

MESH TOPOLOGY

ns3-> src->examples->mesh.cc just run in terminal there is no need of net anim for mesh topology ... only 6 dots will appear .

```
/* -*- Mode:C++; c-file-style:"gnu"; indent-tabs-mode:nil; -*- */
/*
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 *
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 *
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 *
 *
 * By default this script creates m_xSize * m_ySize square grid topology with
 * IEEE802.11s stack installed at each node with peering management
 * and HWMP protocol.
 * The side of the square cell is defined by m_step parameter.
 * When topology is created, UDP ping is installed to opposite corners
 * by diagonals. packet size of the UDP ping and interval between two
 * successive packets is configurable.
 *
 * m_xSize * step
 * |<----->|
 * step
 * |<--->|
 * * --- * --- * <---Ping sink _
 * | \ | / | ^
 * | \ | / | |
 * * --- * --- * m_ySize * step |
 * | / | \ | |
 * | / | \ | |
 * * --- * --- *
 * ^ Ping source
 *
 * See also MeshTest::Configure to read more about configurable
 * parameters.
 */

#include <iostream>
#include <sstream>
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#include <fstream>
#include "ns3/core-module.h"
#include "ns3/internet-module.h"
#include "ns3/network-module.h"
#include "ns3/applications-module.h"
#include "ns3/mesh-module.h"
#include "ns3/mobility-module.h"
#include "ns3/mesh-helper.h"
#include "ns3/yans-wifi-helper.h"

using namespace ns3;

NS_LOG_COMPONENT_DEFINE ("TestMeshScript");

/**
 * \ingroup mesh
 * \brief MeshTest class
 */
class MeshTest
{
public:
    /// Init test
    MeshTest ();
    /**
     * Configure test from command line arguments
     *
     * \param argc command line argument count
     * \param argv command line arguments
     */
    void Configure (int argc, char ** argv);
    /**
     * Run test
     * \returns the test status
     */
    int Run ();
private:
    int    m_xSize; ///< X size
    int    m_ySize; ///< Y size
    double m_step;  ///< step
    double m_randomStart; ///< random start
    double m_totalTime; ///< total time
    double m_packetInterval; ///< packet interval
    uint16_t m_packetSize; ///< packet size
    uint32_t m_nIfaces; ///< number interfaces
    bool    m_chan; ///< channel
    bool    m_pcap; ///< PCAP
    bool    m_ascii; ///< ASCII
    std::string m_stack; ///< stack
    std::string m_root; ///< root
    /// List of network nodes
    NodeContainer nodes;
    /// List of all mesh point devices

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NetDeviceContainer meshDevices;
/// Addresses of interfaces:
Ipv4InterfaceContainer interfaces;
/// MeshHelper. Report is not static methods
MeshHelper mesh;
private:
/// Create nodes and setup their mobility
void CreateNodes ();
/// Install internet m_stack on nodes
void InstallInternetStack ();
/// Install applications
void InstallApplication ();
/// Print mesh devices diagnostics
void Report ();
};
MeshTest::MeshTest () :
    m_xSize (3),
    m_ySize (3),
    m_step (100.0),
    m_randomStart (0.1),
    m_totalTime (100.0),
    m_packetInterval (0.1),
    m_packetSize (1024),
    m_nIfaces (1),
    m_chan (true),
    m_pcap (false),
    m_ascii (false),
    m_stack ("ns3::Dot11sStack"),
    m_root ("ff:ff:ff:ff:ff:ff")
{
}
void
MeshTest::Configure (int argc, char *argv[])
{
    CommandLine cmd (__FILE__);
    cmd.AddValue ("x-size", "Number of nodes in a row grid", m_xSize);
    cmd.AddValue ("y-size", "Number of rows in a grid", m_ySize);
    cmd.AddValue ("step", "Size of edge in our grid (meters)", m_step);
    // Avoid starting all mesh nodes at the same time (beacons may collide)
    cmd.AddValue ("start", "Maximum random start delay for beacon jitter (sec)", m_randomStart);
    cmd.AddValue ("time", "Simulation time (sec)", m_totalTime);
    cmd.AddValue ("packet-interval", "Interval between packets in UDP ping (sec)",
m_packetInterval);
    cmd.AddValue ("packet-size", "Size of packets in UDP ping (bytes)", m_packetSize);
    cmd.AddValue ("interfaces", "Number of radio interfaces used by each mesh point", m_nIfaces);
    cmd.AddValue ("channels", "Use different frequency channels for different interfaces", m_chan);
    cmd.AddValue ("pcap", "Enable PCAP traces on interfaces", m_pcap);
    cmd.AddValue ("ascii", "Enable Ascii traces on interfaces", m_ascii);
    cmd.AddValue ("stack", "Type of protocol stack. ns3::Dot11sStack by default", m_stack);
