

19기 정규세션

ToBig's 18기 강의를 이다인

# Neural Network Basic

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# 01 | Perceptron

## Unit 01 | Perceptron

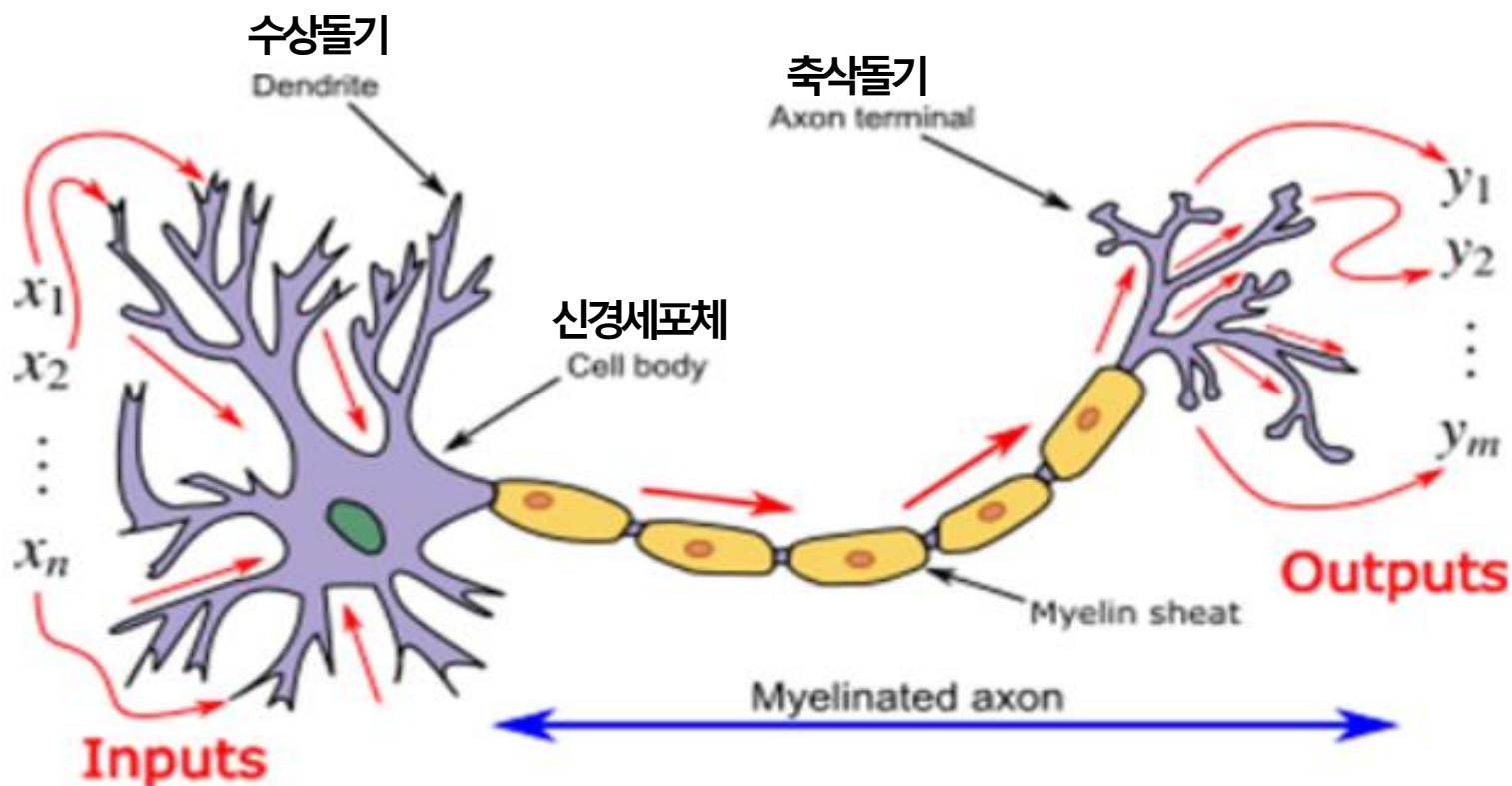
### 인공신경망이란?

What is Artificial neural network(ANN)?

“ 수학적 논리학이 아닌 **인간의 두뇌를 모방하여**  
수많은 뉴런이 연결되어 있는 네트워크를 통해  
문제를 해결하는 기계학습 모델 ”

## Unit 01 | Perceptron

### Neuron (신경세포)



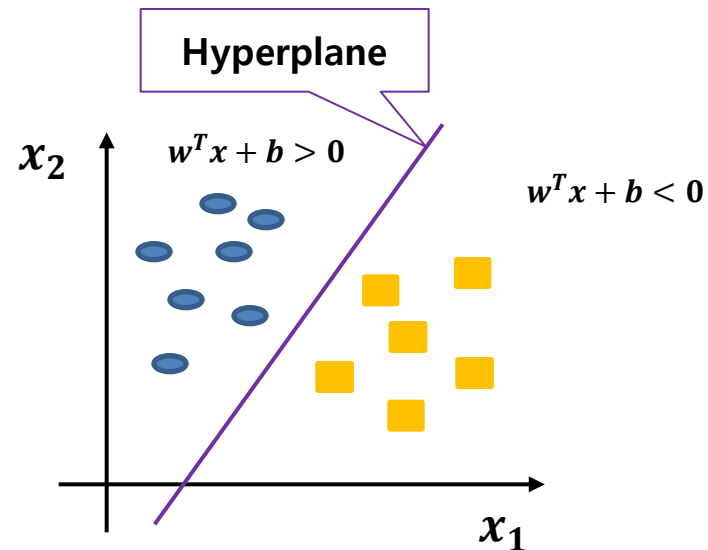
### 시냅스 (Synaptic terminals)



## Unit 01 | Perceptron

# Perceptron

- Binary Classification (i.e.,  $y = \{-1, +1\}$ )
- There exists a linear hyperplane that separates (i.e., data is linearly separable)
- 데이터가 linearly separable 하다는 것은 모든 데이터가 하나의 linear model을 통해서 완벽하게 분류될 수 있어야 한다는 것(error가 0이 되어야 함).



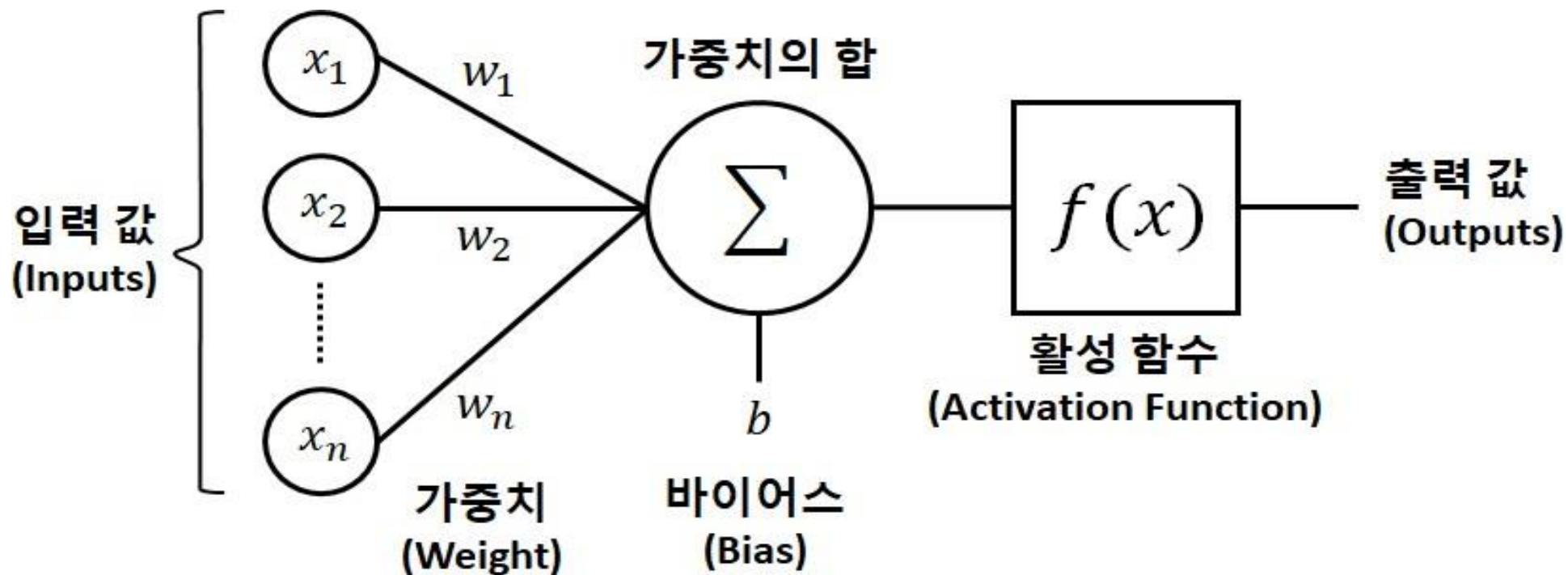
$$\text{hypothesis class } H = \{x: w^T x + b = 0\}$$

$$\text{classifier } h(x) = \text{sign}(w^T x + b)$$

\*  $x$  : 입력값  
   $b$  : bias (편향)  
   $w$  : weight (가중치)

## Unit 01 | Perceptron

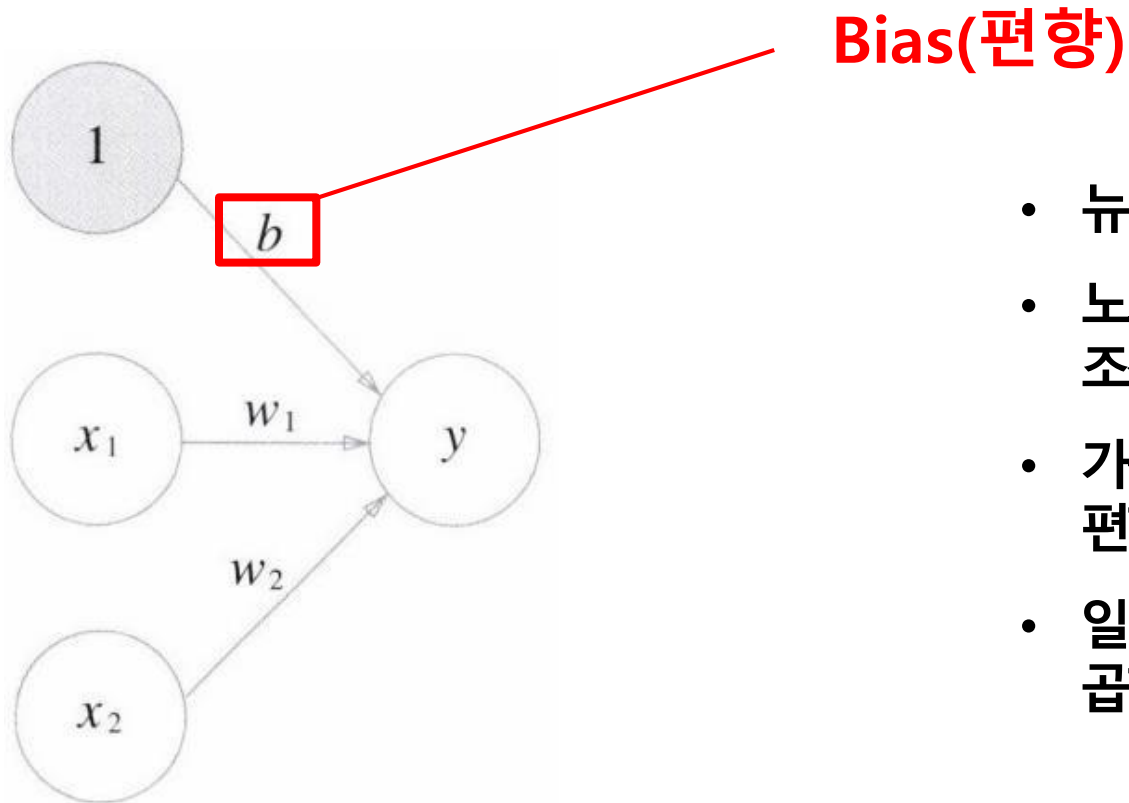
### Perceptron



- 가중치(weight) : 각각의 입력에 대해 중요도를 부여 하는 수치

## Unit 01 | Perceptron

# Perceptron

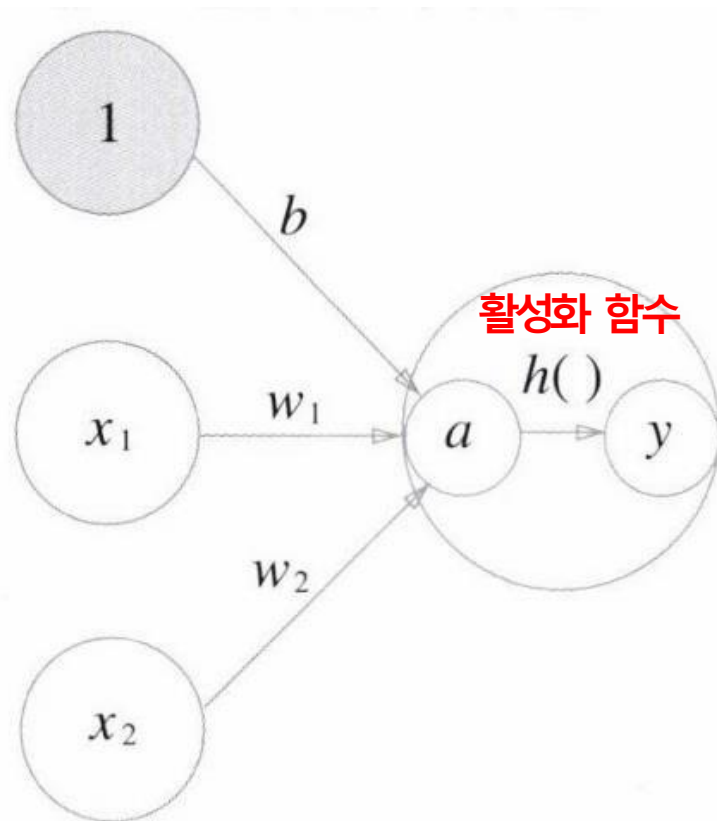


- 뉴런이 얼마나 쉽게 활성화 되느냐를 제어
- 노드의 민감도를 조정하거나 활성화를 조정하는 역할
- 가중치 만으로 세밀한 조정이 되지 않을 시 편향을 주어 조정이 가능하다.
- 일반적으로 입력값을 1로 고정하고 편향  $b$ 를 곱한 변수로 표현한다.



