

# Objective

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2. The replacement and the original events should be as close as possible.

Each event is characterized by a vector of losses in Subareas.

Year	Event	Subarea							
		Country loss	State 1 loss	.	.	State S loss	County 1 loss	.	County C loss
1	12	-	-	-	-	-	-	-	-
2	21	-	-	-	-	-	-	-	-
2	40	-	-	-	-	-	-	-	-
2	42	-	-	-	-	-	-	-	-
3	61	-	-	-	-	-	-	-	-
3	62	-	-	-	-	-	-	-	-
3	80	-	-	-	-	-	-	-	-
.	.	-	-	-	-	-	-	-	-
.	.	-	-	-	-	-	-	-	-

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Previous work selects the nearest neighbor using [L1](#) (Manhattan) distance function with modification.

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- Loss difference in each Subarea is multiplied by a factor. The factor seems adhoc and its motivation is unclear. The legacy document questioned its necessity.

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# Evaluation metric

We evaluate the upsampled catalog by computing the difference between its EPs and the “true” catalog’s EPs.

Coefficient of determination:

$$r^2 = 1 - \frac{\sum_{s=1}^S \sum_{y=1}^{100K} \left[ \text{loss}^{\text{upsampled}} (\text{Subarea}_s, \text{Year}_y) - \text{loss}^{\text{truth}} (\text{Subarea}_s, \text{Year}_y) \right]^2}{\sum_{s=1}^S \sum_{y=1}^{100K} \left[ \overline{\text{loss}} - \text{loss}^{\text{truth}} (\text{Subarea}_s, \text{Year}_y) \right]^2}$$

where  $\overline{\text{loss}} = \frac{1}{100K \cdot S} \sum_{s=1}^S \sum_{y=1}^{100K} \text{loss}^{\text{truth}} (\text{Subarea}_s, \text{Year}_y)$ .

1.  $\text{loss} (\text{Subarea}_s, \text{Year}_y)$  is the  $y$ -th ordered annual loss in  $\text{Subarea}_s$ .

	Coefficient of Determination			
	Overall	Country	States	Counties
Previous work:	0.988	0.991	0.986	0.974
L <sub>2</sub> (Euclidean)	0.991	0.992	0.990	0.980
L <sub>1</sub> (Manhattan)	0.990	0.990	0.990	0.979
L <sub>0.25</sub>	0.957	0.947	0.957	0.949
L <sub>0.33</sub>	0.972	0.965	0.973	0.965
L <sub>0.4</sub>	0.978	0.973	0.979	0.971
L <sub>0.5</sub>	0.985	0.982	0.986	0.976
L <sub>0.6</sub>	0.987	0.985	0.988	0.977
L <sub>0.7</sub>	0.989	0.987	0.989	0.978
L <sub>0.75</sub>	0.989	0.988	0.989	0.978
L <sub>0.8</sub>	0.990	0.989	0.990	0.979
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L <sub>2</sub> with weights of 1/sqrt(SubArea total Loss)	0.989	0.988	0.988	0.980
Inner product	0.310	0.341	0.189	-0.254
Symmetric cross entropy	0.837	0.856	0.796	0.696

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4. Table shows Euclidean leads the board, but most other distance measures also yield sufficiently high  $r^2$ s.
5. Computation shortcut: for each event, use the countrywide losses to determine its nearest 1000 neighbors. The computation is trivial because losses in 1-d space can be searched after sorting. Then among the 1000 candidates, compute distances and select the nearest neighbor  $\implies$  10x speedup. Sparse representation of events  $\implies$  +10x speedup.

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# 100 events sampled at random

Color scale is not linear  
to loss.

Similarity in spatial  
footprints alone does  
not dictate closeness  
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Overall, New Euclidean  
preserves the spatial  
footprint slightly better,  
but has no consistent  
advantage over the  
previous work for every  
event.

We focus on Euclidean  
and  $L_1$  moving forward.

# Exploration: feature engineering

Year Event	Subarea					Engineered features							
	Country loss	State 1 loss	State S loss	County 1 loss	County C loss	Mean loss of 8 closest counties to County 1	Mean loss of 8 closest counties to County C	Mean loss of 16 closest counties to County 1	Mean loss of 16 closest counties to County C	Mean loss of 32 closest counties to County 1	Mean loss of 32 closest counties to County C	Mean loss of 64 closest counties to County 1	Mean loss of 64 closest counties to County C
1 12	-	-	-	-	-	-	-	-	-	-	-	-	-
2 21	-	-	-	-	-	-	-	-	-	-	-	-	-
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3 61	-	-	-	-	-	-	-	-	-	-	-	-	-
3 62	-	-	-	-	-	-	-	-	-	-	-	-	-
3 80	-	-	-	-	-	-	-	-	-	-	-	-	-
-	-	-	-	-	-	-	-	-	-	-	-	-	-
-	-	-	-	-	-	-	-	-	-	-	-	-	-

Using county losses alone to characterize events can be disastrous because of [curse of dimensionality](#). Distance measure loses potency of distinguishing points in high-D space due to sparsity.

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3	61	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
3	62	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
3	80	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

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Including Country and State losses in the characteristic vector provides more spatial context of an event, and is necessary to let the distance measure identify reasonable neighbors.

