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Theorem 4.1. If f is convex and differentiable, and C is a convex set, then any optimal solution x^* to $\min_{x \in C} f(x)$ must satisfy $-\nabla f(x^*) \in N_C(x^*)$.

Theorem 4.2. The set of optimal solutions to a convex optimization problem is a convex set.

Definition 4.3. If C is convex then

1. **Translation:** $C + a = \{x : x - a \in C\}$
2. **Scaling:** $\alpha C = \{x : \frac{x}{\alpha} \in C\}$
3. **Intersection:** If $\{C_\alpha\}_{\alpha \in A}$ is a collection of convex sets, then $\bigcap_{\alpha \in A} C_\alpha$ is convex.

Theorem 4.4. The following are true:

1. If $C \subseteq \mathbb{R}^n$ is convex, $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$, then $AC + b = \{Ax + b : x \in C\}$ is a convex set.
2. If $f(x) = Ax + b$, then $f^{-1}(C)$ is convex.
3. $C_1 + C_2 = \{x + y : x \in C_1, y \in C_2\}$ is convex.
4. If $C_1 \subseteq \mathbb{R}^m$, $C_2 \subseteq \mathbb{R}^n$ then $C_1 \times C_2 = \{(x, y) \in \mathbb{R}^{m+n} : x \in C_1, y \in C_2\}$ is convex.
5. For any $C \subseteq \mathbb{R}^n \times \mathbb{R}_{>0}^m$, define

$$P(C) = \left\{ \left(\frac{x_1}{t}, \dots, \frac{x_n}{t} \right) : (x_1, \dots, x_n, t) \in C \right\}$$

If C is convex, so are $P(C)$ and $P^{-1}(C)$.

Definition 4.5.

$$\text{epi}(f) = \{(x, t) : x \in \text{dom}(f), t \geq f(x)\}$$

Definition 4.6. First Order Definition of Convexity: If f is differentiable, then f is convex if and only if for all $x, y \in \text{dom}(f)$,

$$f(y) \geq f(x) + \nabla f(x)^T(y - x)$$



Figure 1: First Order Definition of Convexity

Second Order Definition of Convexity: If f is twice differentiable, then f is convex if and only if $\nabla^2 f(x) \succeq 0$.

Definition 4.7. We say $A \succeq B$ if $A - B$ is positive semi-definite. This is equivalent to

$$a^T \nabla^2 f(x) a \geq 0 \quad \text{for all } a \in \mathbb{R}^d$$

Definition 4.8. The *subdifferential* is

$$\partial f(x) = \{g : f(y) \geq f(x) + g^T(y - x), \forall y \in C\}$$

Any such $g \in \partial f(x)$ is called a **subgradient**.

If f is differentiable at x then $\partial f(x) = \{\nabla f(x)\}$.

Theorem 4.9. f is convex if and only if ∂f is non-empty.

5 Jan 27

Definition 5.1. *Gradient Monotonicity:* If f is differentiable, then f is convex if and only if $\nabla f(x)$ is monotone. So we can conclude

$$(\nabla f(x) - \nabla f(y))^T(x - y) \geq 0 \iff f \text{ is convex.}$$

Theorem 5.2. For a $A \in \mathbb{R}^{m \times n}$ we can decompose

$$A = U \sum V^T.$$

where $U \in \mathbb{R}^{m \times k}$ with orthonormal column, $\sigma \in \mathbb{R}^{k \times k}$ is a diagonal matrix with non-negative entries, and $V \in \mathbb{R}^{n \times k}$ with orthonormal column.