## Unit 01 | Perceptron

### 활성화 함수

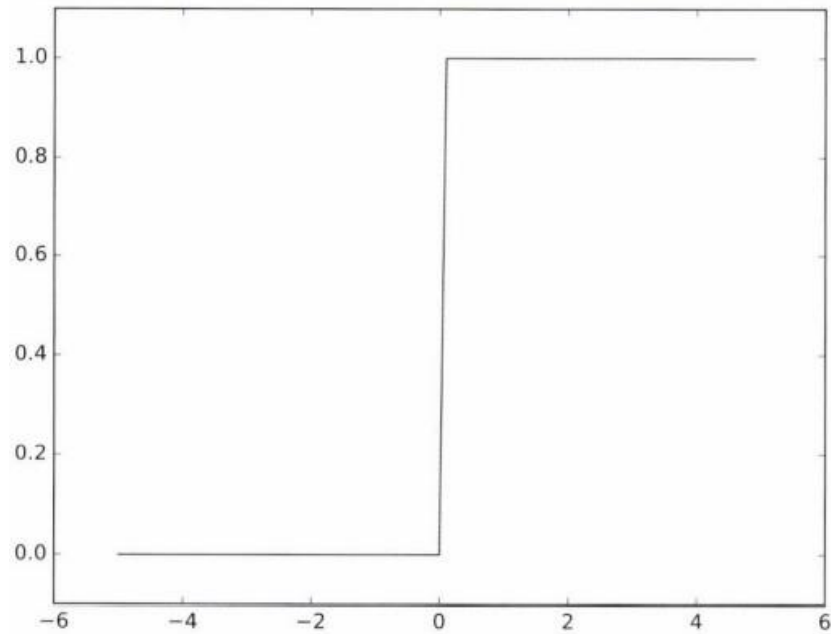


### Activation Function (활성화 함수)

- 입력신호의 총합을 출력 신호로 변환하는 함수
- 활성화 함수로는 Step function, Relu, Sigmoid, tanh 등 여러 함수 존재

## Unit 01 | Perceptron

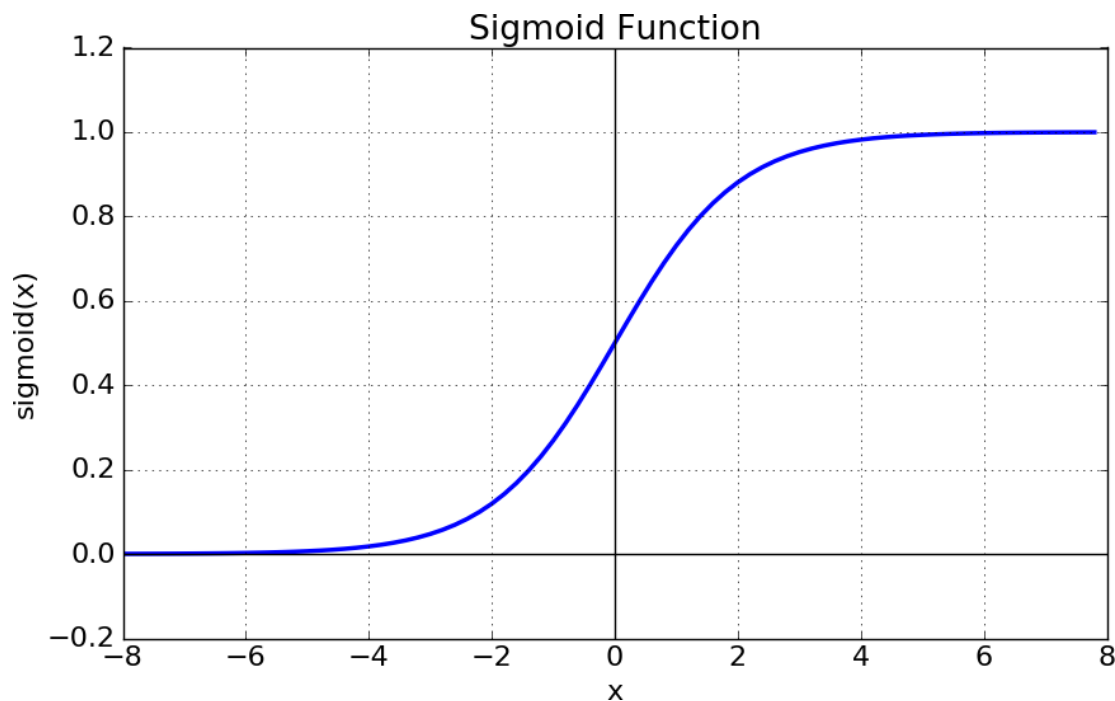
### 활성화 함수 - Step function



- 출력이 0 또는 1
- 활성화할지 말지 여부만 반환

## Unit 01 | Perceptron

### 활성화 함수 - Sigmoid

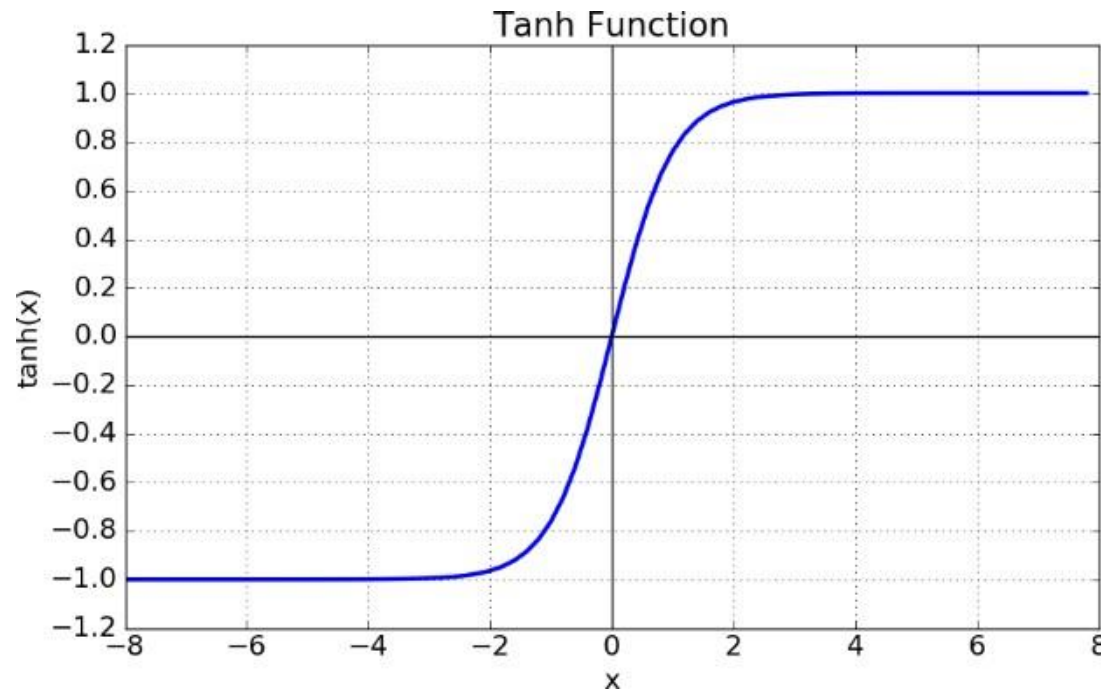


$$h(x) = \frac{1}{1 + \exp(-x)}$$

- 0에서 1 사이의 값 출력
- 활성화 여부가 아닌, 활성화 정도를 반환
- 1에 가까울수록 많이 활성화됐다는 뜻

## Unit 01 | Perceptron

## 활성화 함수 - Tanh



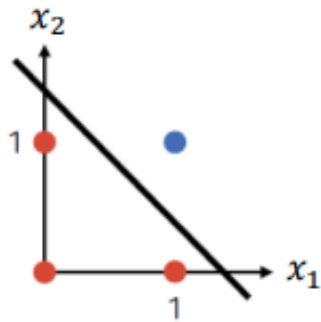
$$\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

- -1에서 1 사이의 값 출력
- 시그모이드 함수보다 범위가 넓어 출력값의 변화폭이 더 크고 이로 인해 기울기 소실 증상이 적음.

## Unit 01 | Perceptron

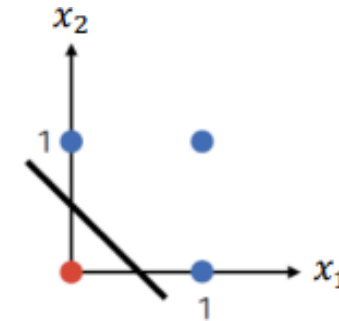
## Perceptron 연산

AND



$x_1$	$x_2$	$y$
1	1	1
1	0	0
0	1	0
0	0	0

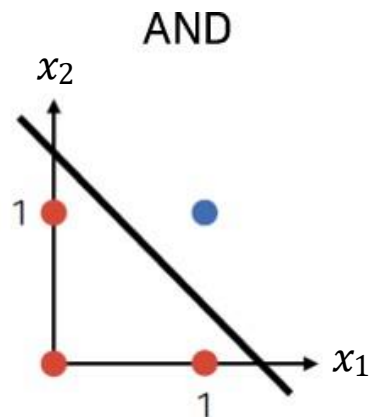
OR



$x_1$	$x_2$	$y$
1	1	1
1	0	1
0	1	1
0	0	0

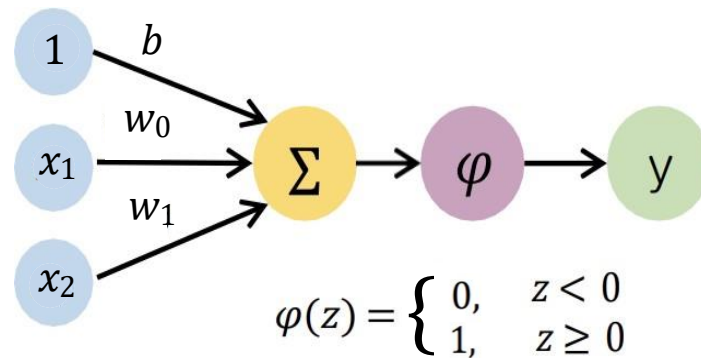
## Unit 01 | Perceptron

## Perceptron 연산



$$w_0 = 1.0, w_1 = 1.0, b = -1.5$$

$x_1$	$x_2$	$S$	$y$
0	0	-1.5	0
0	1	-0.5	0
1	0	-0.5	0
1	1	0.5	1

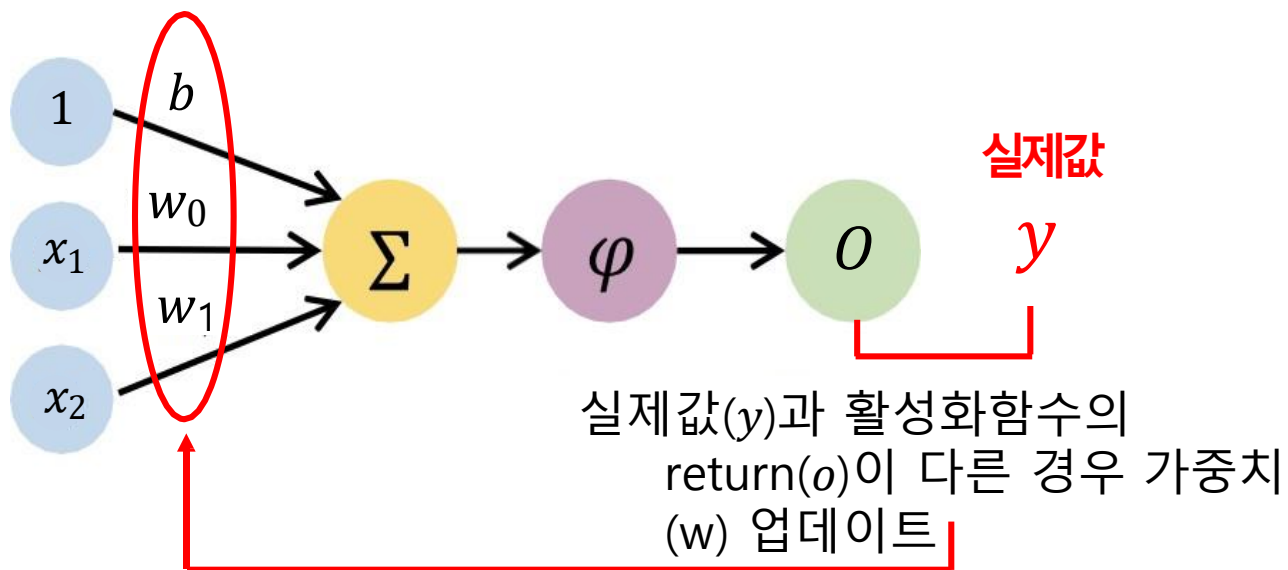


$$\varphi(w_1x_1 + w_2x_2 + w_3) = y$$

- ①  $(1.0 \times 0) + (1.0 \times 0) + (-1.5) = -1.5$   
 $\varphi((1.0 \times 0) + (1.0 \times 0) + (-1.5)) = 0$
- ②  $(1.0 \times 0) + (1.0 \times 1) + (-1.5) = -0.5$   
 $\varphi((1.0 \times 0) + (1.0 \times 1) + (-1.5)) = 0$
- ③  $(1.0 \times 1) + (1.0 \times 0) + (-1.5) = -0.5$   
 $\varphi((1.0 \times 1) + (1.0 \times 0) + (-1.5)) = 0$
- ④  $(1.0 \times 1) + (1.0 \times 1) + (-1.5) = 0.5$   
 $\varphi((1.0 \times 1) + (1.0 \times 1) + (-1.5)) = 1$

