

School of Computing
National University of Singapore
CS4243 Computer Vision and Pattern Recognition
Semester 1, AY 2015/16

Lab 5 Harris Corner Detector

Objective:

To understand and implement a popular corner detector called Harris Corner Detector using python codes

Preparation:

- Download the file HarrisCorner.zip from IVLE into your working directory. Uncompress the file and you should find the following files: Harris_Corner_Lab.pdf, checker.jpg, flower.jpg, building1.png, building2.png.

Introduction: Harris Corner Detector

The following shows the detailed steps of a Harris Corner Detector:

- Get the horizontal edge strength of every point in image and store in g_x .
 - Please use a Sobel kernel for this step.
- Get the vertical edge strength of every point in image and store in g_y .
 - Please use a Sobel kernel for this step.
- Compute the product of derivatives
 - $I_{xx} = g_x * g_x$
 - $I_{xy} = g_x * g_y$
 - $I_{yy} = g_y * g_y$
- Define a Gaussian kernel
 - The following is a block of python codes that generates a Gaussian kernel:

```
def gauss_kernels(size,sigma=1):  
    ## returns a 2d gaussian kernel  
    if size<3:  
        size = 3  
    m = size/2  
    x, y = np.mgrid[-m:m+1, -m:m+1]  
    kernel = np.exp(-(x*x + y*y)/(2*sigma*sigma))  
    kernel_sum = kernel.sum()  
    if not sum==0:  
        kernel = kernel/kernel_sum  
  
    return kernel
```

- Convolve I_{xx} , I_{xy} , I_{yy} using the Gaussian kernel of window size=3 and sigma=1. Place the results in W_{xx} , W_{xy} , W_{yy} respectively.
- Obtain the W matrix as follows:

$$W = \begin{pmatrix} W_{xx} & W_{xy} \\ W_{xy} & W_{yy} \end{pmatrix}$$

- Compute the determinant of W and store in $detW$.
- Compute the trace of W and store in $traceW$.
- Compute the Harris Corner response given by the following equation:

$$response = detW - k * traceW * traceW$$

where $k = 0.06$

Instructions

- Please perform Harris Corner detection on all the pictures in this package (i.e. checker.jpg, flower.jpg, building1.png, building2.png). Remember to read the color images into gray scale. Perform Harris Corner detection on these gray scale images.
- Please note that in practice, one usually does not need to process every pixel. But in this lab, please perform Harris Corner Detection on every pixel.
- Please keep all the responses that are at least 10% of the maximum response value. Mark these positions on the image and save the image.
- Please note that you can only use OpenCV for the following, and only for the following:
 - Read an image using `cv2.imread`
 - Write an image using `cv2.imwrite`
 - You are not allowed to use the other methods in OpenCV and any other packages other than python and its following import:
 - Numpy
 - Matplotlib.pyplot
- You must implement the Harris Corner detector by writing the python codes all by yourself (i.e. you cannot get the codes from elsewhere).

Submission Instruction

Submit the following at the end of your lab session.

1. Print-out of your Python codes.
2. Submit the softcopy of your Python codes and images (with good features marked by squares of size equal to the feature window size) to IVLE.
 - Please put your files in a folder and submit the folder. Use the following convention to name your folder:
MatriculationNumber_yourName_Lab#. For example, if your matriculation number is A1234567B, and your name is Chow Yuen Fatt, for this lab, your file name should be A1234567B_ChowYuenFatt_Lab5.

Please remember to write your name on the hardcopy print-out of your python code. There is no need to submit hardcopy images.