    cmd.AddValue ("root", "Mac address of root mesh point in HWMP", m_root);

    cmd.Parse (argc, argv);

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NS_LOG_DEBUG ("Grid:" << m_xSize << "*" << m_ySize);
NS_LOG_DEBUG ("Simulation time: " << m_totalTime << " s");
if (m_ascii)
{
    PacketMetadata::Enable ();
}
}
void
MeshTest::CreateNodes ()
{
    /*
    * Create m_ySize*m_xSize stations to form a grid topology
    */
    nodes.Create (m_ySize*m_xSize);
    // Configure YansWifiChannel
    YansWifiPhyHelper wifiPhy;
    YansWifiChannelHelper wifiChannel = YansWifiChannelHelper::Default ();
    wifiPhy.SetChannel (wifiChannel.Create ());
    /*
    * Create mesh helper and set stack installer to it
    * Stack installer creates all needed protocols and install them to
    * mesh point device
    */
    mesh = MeshHelper::Default ();
    if (!Mac48Address (m_root.c_str ()).IsBroadcast ())
    {
        mesh.SetStackInstaller (m_stack, "Root", Mac48AddressValue (Mac48Address (m_root.c_str
    ()))));
    }
    else
    {
        //If root is not set, we do not use "Root" attribute, because it
        //is specified only for 11s
        mesh.SetStackInstaller (m_stack);
    }
    if (m_chan)
    {
        mesh.SetSpreadInterfaceChannels (MeshHelper::SPREAD_CHANNELS);
    }
    else
    {
        mesh.SetSpreadInterfaceChannels (MeshHelper::ZERO_CHANNEL);
    }
    mesh.SetMacType ("RandomStart", TimeValue (Seconds (m_randomStart)));
    // Set number of interfaces - default is single-interface mesh point
    mesh.SetNumberOfInterfaces (m_nIfaces);
    // Install protocols and return container if MeshPointDevices
    meshDevices = mesh.Install (wifiPhy, nodes);
    // Setup mobility - static grid topology
    MobilityHelper mobility;
    mobility.SetPositionAllocator ("ns3::GridPositionAllocator",
        "MinX", DoubleValue (0.0),

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        "MinY", DoubleValue (0.0),
        "DeltaX", DoubleValue (m_step),
        "DeltaY", DoubleValue (m_step),
        "GridWidth", UIntegerValue (m_xSize),
        "LayoutType", StringValue ("RowFirst"));
mobility.SetMobilityModel ("ns3::ConstantPositionMobilityModel");
mobility.Install (nodes);
if (m_pcap)
    wifiPhy.EnablePcapAll (std::string ("mp-"));
if (m_ascii)
{
    AsciiTraceHelper ascii;
    wifiPhy.EnableAsciiAll (ascii.CreateFileStream ("mesh.tr"));
}
}
void
MeshTest::InstallInternetStack ()
{
    InternetStackHelper internetStack;
    internetStack.Install (nodes);
    Ipv4AddressHelper address;
    address.SetBase ("10.1.1.0", "255.255.255.0");
    interfaces = address.Assign (meshDevices);
}
void
MeshTest::InstallApplication ()
{
    UdpEchoServerHelper echoServer (9);
    ApplicationContainer serverApps = echoServer.Install (nodes.Get (0));
    serverApps.Start (Seconds (0.0));
    serverApps.Stop (Seconds (m_totalTime));
    UdpEchoClientHelper echoClient (interfaces.GetAddress (0), 9);
    echoClient.SetAttribute ("MaxPackets", UIntegerValue
((uint32_t)(m_totalTime*(1/m_packetInterval))));
    echoClient.SetAttribute ("Interval", TimeValue (Seconds (m_packetInterval)));
    echoClient.SetAttribute ("PacketSize", UIntegerValue (m_packetSize));
    ApplicationContainer clientApps = echoClient.Install (nodes.Get (m_xSize*m_ySize-1));
    clientApps.Start (Seconds (0.0));
    clientApps.Stop (Seconds (m_totalTime));
}
int
MeshTest::Run ()
{
    CreateNodes ();
    InstallInternetStack ();
    InstallApplication ();
    Simulator::Schedule (Seconds (m_totalTime), &MeshTest::Report, this);
    Simulator::Stop (Seconds (m_totalTime));
    Simulator::Run ();
    Simulator::Destroy ();
    return 0;
}

```

```

void
MeshTest::Report ()
{
    unsigned n (0);
    for (NetDeviceContainer::Iterator i = meshDevices.Begin (); i != meshDevices.End (); ++i, ++n)
    {
        std::ostringstream os;
        os << "mp-report-" << n << ".xml";
        std::cerr << "Printing mesh point device #" << n << " diagnostics to " << os.str () << "\n";
        std::ofstream of;
        of.open (os.str ().c_str ());
        if (!of.is_open ())
        {
            std::cerr << "Error: Can't open file " << os.str () << "\n";
            return;
        }
        mesh.Report (*i, of);
        of.close ();
    }
}

int
main (int argc, char *argv[])
{
    MeshTest t;
    t.Configure (argc, argv);
    return t.Run ();
}

```