Image Processing mini project

Diagonal Edge Detection in C++

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Task definition

The theme for the 3rd semester of Medialogy is Visual Computing. Here subjects about how humans and machines perceive images were taught. In the course **Image Processing** it was shown how it is possible to process and manipulate digital images in theory and concept, while the course **Procedural Programming** was about learning the `C++` programming language, as well as the OpenCV framework. To apply the knowledge about image processing in practice, each student were tasked with writing a small program that could process an image in a certain way. Everything should be implemented from scratch; OpenCV should only be used to load in an image and nothing more.

Each mini project was meant as an individual task, and everybody in the group received a different task. The following is the description of the task I received.

> Topic #5: Diagonal Edge Detection
> Make a C/C++ program that can find diagonal edges in an image.
> Input: Greyscale image Output: Binary image where the diagonal edges are white (255) and the rest of the pixels black (0)

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Theory about edge Detection 1

1.1 Edge definition

An edge in an image is basically a place in an image where there is a contrast between two points.

Block [2007] describes an edge as the apparent line around the borders of a two-dimensional object.

Another definition is given by [Moeslund, 2012] who writes that an edge in an image is defined as a position where there is a significant change in gray-level values.

1.2 Edge detection

An edge in a gray scale image occurs when there is a transition in gray level over an amount of pixels. A perfect edge would be a transition from black to white over one pixel as shown on figure 1. In many images, edges like these wont occur (unless itâĂŹs a binary image). The transition will be blurred spreading the transition over more pixels, resulting in a slope-like profile of the gray level transition seen on figure 2. Here the edge is spread over more pixels and will show as a wider edge instead of the 1-pixel transition that shows as a 1-pixel edge. We might say the thickness of the edge is defined by the length of the ramp that in the gray level profile.[1]

[1] FiXme Note: DETTE SKAL SKRIVES SELV!!

