

Argonne
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An Introduction to Linear Regression with Applications to AI

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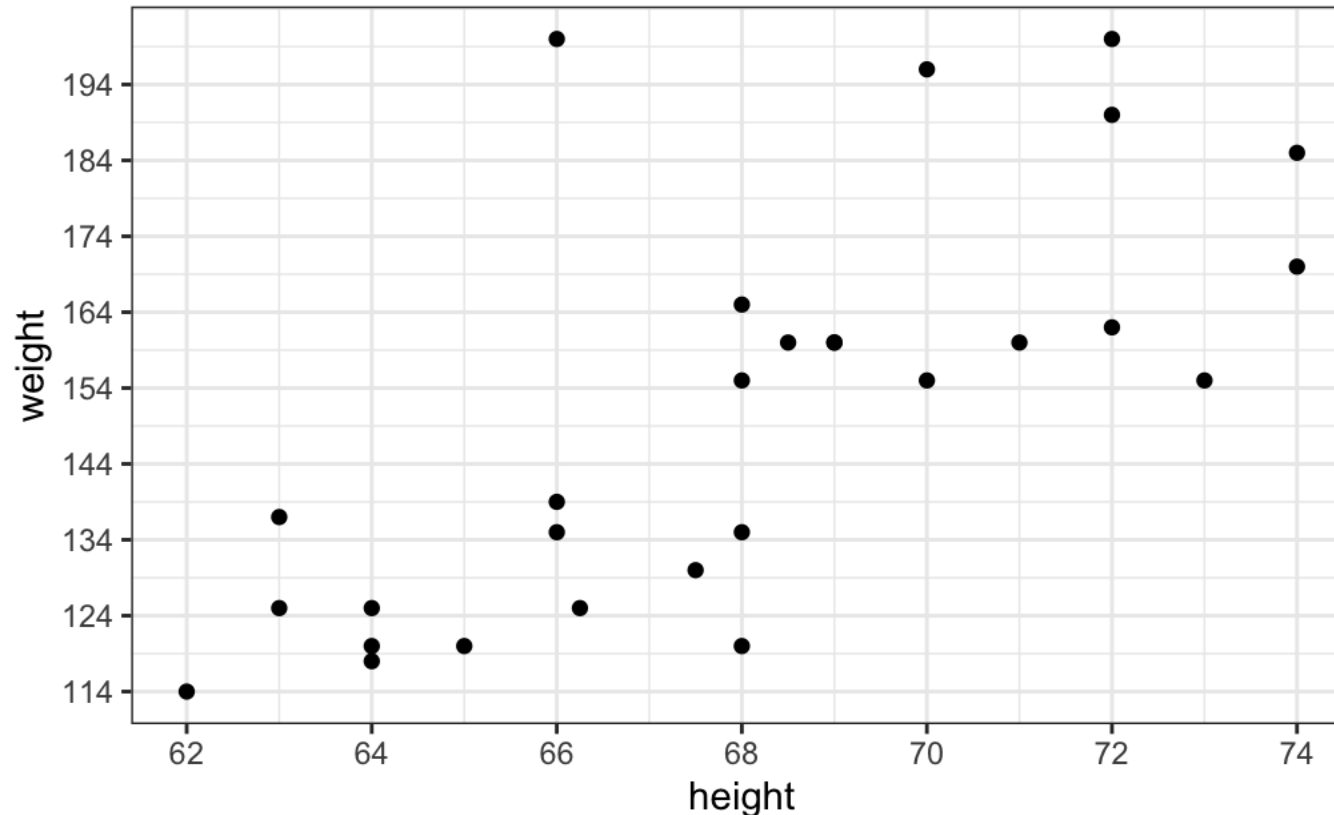
August 13, 2025

Motivation for Linear Regression

- Allows us to investigate the relationship between two or more variables statistically
- Basic introduction to supervised learning
- Can be thought of as a building block of artificial neural networks (many perceptrons)
- Learning Objectives
 1. Fit a SLR model to data and interpret model coefficients (parameters)
 2. Build a Perceptron to solve a regression problem
 3. Build and train a deep neural network using Keras