# Exploration: feature engineering

Year Event	Subarea						Engineered features											
	Country loss	State 1 loss	State 2 loss	State 3 loss	County 1 loss	County 2 loss	Mean loss of 8 closest counties to County 1	Mean loss of 8 closest counties to County C	Mean loss of 16 closest counties to County 1	Mean loss of 16 closest counties to County C	Mean loss of 32 closest counties to County 1	Mean loss of 32 closest counties to County C	Mean loss of 64 closest counties to County 1	Mean loss of 64 closest counties to County C	Mean loss of 128 closest counties to County 1	Mean loss of 128 closest counties to County C	Mean loss of 256 closest counties to County 1	Mean loss of 256 closest counties to County C
1 12	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
2 21	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
2 40	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
2 42	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
3 61	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
3 62	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
3 80	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Using county losses alone to characterize events can be disastrous because of [curse of dimensionality](#). Distance measure loses potency of distinguishing points in high-D space due to sparsity.

As a compromise, we replace convolution of nearby pixels with averaging nearby county losses — the closest 8, 16, 32, 64 counties.

Including Country and State losses in the characteristic vector provides more spatial context of an event, and is necessary to let the distance measure identify reasonable neighbors.

For building spatial context, a radical approach is to characterize the event using losses over a fine regular grid, and employ the feature engineering in convolutional neural net — convolve the loss image with kernels of various sizes, then concatenate the feature maps as the characteristic vector. However this could be too computationally heavy as the feature dimensionality can be massive.



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1 12	-	-	-	-	-	-	-	-	-	-	-	-	-			
2 21	-	-	-	-	-	-	-	-	-	-	-	-	-			
2 40	-	-	-	-	-	-	-	-	-	-	-	-	-			
2 42	-	-	-	-	-	-	-	-	-	-	-	-	-			
3 61	-	-	-	-	-	-	-	-	-	-	-	-	-			
3 62	-	-	-	-	-	-	-	-	-	-	-	-	-			
3 80	-	-	-	-	-	-	-	-	-	-	-	-	-			
-	-	-	-	-	-	-	-	-	-	-	-	-	-			
-	-	-	-	-	-	-	-	-	-	-	-	-	-			

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For building spatial context, a radical approach is to characterize the event using losses over a fine regular grid, and employ the feature engineering in convolutional neural net — convolve the loss image with kernels of various sizes, then concatenate the feature maps as the characteristic vector. However this could be too computationally heavy as the feature dimensionality can be massive.

As a compromise, we replace convolution of nearby pixels with averaging nearby county losses — the closest 8, 16, 32, 64 counties.

With the engineered features, Country and State losses can be obsolete and may have negative impact. Keep them for now.

# 100 events sampled at random

Overall, “Euclidean + extended dimensions” preserves the spatial footprint slightly better, but still has no consistent advantage for all events.

	Overall	Country	States	Counties
Previous work:	0.988	0.991	0.986	0.974
L <sub>2</sub> (Euclidean)	0.991	0.992	0.990	0.980
L <sub>1</sub> (Manhattan)	0.989	0.989	0.989	0.979

# Exploration: feature engineering, exclude country and states

Year	Event	Subarea					Engineered features									
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1	12	-	-	-	-	-	-	-	-	-	-	-	-	-		
2	21	-	-	-	-	-	-	-	-	-	-	-	-	-		
2	40	-	-	-	-	-	-	-	-	-	-	-	-	-		
2	42	-	-	-	-	-	-	-	-	-	-	-	-	-		
3	61	-	-	-	-	-	-	-	-	-	-	-	-	-		
3	62	-	-	-	-	-	-	-	-	-	-	-	-	-		
3	80	-	-	-	-	-	-	-	-	-	-	-	-	-		
-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		

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Overall,  
 "Euclidean +  
 dim extended +  
 Country and  
 States  
 excluded"  
 preserves  
 spatial  
 footprints  
 better than  
 "Euclidean +  
 dim extended".

# Jaccard (binary distance)

	Overall	Country	States	Counties
Previous work:	0.988	0.991	0.986	0.974
L <sub>2</sub> (Euclidean)	0.989	0.989	0.989	0.980
L <sub>1</sub> (Manhattan)	0.988	0.987	0.988	0.979
Jaccard	0.930	0.928	0.916	0.897

Jaccard/binary is  
the best to  
preserve the  
spatial footprint,  
but it does not  
take loss  
magnitudes into  
account and thus  
yields poor  $r^2$ .

## Conclusion and next steps

1. Product team's approach appears good enough in terms of  $r^2$ . The scaling factors in their approach may be overengineered.

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3. Sophistication: because Jaccard/binary is the best to preserve spatial footprint but struggles with  $r^2$ , we could try:
  - 3.1 Using Jaccard, store the  $K$  (e.g.  $K = 5$ ) nearest neighbors for each event.

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  - 3.1 Using Jaccard, store the  $K$  (e.g.  $K = 5$ ) nearest neighbors for each event.
  - 3.2 For each event, if the Euclidean NN is among the Jaccard  $K$  NNs, freeze the replacement event to the Euclidean NN.
  - 3.3 For all the other events, run stochastic optimization that maximizes  $r^2$  by selecting one of the  $K$  nearest neighbors.



# Paper topics ranked by preferences

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3. Catalog downsampling. The avenue will be a little different since the star of the show is the data structure designed for updating order statistics of high-D data. There are tons of algorithm researches on how to find/approximate quantiles in a data streaming environment. Our work could be relevant.

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4. Four-point regridding. A long shot but there might be rich theoretical/numerical materials that can be mined or built.

## **Temporary page!**

$\text{\LaTeX}$  was unable to guess the total number of pages correctly. As there was some unprocessed data that should have been added to the final page this extra page has been added to receive it.

If you rerun the document (without altering it) this surplus page will go away, because  $\text{\LaTeX}$  now knows how many pages to expect for this document.