The code 2

```
1  #include <opencv2/highgui/highgui.hpp>
2  #include <iostream>
3
4  using namespace cv;
5  using namespace std;
6
7  enum SobelDirection
8  {
9    Diagonal_Right,
10   Diagonal_Left,
11   Vertical,
12   Horizontal
13 };
14
15 const int THRESHOLD_GRAYSCALE = 133; // optimal value was found using ImageJ
16 const int THRESHOLD_SOBEL = 30; // found by experimenting
17
18 Mat ConvertColorImageToBlackWhite(Mat colorImage);
19 Mat MeanFilter(Mat input);
20 Mat ThresholdBlackWhiteImage(Mat blackWhiteImage, int threshold);
21 Mat SobelEdgeDetecting(Mat input, enum SobelDirection direction, bool useMeanFilterBeforeDoingEdgeDetecting, int threshold);
22 Mat AddTwoMatsTogether(Mat matA, Mat matB);
23 void SortValues(uchar* a, int size);
24
25
26
27 int main()
28 {
29   cout << "Edge detection using the Sobel kernel (and OpenCV to load images)" << endl;
30   cout << "By Gustav Dahl - Medialogy 3rd semester 2012 - Aalborg University\n\n";
31   // Load the image
32     Mat colorImage = imread("building.jpg");
33     if (colorImage.empty())
34     {
35         cout << "Cannot load image!" << endl;
36         return -1;
37     }
```

```
38
39  cout << "Processing image. Please wait..." << endl;
40
41  // Convert to black-white
42  Mat gray = ConvertColorImageToBlackWhite(colorImage);
43  cv::imwrite("grayscale.jpg", gray);
44
45  // Mean (black and white only)
46  Mat mean = MeanFilter(gray);
47  imwrite("mean.jpg", mean);
48
49  // Threshold
50  Mat threshold = ThresholdBlackWhiteImage(gray, THRESHOLD_GRAYSCALE)↩
        ;
51  imwrite("threshold.jpg", threshold);
52
53  // Edge detecting
54  Mat edge_diagonal_right = SobelEdgeDetecting(gray, Diagonal_Right, ↩
        true, THRESHOLD_SOBEL);
55  Mat edge_diagonal_left = SobelEdgeDetecting(gray, Diagonal_Left, ↩
        true, THRESHOLD_SOBEL);
56  Mat edge_vertical = SobelEdgeDetecting(gray, Vertical, true, ↩
        THRESHOLD_SOBEL);
57  Mat edge_horizontal = SobelEdgeDetecting(gray, Horizontal, true, ↩
        THRESHOLD_SOBEL);
58
59  Mat verti_plus_horiz = AddTwoMatsTogether(edge_vertical, ↩
        edge_horizontal);
60  Mat diagonal_right_plus_left = AddTwoMatsTogether(↩
        edge_diagonal_right, edge_diagonal_left);
61  Mat diagonal_plus_vertical_horizontal = AddTwoMatsTogether(↩
        verti_plus_horiz, diagonal_right_plus_left);
62
63  imwrite("diagonal_right.jpg", edge_diagonal_right);
64  imwrite("edge_diagonal_left.jpg", edge_diagonal_right);
65  imwrite("edge_vertical.jpg", edge_vertical);
66  imwrite("edge_horizontal.jpg", edge_horizontal);
67  imwrite("verti_plus_horiz.jpg", verti_plus_horiz);
68  imwrite("diagonal_right_plus_left.jpg", diagonal_right_plus_left);
69  imwrite("diagonal_plus_vertical_horizontal.jpg", ↩
        diagonal_plus_vertical_horizontal);
70
71    cv::imshow("Original image", colorImage);
72  cv::imshow("Grayscale image", gray);
73  cv::imshow("Mean filter", mean);
74  cv::imshow("Binary image", threshold);
75  cv::imshow("Edge diagonal right", edge_diagonal_right);
76  cv::imshow("Edge diagonal left", edge_diagonal_left);
77  cv::imshow("Edge vertical", edge_vertical);
78  cv::imshow("Edge horizontal", edge_horizontal);
79  cv::imshow("Diagonal plus vertical and horizontal", ↩
        diagonal_plus_vertical_horizontal);
```

```
80
81      waitKey(0);
82  }
83
84  Mat ConvertColorImageToBlackWhite(Mat colorImage)
85  {
86    // Mat(rows, columns, type)
87    // rows = y = 300
88    // cols = x = 600
89
90    Mat grayScaleImage(colorImage.rows, colorImage.cols, CV_8UC1); // ↩
        new image with only 1 channel
91
92    // Formula for converting from color to grayscale (3.3, p. 30 in ↩
        Introduction to Video and Image Processing book)
93    // I = weightR * R + weightG * G + weightB * B
94
95    // Common weight values used in TV production to calculate to ↩
        grayscale
96    float RedWeight = 0.299;
97    float GreenWeight = 0.587;
98    float BlueWeight = 0.114;
99
100
101   // Iterate through all the pixels and apply the formula for ↩
        grayscale
102   for (int y = 0; y < colorImage.rows; y++) // rows
103   {
104     for (int x = 0; x < colorImage.cols; x++)
105     {
106       // Calculate grayscale value
107       int grayValue = colorImage.at<cv::Vec3b>(y, x)[0] * BlueWeight
108         + colorImage.at<cv::Vec3b>(y, x)[1] * GreenWeight
109         + colorImage.at<cv::Vec3b>(y, x)[2] * RedWeight;
110
111       // Apply the grayscale value (0-255)
112       grayScaleImage.at<uchar>(y, x) = grayValue;
113
114     }
115   }
116   return grayScaleImage;
117 }
118
119 Mat MeanFilter(Mat input)
120 {
121   // 3x3 kernel size
122
123   Mat mean = input.clone();
124
125   // Loop through all pixels
126   for (int y = 0; y < input.rows-2; y++)