Definition 5.3. (u_i, v_i, σ_i) form a s.v. triplet if $Av_i = \sigma_i u_i$ and $A^T u_i = \sigma_i v_i$ $\|u_i\| = \|v_i\| = 1$ and $\sigma_i \geq 0$

Theorem 5.4. For any $A \in \mathbb{R}^{n \times n}$ then $A^T A$ is always positive semi definite

Proof. We can write $A = V \sum U$ then $A^T A = V \sum U^T U \sum V^T = V \sum^2 V^T$ □

Definition 5.5. *Spectral Radius:* $\max_i \{|\lambda_i| : \lambda_i \in \Lambda(A)\} = \rho(A)$

Definition 5.6. The norm must satisfy the following properties:

1. $\|A\| \geq 0$
2. $\|\alpha A\| = |\alpha| \|A\|$
3. $\|A\| = 0$ if and only if $A = 0$
4. $\|A + A'\| \leq \|A\| + \|A'\|$

Definition 5.7. *Operator/Spectral Norm:*

$$\|A\|_{op} = \|A\|_2 = \max_{\|x\|=1} \|Ax\|_2.$$

Definition 5.8. *Frobenius Norm:*

$$\|A\|_F = \sqrt{\sum_{i,j} A_{ij}^2}.$$

Definition 5.9. f is L -Lipschitz if

$$|f(x) - f(y)| \leq L \|x - y\|_2 \quad \forall x, y \in \text{dom}(f).$$

If f is differentiable then f is L -Lipschitz if and only if $|\nabla f| \leq L$

Definition 5.10. Differentiable f is β -smooth if

$$\|\nabla f(x) - \nabla f(y)\|_2 \leq \beta \|x - y\|_2 \quad \forall x, y \in \text{dom}(f).$$

If f is twice differentiable then f is β -smooth if and only if $\nabla^2 f(x) \preceq \beta I$.

Theorem 5.11. If f is twice differentiable and β -smooth then

$$f(y) \leq f(x) + \nabla f(x)^T(y - x) + \frac{\beta}{2} \|y - x\|_2^2 \quad \forall x, y \in \text{dom}(f).$$

6 Feb 3

Definition 6.1. "Descent Direction" any h for which $f(x + \eta h) \leq f(x)$.

Theorem 6.2. Assume f differentiable and β -smooth with $x_{t+1} \leftarrow x_t - \eta \nabla f(x_t)$.

1. If $\eta \leq \frac{2}{\beta}$ then $f(x_{t+1}) \leq f(x_t)$
2. If $\eta \leq \frac{1}{\beta}$ then $f(x_{t+1}) \leq f(x_t) - \frac{\eta}{2} \|\nabla f(x_t)\|_2^2$

Proof. Recall

$$f(y) \leq f(x) + \nabla f(x)^T(y - x) + \frac{\beta}{2} \|y - x\|_2^2.$$

and

$$\|\nabla f(y) - \nabla f(x)\|_2 \leq \beta \|y - x\|_2.$$

Let $y \leftarrow x + h$ then $f(x + h) \leq f(x) + \nabla f(x)^T h + \frac{\beta}{2} \|h\|_2^2$

1. If $h = -\frac{2}{\beta} \nabla f(x)$ then $\nabla f(x)^T h = -\frac{2}{\beta} \|\nabla f(x)\|_2^2$ and $\frac{\beta}{2} \|h\|_2^2 = \frac{2}{\beta} \|\nabla f(x)\|_2^2$ so $f(x + h) \leq f(x)$
2. If $h = -\frac{1}{\beta} \nabla f(x)$ then $\nabla f(x)^T h = -\frac{1}{\beta} \|\nabla f(x)\|_2^2$ and $\frac{\beta}{2} \|h\|_2^2 = \frac{1}{2\beta} \|\nabla f(x)\|_2^2$.

□

Theorem 6.3. If f is differentiable, β smooth, and x^* be any optimizer. For any $k > 0$

$$\min_{i=0, \dots, k} \|\nabla f(x_i)\|_2 \leq \sqrt{\frac{2\beta}{k} \left(\underbrace{f(x_0) - f(x^*)}_{\Delta_0} \right)}.$$

Proof. AFSOC $\forall i \in \{0, \dots, k\}$, $\|\nabla f(x_i)\|_2 > \sqrt{\frac{2\beta}{k} \Delta_0}$ Then we have

$$f(x_{i+1}) < f(x_i) - \frac{1}{2\beta} \left(\frac{2\beta \Delta_0}{k} \right). \quad (\forall i \in \{0, \dots, k\})$$

