

Vector Subspaces of \mathbb{R}^n , Linear dependence

Linear Span

Column vectors ($n \times 1$) matrices.

Vectors in \mathbb{R}^n are always

Column vectors

A subset V of \mathbb{R}^n is called a Vector Subspace

if (i) V is non empty.

(ii) $x \in V$ and $a \in \mathbb{R} \Rightarrow ax \in V$

(iii) $x, y \in V \Rightarrow x+y \in V$

Example: Let $V = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 \mid x+y-3z=0 \right\}$.

Then V is a vector subspace.

Evidently zero vector $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \in V$ and so $V \neq \emptyset$.
It is readily checked that if $\begin{bmatrix} x \\ y \\ z \end{bmatrix} \in V$ then $\begin{bmatrix} ax \\ ay \\ az \end{bmatrix} \in V$ for $a \in \mathbb{R}$.

Check: if $\begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}, \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} \in V$

$$\begin{aligned} x_1 + y_1 - 3z_1 &= 0 \\ x_2 + y_2 - 3z_2 &= 0 \end{aligned} \quad \Rightarrow (x_1 + x_2) + (y_1 + y_2) - 3(z_1 + z_2) = 0$$
$$\Rightarrow \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} \in V$$

Exercise: Explain why $V = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 \mid x+y-3z=1 \right\}$
is NOT a vector Subsp. of \mathbb{R}^3

Suppose V is a vect. Subsp. of \mathbb{R}^n

Since $V \neq \emptyset$ select $\mathbf{x} \in V$ and select $a = 0 \in \mathbb{R}$
Then $a\mathbf{x} \in V$ i.e. $0 \in V$

Ex: Show that (i) a line passing through origin in \mathbb{R}^3
is a vector subspace ~~in \mathbb{R}^3~~ ^{of \mathbb{R}^3}

(ii) A plane passing through ~~origin~~ ^{in \mathbb{R}^3} is a vect. Subsp.

(iii) \mathbb{R}^3 itself is a vect. Subsp. of \mathbb{R}^3

(iv) The Singleton $\left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$ is a vector Subsp. of \mathbb{R}^3 .

Ques: Are there any others? Justification ??

Linear Combinations: Suppose $v_1, v_2, \dots, v_k \in \mathbb{R}^n$

and $a_1, \dots, a_k \in \mathbb{R}$ then $a_1 v_1 + a_2 v_2 + \dots + a_k v_k$

is called ~~the~~ a lin. Comb. of v_1, \dots, v_k with
Coeff. a_1, \dots, a_k

Let us now consider the set of all possible
Linear Combinations of v_1, \dots, v_k with arb. real
coeff.

$$V = \{a_1 v_1 + \dots + a_k v_k \mid a_1, \dots, a_k \in \mathbb{R}\} \quad (*)$$

Check: V is a vector subspace of \mathbb{R}^n .
This is called the linear Span of $\{v_1, \dots, v_k\}$.

Ques:

Suppose V is a vector subsp. of \mathbb{R}^n
Can you find a finite subset S of V such that—
 V is exactly the linear span of S . We shall
answer this question soon.

Going back to $(*)$ we say V is generated by
 $\{v_1, \dots, v_k\}$

Example: $x + y - 3z = 0$ or

$$V = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 \mid x + y - 3z = 0 \right\}.$$

Certainly $v_1 = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}$ lie in V .

Prove that Linear Aspan of $\begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}$ is
Exactly ✓

Since we are in \mathbb{R}^3 you could begin with a
geometrical reasoning (parallelogram law of vect. add.
with a, v_1 and $a_2 v_2$).

Can you back it up with algebraic justification?

So $V = \text{lin. Span } \{v_1, v_2\}$.

Is it possible to find a single vector w_0 s.t.
 $V = \text{lin. Span } \{w_0\}$? Why??

What about finding a set S with 3 vectors.

s.t $\text{Lin. Span } S = V$? If you were
asked to select a spanning set which one would you choose?
Optimality?

You may now begin to suspect - that
for this Example a Spanning Set

- (i) Cannot be a Singleton.
- (ii) Can have more than 2 elts but that would cause redundancy (more than what you need)

So the Optimal two element Spanning Set
must have to do with the fact that a plane is two Dimensional.

Dimension is the most fundamental idea in Mathematics and we are converging towards a rigorous and precise notion of dimension.

Before defining dimension we need one more basic notion:

Linear dependence / lin. indep. of vectors $v_1, \dots, v_k \in \mathbb{R}^n$

Recall the notion of Collinearity in \mathbb{R}^3 .

