f(x) dx yelocity) acceleration | | | | | | |
| STATEMENT STATEMENT CONTROL OF CO | | | | | | | |
| | Area (shaded) = $\int_{a}^{b} f(x) dx$ | | | | | | |
| | ti to time to to time | | | | | | |
| | g f(x) prog (chaded) "top - hottom" | | | | | | |
| | u | | /// | 1 t(x) -g(x) d | | | |
| | a b x y i i g(x) Area (shaded) | | | | | | |
| | Mills | area (snaded) = $-\int_0^b f(x) dx$ = $\int_0^b f(x) - g(x) dx$ | | | | | |
| | | y=f(x) | | 1 | + 1691 | xb(x) - $f(x)dx$ | |
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