Continuing down the chain we have

$$f(x_{k+1}) < f(x_0) - \Delta_0 < f(x^*).$$

Thus a contradiction. □

Theorem 6.4. If f is β -smooth and convex, $\eta = \frac{1}{\beta}$ and x^* any minimum then

$$f(x_k) - f(x^*) \leq \frac{\beta \|x_0 - x^*\|_2^2}{2k}.$$

Proof. Observe that

$$\|x_{t+1} - x^*\|^2 = \|x_t - x^* - \eta \nabla f(x_t)\|^2 = \|x_t - x^*\|^2 - \eta^2 \|\nabla f(x_t)\|^2 - 2\eta \nabla f(x_t)^T (x_t - x^*).$$

Rearranging and by convexity we have

$$\begin{aligned} f(x_t) - f(x^*) &\leq \nabla f(x_t)^T (x_t - x^*) = \frac{1}{2\eta} \left[\underbrace{\|x_t - x^*\|^2}_{\delta_t} - \underbrace{\|x_{t+1} - x^*\|^2}_{\delta_{t+1}} + \frac{\eta}{2} \|\nabla f(x_t)\|^2 \right] \\ &\leq \frac{1}{2\eta} [\delta_t - \delta_{t+1} + 2\eta(f(x_t) - f(x_{t+1}))] \\ &= \frac{1}{2\eta} (\delta_t - \delta_{t+1}) + f(x_t) - f(x_{t+1}) \end{aligned}$$

So we have

$$f(x_{t+1}) - f(x^*) \leq \frac{\beta}{2} (\delta_t - \delta_{t+1}).$$

Adding across all terms

$$\sum_{i=0}^{k-1} f(x_{i+1}) - f(x^*) \leq \frac{\beta}{2} (\|x_0 - x^*\|^2).$$

So we have the relation

$$k(f(x_k) - f(x^*)) \leq \sum_{i=0}^{k-1} f(x_{i+1}) - f(x^*) \leq \frac{\beta}{2} \|x_0 - x^*\|^2.$$

□

Definition 6.5. f is α -strongly convex if

$$f(tx + (1-t)y) \leq tf(x) + (1-t)f(y) - \frac{\alpha}{2}t(1-t)\|x - y\|_2^2.$$

Additionally, if f is differentiable then

$$f(y) \geq f(x) + \nabla f(x)^T(y - x) + \frac{\alpha}{2}\|y - x\|_2^2.$$

If f is twice differentiable then f is α -strongly convex if and only if $\nabla^2 f(x) \succeq \alpha I$.

Theorem 6.6. Assume f is β -smooth, α -strongly convex, $\eta = \frac{1}{\beta}$ then $\|x_k - x^*\|^2 \leq \left(1 - \frac{1}{\gamma}\right)^k \|x_0 - x^*\|^2$.

We define the conditional number as $\gamma = \frac{\beta}{\alpha}$

Proof.

$$\frac{\alpha}{2}\|x_k - x^*\|^2 \leq \frac{\beta}{2} (\|x_t - x^*\|^2 - \|x_{t+1} - x^*\|^2) \leq \left(1 - \frac{\alpha}{\beta}\right) \|x_t - x^*\|^2 \leq \left(1 - \frac{1}{\gamma}\right) \|x_k - x^*\|^2.$$

□

7 Feb 5

Recall 7.1. From previous class

1. $f(x + \eta h) \approx f(x) + \eta h^T \nabla f(x)$ and when we set $h = -\nabla f(x)$ we have

$$f(x - \eta \nabla f(x)) \approx f(x) - \eta \|\nabla f(x)\|_2^2.$$

Backtracking Line Search: Pick $\gamma_1 \in (0, 1)$ and $\gamma_2 \in (0, 1)$, start with initial step size η . While $f(x - \eta \nabla f(x)) > f(x) - \gamma_1 \eta \|\nabla f(x)\|_2^2$ (Armijo condition not satisfied), set $\eta \leftarrow \gamma_2 \eta$ and retry. Once the condition is satisfied, use step size η to update $x \leftarrow x - \eta \nabla f(x)$.