Vectors $v_1, v_2 \in \mathbb{R}^3$ are Collinear iff one of them is a multiple of the other say $v_2 = \lambda v_1$

$$\text{i.e. } \lambda v_1 + (-1)v_2 = 0.$$

Ex: Show that vectors $v_1, v_2 \in \mathbb{R}^3$ are collinear iff \exists scalars a_1, a_2 $\begin{cases} \text{not both zero} \\ \text{Symm} \end{cases}$ Formulation.

$$\text{s.t. } a_1 v_1 + a_2 v_2 = 0$$

Vectors $v_1, v_2, v_3 \in \mathbb{R}^3$ are said to be Coplanar if one of them lies in the plane of the other two

$$\text{say } v_3 = \lambda v_1 + \mu v_2.$$

Ex: Prove: v_1, v_2, v_3 coplanar iff \exists scalars a_1, a_2, a_3 $\begin{cases} \text{not all zero} \\ \text{such that } a_1 v_1 + a_2 v_2 + a_3 v_3 = 0. \end{cases}$

Def: Vectors $v_1, \dots, v_k \in \mathbb{R}^n$ are said to be
— linearly dependent if \exists scalars a_1, \dots, a_k
[not all zero] s.t. $a_1 v_1 + \dots + a_k v_k = 0$.

If v_1, \dots, v_k are not linearly dependent
we say they are linearly independent
That is v_1, \dots, v_k linearly independent

if for scalars a_1, \dots, a_k
 $a_1 v_1 + \dots + a_k v_k = 0 \Rightarrow a_1 = a_2 = \dots = a_k = 0$.

Convention: Empty set is linearly independent
If a set $\{v_1, \dots, v_k\}$ contains zero vector it is linearly dependent
Ex: Subset of a Lin Indep. Set is again lin. indep.

First Fundamental Lemma in Linear Algebra.

Suppose V is a vector Subsp. of \mathbb{R}^n

and V is generated by k -vectors - Then
any set of $(k+1)$ or more vectors in V are
linearly dependent

Proof: By induction on k . Case $k=1$:

Let $V = \text{Span } \{v_0\}$.

Let $v_1, v_2 \in V$ So $v_1 = av_0$
 $v_2 = bv_0$.

If $a=0$ or $b=0$ Then $\{v_1, v_2\}$ is linearly dep.

If $a \neq 0, b \neq 0$ Then

$bv_1 - av_2 = 0$; Coeff. $b, -a$ not both zero.

$\therefore \{v_1, v_2\}$ lin. dep.

Assume the result for k . This is strong.
we prove it for $k+1$

Well, let $\text{Span}\{v_1, \dots, v_{k+1}\} = V$

Take $(k+2)$ vectors $w_1, w_2, \dots, w_{k+1}, w_{k+2} \in V$

$$\therefore w_1 = a_{1,1} v_1 + \dots + a_{1,k} v_k + a_{1,k+1} v_{k+1}$$

$$w_2 = a_{2,1} v_1 + \dots + a_{2,k} v_k + a_{2,k+1} v_{k+1}$$

...

$$w_{k+1} = a_{k+1,1} v_1 + \dots + a_{k+1,k} v_k + a_{k+1,k+1} v_{k+1}$$

$$w_{k+2} = a_{k+2,1} v_1 + \dots + a_{k+2,k} v_k + \{a_{k+2,k+1} v_{k+1}\}$$

Now if $a_{1,k+1} = \dots = a_{k+2,k+1} = 0$

then $w_1, w_2, \dots, w_{k+1}, w_{k+2}$ all lie in the linear

$\text{Span}\{v_1, \dots, v_k\}$ = Vect. Sp. gen. by k -vectors

linearly dep.

By induction hypo. $w_1, \dots, w_{k+1}, w_{k+2}$ linearly dep.

Next assume $a_{1,k+1}, \dots, a_{k+2,k+1}$ is $\neq 0$.
(One of) By renaming $a_{k+2,k+1} \neq 0$.

Look at the $(k+1)$ vectors

$$w_1 = \frac{a_{1, k+1}}{a_{k+2, k+1}} w_{k+2}, \dots, w_{k+1} = \frac{a_{k+1, k+1}}{a_{k+2, k+1}} w_{k+2}$$

These lie in $\text{Span}\{v_1, \dots, v_k\}$ (how?)

