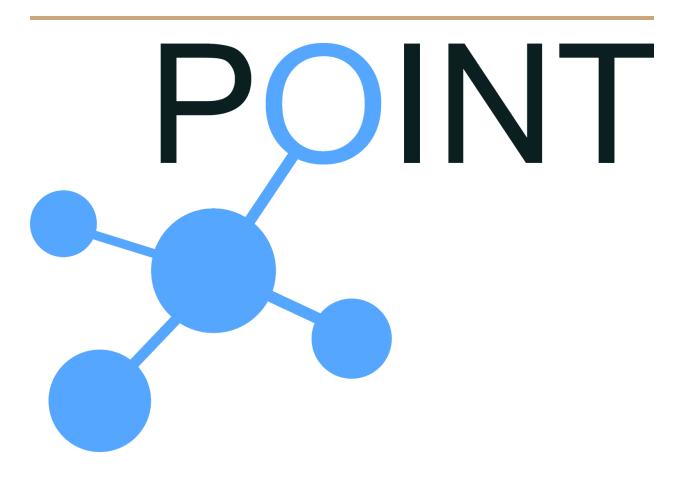
H2020 i**P O**ver IcN- the betTer IP (POINT)

# HowTo-loT

Installation and Configuration of the IoT Devices Operating the RIOT-OS



**List of Authors:** 

Eero Hakala

# 1. Overview

- 2. Getting started with CoAP
  - 2.1 Development environment for ELL-i leaf nodes
    - 2.1.1 Getting the files
    - 2.1.2 Create the docker images for development and flashing
    - 2.1.3 Compile, flash and test
- 3. Software structure of ELL-i node

# 1. Overview

### ELL-i arm based embedded devices

The application is based on FIWARE framework (https://www.fiware.org) with the following pieces:

CoAP server == iot agent == context broker (orion) == freeboard

# 2. Getting started with CoAP

Experimenting with CoAP using a single (linux) host and libcoap. Description of installing and using libcoap (coap-client and coap-server)

http://wiki.point-h2020.eu/pointwiki/index.php?title=Using\_libCoAP

# 2.1 Development environment for ELL-i leaf nodes

RIOT version is fixed to 2016.10-branch and a new board is added for nucleo-f401 that has A/D defined: adc\_f401

```
/*******
        | ell-i wrk |
        *****
       this is the base working directory
/*****
               /*******
                             /********
 RIOT |
                 | examples |
                                | dockerfiles|
                |2016.04-branch|
*****
                ******
                               ******
- boards
                 - examples
                                 - riotdeve
                 = ell-i_server
                                 = Dockerfile
- core
- cpu
                                 - riotflash
- dist
                                  = Dockerfile
- doc
- drivers
- examples
- pkg
- sys
- tests
```

The idea to arrange the folders like this is to keep the application (in the ell-i\_wrk/examples

directory) separate from operating system (resides in ell-i\_wrk/RIOT)!

The process is quite straightforward:

- create a working directory and get the needed files
- create development environment
- Compile, flash and test

# 2.1.1 Getting the files

Copy files using links from point wiki to a suitable directory (ell-i\_wrk) http://wiki.point-h2020.eu/pointwiki/index.php?title=File:Ell-i\_dockerfiles.tar http://wiki.point-h2020.eu/pointwiki/index.php?title=File:Ell-i\_examples.tar

http://wiki.point-h2020.eu/pointwiki/index.php?title=File:Ell-i\_adc\_f401.tar

### and then create the environment

```
$ git clone https://github.com/RIOT-OS/RIOT
$ cd RIOT/
$ git checkout 2016.04-branch
$ cd ..
$ tar xvf ell-i_adc_f401.tar
$ tar xvf ell-i_dockerfiles.tar
$ tar xvf ell-i examples.tar
```

Connect the embedded device (using both USB and ethernet!), note that you can get power either from USB-connection [U5V] or from ethernet (if the network is POE enabled [E5V]) ==> JP5 (PWR)!

