```
File: MICROS18.c, Date: 17/01/2021, Time: 09:49:47 p. m.
/****************
This program was created by the
CodeWizardAVR V2.60 Evaluation
Automatic Program Generator
© Copyright 1998-2012 Pavel Haiduc, HP InfoTech s.r.l.
http://www.hpinfotech.com
Project :
Version :
Date
Author :
Company :
Comments:
               : ATmega8535L
: Application
Chip type
Program type
AVR Core Clock frequency: 1,000000 MHz
Memory model : Small
External RAM size
                     : 0
Data Stack size
                      : 128
*****************
#include <mega8535.h>
#include <delay.h>
// Alphanumeric LCD functions
#include <alcd.h>
#define cambio PIND.0
#define ha PIND.1
#define mm PIND.2
#define sd PIND.3
float cel;
int tem;
int desplz;
int cont antidelay, time antidelay;
bit btnp,btna;
unsigned char unidades, decenas, decimas, cn, seg=0, min=0, hor=0, dia=25, mes=10, change;
unsigned short ve=19, ar=97;
const char car=48; //codigo ascii
// Declare your global variables here
#define ADC VREF TYPE ((0<<REFS1) | (1<<REFS0) | (1<<ADLAR))
// Read the 8 most significant bits
// of the AD conversion result
unsigned char read adc (unsigned char adc input)
ADMUX=adc input | ADC VREF TYPE;
// Delay needed for the stabilization of the ADC input voltage
delay us(10);
// Start the AD conversion
ADCSRA | = (1 << ADSC);
// Wait for the AD conversion to complete
while ((ADCSRA & (1<<ADIF)) ==0);
ADCSRA | = (1 << ADIF);
return ADCH;
void main(void)
// Declare your local variables here
// Input/Output Ports initialization
// Port A initialization
// Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=In Bit1=In Bit0=In
DDRA=(0<<DDA7) | (0<<DDA6) | (0<<DDA5) | (0<<DDA4) | (0<<DDA3) | (0<<DDA2) | (0<<DDA1) | (0<<DDA1) |
// State: Bit7=T Bit6=T Bit5=T Bit4=T Bit3=T Bit2=T Bit1=T Bit0=T
PORTA=(0<<PORTA7) | (0<<PORTA6) | (0<<PORTA5) | (0<<PORTA4) | (0<<PORTA3) | (0<<PORTA2) | (0<<PORTA1) | (0<<PORTA1) |
// Port B initialization
// Function: Bit7=Out Bit6=Out Bit5=Out Bit4=Out Bit3=Out Bit2=Out Bit1=Out Bit0=Out
DDRB=(1<<DDB7) | (1<<DDB6) | (1<<DDB5) | (1<<DDB4) | (1<<DDB3) | (1<<DDB2) | (1<<DDB1) | (1<<DDB0);
// State: Bit7=0 Bit6=0 Bit5=0 Bit4=0 Bit3=0 Bit2=0 Bit1=0 Bit0=0
```

```
File: MICROS18.c, Date: 17/01/2021, Time: 09:49:47 p. m.
PORTB=(0<<PORTB7) | (0<<PORTB6) | (0<<PORTB5) | (0<<PORTB4) | (0<<PORTB3) | (0<<PORTB2) | (0<<PORTB1) | (0<<PORTB1) |
// Port C initialization
// Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=In Bit1=In Bit0=In
DDRC=(0<<DDC7) | (0<<DDC6) | (0<<DDC5) | (0<<DDC4) | (0<<DDC3) | (0<<DDC2) | (0<<DDC1) | (0<<DDC0);
// State: Bit7=T Bit6=T Bit5=T Bit4=T Bit3=T Bit2=T Bit1=T Bit0=T