127   {
```

```
128     for (int x = 0; x < input.cols-2; x++)
129     {
130       if (x - 2 < 0 || y - 2 < 0) // don't go out of bounds
131         continue;
132 
133       mean.at<uchar>(y, x) = (
134         input.at<uchar>(y-2, x-2) + input.at<uchar>(y-2, x-1)
135         + input.at<uchar>(y-2, x) + input.at<uchar>(y-2, x+1)
136         + input.at<uchar>(y-2, x+2) + input.at<uchar>(y-1, x-2)
137         + input.at<uchar>(y-1, x-1) + input.at<uchar>(y-1, x)
138         + input.at<uchar>(y-1, x+1) + input.at<uchar>(y-1, x+2)
139         + input.at<uchar>(y, x-2) + input.at<uchar>(y, x-1)
140         + input.at<uchar>(y, x) + input.at<uchar>(y, x+1)
141         + input.at<uchar>(y, x+2) + input.at<uchar>(y+1, x-2)
142         + input.at<uchar>(y+1, x-1) + input.at<uchar>(y+1, x)
143         + input.at<uchar>(y+1, x+1) + input.at<uchar>(y+1, x+2)
144         + input.at<uchar>(y+2, x-2) + input.at<uchar>(y+2, x-1)
145         + input.at<uchar>(y+2, x) + input.at<uchar>(y+2, x+1)
146         + input.at<uchar>(y+2, x+2)
147         ) / 25;
148     }
149   }
150 
151   return mean;
152 }
153 
154 Mat ThresholdBlackWhiteImage(Mat blackWhiteImage, int threshold)
155 {
156   Mat image = blackWhiteImage.clone();
157 
158   // Loop through all pixels and set them to either 255 (white) or 0 ↩
        (black) using the threhold value
159   for (int y = 0; y < image.rows; y++)
160   {
161     for (int x = 0; x < image.cols; x++)
162     {
163       if (image.at<uchar>(y, x) >= threshold)
164         image.at<uchar>(y, x) = 255;
165       else
166         image.at<uchar>(y, x) = 0;
167     }
168   }
169 
170   return image;
171 }
172 
173 Mat SobelEdgeDetecting(Mat input, enum SobelDirection direction, bool↩
      useMeanFilterBeforeDoingEdgeDetecting, int threshold)
174 {
175   Mat edge = input.clone();
176 
177   if (useMeanFilterBeforeDoingEdgeDetecting)
```

```
178     edge = MeanFilter(edge);
179
180   // Apply diagonal edge detecting RIGHT
181   if (direction == Diagonal_Right)
182   {
183     for (int y = 0; y < input.rows-1; y++)
184     {
185       for (int x = 0; x < input.cols-1; x++)
186       {
187         if (x-1 < 0 || y-1 < 0) // don't go out of bounds
188           continue;
189
190
191         // temp value is used to not get overflow (value cannot be ↩
                less than 0 or greater than 255)
192         int temp = (
193           (input.at<uchar>(y-1, x-1)) * -2
194           + (input.at<uchar>(y, x-1)) * -1
195           + (input.at<uchar>(y+1, x-1)) * 0
196           + (input.at<uchar>(y-1, x)) * -1
197           + (input.at<uchar>(y, x)) * 0
198           + (input.at<uchar>(y+1, x+0)) * 1
199           + (input.at<uchar>(y-1, x+1)) * 0
200           + (input.at<uchar>(y, x+1)) * 1
201           + (input.at<uchar>(y+1, x+1)) * 2
202           );
203
204
205         // Map values from 0 to 255
206         if (temp < 0)
207           temp = 0;
208         else if (temp > 255)
209           temp = 255;
210
211
212         edge.at<uchar>(y, x) = temp;
213       }
214     }
215   }
216   else if (direction == Diagonal_Left)
217   { // Apply diagonal edge detecting LEFT
218     for (int y = 0; y < input.rows-1; y++)
219     {
220       for (int x = 0; x < input.cols-1; x++)
221       {
222         if (x-1 < 0 || y-1 < 0) // don't go out of bounds
223           continue;
224
225         // temp value is used to not get overflow (value cannot be ↩
                less than 0 or greater than 255)
226         int temp = (
227           (input.at<uchar>(y-1, x-1)) * -2
```

```
228           + (input.at<uchar>(y, x-1)) * -1
229           + (input.at<uchar>(y+1, x-1)) * 0
230           + (input.at<uchar>(y-1, x)) * -1
231           + (input.at<uchar>(y, x)) * 0
232           + (input.at<uchar>(y+1, x+0)) * 1
233           + (input.at<uchar>(y-1, x+1)) * 0
234           + (input.at<uchar>(y, x+1)) * 1
235           + (input.at<uchar>(y+1, x+1)) * 2
236           );
237
238         // Map values from 0 to 255
239         if (temp < 0)
240           temp = 0;
241         else if (temp > 255)
242           temp = 255;
243
244
245         edge.at<uchar>(y, x) = temp;
246       }
247     }
248   }
249   else if (direction == Vertical)
250   {
251     // Apply diagonal edge detecting tVERTICAL
252     for (int y = 0; y < input.rows-1; y++)
253     {
254       for (int x = 0; x < input.cols-1; x++)
255       {
256         if (x-1 < 0 || y-1 < 0) // don't go out of bounds
257           continue;
258
259         // temp value is used to not get overflow (value cannot be ↩
               less than 0 or greater than 255)
260         int temp = (
261           (input.at<uchar>(y-1, x-1)) * -1
262           + (input.at<uchar>(y, x-1)) * -2
