

## Spagetti data model

- Polygon with  $n$  vertices has  $2n$  possible representations
- Polygon and polyline structure is identical
- No guarantee that a polygon/polyline is simple/convex
- Regions may have overlapping/containment relations

## Topological invariants

- Homeomorphism = topological isomorphism = continuous mapping preserving topological properties
- Topologically invariant properties: properties preserved by continuous (topological) transformations



## Topology: qualitative properties

- Study of properties of form invariant under continuous deformation

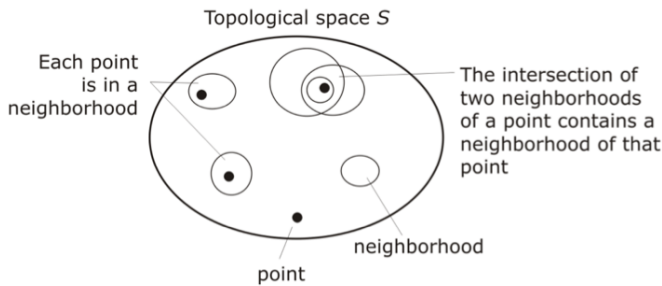


Open set

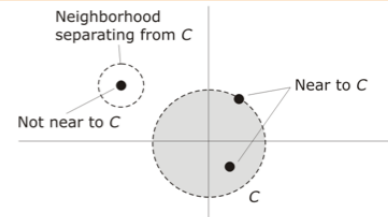


Closed set

## Point-set topology



## Open and Closed Sets



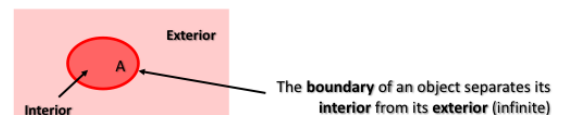
- Let  $S$  be a topological space and  $X$  be a subset of points of  $S$ . An individual point  $x$  is near to  $X$  if every neighborhood of  $x$  contains some point of  $X$ .
- $X$  is *open* if every point of  $X$  can be surrounded by a neighborhood that is entirely within  $X$ .
- $X$  is *closed* if it contains all its near points.

## Formalisation of topological relationships

- To query topological spatial relationships efficiently, a formalism has to be found;
- Such a formalism should:
  - ▣ Be efficiently computable and enable reasoning
  - ▣ Succinct and expressive
  - ▣ Result in equivalent relationships for topologically isomorphic geometries

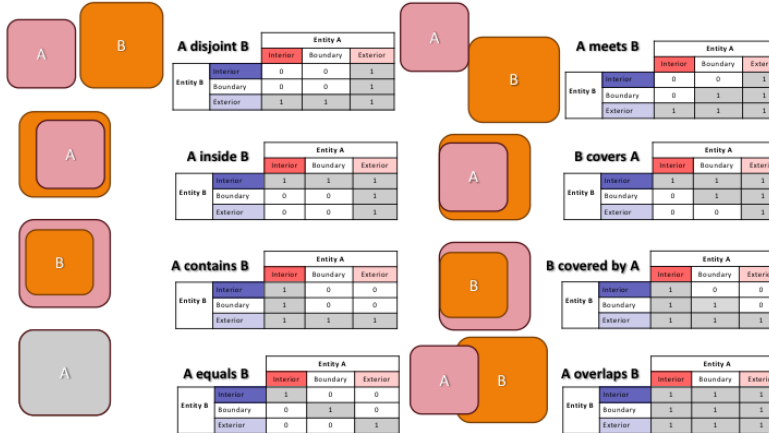
## 9IM

- Egenhofer et al. worked on a formal model of topological spatial relations in the late 1980s and early 1990s
- The 9-intersection model describes binary topological relationships between in terms of *interiors*, *boundaries* and *exteriors* for two spatial entities in two dimensions



## Named spatial predicates in 9IM

0 = FALSE, 1 = TRUE (not dimensionality, here)