PORTC=(0<<PORTC7) | (0<<PORTC6) | (0<<PORTC5) | (0<<PORTC4) | (0<<PORTC3) | (0<<PORTC2) | (0<<PORTC1) | (0<<PORTC1) |
// Port D initialization
// Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=In Bit1=In Bit0=In
DDRD=(0<<DDD7) | (0<<DDD6) | (0<<DDD5) | (0<<DDD4) | (0<<DDD3) | (0<<DDD2) | (0<<DDD1) | (0<<DDD1) |
// State: Bit7=P Bit6=P Bit5=P Bit4=P Bit3=P Bit2=P Bit1=P Bit0=P
PORTD=(1<<PORTD7) | (1<<PORTD6) | (1<<PORTD5) | (1<<PORTD4) | (1<<PORTD3) | (1<<PORTD2) | (1<<PORTD1) | (1<<PORTD1) |
// Timer/Counter 0 initialization
// Clock source: System Clock
// Clock value: Timer 0 Stopped
// Mode: Normal top=0xFF
// OCO output: Disconnected
TCCR0=(0<<WGM00) | (0<<COM01) | (0<<COM00) | (0<<WGM01) | (0<CS02) | (0<<CS01) | (0<CS00);
TCNT0=0x00;
OCR0=0x00;
// Timer/Counter 1 initialization
// Clock source: System Clock
// Clock value: Timer1 Stopped
// Mode: Normal top=0xFFFF
// OC1A output: Disconnected
// OC1B output: Disconnected
// Noise Canceler: Off
// Input Capture on Falling Edge
// Timer1 Overflow Interrupt: Off
// Input Capture Interrupt: Off
// Compare A Match Interrupt: Off
// Compare B Match Interrupt: Off
TCCR1A=(0<<COM1A1) | (0<<COM1A0) | (0<<COM1B1) | (0<<COM1B0) | (0<<WGM11) | (0<<WGM10);
TCCR1B=(0<<ICNC1) | (0<<ICES1) | (0<<WGM13) | (0<<WGM12) | (0<<CS12) | (0<<CS11) | (0<<CS10);
TCNT1H=0\times00:
TCNT1L=0x00;
ICR1H=0 \times 00;
ICR1L=0 \times 00;
OCR1AH=0x00:
OCR1AL=0x00;
OCR1BH=0\times00:
OCR1BL=0 \times 00;
// Timer/Counter 2 initialization
// Clock source: System Clock
// Clock value: Timer2 Stopped
// Mode: Normal top=0xFF
// OC2 output: Disconnected
ASSR=0<<AS2;
TCCR2=(0<<WGM20) | (0<<COM21) | (0<<COM20) | (0<<WGM21) | (0<CS22) | (0<<CS21) | (0<CS20);
TCNT2=0x00;
OCR2=0x00;
// Timer(s)/Counter(s) Interrupt(s) initialization
TIMSK=(0<<OCIE2) | (0<<TOIE2) | (0<<TICIE1) | (0<<OCIE1A) | (0<<OCIE1B) | (0<<TOIE1) | (0<<COCIE0) | (0<<TOIE0);
// External Interrupt(s) initialization
// INTO: Off
// INT1: Off
// INT2: Off
MCUCR=(0<<ISC11) | (0<<ISC10) | (0<<ISC01) | (0<<ISC00);
MCUCSR = (0 << ISC2);
// USART initialization
// USART disabled
UCSRB=(0<<RXCIE) | (0<<TXCIE) | (0<<UDRIE) | (0<<RXEN) | (0<<TXEN) | (0<UCSZ2) | (0<<RXB8) | (0<<TXB8);
// Analog Comparator initialization
// Analog Comparator: Off
ACSR=(1<<ACD) | (0<<ACBG) | (0<<ACO) | (0<<ACI) | (0<<ACIE) | (0<<ACIC) | (0<<ACIS1) | (0<<ACIS1) |
// ADC initialization
// ADC Clock frequency: 500,000 kHz
// ADC Voltage Reference: AVCC pin
// ADC High Speed Mode: Off
// ADC Auto Trigger Source: ADC Stopped
// Only the 8 most significant bits of
// the AD conversion result are used
```

```
File: MICROS18.c, Date: 17/01/2021, Time: 09:49:47 p. m.