## Unit 01 | Perceptron

## Perceptron 학습



## 가중치 조정 식

$$w_i \leftarrow w_i + \eta(y - o)x_i$$

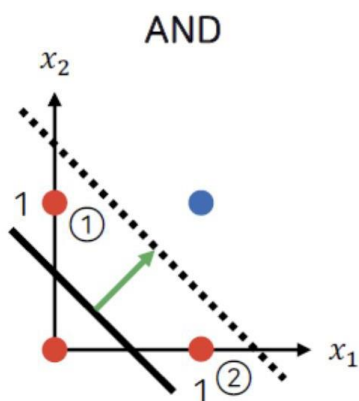


## 학습률(learning rate)

너무 작으면 학습 속도가 매우 느리고 너무 크면 가중치를 미세하게 조정하지 못하기 때문에 최적의 가중치를 찾기 어려움

## Unit 01 | Perceptron

## Perceptron 학습



$$w_1 = 0.55, w_2 = 0.55, b = -0.65$$

$x_1$	$x_2$	$o$	$y$
0	0	0	0
0	1	1	0
1	0	1	0
1	1	1	1

①

②

$$w_i \leftarrow w_i + \eta(y - o)x_i \quad \eta = 0.05$$

$$\begin{aligned} b &\leftarrow b + 0.05(0 - 1) \times 1 \\ \textcircled{1} \quad w_1 &\leftarrow w_1 + 0.05(0 - 1) \times 0 \\ w_2 &\leftarrow w_2 + 0.05(0 - 1) \times 1 \end{aligned}$$

$$\begin{aligned} b &\leftarrow -0.65 + 0.05(0 - 1) \times 1 = -0.7 \\ w_1 &\leftarrow 0.55 + 0.05(0 - 1) \times 0 = 0.55 \\ w_2 &\leftarrow 0.55 + 0.05(0 - 1) \times 1 = 0.5 \end{aligned}$$

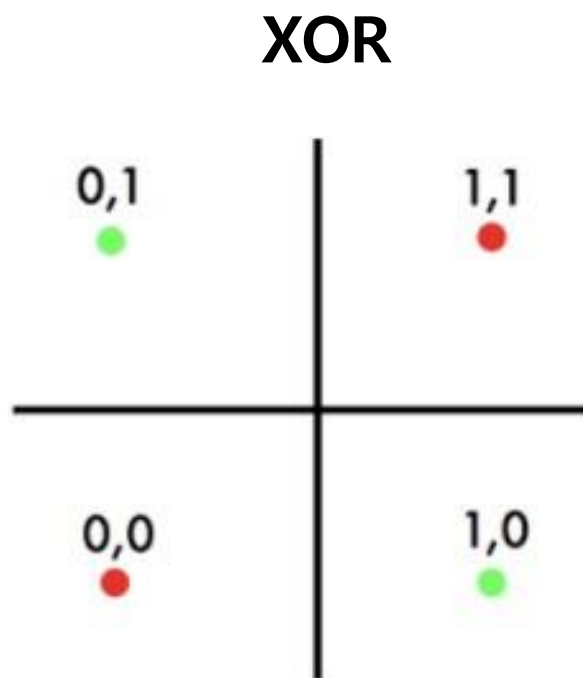
$$\begin{aligned} b &\leftarrow b + 0.05(0 - 1) \times 1 \\ \textcircled{2} \quad w_1 &\leftarrow w_1 + 0.05(0 - 1) \times 1 \\ w_2 &\leftarrow w_2 + 0.05(0 - 1) \times 0 \end{aligned}$$

$$\begin{aligned} b &\leftarrow -0.65 + 0.05(0 - 1) \times 1 = -0.7 \\ w_1 &\leftarrow 0.55 + 0.05(0 - 1) \times 1 = 0.5 \\ w_2 &\leftarrow 0.55 + 0.05(0 - 1) \times 0 = 0.55 \end{aligned}$$



## Unit 01 | Perceptron

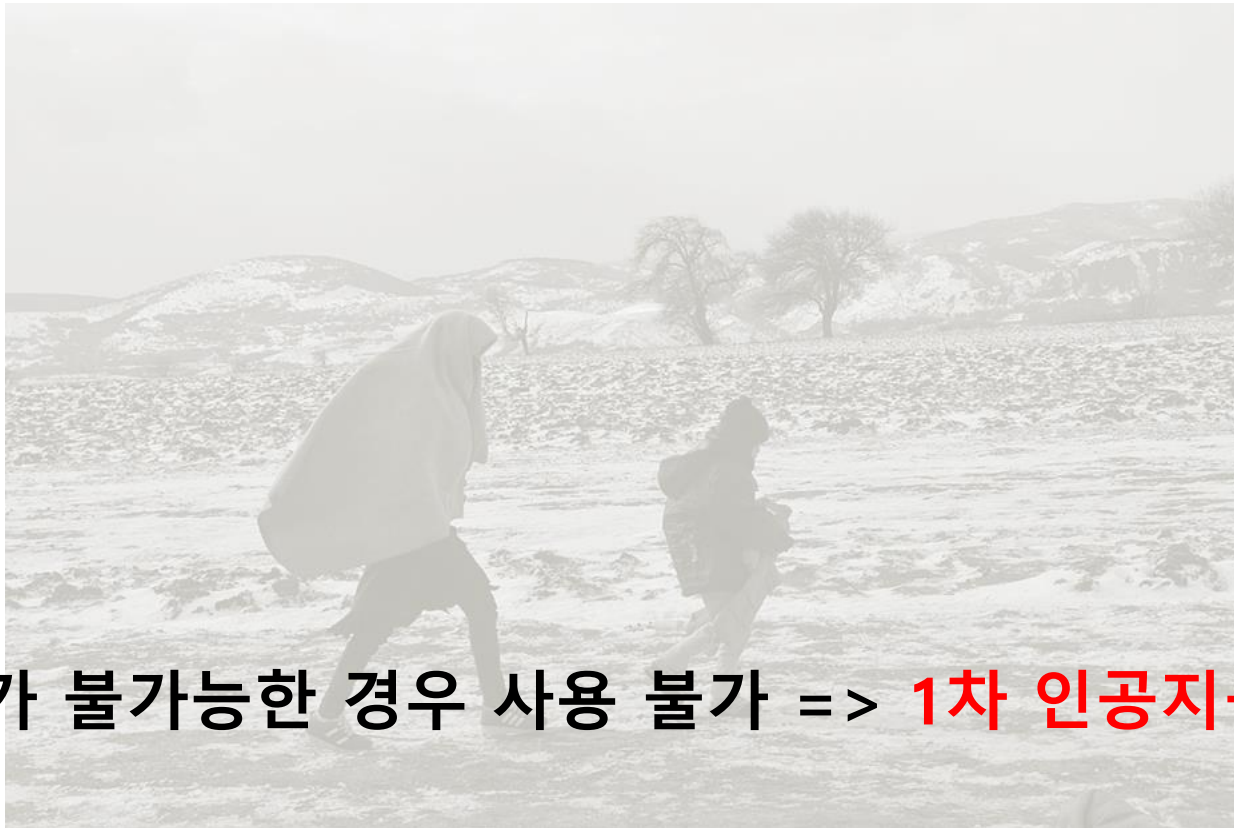
### Perceptron의 한계



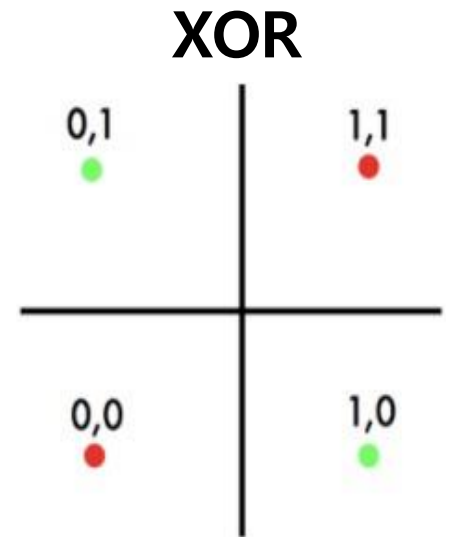
1969년 MIT AI랩 창립자 Minsky& Papert  
**‘현재의 퍼셉트론으로는 XOR 문제를 해결할 수 없다.’**

## Unit 01 | Perceptron

### Perceptron의 한계



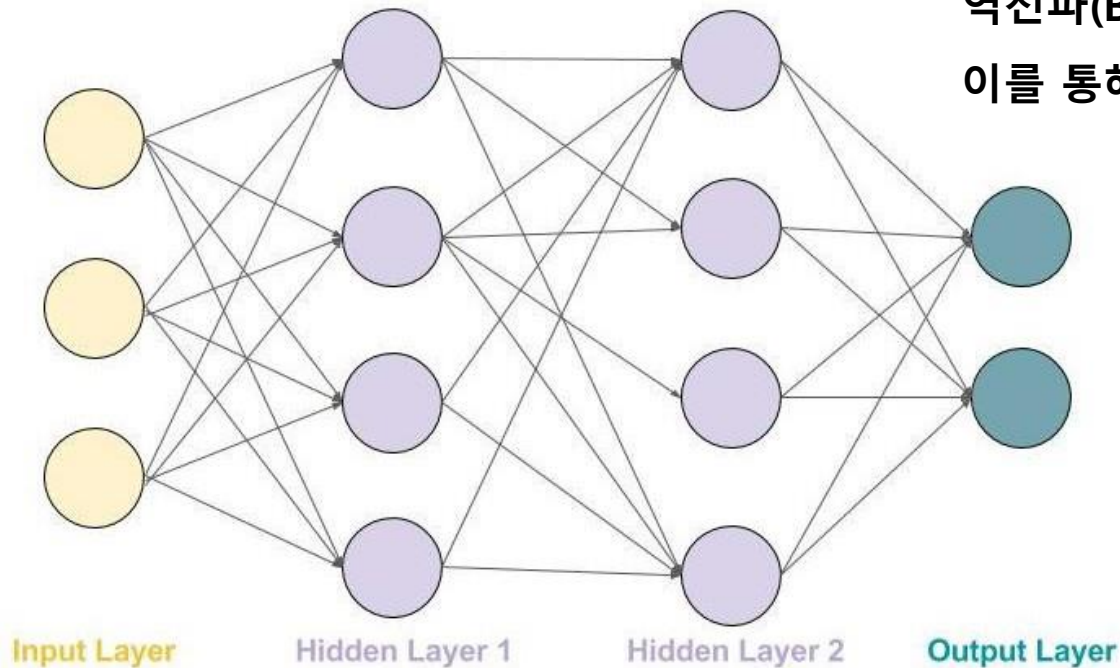
선형 분리가 불가능한 경우 사용 불가 => 1차 인공지능의 겨울



## **02 | Backpropagation**

## Unit 02 | Backpropagation

# Multi Layer Perceptron



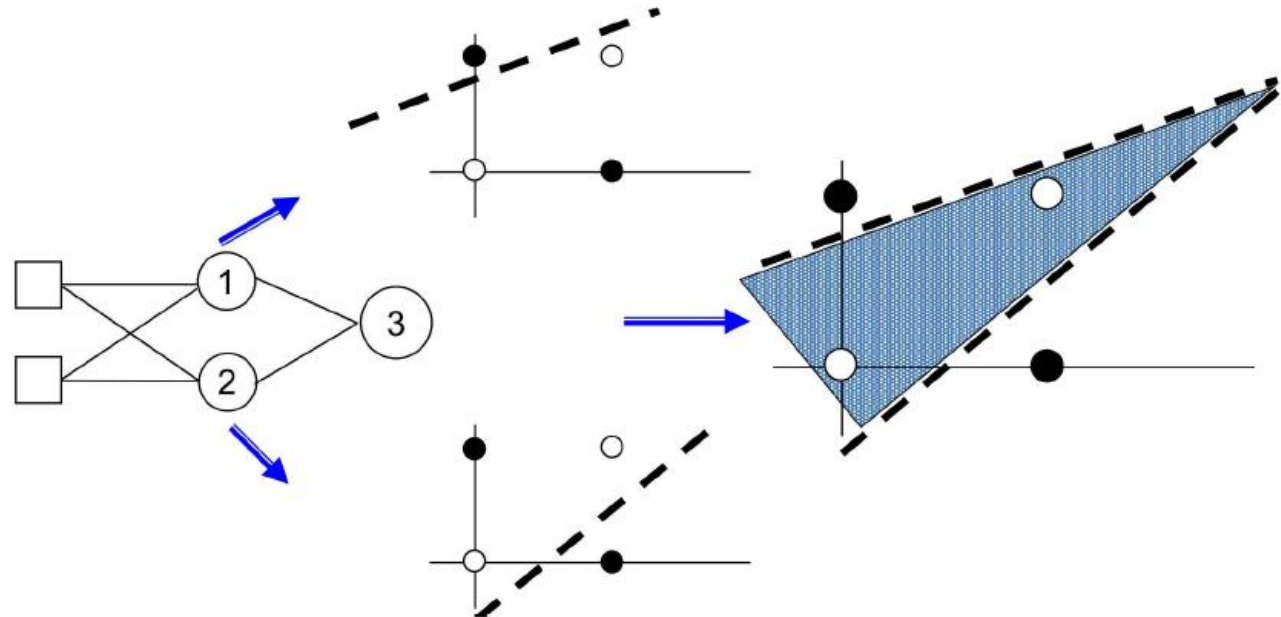
1986년 제프리 힌튼이 다층 퍼셉트론(Multi Layer Perceptron), 역전파(Back Propagation)을 실험적으로 증명.  
이를 통해 오랜 AI의 거울을 불러 온 XOR 문제 해결