Recall 7.2. g is a subgradient of f at x if

$$f(y) \geq f(x) + g^T(y - x) \quad \forall y \in \text{dom}(f).$$

Lemma 7.3. The following are true:

1. $\partial f(x)$ makes sense for non convex functions too, could be empty
2. If f is convex, then for $x \in \text{RelInt}(\text{dom}(f))$ we have that $\partial f(x)$ is non-empty
3. $\partial f(x)$ is a convex
4. If f is convex and differentiable at x then $\partial f(x) = \{\nabla f(x)\}$
5. If $\partial f(x)$ is non-empty everywhere, f is convex.

Theorem 7.4. The following are true:

1. $\partial(af) = a\partial f(x)$
2. $\partial(f + g) = \partial f(x) + \partial g(x)$
3. If $g(x) = f(Ax + b)$ then $\partial g(x) = A^T \partial f(Ax + b)$

Example 7.5. For $f(x) = \max_{i=1, \dots, n} f_i(x)$ we have $\partial f(x) = \text{Conv} \left(\bigcup_{i=1, \dots, n} \partial f_i(x) \right)$

Example 7.6. For $f(x) = |x|$ we have $\partial f(x) = \text{sign}(x) = \max -x, x$ so $\partial f(0) = [-1, 1]$.

Example 7.7. Let C be a convex set and $I_C(x) = \begin{cases} 0 & x \in C \\ \infty & x \notin C \end{cases}$ is convex. Additionally, for $x \in C$, $\partial I_C(x) = N_C(x) = \{g : g^T(y - x) \leq 0 \forall y \in C\}$

Proof. For $x \in C$, $I_C(y) \geq I_C(x) + g^T(y - x)$ for all $y \in C$ then we have

$$0 \geq 0 + g^T(y - x).$$

□

Definition 7.8. Subgradient Method: $x_{t+1} \leftarrow x_t - \eta g_x$ for some $g_x \in \partial f(x)$

1. Subgradients are in general not descent directions
2. The min norm subgradient is a descent direction

Example 7.9. $f(x) = \|x\|_2 = \sqrt{\sum_{i=1}^n x_i^2}$ is convex, then for $x \neq 0$ we have $\partial f(x) = \frac{x}{\|x\|_2}$.

$$\partial f(0) = \{g : \|g\|_2 \leq 1\}.$$

8 Feb 10

Definition 8.1. For the subgradient method for $\min_{x \in \mathbb{R}^n} f(x)$ and f convex where

$$x_{t+1} = x_t - \eta_t g_t \text{ where } g_t \in \partial f(x_t).$$

We define the best iterate as

$$x_T^{(\text{best})} = \arg \min_{i=0, \dots, T} f(x_i).$$

Theorem 8.2. Assume f is G -lipschitz and convex. Let $\|x_0 - x^*\| \leq R$ then pick

$$\eta_t = \frac{R}{G\sqrt{T}} \text{ guarantees that } f(x_T^{(\text{best})}) - f(x^*) \leq \frac{GR}{\sqrt{T}}.$$

Theorem 8.3. A convex function f is G -lipschitz iff

$$\|g_x\| \leq G \quad \forall x \in \text{dom}(f) \text{ and } \forall g_x \in \partial f(x).$$

Theorem 8.4. For nonconvex, differentiable f , f being G -lipschitz iff

$$\|\nabla f(x)\| \leq G \quad \forall x \in \text{dom}(f).$$

Theorem 8.5. Assume f is convex and G -Lipschitz, and that an optimal solution x^* exists with $\|x_0 - x^*\| \leq R$ for some $R > 0$.

Pick $\eta_t \rightarrow 0$ such that $\sum_{t=1}^{\infty} \eta_t = \infty$ and $\sum_{t=1}^T \eta_t^2 < \infty$ then

$$f(x_T^{(\text{best})}) \rightarrow f(x^*) \text{ as } T \rightarrow \infty.$$

Theorem 8.6. For the subgradient method with step sizes $\{\eta_t\}_{t=1}^T$ on a convex, G -Lipschitz function f , we have

$$f(x_T^{(\text{best})}) - f(x^*) \leq \frac{\|x_0 - x^*\|^2 + G^2 \sum_{t=1}^T \eta_t^2}{2 \sum_{t=1}^T \eta_t}.$$

This theorem implies Theorem 8.2 by letting $\eta_t = \frac{R}{G\sqrt{T}}$



Figure 2: Subgradient method: the path may zigzag (subgradients need not be descent directions). The **best** iterate $x_T^{(\text{best})}$ minimizes f over $\{x_0, \dots, x_T\}$. The bound shrinks when $\sum \eta_t$ is large (more “progress”) and when $\|x_0 - x^*\|$ and $\sum \eta_t^2$ are small.