So by induction hypo. They are Lin. Dep.

$$\therefore c_1 \left(w_1 - \frac{a_{1, k+1}}{a_{k+2, k+1}} w_{k+2} \right) + \dots + c_{k+1} \left(w_{k+1} - \frac{a_{k+1, k+1}}{a_{k+2, k+1}} w_{k+2} \right) = 0$$

at least one of $c_1, \dots, c_{k+1} \neq 0$.

$$\therefore c_1 w_1 + \dots + c_{k+1} w_{k+1} + \gamma w_{k+2} = 0$$

at least one of $c_1, \dots, c_{k+1}, \gamma \neq 0$

$\therefore w_1, \dots, w_{k+2}$ Lin Dep.

proof is complete.

Basis and Dimension

Two Conventions: Empty set \emptyset is linearly independent —
Lin-Span of \emptyset is $\{0\}$.

Def.: Suppose V is a vector Subspace of \mathbb{R}^n — then a
Subset S of V is called a Basis of V

if (i) S is linearly indep.

(ii) Linear Span of $S = V$

Ex: If $V = \{0\}$ set consisting of only the zero vector
then \emptyset is (the) basis of V

Ex: Let $V = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 \mid x+y-3z=0 \right\}$.

Cheek that $S = \left\{ \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$ is a basis

We shall see that Every Vector Subsp of \mathbb{R}^n has a
basis.

Thm: If V is a vector subspace of \mathbb{R}^n then

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(i) V has a basis

(ii) Any two bases have the same # of elements.

Proof: Clear if V is the zero vector space.

So assume V contains non zero vectors. Pick $v_1 \in V$.
 $v_1 \neq 0$.

$V_1 = \{av_1 / a \in \mathbb{R}\} = \text{Linear Span of } \{v_1\}$

If $V_1 = V$ we are through since $\{v_1\}$ spans V and
is lin. indep. set.

Suppose $V_1 \subsetneq V$. Pick $v_2 \in V - V_1$

Claim: $\{v_1, v_2\}$ is linearly indep.

Well, $av_1 + bv_2 = 0 \Rightarrow v_2 = -\frac{a}{b}v_1 \in V_1$ (Contradiction)
in case $b \neq 0$.

If $b=0$ then we get $av_1 = 0 \Rightarrow a=0$ (since $v_1 \neq 0$)

$\therefore av_1 + bv_2 = 0 \Rightarrow a=b=0$

If $V_2 = \text{Lin. Span} \{v_1, v_2\} = V$ we are through
Since $\{v_1, v_2\}$ serves as a basis for V

Else, $V_2 \subsetneq V$ so select $v_3 \in V - V_2$

Claim: $\{v_1, v_2, v_3\}$ lin. indep.

Well, Suppose $av_1 + bv_2 + cv_3 = 0$
Then $c=0 \Rightarrow av_1 + bv_2 = 0 \Rightarrow a=b=0$ ($\because \{v_1, v_2\}$ lin
indep)

If $c \neq 0$ then $v_3 = -\frac{a}{c}v_1 - \frac{b}{c}v_2 \in V_2$ (Contradiction)

Proceeding thus we keep constructing vectors v_1, v_2, \dots, v_k
s.t. $\{v_1, \dots, v_k\}$ linearly indep.

$V_k = \text{lin. Span} \{v_1, \dots, v_k\} = V$ in which case
 $\{v_1, \dots, v_k\}$ is a basis. Process stops.

Or else the process goes to the next stage.
with $v_{k+1} \in V - V_k$ etc.,

Claim: The process must stop in at most n -steps!

Suppose not then we can construct linearly indep vectors v_1, \dots, v_{n+1} in \mathbb{R}^n which contradicts the Fundamental Lemma (\mathbb{R}^n is generated by n -vectors $\hat{e}_1, \dots, \hat{e}_n$ so any set of $(n+1)$ vectors is linearly dependent). Claim is proved.

Thereby (i) is established.
To prove (ii) let S_1, S_2 be two bases

$$|S_1| = k \\ |S_2| = l.$$

Linear Span $S_1 = V$ and $S_2 \subset V$

So V is generated by k vectors ; S_2 is lin. indep set of l vectors $\Rightarrow l \leq k$. Similarly $k \leq l$
 $\therefore k = l$.

Definition: Let V be a vector subsp of \mathbb{R}^n

* then $\text{Dim } V$ is -the Cardinality of any basis of V . (The concept is well-defined)

Exercise: (i) Show that vectors $v_1, v_2, v_3 \in \mathbb{R}^3$ are linearly indep iff $\det(v_1, v_2, v_3) \neq 0$.

