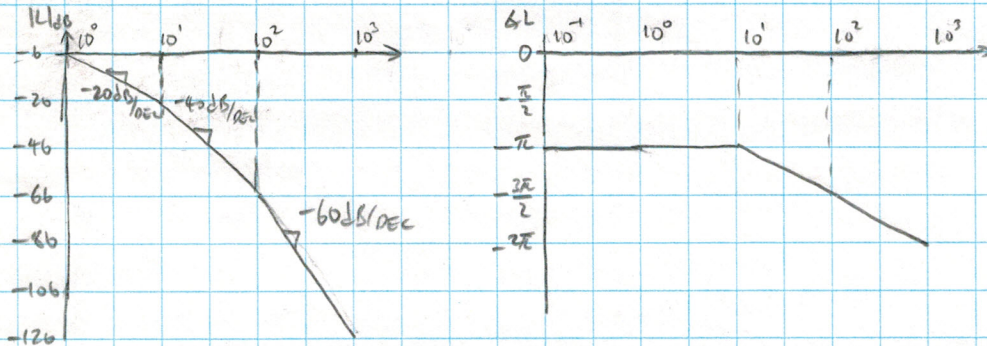


$$1. L = \frac{500}{s(s+10)(s+100)} = \frac{1}{2s(1+\frac{s}{10})(1+\frac{s}{100})}$$

$$|L|_{dB} = -20 \log 2 - 20 \log |s| - 20 \log |1+\frac{s}{10}| - 20 \log |1+\frac{s}{100}|$$

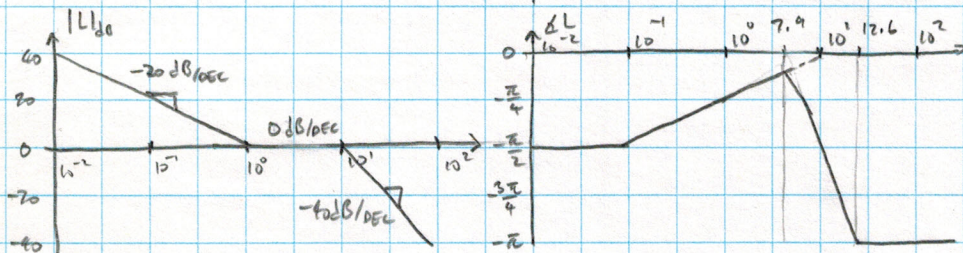
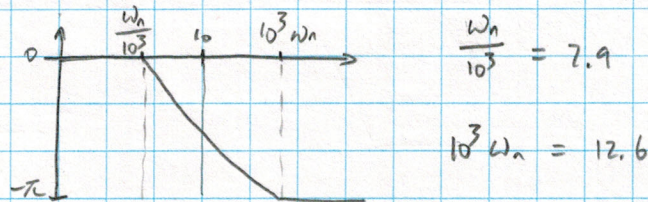
$$\Delta L = -\Delta(20) - \Delta|s| - \Delta|1+\frac{s}{10}| - \Delta|1+\frac{s}{100}|$$



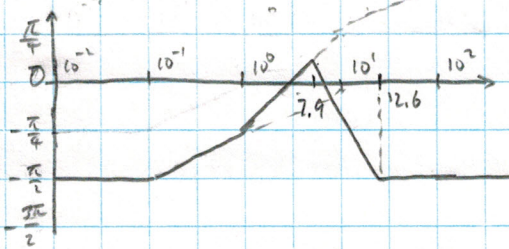
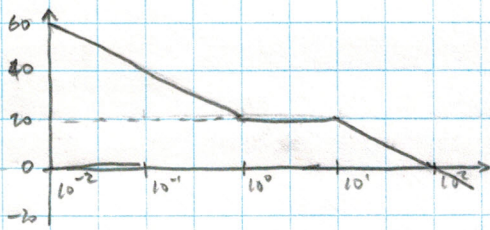
$$2. L = \frac{100(s+1)}{s(s^2+2s+100)} = \frac{(s+1)}{s((\frac{s}{10})^2 + \frac{2}{100}s + 1)} \leftarrow \omega_n = 10 \quad \zeta = 0.1$$

$$|L|_{dB} = -\log |s| + \log |s+1| - \log |(\frac{s}{10})^2 + \frac{2}{100}s + 1| \leftarrow \text{TREAT LIKE DOUBLE POLE AT } s = 10$$