## Unit 02 | Backpropagation

# Multi Layer Perceptron

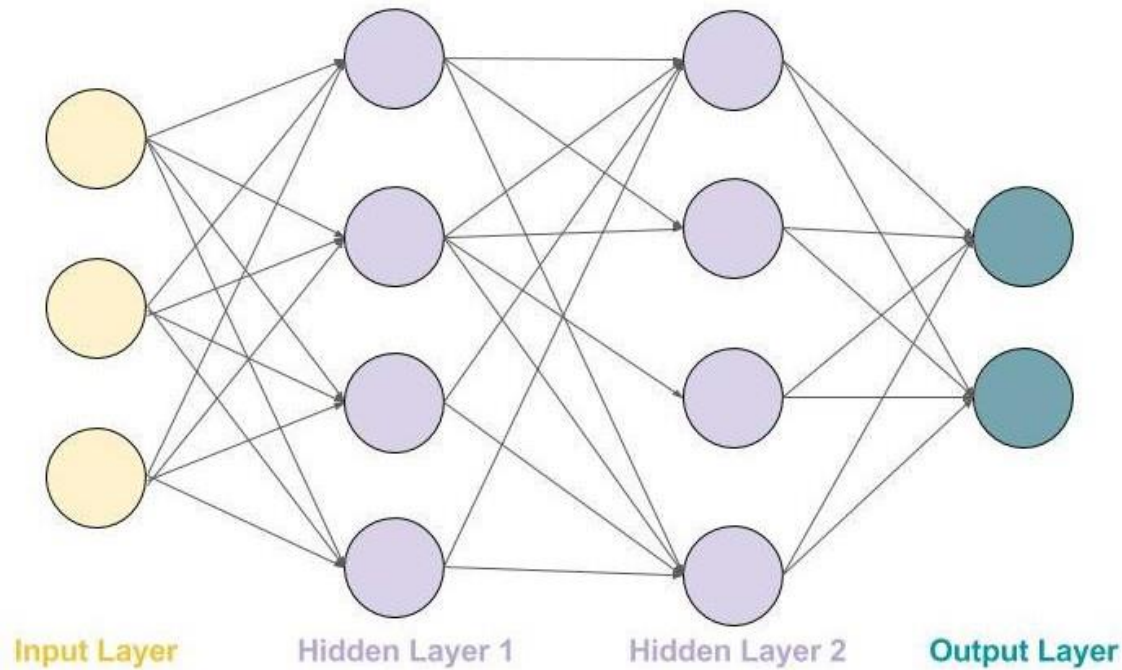
하나의 퍼셉트론으로는 해결하지 못했던 xor문제도 여러 퍼셉트론을 쌓는다면 해결 가능

XOR



## Unit 02 | Backpropagation

# Multi Layer Perceptron



MLP를 학습시키는 방법

: 오류 역전파

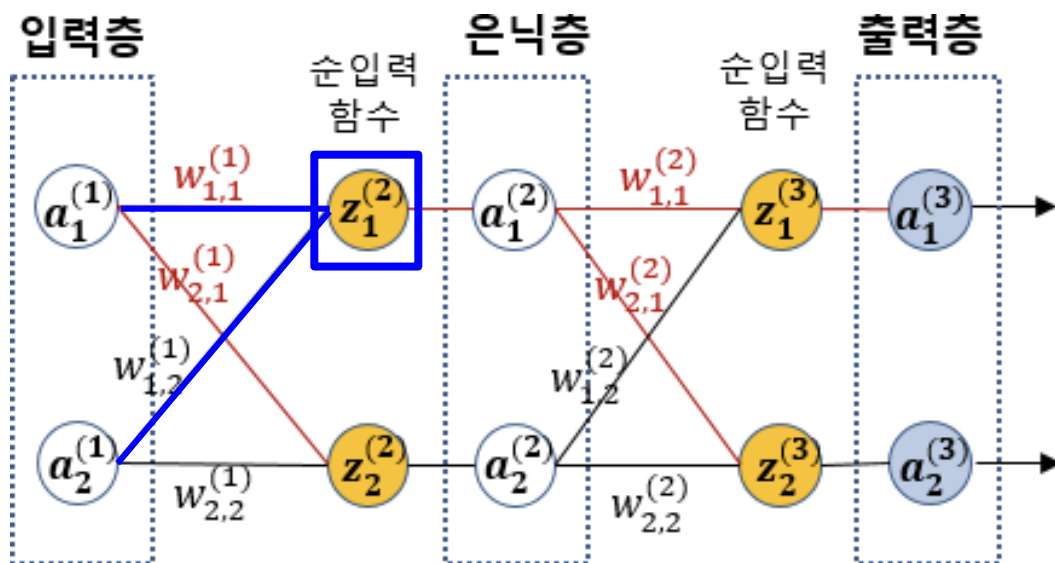
## Unit 02 | Backpropagation

### 역전파(Backpropagation)

**순전파(Feedforward)** 알고리즘에서 발생한 오차를 줄이기 위해  
새로운 가중치를 업데이트하고, 새로운 가중치로 다시 학습하는 과정

## Unit 02 | Backpropagation

## 순전파(Feedforward)



$$\phi(z) = \frac{1}{1 + e^{-z}}$$

$$z_1^{(2)} = w_{1,1}^{(1)} a_1^{(1)} + w_{1,2}^{(1)} a_2^{(1)}$$

$$a_1^{(2)} = \phi(z_1^{(2)})$$

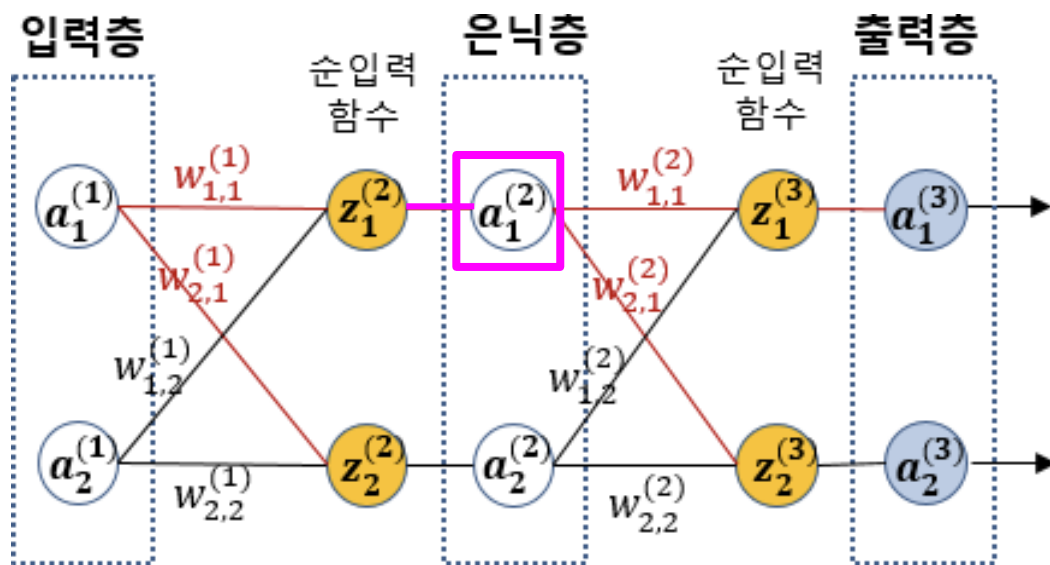
$$z_1^{(3)} = w_{1,1}^{(2)} a_1^{(2)} + w_{1,2}^{(2)} a_2^{(2)}$$