Proof.

$$\begin{aligned} \|x_{t+1} - x^*\|^2 &= \|x_t - \eta_t g_t - x^*\|^2 \\ &= \|x_t - x^*\|^2 - 2\eta_t g_t^T (x_t - x^*) + \eta_t^2 \|g_t\|^2 \\ &\leq \|x_t - x^*\|^2 + 2\eta_t (f(x^*) - f(x_t)) + \eta_t^2 G^2 \end{aligned} \quad (*)$$

Last step follows from $f(x^*) \geq f(x_t) + g_t^T (x^* - x_t) \iff -g_t^T (x_t - x^*) \geq f(x^*) - f(x_t)$.

Adding (*) up from $0, \dots, T-1$ we have

$$\|x_T - x^*\|^2 \leq \|x_0 - x^*\|^2 + G^2 \sum_{t=0}^{T-1} \eta_t^2 + 2 \sum_{t=0}^{T-1} \eta_t (f(x^*) - f(x_t)).$$

So

$$2 \sum_{t=0}^{T-1} \eta_t \left(f(x_T^{(\text{best})}) - f(x^*) \right) \leq 2 \sum_{t=0}^{T-1} \eta_t (f(x^*) - f(x_t)) \leq \|x_0 - x^*\|^2 + G^2 \sum_{t=0}^{T-1} \eta_t^2.$$

□

Theorem 8.7. *Polyak's Stepsize: If $f(x^*)$ is known,*

$$\eta_t = \frac{f(x_t) - f(x^*)}{\|g_t\|^2}.$$

Theorem 8.8. *Given C_1, \dots, C_k convex sets find $x^* \in \bigcap_{i=1}^k C_i$.*

Proof. Define $f_i(x) = \min_{y \in C_i} \|x - y\|^2 = \text{dist}(x, C_i)$ and $f(x) = \max_{i=1, \dots, k} f_i(x)$.

If $x^* \in C_1 \cap \dots \cap C_k$ then $f(x^*) = 0$.

Recall: $\partial f(x) = \text{Conv} \left(\bigcup_{i=1, \dots, k} \partial f_i(x) \right)$.

Let $P_C(x) = \arg \min_{y \in C} \|x - y\|$

Lemma 8.9. *u is the projection of x onto C iff $\langle x - u, y - u \rangle \leq 0 \forall y \in C$*

We have $f_i(x) = \|x - P_{C_i}(x)\|^2$ so $\partial f_i(x) = \frac{x - P_{C_i}(x)}{\|x - P_{C_i}(x)\|}$ if $x \neq 0$.

$$x_{t+1} = x_t - f(x_t) \cdot \frac{x_t - P_{C_i}(x_t)}{\|x_t - P_{C_i}(x_t)\|} = P_{C_i}(x_t).$$

□

9 Feb 12

Definition 9.1. For $\min_{x \in C} f(x)$ we define the projected subgradient method to be

$$\begin{cases} y_{t+1} = x_t - \eta_t g_t \\ x_{t+1} = P_C(y_t) \end{cases}.$$

Theorem 9.2. $P_C(x) = \arg \min_{y \in C} \|x - y\|^2$

Proof. We have $z = P_C(x)$ iff $\forall y \in C, \langle x - z, y - z \rangle \leq 0$. Then for

$$\underbrace{-\nabla f(z)}_{x-z} \in \underbrace{N_C(z)}_{\{g: g^T(y-z) \leq 0 \ \forall y \in C\}}.$$

so we have $(x - z)^T(y - z) \leq 0$

□

Lemma 9.3. Projections are contractions:

$$\| \underbrace{P_C(x_1)}_{z_1} - \underbrace{P_C(x_2)}_{z_2} \|_2 \leq \|x_1 - x_2\|_2.$$