

Multivariate Data Analysis

Assignment 1

Question 1

We assume that the outcome variable y_i is drawn ^{independently} from a Poisson distribution following:
 $P(Y=y_i | \mu_i) = \frac{e^{-\mu_i} \cdot \mu_i^{y_i}}{y_i!}$ where $y_i = 0, 1, 2, \dots$ and $\ln \mu_i = \alpha_i^T \theta$ and $\log \mu_i = \alpha_i^T \theta$ where $\theta \sim \mathcal{N}(0, \sigma^2, I_p)$

Poisson distribution states that $E[y_i | \alpha_i] = \text{Var}(y_i | \alpha_i) = \mu_i = e^{\alpha_i^T \theta}$

So we can estimate θ by maximizing the log-likelihood function:

$$L(\theta) = \log\left(\prod_{i=1}^n \frac{e^{-\mu_i} \cdot \mu_i^{y_i}}{y_i!}\right) = -\sum_{i=1}^n \mu_i + \sum_{i=1}^n y_i \alpha_i^T \theta + \sum_{i=1}^n \ln(y_i!)$$

Question 2

Gradient: $\frac{\partial L(\theta)}{\partial \theta_i} = \sum_{j=1}^n (y_j - \mu_j) \cdot \alpha_{ji} \rightarrow \frac{\partial L(\theta)}{\partial \theta} = \sum_{i=1}^n (y_i - \mu_i) \cdot \alpha_i \rightarrow \Delta L(\theta) = X^T (y - \mu)$

Hessian: $\frac{\partial}{\partial \theta_k} \cdot \frac{\partial L(\theta)}{\partial \theta_j} = -\sum_{i=1}^n \alpha_{ij} \alpha_{ik} \mu_i \rightarrow \frac{\partial^2 L(\theta)}{\partial^2 \theta} = -\sum_{i=1}^n \alpha_i \alpha_i^T \mu_i \rightarrow H(\theta) = X^T \mu X$

Question 3-4-5 | See code in Appendix (end of pdf)

Assignment 2 -> Questions 3-5

```
data = table2array(readtable("dataexercise2.csv"))
```

```
data = 70x5
    0.3668    0.7738   -0.3517   -0.7888    1.0000
    0.5239    2.1021    0.7871   -0.7156    6.0000
    0.2103    1.0691    0.5585    0.5619    1.0000
    0.8193    1.6103   -0.8128   -0.1293    9.0000
    0.5014    1.9799   -0.8055   -0.3423    3.0000
    0.5594    2.9724   -0.1054   -0.4052    8.0000
    0.5236    2.6627    0.4974    0.0003    2.0000
    0.4159    1.2459    0.1707    0.5294    6.0000
    0.5402    1.4927    0.0729   -0.1947     0
    0.6896    0.5877   -0.0903    0.6626    3.0000
    ⋮
```

```
x = data(:,1:4);
y = data(:,5);

n = height(data);
p = width(x);
```

Question 3:

Implement a Newton algorithm for computing the Laplace approximation to the posterior distribution.

```
newton_nbr_it = 100;

%aprior
sigma = 4;
cov_matrix = sigma^2*eye(p);
thetas = [0 0 0 0];

for i=1:newton_nbr_it
    thetas = thetas + calculateGradient(x,y,thetas,cov_matrix)/calculateHessian(x,thetas,cov_ma
end
```

Report mean and covariance matrix of the approximation.

```
mean = thetas
```

```
mean = 1x4
    -1.2870    -0.3880    -0.0222     0.0635
```

```
cov = -inv(calculateHessian(x,mean,cov_matrix))
```

```
cov = 4x4
    0.0262   -0.0070     0.0007   -0.0009
   -0.0070     0.0028   -0.0002     0.0005
    0.0007   -0.0002     0.0136   -0.0013
```

-0.0009 0.0005 -0.0013 0.0110

Question 4:

Implement a random-walk Metropolis Hastings algorithm to sample from the posterior.

```
best_theta = mean
```