Setup the tty-connection using /dev/ttyACM0 (in ubuntu!!) with e.g. minicom

### 2.1.2 Create the docker images for development and flashing

```
$ docker build --rm -t rdeve dockerfiles/riotdeve
$ docker build --rm -t rflash dockerfiles/riotflash
```

# 2.1.3 Compile, flash and test

### Compile (all in same row!)

```
$ docker run -it --rm --privileged -v $(pwd):/data/riotbuild rdeve make -C
examples/ellin_server BOARD=adc_f401 QUIET=1
```

#### Flash (all in same row!)

```
$ docker run -it --rm --privileged -v $(pwd):/data/riotbuild rflash make -C
examples/ellin server BOARD=adc f401 QUIET=1 flash
```

#### monitor & control with USB-serial:

```
main(): This is RIOT! (Version: 2016.10-devel-1763-geca49b-5f268b48a498-2016)
ELL-i nanocoap example application
Configured network interfaces:
Iface 5    HWaddr: d8:80:39:02:c0:e7

MTU:1500    HL:64    RTR    RTR_ADV
    Source address length: 6
    Link type: wired
    inet6 addr: ff02::1/128    scope: local [multicast]
    inet6 addr: fe80::da80:39ff:fe02:c0e7/64    scope: local
    inet6 addr: ff02::1:ff02:c0e7/128    scope: local [multicast]
    inet6 addr: ff02::2/128    scope: local [multicast]
Waiting for incoming UDP packet...
```

### the test setup

LED (in series with 1k) ON/OFF controlled (digital out, pin PA10) reading status with digital input LOW/HIGH, reading luminosity with LDR (in series with 4.7k) value is read from pin PA0 (analog in), those both can confirm the LED state. Connected pins: PA10, PA0, GND and 3.3V)

test the application with CoAP client (monitor: USB [IPv6 address listed], CoAP: ethernet)

```
echo 01 |coap-client -m put coap://[fe80::da80:39ff:fe02:c0e7%eth0]/output-digital/PA10 -f - coap-client -m get coap://[fe80::da80:39ff:fe02:c0e7%eth0]/input-analog/PA0 coap-client -m get coap://[fe80::da80:39ff:fe02:c0e7%eth0]/input-digital/PA10 echo 1 |coap-client -m put coap://[fe80::da80:39ff:fe02:c0e7%eth0]/output-digital/PA10 -f - coap-client -m get coap://[fe80::da80:39ff:fe02:c0e7%eth0]/input-analog/PA0 coap-client -m get coap://[fe80::da80:39ff:fe02:c0e7%eth0]/input-digital/PA10
```

http://wiki.point-h2020.eu/pointwiki/images/thumb/9/9c/Ell-i\_server\_test-setup\_for-digital\_in-out\_and\_analog-in.png/120px-Ell-i\_server\_test-setup\_for-digital\_in-out\_and\_analog-in.png

http://wiki.point-h2020.eu/pointwiki/images/thumb/1/16/Ell-i\_server\_test-setup\_for-digital\_in-out\_and\_analog-in\_breadboarding.png/90px-Ell-i\_server\_test-setup\_for-digital\_in-out\_and\_analog-in\_breadboarding.png

# 3. Software structure of ELL-i node

ELL-i CoAP server is based on (RIOT-OS) nanocoap and it is implemented using RIOT-OS 2016.10-branch.

### ELL-i leaf node is defined in examples/ellin\_server directory:

```
main.c initiates the application

coap_handler.c all functionalities defined here (the handlers and corresponding path definitions)

Makefile
```

### RIOT-OS modules, best list in Makefile

The structure of a typical (nano)CoAP-server application is straightforward:

```
main.c takes care of initialization
coap handler.c contains the server logic
```

Adding functionalities is easy: you need only change coap\_handler.c

# This database defines supported features

```
/* must be sorted by path (alphabetically) */
const coap_resource_t coap_resources[] = {
    COAP_WELL_KNOWN_CORE_DEFAULT_HANDLER,
    { "/testi2/PA10", COAP_GET, _riot_testi2_PA10_handler },
    { "/testi3/PA10", COAP_GET, _riot_testi3_PA10_handler },
};
```

These again are the corresponding function calls, what should be done is added here!

```
static ssize_t _riot_testi2_PA10_handler(coap_pkt_t *pkt, uint8_t *buf, size_t len)
{
    const char *teksti = "testi2";
```

Supported features are GET, PUT and POST. CoAP observe is an future RIOT feature