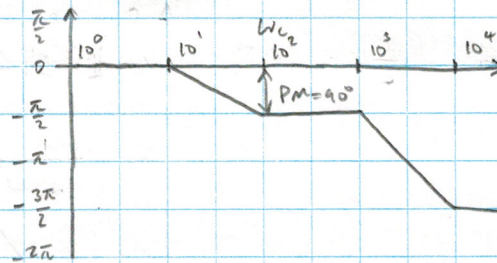
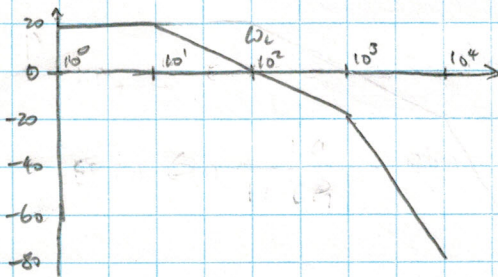
$$\Delta L = -\Delta(s) + \Delta(s+1) - \Delta((\frac{s}{10})^2 + \frac{2}{100}s + 1)$$



$$3. L = \frac{100(s+1)(s+10)}{s(s^2+2s+100)} = \frac{10(s+1)(1+\frac{s}{10})}{s((\frac{s}{10})^2 + \frac{2}{100}s + 1)} \leftarrow \omega_n = 10, \zeta = 0.1$$



$$4. G(s) = \frac{10^8}{(s+10)(s+10^3)^2} = \frac{10}{(1+\frac{s}{10})(1+\frac{s}{1000})^2}$$



$$\omega_c = 100$$

$$C(s) = \frac{T_i s + 1}{T_i s} \quad \frac{1}{T_i} = 0.1 \omega_c, \quad T_i \geq 0.1$$

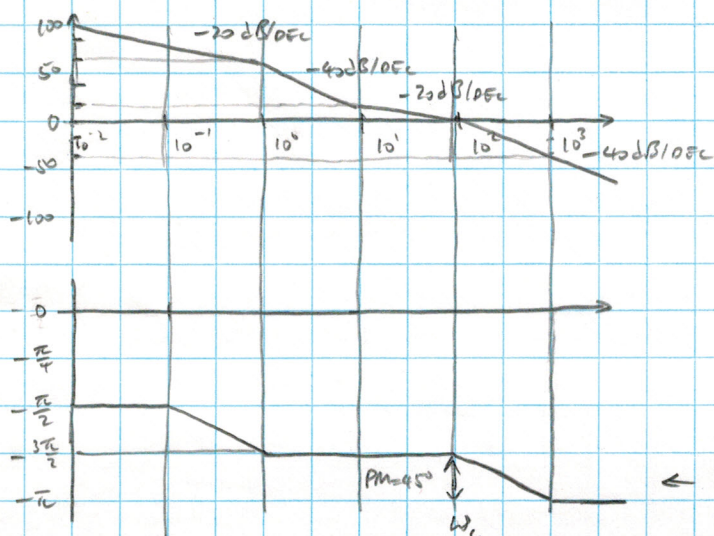
$$C(s) = \frac{0.1s + 1}{0.1s}$$

5. $PM = \tan^{-1} \left(\frac{2\beta}{\sqrt{2\beta} + \sqrt{1+4\beta^2}} \right)$ $\omega_{BW} = \omega_n \sqrt{(1-2\beta^2) + \sqrt{4\beta^4 - 4\beta^2 + 2}}$, $\omega_c \approx 0.5 \omega_{BW}$

i) $G(s) = \frac{s+10}{s(s+1)(s+100)}$, $\%OS = 1.44\%$, $T_s = 0.06s$

$\zeta = 0.803$ \rightarrow $PM = 70^\circ$
 $\omega_{BW} = 72 \text{ rad/s}$, $\omega_c = 36 \text{ rad/s}$

ii) $r(t) = 1(t)$: IMP $\Rightarrow e(\infty) = 0$ AS LONG AS CLS IS BIBO
 $r(t) = t \cdot 1(t)$: FVT $\Rightarrow C(0) = K = 10^4$