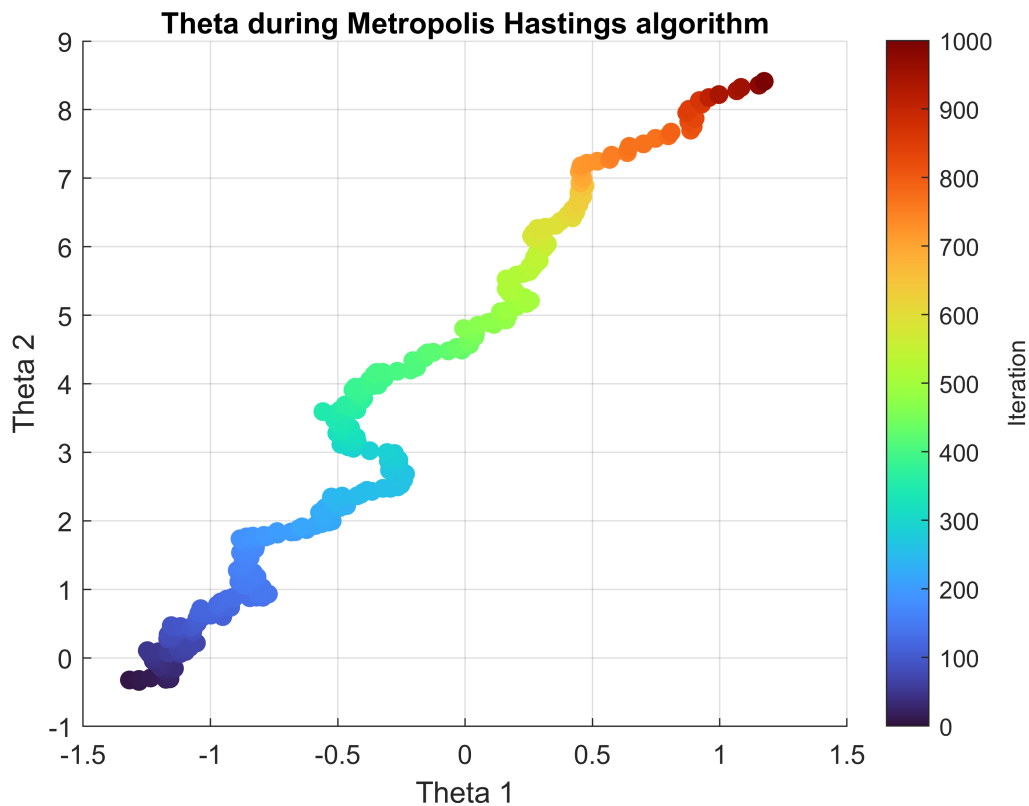
```
best_theta = 1×4  
-1.2870   -0.3880   -0.0222   0.0635
```

```
sigma_proposal = 0.03;  
  
c=0;  
MH_nbr_it = 1000;  
thetas = zeros(MH_nbr_it,4);  
for i=1:MH_nbr_it  
    prop_theta = best_theta + sigma_proposal*mvnrnd([0 0 0 0],eye(p));  
  
    prop_posterior = calculateLogPrior(prop_theta,eye(p))+calculateLogLik(x,y,prop_theta);  
    best_posterior = calculateLogPrior(best_theta,sigma*eye(p))+calculateLogLik(x,y,best_theta);  
  
    ratio = prop_posterior-best_posterior;  
    alpha = min(1,max(0,ratio));  
  
    u = rand;  
    if u < alpha  
        c=c+1;  
        best_theta = prop_theta;  
    end  
    thetas(i,:) = best_theta;  
end  
display("Acceptance rate = "+c/MH_nbr_it)
```

```
"Acceptance rate = 0.309"
```

Make a plot of the iterates where you plot θ_2 versus θ_1 , with colour indicating the iteration number.

```
cmap = turbo(MH_nbr_it);  
scatter(thetas(:,1),thetas(:,2),50,cmap, 'filled')  
title('Theta during Metropolis Hastings algorithm')  
xlabel('Theta 1')  
ylabel('Theta 2')  
grid on  
colormap(cmap)  
c = colorbar;  
c.Label.String = 'Iteration';  
caxis([0, MH_nbr_it])
```



Report the Monte-Carlo estimate of the posterior mean.

```
display("Monte Carlo estimate = ["+sum(thetas(:,1))/length(thetas(:,1))+',' '+sum(thetas(:,2))/length(thetas(:,2))+"")
```

```
"Monte Carlo estimate = [0.044382,4.8425]"
```

Question 5:

Implement a Gibbs sampler that iteratively samples from the full conditionals of

θ and $\tilde{\sigma}$.

```
Gibbs_nbr_it = 1000;
b = 0.2;
a = 0.2;
sigma_proposal = 0.03;
sigma = 4;

sigmas = zeros(Gibbs_nbr_it,1);
sigmas(1)=sigma;
for i=2:Gibbs_nbr_it
    prop_theta = best_theta + sigma_proposal*mvnrnd([0 0 0 0],eye(p));

    prop_posterior = calculateLogPrior(prop_theta,eye(p))+calculateLogLik(x,y,prop_theta);
    best_posterior = calculateLogPrior(best_theta,sigma*eye(p))+calculateLogLik(x,y,best_theta);
```

```

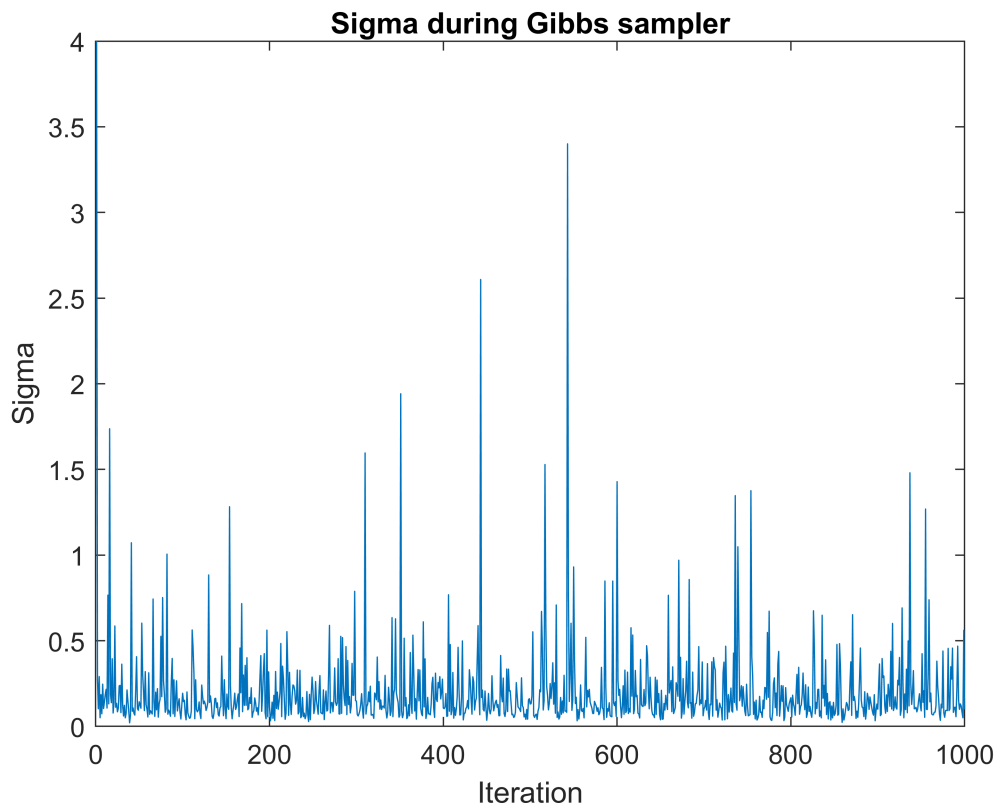
ratio = prop_posterior-best_posterior;
alpha = min(1,max(0,ratio));

u = rand;
if u < alpha
    best_theta = prop_theta;
end

sigma = 1/gamrnd(a+(p/2),b+(norm(best_theta))/2);
sigmas(i,:)=sigma;
end

plot(sigmas)
title('Sigma during Gibbs sampler')
xlabel('Iteration')
ylabel('Sigma')

```



```

function lambda = calculateLambda(x,theta)
    lambda = exp(-x*transpose(theta));
end

function gradient = calculateGradient(x,y,theta,cov_matrix)
    n = height(x);

    gradient = 0;
    for i=1:n

```

```

        x_i = x(i,:);
        y_i = y(i,:);
        lambda_i = calculateLambda(x_i,theta);
        gradient = gradient + ((y_i-lambda_i)*x_i - theta/cov_matrix);
    end
end

function hessian = calculateHessian(x,theta,cov_matrix)
    n = height(x);

    hessian = 0;
    for i=1:n
        x_i = x(i,:);
        lambda_i = calculateLambda(x_i,theta);
        hessian = hessian - lambda_i*transpose(x_i)*x_i - inv(cov_matrix);
    end
end

function loglik = calculateLogLik(x,y,theta)
    n = height(x);

    loglik = 0;
    for i=1:n
        x_i = x(i,:);
        y_i = y(i,:);
        lambda_i = calculateLambda(x_i,theta);
        loglik = loglik + (-lambda_i+y_i*x_i*transpose(theta)-log(factorial(y_i)));
    end
end

function logprior = calculateLogPrior(theta,cov)
    logprior = log(mvnpdf(theta,[0 0 0 0],cov));
end

```