ADMUX=ADC VREF TYPE;
ADCSRA=(1-<ADEN) | (0<ADSC) | (0<ADATE) | (0<ADIF) | (0<ADIE) | (0<ADIE) | (0<ADPS2) | (0<ADPS1) | (1<ADPS0);
SFIOR=(1<<ADHSM) | (0<<ADTS2) | (0<<ADTS1) | (0<<ADTS0);
// SPI initialization
// SPI disabled
SPCR=(0<<SPIE) | (0<<SPE) | (0<<DORD) | (0<<MSTR) | (0<<CPOL) | (0<<CPHA) | (0<<SPR1) | (0<<SPR0);
// TWI initialization
// TWI disabled
TWCR=(0<<TWEA) | (0<<TWSTA) | (0<<TWSTO) | (0<<TWEN) | (0<<TWIE);
// Alphanumeric LCD initialization
// Connections are specified in the
// Project|Configure|C Compiler|Libraries|Alphanumeric LCD menu:
// RS - PORTB Bit 0
// RD - PORTB Bit 1
// EN - PORTB Bit 2
// D4 - PORTB Bit 4
// D5 - PORTB Bit 5
// D6 - PORTB Bit 6
// D7 - PORTB Bit 7
// Characters/line: 16
lcd init(16);
desplz=0;
cont_antidelay=0;
time antidelay=20;
while (1)
            delay ms(1);
            if(cambio==0)
                btna=0;
                else
                htna=1:
            if((btnp==1) &&(btna==0)) {
            if(change==0) {
            change=1;
              change=0;
            btnp=btna;
          lcd_gotoxy(11,0);
          lcd putsf("ESCOM");
          cn=read adc(0);
          cel=cn*\overline{1.45};
          if(cel>99)
          cel=99;
          tem=cel*10;
          decenas=tem/100;
          tem%=100;
          decimas=tem%10;
          unidades=tem/10;
          lcd gotoxy(10,1);
          lcd putchar(decenas+car);
          lcd_gotoxy(11,1);
          lcd putchar(unidades+car);
          lcd gotoxy(12,1);
          lcd_putchar('.');
          lcd_gotoxy(13,1);
          lcd putchar(decimas+car);
          lcd gotoxy(14,1);
          lcd_putchar(car+175);
          lcd gotoxy(15,1);
          lcd putchar('C');
                if(change==1) {
            if(ha==0){
            if(cont antidelay>time antidelay) {
```

File: MICROS18.c, Date: 17/01/2021, Time: 09:49:47 p. m. cont antidelay=0;hor++; }else{ cont antidelay++; **if** (mm==0) { if(cont antidelay>time antidelay) { cont_antidelay=0;min++; }else{ cont_antidelay++; **if**(sd==0){ if(cont antidelay>time antidelay){ cont antidelay=0;seg++; }else{ cont antidelay++; }else{ **if**(ha==0){ if(cont antidelay>time antidelay) { cont antidelay=0; ar++; **if**(ar>99){ ye++; ar=0; }else{ cont antidelay++; **if** (mm==0) { if(cont_antidelay>time_antidelay) { cont_antidelay=0; mes++; }else{ cont_antidelay++; **if**(sd==0){ if(cont antidelay>time antidelay) { cont antidelay=0; dia++; }else{ cont antidelay++; if(desplz>49) { desplz=0;seg++; }else{ desplz++; **if**(seg>59){ min++; seg=0;**if**(min>59) { hor++; min=0;seg=0;**if**(hor>23){ dia++; hor=0;seg=0;min=0;

if (dia>31) {
mes++;
dia=0;

if(mes>12){ ar++;

```
File: MICROS18.c, Date: 17/01/2021, Time: 09:49:47 p. m.
        if(ar>99){
        ye++;
        ar=0;
         lcd_gotoxy(0,1);
        lcd_putchar(hor/10+car);
        lcd_gotoxy(1,1);
lcd_putchar(hor%10+car);
        lcd gotoxy(2,1);
        lcd putchar(':');
        lcd_gotoxy(3,1);
        lcd putchar(min/10+car);
        lcd\_gotoxy(4,1);
        lcd putchar(min%10+car);
        lcd gotoxy(5,1);
        lcd_putchar(':');
        lcd gotoxy(6,1);
        lcd putchar(seg/10+car);
        lcd_gotoxy(7,1);
        lcd_putchar(seg%10+car);
        lcd gotoxy(0,0);
        lcd_putchar(ye/10+car);
lcd_gotoxy(1,0);
        lcd_putchar(ye%10+car);
        lcd gotoxy(2,0);
        lcd_putchar(ar/10+car);
        lcd_gotoxy(3,0);
        lcd putchar(ar%10+car);
        lcd gotoxy(4,0);
        lcd_putchar('-');
        lcd gotoxy(5,0);
        lcd putchar(mes/10+car);
        lcd\_gotoxy(6,0);
        lcd_putchar(mes%10+car);
        lcd_gotoxy(7,0);
lcd_putchar('-');
        lcd gotoxy(8,0);
        lcd_putchar(dia/10+car);
lcd_gotoxy(9,0);
        lcd putchar(dia%10+car);
     }
```

}