$$a_1^{(3)} = \phi(z_1^{(3)})$$



## Unit 02 | Backpropagation

## 순전파(Feedforward)



$$\phi(z) = \frac{1}{1 + e^{-z}}$$

$$z_1^{(2)} = w_{1,1}^{(1)} a_1^{(1)} + w_{1,2}^{(1)} a_2^{(1)}$$

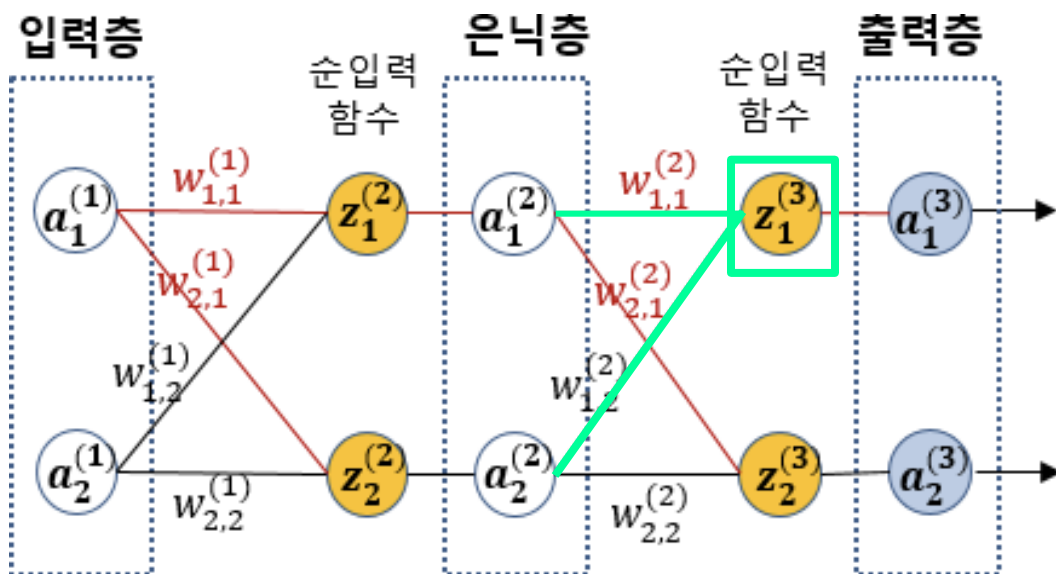
$$a_1^{(2)} = \phi(z_1^{(2)})$$

$$z_1^{(3)} = w_{1,1}^{(2)} a_1^{(2)} + w_{1,2}^{(2)} a_2^{(2)}$$

$$a_1^{(3)} = \phi(z_1^{(3)})$$

## Unit 02 | Backpropagation

## 순전파(Feedforward)



$$\phi(z) = \frac{1}{1 + e^{-z}}$$

$$z_1^{(2)} = w_{1,1}^{(1)} a_1^{(1)} + w_{1,2}^{(1)} a_2^{(1)}$$

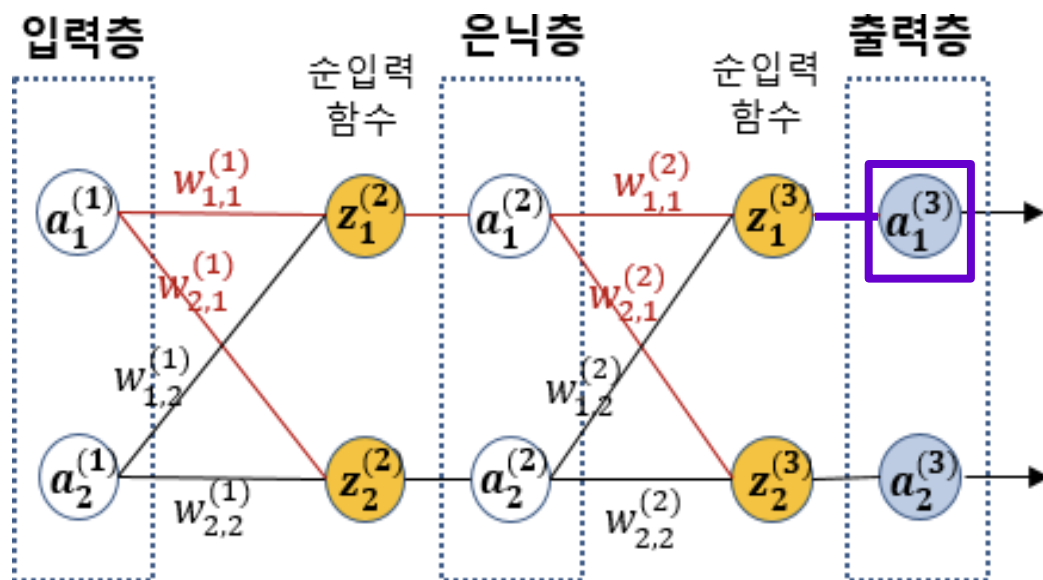
$$a_1^{(2)} = \phi(z_1^{(2)})$$

$$z_1^{(3)} = w_{1,1}^{(2)} a_1^{(2)} + w_{1,2}^{(2)} a_2^{(2)}$$

$$a_1^{(3)} = \phi(z_1^{(3)})$$

## Unit 02 | Backpropagation

## 순전파(Feedforward)



$$\phi(z) = \frac{1}{1 + e^{-z}}$$

$$z_1^{(2)} = w_{1,1}^{(1)} a_1^{(1)} + w_{2,1}^{(1)} a_2^{(1)}$$

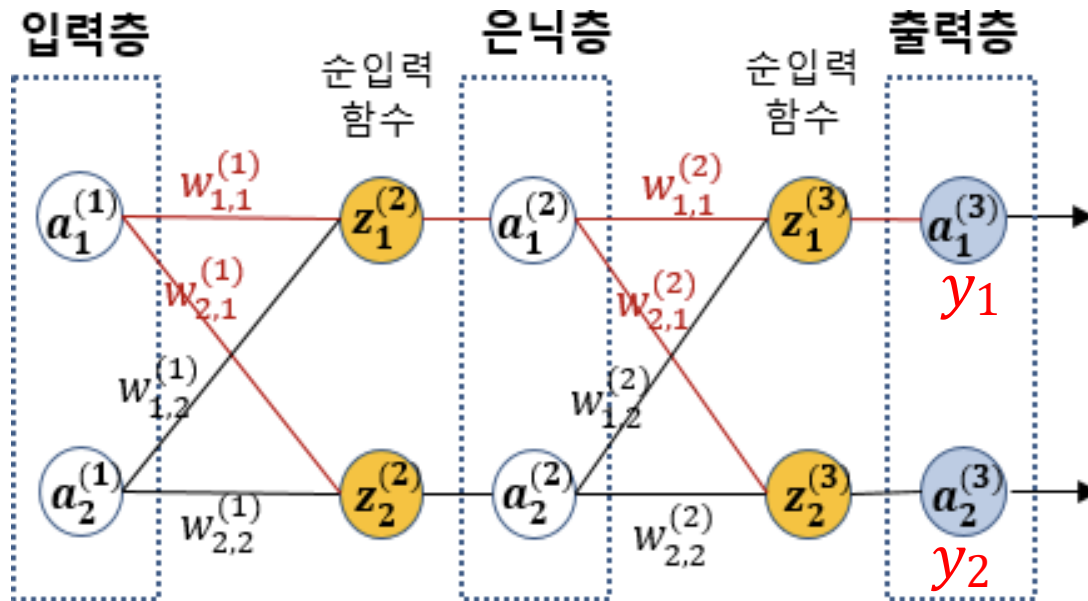
$$a_1^{(2)} = \phi(z_1^{(2)})$$

$$z_1^{(3)} = w_{1,1}^{(2)} a_1^{(2)} + w_{2,1}^{(2)} a_2^{(2)}$$

$$a_1^{(3)} = \phi(z_1^{(3)})$$

## Unit 02 | Backpropagation

## 손실함수(Cost Function)



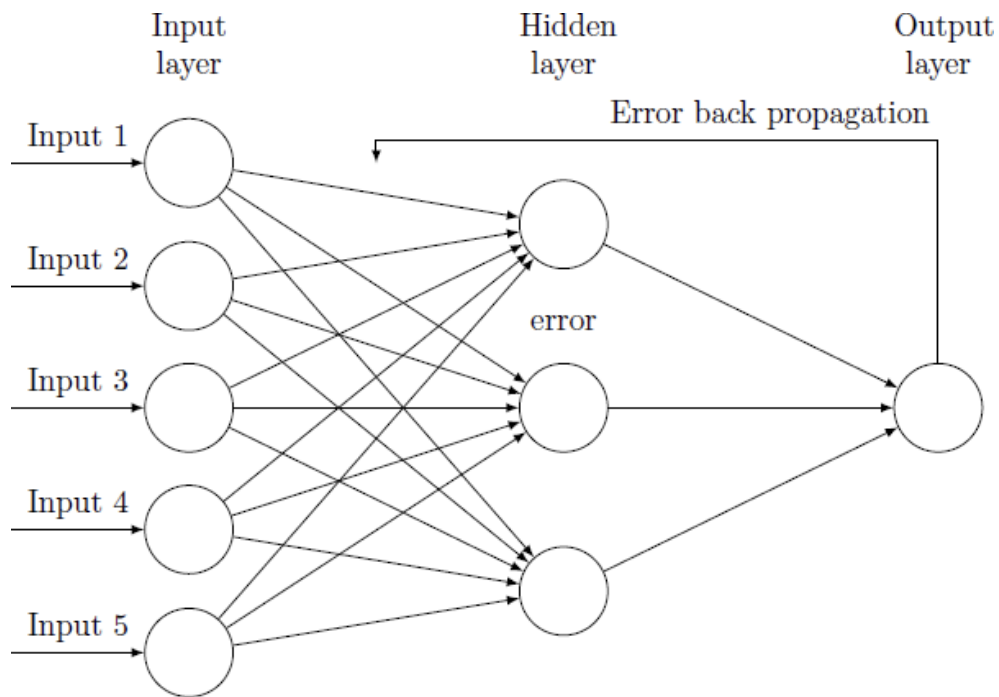
$$\text{MSE} = \frac{1}{2N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$$

$$J_1 = \frac{1}{2} (a_1^{(3)} - y_1)^2$$

$$J_2 = \frac{1}{2} (a_2^{(3)} - y_2)^2$$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



- Input과 output 값을 알고 있는 상태에서 신경망을 학습시키는 방법
- 출력부터 반대 방향으로 순차적으로 편미분을 수행해 가면서 weight와 bias 값을 갱신시킴

$$w_j = w_j - \eta \frac{\partial J_{total}}{\partial w_j}$$

가중치 업데이트 식

## Unit 02 | Backpropagation

## 편미분

다변수함수의 특정 변수를 제외한 나머지 변수를 상수로 생각하여 미분

$$z = f(x, y) = x^2 + xy + y^2$$

$$\frac{\partial z}{\partial x} = 2x + y, \quad \frac{\partial z}{\partial y} = 2y + x$$

$$\Delta f(x, y) = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) = (2x + y, 2y + x)$$

## Unit 02 | Backpropagation

## Chain Rule

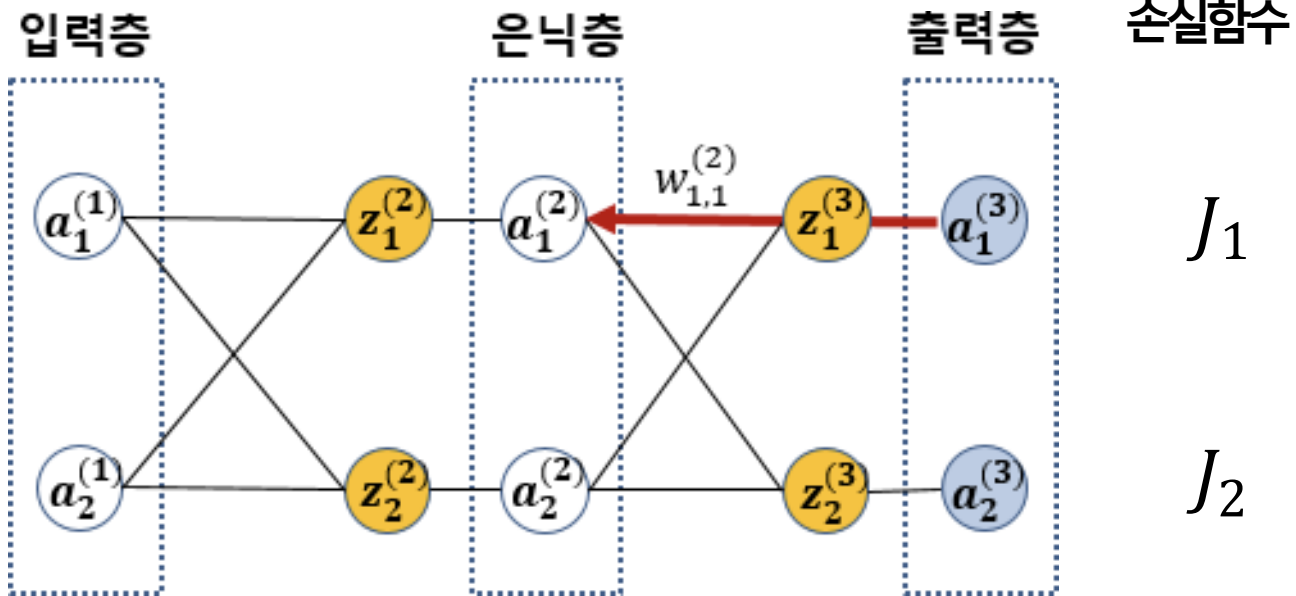
연쇄 법칙, 합성 함수를 미분할 때의 계산 공식

$$f(g(x))' = f'(g(x))g'(x)$$

$$y = f(u), u = g(x) \text{ 일 때, } \frac{\partial y}{\partial x} = \frac{\partial y}{\partial u} \cdot \frac{\partial u}{\partial x} \text{ 성립}$$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



$$w_j = w_j - \eta \frac{\partial J_{total}}{\partial w_j}$$

$$w_{1,1}^{(2)} = w_{1,1}^{(2)} - \frac{\partial J_{total}}{\partial w_{1,1}^{(2)}}$$

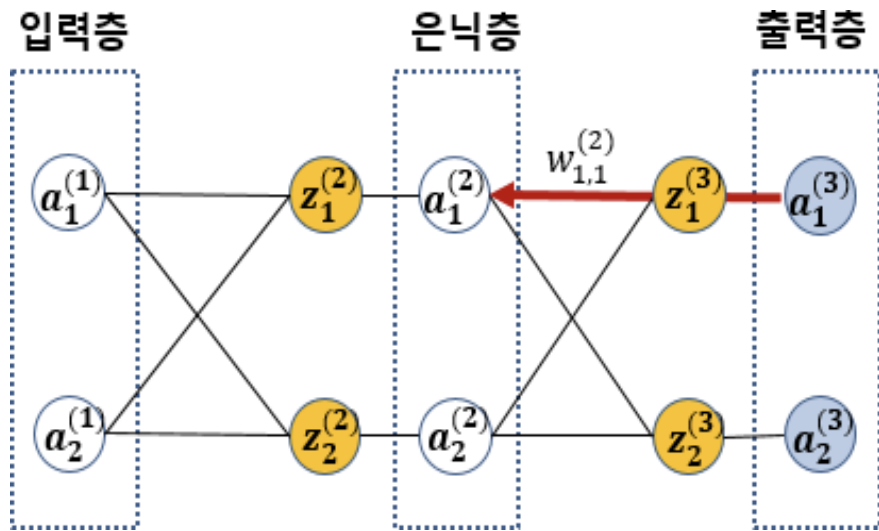
역전파의 출발노드인  $a_1^{(3)}$ 의  $J_{total}$ 은  $J_1$

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = \frac{\partial J_1}{\partial a_1^{(3)}} \times \frac{\partial a_1^{(3)}}{\partial z_1^{(3)}} \times \frac{\partial z_1^{(3)}}{\partial w_{1,1}^{(2)}}$$



## Unit 02 | Backpropagation

### 역전파(Backpropagation)



$J_1$

$J_2$

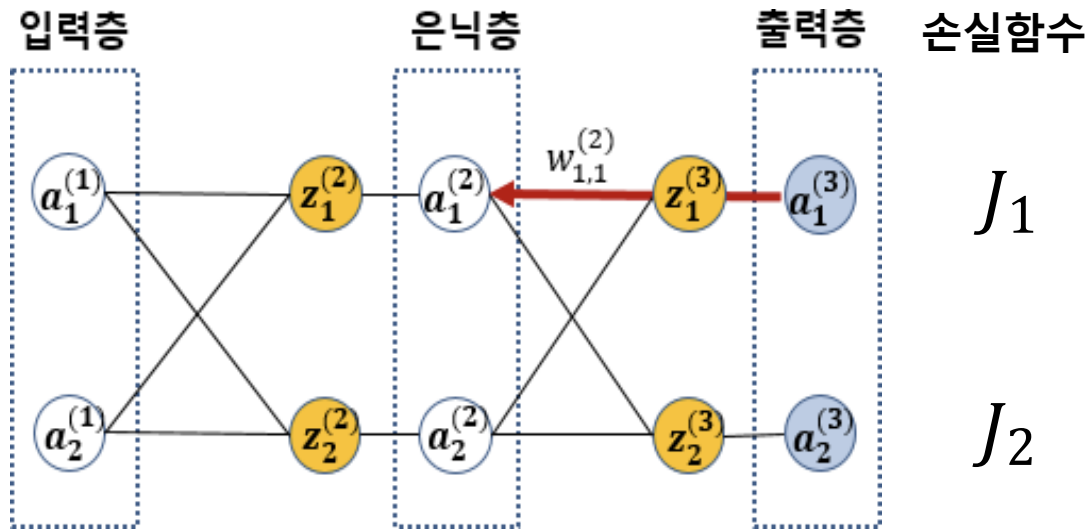
$$\frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = \underbrace{-\frac{\partial J_1}{\partial a_1^{(3)}}}_{\textcircled{1}} \times \underbrace{\frac{\partial a_1^{(3)}}{\partial z_1^{(3)}}}_{\textcircled{2}} \times \underbrace{\frac{\partial z_1^{(3)}}{\partial w_{1,1}^{(2)}}}_{\textcircled{3}}$$

참고:  $J_1 = \frac{1}{2} (a_1^{(3)} - y_1)^2$

①  $\frac{\partial J_1}{\partial a_1^{(3)}} = \frac{1}{2} \frac{\partial}{\partial a_1^{(3)}} (a_1^{(3)} - y_1)^2 = (a_1^{(3)} - y_1)$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



$$\frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = \underbrace{-\frac{\partial J_1}{\partial a_1^{(3)}}}_{\textcircled{1}} \times \underbrace{\frac{\partial a_1^{(3)}}{\partial z_1^{(3)}}}_{\textcircled{2}} \times \underbrace{\frac{\partial z_1^{(3)}}{\partial w_{1,1}^{(2)}}}_{\textcircled{3}}$$