## Masks for 9-IM

$$\text{bin}(\text{DE9IM}(a, b)) = 9\text{IM}(a, b) = \begin{bmatrix} a^\circ \cap b^\circ \neq \emptyset & a^\circ \cap \partial b \neq \emptyset & a^\circ \cap b^\circ \neq \emptyset \\ \partial a \cap b^\circ \neq \emptyset & \partial a \cap \partial b \neq \emptyset & \partial a \cap b^\circ \neq \emptyset \\ a^\circ \cap b^\circ \neq \emptyset & a^\circ \cap \partial b \neq \emptyset & a^\circ \cap b^\circ \neq \emptyset \end{bmatrix}$$

Alternative notation:



Equals	$\begin{bmatrix} T & F & F \\ F & T & F \\ F & F & T \end{bmatrix}$
Disjoint	$\begin{bmatrix} F & F & F \\ F & F & F \\ F & F & F \end{bmatrix}$
Touches (meets)	$\begin{bmatrix} F & T & F \\ T & T & F \\ F & T & F \end{bmatrix}$
Contains	$\begin{bmatrix} T & F & F \\ F & T & F \\ F & F & T \end{bmatrix}$
Covers	$\begin{bmatrix} T & T & F \\ F & T & F \\ F & F & T \end{bmatrix}$

<< Mask string code:

T – TRUE,

F – FALSE,

\* – don't care

Or dimensions:

0 – point

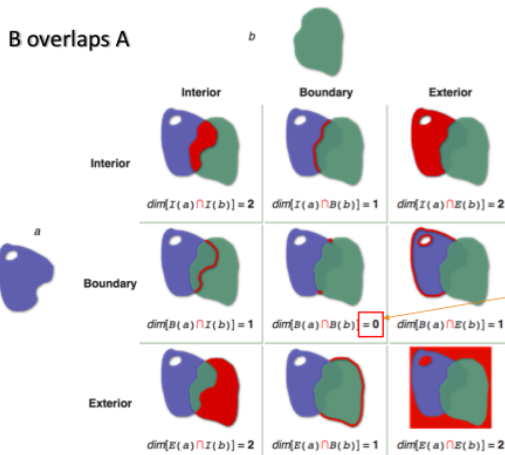
1 – line

2 – polygon

\* – don't care

`ST_Relate(geomA, geomB, intersectionMatrixPattern);`

## Dimensionally extended 9-IM



**Note: 9IM (and DE9IM) can be applied to geometries of different dimensionalities (e.g., 1D with 2D: line crosses polygon)**

Clementini, Di Felice, van Oosterom, (1993). "A small set of formal topological relationships suitable for end-user interaction". In Abel, Ooi. *Advances in Spatial Databases: Third International Symposium, SSD '93 Singapore. Lecture Notes in Computer Science*. 692/1993. Springer. pp. 277–295

## Topological queries

### Spatial join – two ways to write:

- SELECT s.state, r.name FROM SPATIAL.US\_STATES AS s, SPATIAL.US\_RIVERS AS r WHERE ST\_WITHIN(r.geom,s.geom)
- SELECT \* FROM SPATIAL.US\_STATES AS s JOIN SPATIAL.US\_RIVERS AS r ON ST\_WITHIN(r.geom,s.geom)

### Return intersection geometry:

- SELECT ST\_AsText(ST\_Intersection('POINT(0 0)::geometry', 'LINESTRING (0 0, 0 2)::geometry));

### Using Masks

- Find mask:** SELECT ST\_Relate(ST\_GeometryFromText('POINT(1 2)'), ST\_Buffer(ST\_GeometryFromText('POINT(1 2)'),2));
- Or test:** SELECT ST\_Relate(ST\_GeometryFromText('POINT(1 2)'), ST\_Buffer(ST\_GeometryFromText('POINT(1 2)'),2), '\*FF\*FF2I2');
- Using binary predicates (based on envelopes only)
- <http://postgis.net/docs/manual-2.2/reference.html#Operators>
- Faster evaluation, approximate results! (see Lecture on indexes)

## Maintaining Topological Relationships

- Certain entity types may have to comply to specified spatial relationships:
  - Ship cannot float on land;
  - Tree has to stand in a parcel (not in a lake)
  - Car has to be on the road...
- We can maintain such relationships using spatial triggers (a trigger is an automatically executed piece of code within a database):
  - On insert, update;
  - On delete,...