263           + (input.at<uchar>(y+1, x-1)) * -1
264           + (input.at<uchar>(y-1, x)) * -0
265           + (input.at<uchar>(y, x)) * 0
266           + (input.at<uchar>(y+1, x+0)) * 0
267           + (input.at<uchar>(y-1, x+1)) * 1
268           + (input.at<uchar>(y, x+1)) * 2
269           + (input.at<uchar>(y+1, x+1)) * 1
270           );
271
272         // Map values from 0 to 255
273         if (temp < 0)
274           temp = 0;
275         else if (temp > 255)
276           temp = 255;
277
278
```

```
279         edge.at<uchar>(y, x) = temp;
280       }
281     }
282   }
283   else if (direction == Horizontal)
284   {
285     // Apply diagonal edge detecting HORIZONTAL
286     for (int y = 0; y < input.rows-1; y++)
287     {
288       for (int x = 0; x < input.cols-1; x++)
289       {
290         if (x-1 < 0 || y-1 < 0) // don't go out of bounds
291           continue;
292 
293         // temp value is used to not get overflow (value cannot be ↩
               less than 0 or greater than 255)
294         int temp = (
295           (input.at<uchar>(y-1, x-1)) * -1
296           + (input.at<uchar>(y, x-1)) * 0
297           + (input.at<uchar>(y+1, x-1)) * 1
298           + (input.at<uchar>(y-1, x)) * -2
299           + (input.at<uchar>(y, x)) * 0
300           + (input.at<uchar>(y+1, x+0)) * 2
301           + (input.at<uchar>(y-1, x+1)) * -1
302           + (input.at<uchar>(y, x+1)) * 0
303           + (input.at<uchar>(y+1, x+1)) * 1
304           );
305 
306         // Map values from 0 to 255
307         if (temp < 0)
308           temp = 0;
309         else if (temp > 255)
310           temp = 255;
311 
312 
313         edge.at<uchar>(y, x) = temp;
314       }
315     }
316   }
317   else
318   {
319     // Error text
320     putText(edge, "ERROR - Sobel type not defined!", Point(10, 50), ↩
          FONT_HERSHEY_PLAIN, 2, Scalar(0, 0, 255), 4, 8, false);
321     putText(edge, "ERROR - Sobel type not defined!", Point(10, 150), ↩
          FONT_HERSHEY_PLAIN, 2, Scalar(0, 0, 255), 4, 8, false);
322     putText(edge, "ERROR - Sobel type not defined!", Point(10, 250), ↩
          FONT_HERSHEY_PLAIN, 2, Scalar(0, 0, 255), 4, 8, false);
323     putText(edge, "ERROR - Sobel type not defined!", Point(10, 300), ↩
          FONT_HERSHEY_PLAIN, 2, Scalar(0, 0, 0), 4, 8, false);
324     putText(edge, "ERROR - Sobel type not defined!", Point(10, 450), ↩
          FONT_HERSHEY_PLAIN, 2, Scalar(0, 0, 0), 4, 8, false);
```

```
325     putText(edge, "ERROR - Sobel type not defined!", Point(10, 600), ↩
            FONT_HERSHEY_PLAIN, 2, Scalar(0, 0, 0), 4, 8, false);
326   }
327
328   // Threshold
329   edge = ThresholdBlackWhiteImage(edge, 30);
330   return edge;
331 }
332
333 Mat AddTwoMatsTogether(Mat matA, Mat matB) // should be same size!
334 {
335   Mat output = matA.clone();
336
337   for (int y = 0; y < matA.rows; y++)
338   {
339     for (int x = 0; x < matA.cols; x++)
340     {
341       output.at<uchar>(y, x) = matA.at<uchar>(y, x) + matB.at<uchar>(↩
              y, x);
342     }
343
344   }
345
346   output = ThresholdBlackWhiteImage(output, THRESHOLD_GRAYSCALE);
347   return output;
348 }
349
350 // Not working yet
351 /*void MedianFilter(Mat input, int kernelSize)
352 {
353   if (kernelSize % 2 == 0) // don't use even numbers
354     kernelSize++;
355
356   int radius = kernelSize / 2; // e.g. kernel is 7X7 --> radius is 3
357
358   uchar neighborPixels[9];
359
360   for (int y = radius; radius < (input.rows - radius); y++)
361   {
362     int counter = 0;
363     for (int x = radius; x < (input.cols - radius); x++)
364     {
365       // Done
366       if (counter >= 9)
367       {
368         //start sort
369         // put pixels back in
370       }
371       neighborPixels[x*y] = input.at<uchar>(y, x);
372       counter++;
373     }
374   }
```

```
}*/

// Not working yet
/*uchar* SortValues(uchar* a, int size)
{
  cout << "Before the bubblesort:" << endl;
  for (int i = 0; i < size; i++)
    cout << a[i] << endl;

  // Bubble list
  bool swapped = true;

  while (swapped)
  {
    swapped = false;
    for (int i = 1; i < size; i++)
    {
      if (a[i-1] > a[i])
      {
        // Sort numbers
        int temp = a[i-1];
        a[i-1] = a[i];
                a[i] = temp;

                swapped = true;
      }
    }
  }

  cout << "After the bubblesort:" << endl;
  for (int i = 0; i < size; i++)
    cout << a[i] << endl;

  uchar* aPointer = a;
  //return aPointer;
}*/
```

Bibliography

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Moeslund, **2012**. Thomas B. Moeslund. *Introduction to Video and Image Processing - Building real systems and applications*. ISBN: 978-1447125020, Handbook. Springer, 2012.