참고:  $a_1^{(3)} = \phi(z_1^{(3)})$      $\sigma'(x) = \frac{\partial}{\partial x} \frac{1}{1+e^{-x}}$

$$= \frac{e^{-x}}{(1+e^{-x})^2}$$

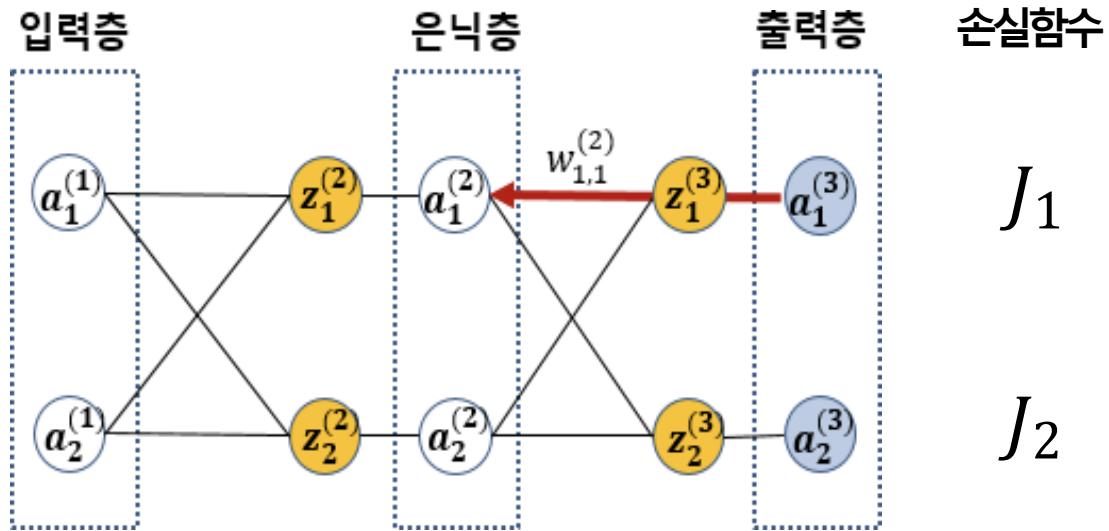
$$= \frac{1}{1+e^{-x}} \cdot \frac{e^{-x}}{1+e^{-x}}$$

$$= \sigma(x)(1 - \sigma(x))$$

②  $\frac{\partial a_1^{(3)}}{\partial z_1^{(3)}} = \phi(z_1^{(3)}) (1 - \phi(z_1^{(3)})) = a_1^{(3)} (1 - a_1^{(3)})$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



$$\frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = \underbrace{-\frac{\partial J_1}{\partial a_1^{(3)}}}_{\textcircled{1}} \times \underbrace{\frac{\partial a_1^{(3)}}{\partial z_1^{(3)}}}_{\textcircled{2}} \times \underbrace{\frac{\partial z_1^{(3)}}{\partial w_{1,1}^{(2)}}}_{\textcircled{3}}$$

참고:  $z_1^{(3)} = w_{1,1}^{(2)} a_1^{(2)} + w_{1,2}^{(2)} a_2^{(2)}$

$\textcircled{3} \quad \frac{\partial z_1^{(3)}}{\partial w_{1,1}^{(2)}} = a_1^{(2)}$

## Unit 02 | Backpropagation

## 역전파(Backpropagation)

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = \boxed{\frac{\partial J_1}{\partial a_1^{(3)}}} \times \boxed{\frac{\partial a_1^{(3)}}{\partial z_1^{(3)}}} \times \boxed{\frac{\partial z_1^{(3)}}{\partial w_{1,1}^{(2)}}} = \overset{\textcircled{1}}{(a_1^{(3)} - y_1)} \times \overset{\textcircled{2}}{a_1^{(3)}(1 - a_1^{(3)})} \times \overset{\textcircled{3}}{a_1^{(2)}}$$
$$\delta_1^{(3)} = \frac{\partial J_1}{\partial z_1^{(3)}} = (a_1^{(3)} - y_1) \times a_1^{(3)}(1 - a_1^{(3)})$$

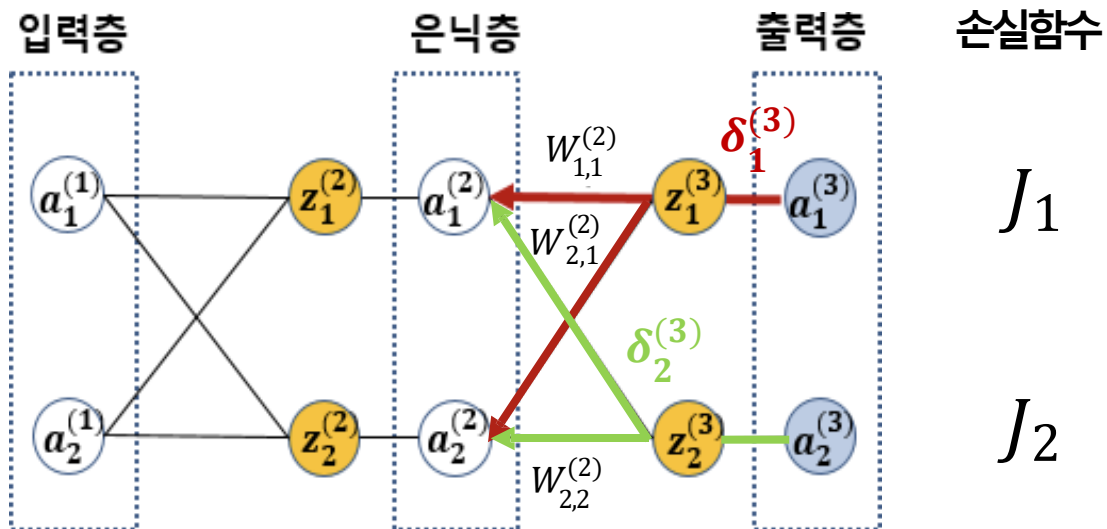
$$w_{1,1}^{(2)} = w_{1,1}^{(2)} - \frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = \boxed{w_{1,1}^{(2)} - \delta_1^{(3)} a_1^{(2)}}$$

## Unit 02 | Backpropagation

## 역전파(Backpropagation)

$$\delta_1^{(3)} = -\frac{\partial J_1}{\partial z_1^{(3)}} = (a_1^{(3)} - y_1) \times a_1^{(3)}(1 - a_1^{(3)})$$

$$w_{1,1}^{(2)} = w_{1,1}^{(2)} - \frac{\partial J_{total}}{\partial w_{1,1}^{(2)}} = w_{1,1}^{(2)} - \delta_1^{(3)} a_1^{(2)}$$



같은 방식으로

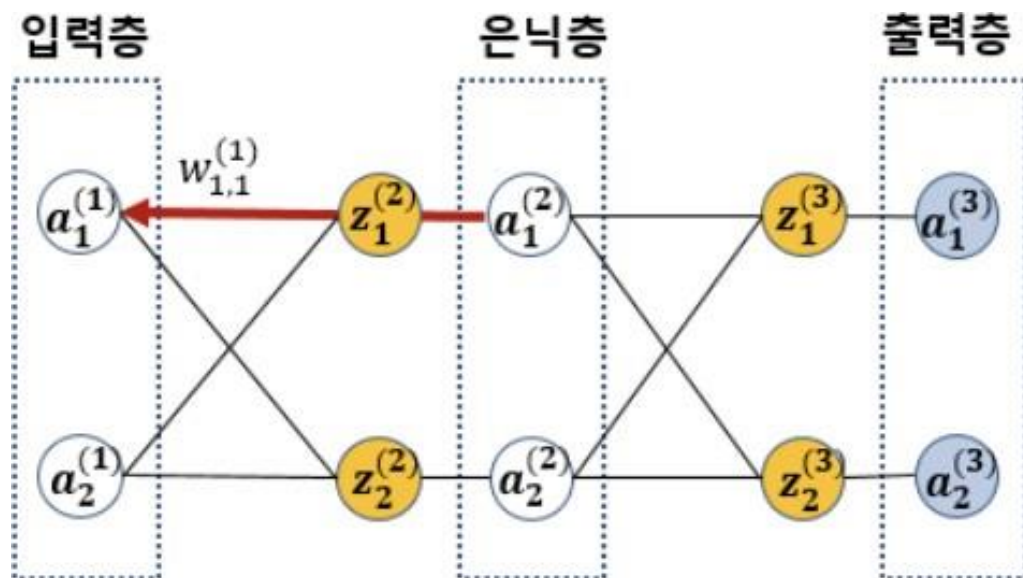
$$\delta_2^{(3)} = \frac{\partial J_2}{\partial z_2^{(3)}} = (a_2^{(3)} - y_2) \times a_2^{(3)}(1 - a_2^{(3)})$$

$$w_{2,1}^{(2)} = w_{2,1}^{(2)} - \delta_2^{(3)} a_1^{(2)}$$

$$w_{2,2}^{(2)} = w_{2,2}^{(2)} - \delta_2^{(3)} a_2^{(2)}$$

## Unit 02 | Backpropagation

## 역전파(Backpropagation)

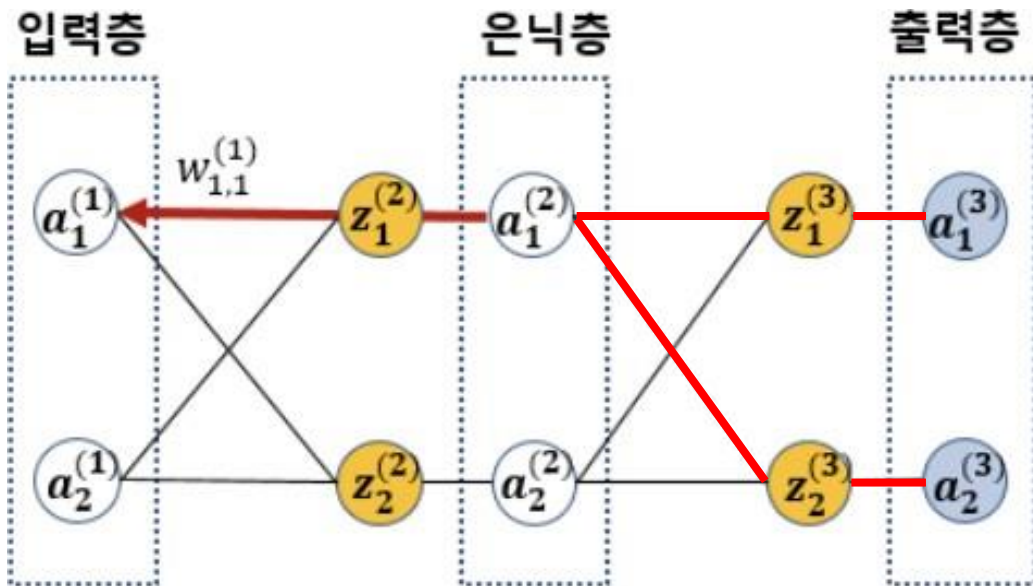


$$w_j = w_j - \eta \frac{\partial J_{total}}{\partial w_j}$$

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \frac{\partial J_{total}}{\partial a_1^{(2)}} \times \frac{\partial a_1^{(2)}}{\partial z_1^{(2)}} \times \frac{\partial z_1^{(2)}}{\partial w_{1,1}^{(1)}}$$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



손실함수

$J_1$

$J_2$

$$w_j = w_j - \eta \frac{\partial J_{total}}{\partial w_j}$$

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \frac{\partial J_{total}}{\partial a_1^{(2)}} \times \frac{\partial a_1^{(2)}}{\partial z_1^{(2)}} \times \frac{\partial z_1^{(2)}}{\partial w_{1,1}^{(1)}}$$

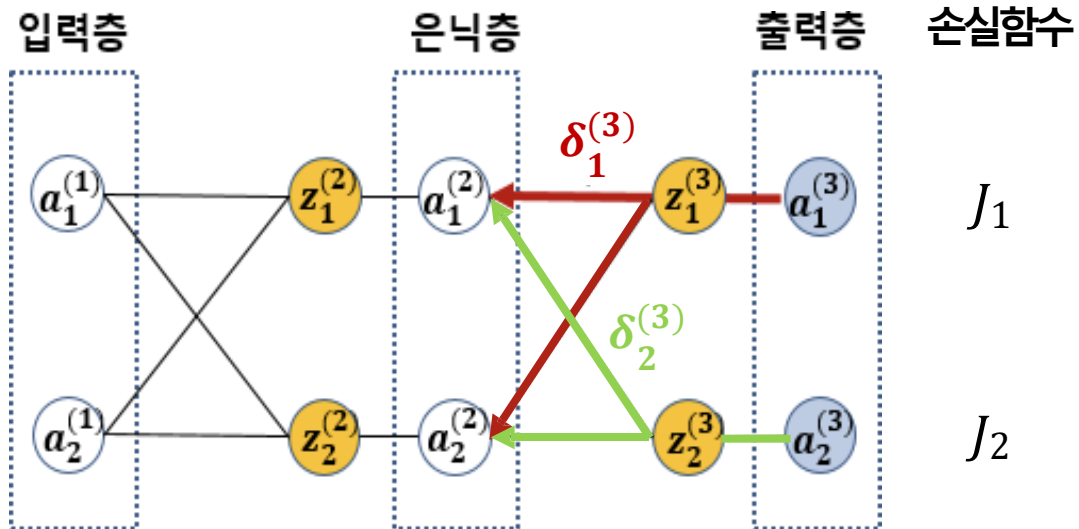
$a_1^{(2)}$ 의  $J_{total}$ 은  $J_1 + J_2$

$$\frac{\partial J_{total}}{\partial a_1^{(2)}} = \frac{\partial J_1}{\partial a_1^{(2)}} + \frac{\partial J_2}{\partial a_1^{(2)}} = \frac{\partial J_1}{\partial z_1^{(3)}} \times \frac{\partial z_1^{(3)}}{\partial a_1^{(2)}} + \frac{\partial J_2}{\partial z_2^{(3)}} \times \frac{\partial z_2^{(3)}}{\partial a_1^{(2)}}$$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \frac{\partial J_{total}}{\partial a_1^{(2)}} \times \frac{\partial a_1^{(2)}}{\partial z_1^{(2)}} \times \frac{\partial z_1^{(2)}}{\partial w_{1,1}^{(1)}}$$



$$\delta_1^{(3)} = \frac{\partial J_1}{\partial z_1^{(3)}} = (a_1^{(3)} - y_1) \times a_1^{(3)} (1 - a_1^{(3)})$$