## Spatial trigger

- Make sure a point is within a polygon

## Persistent topology

- We may want to persist a certain topological relationship between geometries in a database:
  - ▣ For (topo)logical integrity assurance (parcels not overlapping, streets connected at junctions...)
  - ▣ To increase speed and efficiency of processing (many comparisons need not be re-computed)
  - ▣ To reduce storage load (no duplicate storage of shared edges,...)

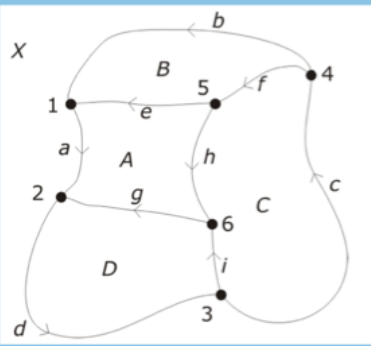


## Planar partitions of space

- Polygons completely covering space;
- No overlaps, no gaps;
- Some mathematical properties of *finite, connected, planar* graphs of *f* faces (*n*-nodes, *e*-edges, *f*-faces):
  - ▣ Euler's characteristic:
 
$$n - e + f = 2$$
  - ▣ Average node *degree* (number of edges incident with a node) < 6
  - ▣ Note: we will revisit graphs in the lecture on networks

## NAA Planar decomposition

### □ Node-Arc-Area Topology



Arcs (Edges)

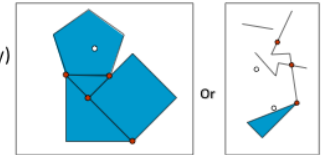
Arc	S_node	E_node	L_Face	R_Face
a	1	2	A	X
b	4	1	B	X
c	3	4	C	X
d	2	3	D	X
e	5	1	A	B
f	4	5	C	B
g	6	2	D	A
h	5	6	C	A
i	3	6	D	C

Nodes: 6  
Arcs: 9  
Faces: 5

$$N - A + F = 6 - 9 + 5 = 2$$

## Topological data model

- Explicitly stores topological relationships of 0-nD geometries
- Topological elements:
  - ▣ Nodes [point, edge]
  - ▣ Arcs (edge, if orientation is not important) [node-start, node-end, right-face, left-face]
  - ▣ Faces (= polygon) [{arcs}]
- Distinguishes:
  - ▣ Start and End nodes (for connectivity)
  - ▣ Left and Right faces (for adjacency)



## Node – Arc – Area Topology

- Each directed arc has exactly one start and one end node.
- Each node must be the start node or end node (maybe both) of at least one directed arc.
- Each area is bounded by one or more directed arcs.
- Directed arcs may intersect only at their end nodes.
- Each directed arc has exactly one area on its right and one area on its left.
- Each area must be the left area or right area (maybe both) of at least one directed arc.

## NAA Conceptual model



ARC(ARC\_ID,  
BEGIN\_NODE, END\_NODE,  
LEFT\_AREA, RIGHT\_AREA)  
POLYGON(AREA\_ID,  
ARC\_ID, SEQUENCE.NO)  
POLYLINE(ARC\_ID,  
POINT\_ID, SEQUENCE.NO)  
POINT(POINT\_ID,  
X.COORD, Y.COORD)  
NODE(NODE\_ID,  
POINT\_ID)

ArcGIS: AAT(FNODE,  
TNODE, LPOLY, RPOLY,  
LENGTH, Adm-ID)

## What to do with topology

- Create topology for cleaning data;
- Create topology before simplification of boundaries of planar decompositions;
- Create topology if neighbourhoods matter (e.g., cadaster)