USE LEAD CONTROLLER TO ADD PHASE AT ω_c DESIRED AND ADD $\phi_{max} = 70 - 45 = 35^\circ$

$G_1(s) = \frac{T_1 s + 1}{\alpha_1 T_1 s + 1}$, $\alpha_1 = \frac{1 - \sin \phi_{max}}{1 + \sin \phi_{max}} = 0.4$

$36 = \frac{T_1}{T_1 \sqrt{0.4}}$, $T_1 = 0.04$

$G_1(s) = \frac{0.04s + 1}{0.016s + 1}$

$10 \log \left(\frac{1}{\alpha_2} \right) = 3.98$, $20 \log \left(\frac{1}{\alpha_2} \right) = 7.96$ \leftarrow USE LAG COMPENSATION TO DECREASE GAIN BY 12 dB AT HIGH FREQUENCIES.

$G_2(s) = \frac{T_2 s + 1}{\alpha_2 T_2 s + 1}$, $\alpha_2 > 1$

$-20 \log(\alpha_2) = -12 \text{ dB}$, $\alpha_2 = 4$

$\frac{1}{T_2} = 0.1 \omega_c$, $T_2 = 0.28$

$G_2(s) = \frac{0.28s + 1}{1.12s + 1}$

$C(s) = K G_1(s) G_2(s)$

6. a) $\omega_c \approx 30 \text{ rad/s} \rightarrow \text{PM} \approx 80^\circ$

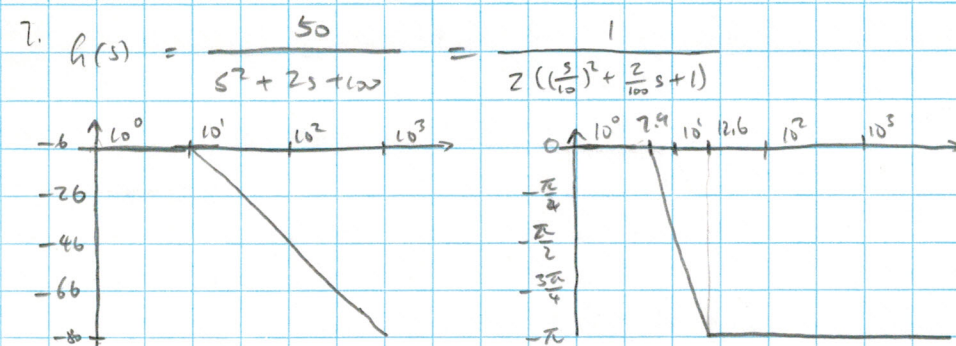
4

b) $C(s) = k \left(\frac{T_1 s + 1}{T_1 s} \right) =$

Pick $k = 1 \Rightarrow C(s) = \frac{T_1 s + 1}{T_1 s}$

$\frac{1}{T_1} = 0.1 \omega_c \rightarrow T_1 = \frac{1}{3} \text{ rad/s}$

$C(s) = 3 \frac{\frac{1}{3} s + 1}{s}$



$\phi_{\max} = 30.3^\circ$

$C_1(s) = k \frac{T_1 s + 1}{\alpha_1 T_1 s + 1} \quad \frac{1}{T_1} = 0.1 \omega_c \quad T_1 = 1, \quad \alpha = \frac{1}{100}$

$C_1(s) = \frac{s + 1}{\frac{1}{100} s + 1}$

$C_2(s) = k_2 \frac{T_2 s + 1}{\alpha_2 T_2 s + 1} \quad \alpha_2 = 20, \quad \frac{1}{T_2} = 0.1 \omega_c = 4.73 \text{ rad/s}$

$C_2(s) = 20 \frac{0.473 s + 1}{20(0.473) s + 1} = 20 \frac{0.473 s + 1}{9.46 s + 1}$

$C(s) = C_1(s) C_2(s) = \left(\frac{s + 1}{\frac{1}{100} s + 1} \right) \left(20 \frac{0.473 s + 1}{9.46 s + 1} \right)$