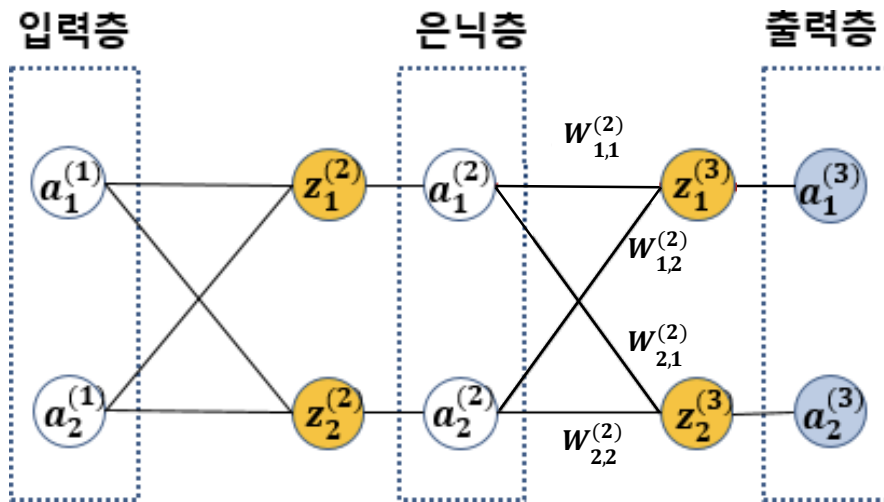
$$\delta_2^{(3)} = \frac{\partial J_2}{\partial z_2^{(3)}} = (a_2^{(3)} - y_2) \times a_2^{(3)} (1 - a_2^{(3)})$$

$$\begin{aligned} \frac{\partial J_{total}}{\partial a_1^{(2)}} &= \frac{\partial J_1}{\partial a_1^{(2)}} + \frac{\partial J_2}{\partial a_1^{(2)}} = \frac{\partial J_1}{\partial z_1^{(3)}} \times \frac{\partial z_1^{(3)}}{\partial a_1^{(2)}} + \frac{\partial J_2}{\partial z_2^{(3)}} \times \frac{\partial z_2^{(3)}}{\partial a_1^{(2)}} \\ &= \delta_1^{(3)} w_{1,1}^{(2)} + \delta_2^{(3)} w_{2,1}^{(2)} \end{aligned}$$



## Unit 02 | Backpropagation

### 역전파(Backpropagation)



$$z_1^{(3)} = w_{1,1}^{(2)} a_1^{(2)} + w_{1,2}^{(2)} a_2^{(2)}$$

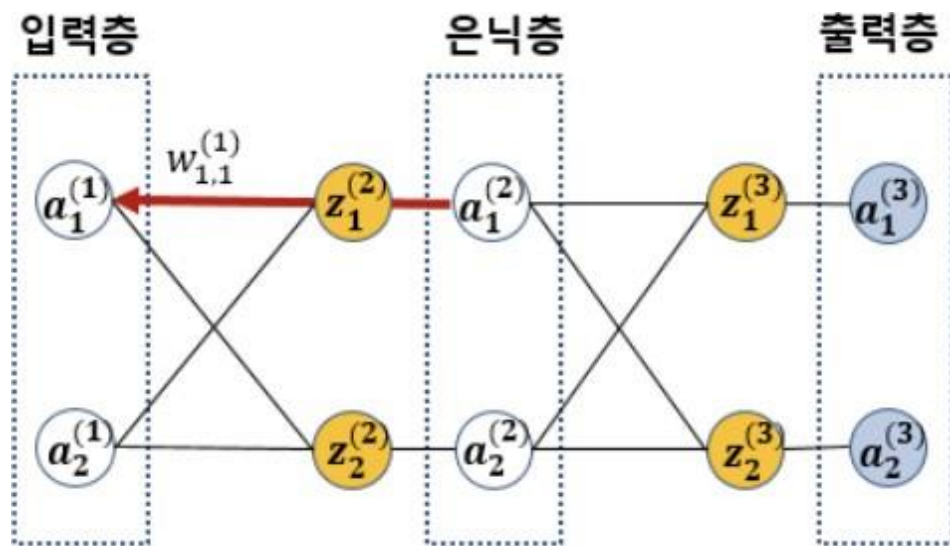
$$z_2^{(3)} = w_{2,1}^{(2)} a_1^{(2)} + w_{2,2}^{(2)} a_2^{(2)}$$

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \frac{\partial J_{total}}{\partial a_1^{(2)}} \times \frac{\partial a_1^{(2)}}{\partial z_1^{(2)}} \times \frac{\partial z_1^{(2)}}{\partial w_{1,1}^{(1)}}$$

$$\begin{aligned} \frac{\partial J_{total}}{\partial a_1^{(2)}} &= \frac{\partial J_1}{\partial a_1^{(2)}} + \frac{\partial J_2}{\partial a_1^{(2)}} = \frac{\partial J_1}{\partial z_1^{(3)}} \times \frac{\partial z_1^{(3)}}{\partial a_1^{(2)}} + \frac{\partial J_2}{\partial z_2^{(3)}} \times \frac{\partial z_2^{(3)}}{\partial a_1^{(2)}} \\ &= \delta_1^{(3)} w_{1,1}^{(2)} + \delta_2^{(3)} w_{2,1}^{(2)} \end{aligned}$$

## Unit 02 | Backpropagation

## 역전파(Backpropagation)

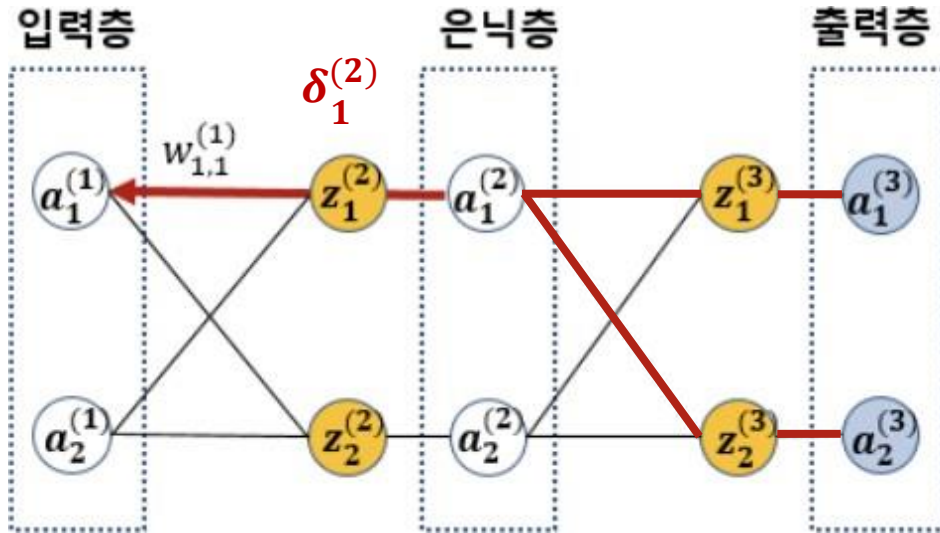


$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \frac{\partial J_{total}}{\partial a_1^{(2)}} \times \frac{\partial a_1^{(2)}}{\partial z_1^{(2)}} \times \frac{\partial z_1^{(2)}}{\partial w_{1,1}^{(1)}}$$

$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \left( \delta_1^{(3)} w_{1,1}^{(2)} + \delta_2^{(3)} w_{2,1}^{(2)} \right) \times a_1^{(2)} \left( 1 - a_1^{(2)} \right) \times a_1^{(1)}$$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



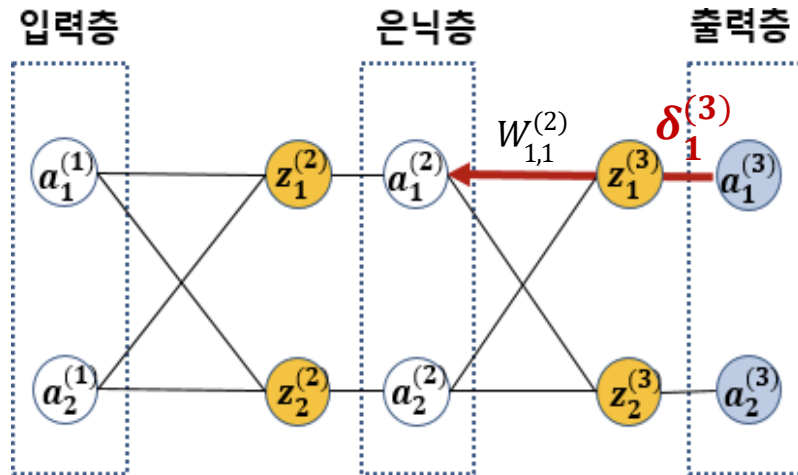
$$\frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \left( \delta_1^{(3)} w_{1,1}^{(2)} + \delta_2^{(3)} w_{2,1}^{(2)} \right) \times a_1^{(2)} (1 - a_1^{(2)}) \times a_1^{(1)}$$

$$\delta_1^{(2)} = (\delta_1^{(3)} w_{1,1}^{(2)} + \delta_2^{(3)} w_{2,1}^{(2)}) \times a_1^{(2)} (1 - a_1^{(2)})$$

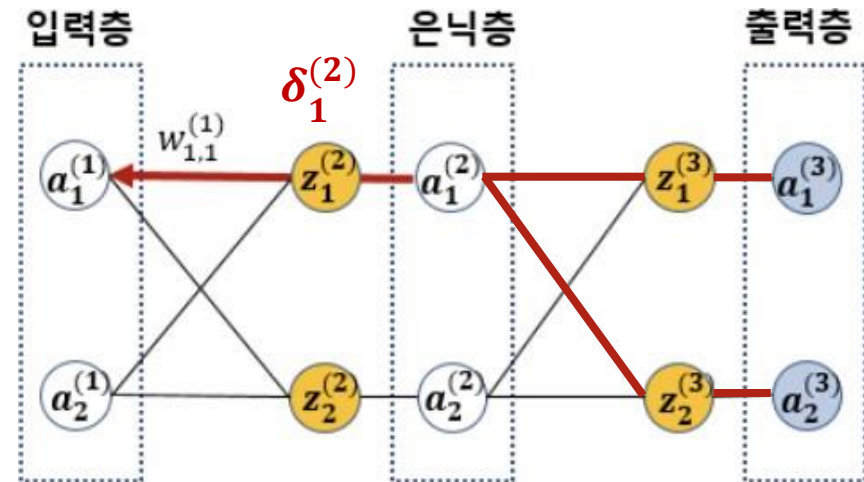
$$w_{1,1}^{(1)} = w_{1,1}^{(1)} - \frac{\partial J_{total}}{\partial w_{1,1}^{(1)}} = \boxed{w_{1,1}^{(1)} - \delta_1^{(2)} a_1^{(1)}}$$

## Unit 02 | Backpropagation

### 역전파(Backpropagation)



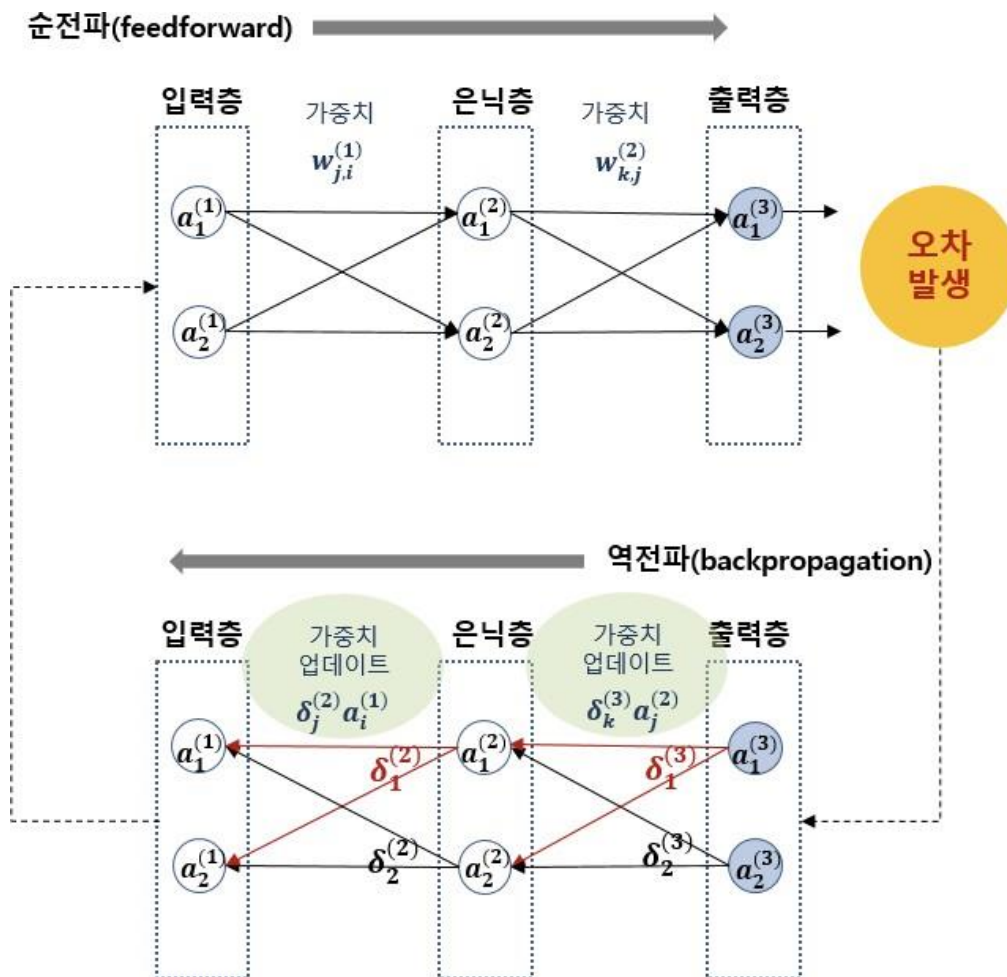
$$w_{1,1}^{(2)} = w_{1,1}^{(2)} - \delta_1^{(3)} a_1^{(2)}$$



$$w_{1,1}^{(1)} = w_{1,1}^{(1)} - \delta_1^{(2)} a_1^{(1)}$$

## Unit 02 | Backpropagation

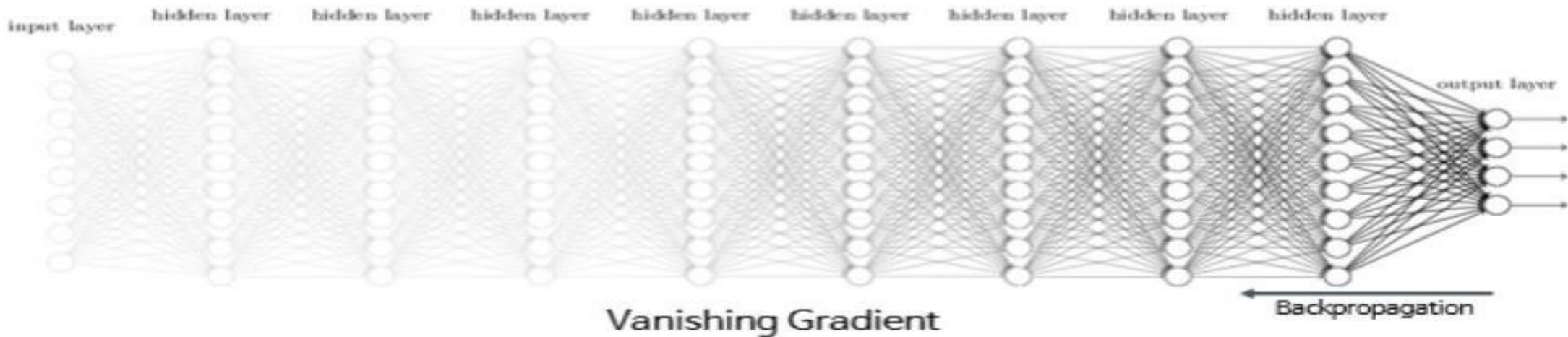
### 역전파 (Backpropagation)