(ii) Show that vectors $v_1, v_2 \in \mathbb{R}^3$ are linearly indep. iff $\det \begin{pmatrix} v_1 \cdot v_1 & v_1 \cdot v_2 \\ v_2 \cdot v_1 & v_2 \cdot v_2 \end{pmatrix} > 0$.

Fact: Vectors $v_1, \dots, v_k \in \mathbb{R}^n$ are linearly indep iff $\det(v_i \cdot v_j)_{1 \leq i, j \leq k} \neq 0$. } Proof: Needs More Theory

(This det is called -the Gram-det.

④ Interpretation: Vol of -the k -parallelpiped in \mathbb{R}^n Spanned by v_1, \dots, v_k).

Rank of a Matrix:

Let A be an $m \times n$ matrix.

Columns of A can be regarded as elements of \mathbb{R}^m
 and their linear Span is called the Column Space of A

Rows of A can be regarded as elements of \mathbb{R}^n
 and their linear Span is called the Row Space of A

Def: Row Rank $A = \text{Dim. (Row Sp. of } A\text{)}$

Column Rank $A = \text{Dim (Col. Space of } A\text{)}$

Exercise: Suppose S is a set of vectors and
 $\text{Linear Span } S = V$

Show that (by deleting elements of S if necessary)
 S Contains a subset S_0 which is a basis of V

In particular, we can select a subset of Rows of A
 to obtain a basis for Row Space of A . Ily for Columns.

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Lemma: Let A be a $m \times n$ matrix
 performing an elementary row operation does not
 alter the Column Rank of A .

Specifically if E is an elementary matrix
 or more generally any non sing matrix
 and $c_{i_1}, c_{i_2}, \dots, c_{i_l}$ are linearly indep cols of A
 Then $E c_{i_1}, E c_{i_2}, \dots, E c_{i_l}$ ~~are~~ (the $i_1, i_2, i_2 + h, \dots, i_l + h$)
 Columns of EA are again linearly indep.

Proof: i_1 th col. of EA

$$= (EA) \hat{e}_{i_1} = E(A \hat{e}_{i_1}) = E c_{i_1}$$

Now Suppose $a_{i_1} (E c_{i_1}) + \dots + a_{i_l} (E c_{i_l}) = 0$.
 $\Rightarrow E (a_{i_1} c_{i_1} + \dots + a_{i_l} c_{i_l}) = 0$.

$$\Rightarrow a_{i_1} c_{i_1} + \dots + a_{i_l} c_{i_l} = 0 \quad (\because E \text{ is invertible})$$

$$\Rightarrow a_{i_1} = \dots = a_{i_l} = 0 \quad (\because c_{i_1}, \dots, c_{i_l} \text{ lin. Indep.})$$

Thus the columns of EA marked i_1, \dots, i_l
are linearly independent.

Ex: Suppose $\{v_1, v_2, \dots, v_k\}$ lin. indep vectors in \mathbb{R}^n

Show that $\{v_1, \dots, \hat{v_j}, \lambda v_j, v_{j+1}, \dots, v_k\}$ ($\lambda \neq 0$)
is also lin. indep.

Show that $\{v_1, \dots, \hat{v_{j-1}}, v_j + cv_i, v_{j+1}, \dots, v_k\}$
($j \neq i$)
is also lin. indep.

Show that ~~the~~ ⁸ Rows - the Row Rank of A is not
altered by performing Row Op. on A.

So, neither row rank nor Column Rank
is affected by performing Row Operations on A.

Thm: Row Rank A = Column Rank A.

Proof: Let $k = \text{Row Rank } A$; $l = \text{Column Rank } A$.

By Row exchanges we may assume first k rows of A
are linearly indep and last $m-k$ rows are
linear combinations of first k -rows R_1, \dots, R_k .

Say $R_{k+1} = a_1 R_1 + \dots + a_k R_k$.

$$R'_k = R_k - a_1 R_1$$

Perform the row operations:
in Succession.

$$R'_k = R_k - a_2 R_2, \dots$$

This causes $(k+1)$ st row to be zero.

By we can make $(k+2)$ nd, ..., m th row of A
as zero.