## Unit 02 | Backpropagation

# Vanishing Gradient Problem

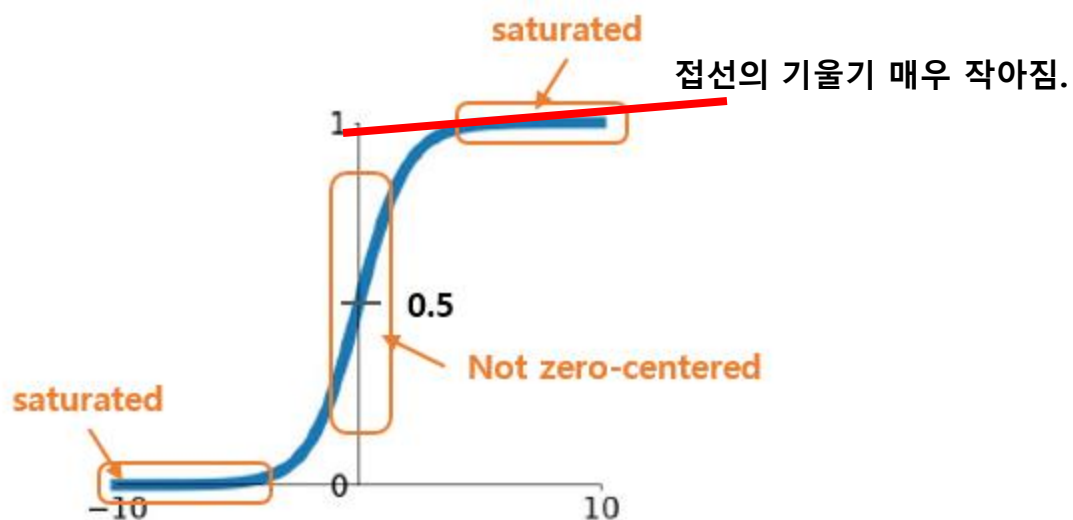
깊이가 깊은 심층신경망에서는 역전파 알고리즘이 입력층으로 전달됨에 따라  
그래디언트가 점점 작아져 결국 가중치 매개변수가 업데이트 되지 않는 경우가 발생



## Unit 02 | Backpropagation

# Vanishing Gradient Problem - sigmoid

## Sigmoid

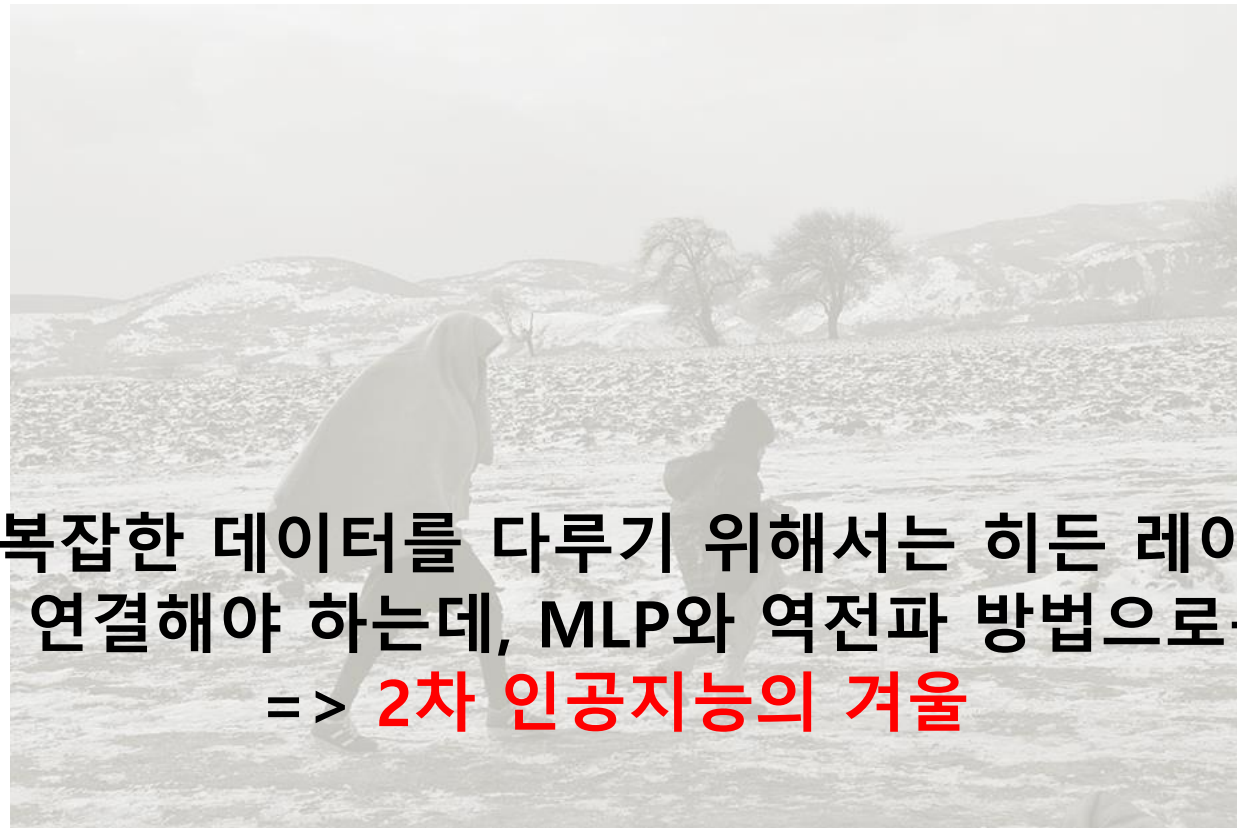


- 기울기가 작아지는 좌우 부분은 미분하면 0이 됨
- 역전파를 이용하여 편미분할 때  $\frac{dj_{total}}{dw}$  가 0이되어 가중치 업데이트가 없어지는 현상이 saturated 현상



## Unit 02 | Backpropagation

# Vanishing Gradient Problem

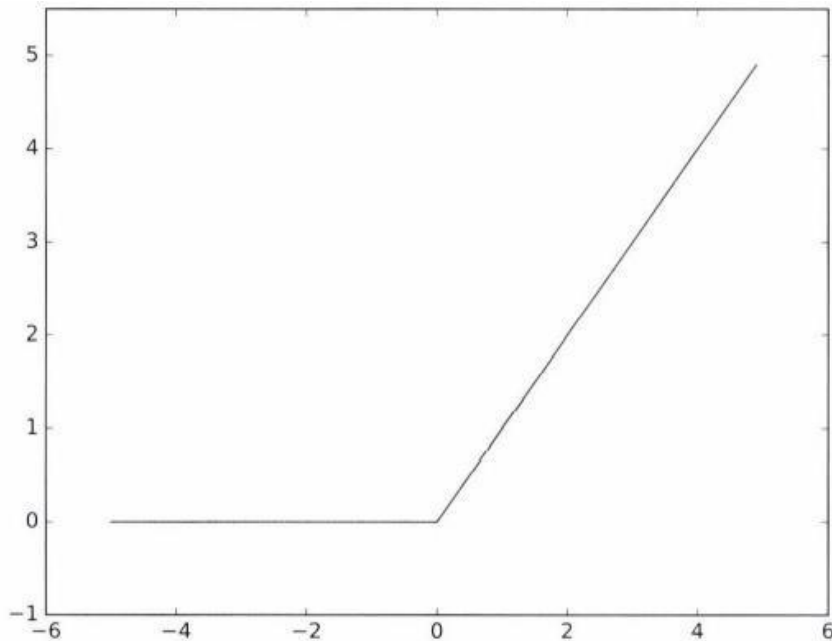


크고 복잡한 데이터를 다루기 위해서는 히든 레이어를  
여러 개 연결해야 하는데, MLP와 역전파 방법으로는 한계  
=> **2차 인공지능의 겨울**



## Unit 02 | Backpropagation

### 활성화함수 - ReLU 함수



$$h(x) = \begin{cases} x & (x > 0) \\ 0 & (x \leq 0) \end{cases}$$

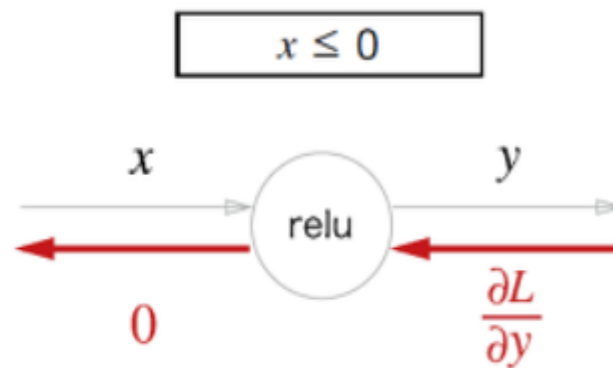
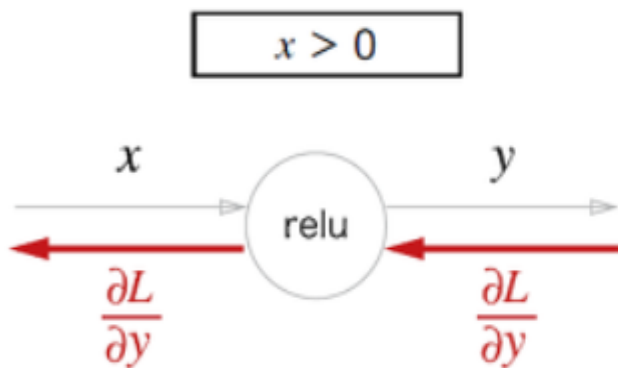
- Vanishing gradient problem 해결!
- 입력이 0 넘으면 값이 클수록 많이 활성화
- 입력이 0 보다 작으면 무조건 비활성화
- 다른 활성화 함수보다 계산 복잡도가 낮아서 학습 속도가 빠름
- 비선형함수

## Unit 02 | Backpropagation

## 활성화함수 - ReLU 함수

$$y = \begin{cases} x & (x > 0) \\ 0 & (x \leq 0) \end{cases}$$

$$\frac{\partial y}{\partial x} = \begin{cases} 1 & (x > 0) \\ 0 & (x \leq 0) \end{cases}$$



## Unit | 과제

**“week3\_NeuralNetworkBasic\_assignment.pdf” 파일의 문제들을  
상세한 풀이과정과 함께 풀어주세요.**

**“week3\_NeuralNetworkBasic\_실습.ipynb” 노트북 파일에서  
코드 실습을 진행해 주세요.**

## Reference

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- 밑바닥부터 시작하는 딥러닝
- 건국대학교 김학수 교수님 '기계학습' 강의
- <https://heeya-stupidbutstudying.tistory.com/38>
- 역전파: <https://m.blog.naver.com/samsjang/221033626685>
- <https://brunch.co.kr/@gdhan/6>
- <https://www.letr.ai/explore/story-20211105-1>
- <https://www.youtube.com/watch?v=bpBdSDEGViA>
- [신경망의 기본 구조 \(velog.io\)](#)
- [텐서플로우 딥러닝 강의 12-2 - ReLU 활성화함수 - YouTube](#)
- [딥러닝 Neural Network AND 함수, XOR 문제 해결 방법 \(tistory.com\)](#)
- [퍼셉트론\(Perceptron\) \(tistory.com\)](#)
- [실체가 손에 잡히는 딥러닝\(3\) “이것만은 꼭 알아두자! 딥러닝의 꽃 - 가중치, 편향, 활성화 함수, 역전파” | Popit](#)
- [\[기계학습\] Neural Networks 1 \(velog.io\)](#)
- 활성화 함수 종류 : [\[ML\] 활성화 함수\(Activation Function\) 종류 정리 \(tistory.com\)](#)
- [Vanishing Gradient Problem\(기울기 소멸 문제\) – 창의 컴퓨팅\(Creative Computing\)](#)

Q & A

들어주셔서 감사합니다.