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Resulting Matrix \tilde{A} looks like

$$\tilde{A} = \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \cdots & \cdots & \ddots & \cdots \\ b_{k1} & b_{k2} & \cdots & b_{kn} \\ 0 & 0 & \cdots & 0 \end{bmatrix}$$

last $(m-k)$ rows are zero.

$$\text{Row Rank } \tilde{A} = \text{Row Rank } A = k.$$

Col. Rank \tilde{A} = Col. Rank $A = l$.
Now look at the columns of \tilde{A} they may be regarded as columns in \mathbb{R}^k (gen. by k -vectors)

So $(k+1)$ or more columns of \tilde{A} are lin Dep.

$$\therefore \text{Column Rank } \tilde{A} \leq k$$

$$\therefore l \leq k.$$

Repeat the same with A^T and we get $k \leq l$
 $\therefore k = l$. Proof is complete.

Exercise: Let \tilde{A} be obtained from A via an Elementary row op. (Tutorial)
(both Square Matrices)

$\det A = \lambda \cdot (\det \tilde{A})$; $\lambda \neq 0$.
Next, if \tilde{A} is obtained from A through a sequence of Elem. Row. Op.

$\det A = \lambda (\det \tilde{A})$; $\lambda \neq 0$.

Deduce that if A can be reduced to In
through a seq of Elem. Row Op. - then

$\det A \neq 0$.

(Tutorial)

So if Columns of A linearly Indep - then
 $\det A \neq 0$ (A is a Sq. Matrix).

Ques

Hint: If cols of A lin. Indep $REF = In$.

Exercises: Suppose $\text{Dim } V = k$ (Tutorial problem)

(i) S is a linearly indep subset of V containing k vectors \rightarrow Then S is a basis $\quad (*)$

(ii) S is a set of k vectors such that-
Linear Span $S = V$

Then S is a basis.

In particular if c_1, \dots, c_n are lin indep columns
of a $n \times n$ matrix A

Lin. Span $\{c_1, \dots, c_n\} = \mathbb{R}^n$
 $\therefore \hat{e}_1 = b_{11} c_1 + b_{21} c_2 + \dots + b_{n1} c_n$

$\hat{e}_2 = b_{12} c_1 + b_{22} c_2 + \dots + b_{n2} c_n$

$\hat{e}_n = b_{1n} c_1 + b_{2n} c_2 + \dots + b_{nn} c_n$

Deduce that $\text{Rank } A = n \Rightarrow A$ invertible
($n \times n$ matrix)

Prove the converse using $(*)$ and $(**)$ or

Tutorial.

Thm: Let A be a Square Matrix

The Following Are Equivalent-

(i) Rows of A lin. Indep.

(ii) Cols of A lin. Indep.

(iii) A is invertible

(iv) $\det A \neq 0$.

Pf: (i) and (ii) are equivalent since
Row Rank = Col. Rank ($= n$ in
this case).

(ii) \Leftrightarrow (iii) Exercise above

(ii) \Rightarrow (iv) Exercise above

cols of A lin. dep.

\therefore Rows of A lin. dep.

$\therefore A \rightarrow \begin{bmatrix} B \\ 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}$ through a seq. of Row op.
 B is $(n-1) \times n$

$$\det A = \lambda \det \begin{bmatrix} B \\ 0 \end{bmatrix} = 0 \quad (\lambda \neq 0).$$

\therefore (ii) \Rightarrow (iv) Proof is Complete

To Prove:

Kronecker - Capelli Thm:

A system of lin. equations $Ax = b$

has a solution iff $\text{Rank } A = \text{Rank } [A : b]$.

Proof: Assume \exists a sol. $\begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = c_1 \hat{e}_1 + \dots + c_n \hat{e}_n$

$\therefore A(c_1 \hat{e}_1 + \dots + c_n \hat{e}_n) = b$

$\therefore c_1 (\text{col } 1) + c_2 (\text{col } 2) + \dots + c_n (\text{col } n) = b$

$\therefore b \in \text{Linear Span } \text{cols}$.

$\therefore b \in \text{Column. Sp. of } A$ or $\left. \begin{array}{l} \text{Col. Space } A = \\ \text{Col. Space } [A : b] \end{array} \right\} \text{Recall } A \hat{e}_j = j^{\text{th}} \text{ col } A$

$\therefore \text{Rank } A = \text{Rank } [A : b]$

Conversely if $\text{Rank } A = \text{Rank } [A : b]$

$\Rightarrow b \in \text{Col. Space of } A$

$\Rightarrow b = c_1 (\text{col } 1) + \dots + c_n (\text{col } n)$ for some scalars c_1, \dots, c_n

$\Rightarrow b = c_1 A \hat{e}_1 + \dots + c_n A \hat{e}_n$

$\Rightarrow b = A(c_1 \hat{e}_1 + \dots + c_n \hat{e}_n) \Rightarrow b = A \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$

and $\begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$ is a sol. of the system.