Simple Linear Regression: Model Definition

- The goal for SLR is to investigate the relationship between the **response** (Y) and the **predictor** (X) variables
- Recall from high school algebra: $y = b + mx$
 - Where m is the slope and b is the y-intercept



Simple Linear Regression: Model Definition

- The general form of the SLR model closely resembles the algebraic equation ($y = b + mx$):

$$Y = \beta_0 + \beta_1 X + \epsilon$$

- For an individual observation (x_i, y_i), the regression equation becomes:

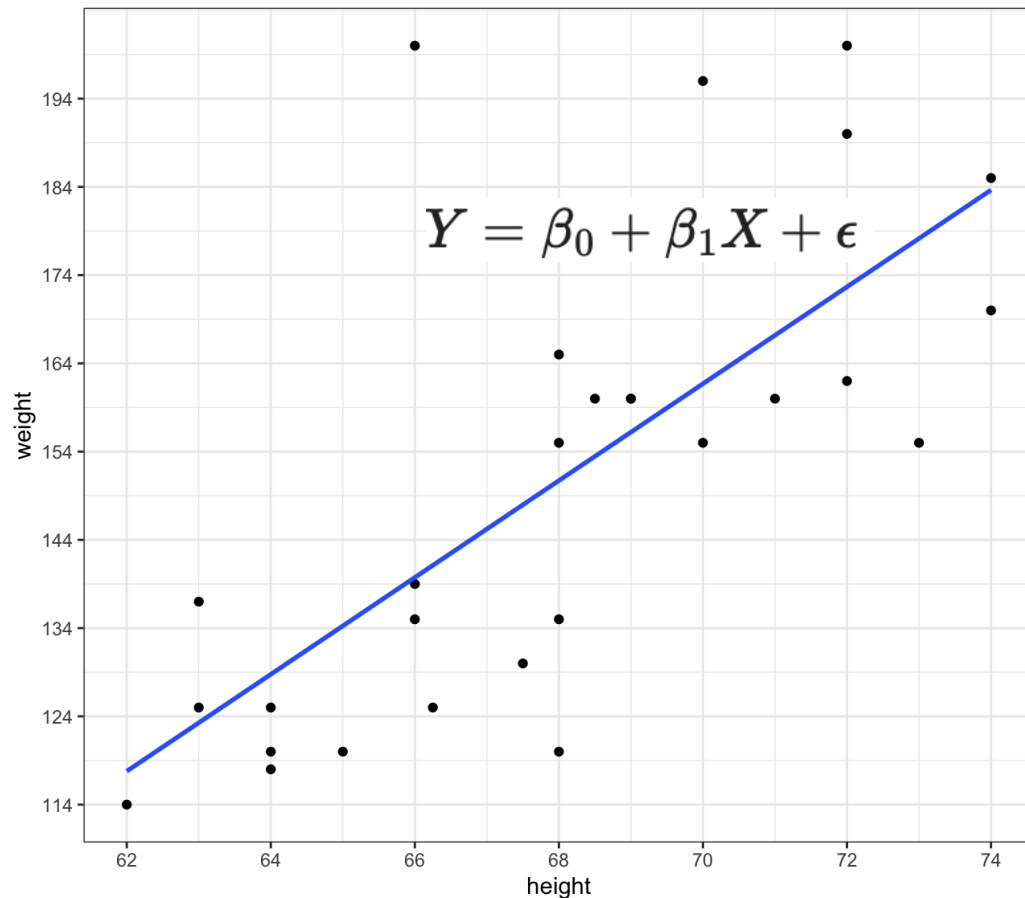
$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

- Where

- β_0 is the population y-intercept,
- β_1 is the population slope
- ϵ_i is the error or deviation of an observation from regression line

- Together, β_0 and β_1 are the (unknown) population model **coefficients** or **parameters**
- The goal of regression is to estimate parameters ($\hat{\beta}$) to describe the relationship between **Y** and **X**
- We estimate $\hat{\beta}$ using the method of Ordinary Least Squares (OLS)

Simple Linear Regression: Errors (Loss)



- Predicted value (\hat{y}_i) based on the \hat{x}_i is obtained by

$$\text{fit}_i = \hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$$

- An error is defined by

$$\text{res}_i = \epsilon_i = y_i - \hat{y}_i$$

- We quantify the total error (loss)

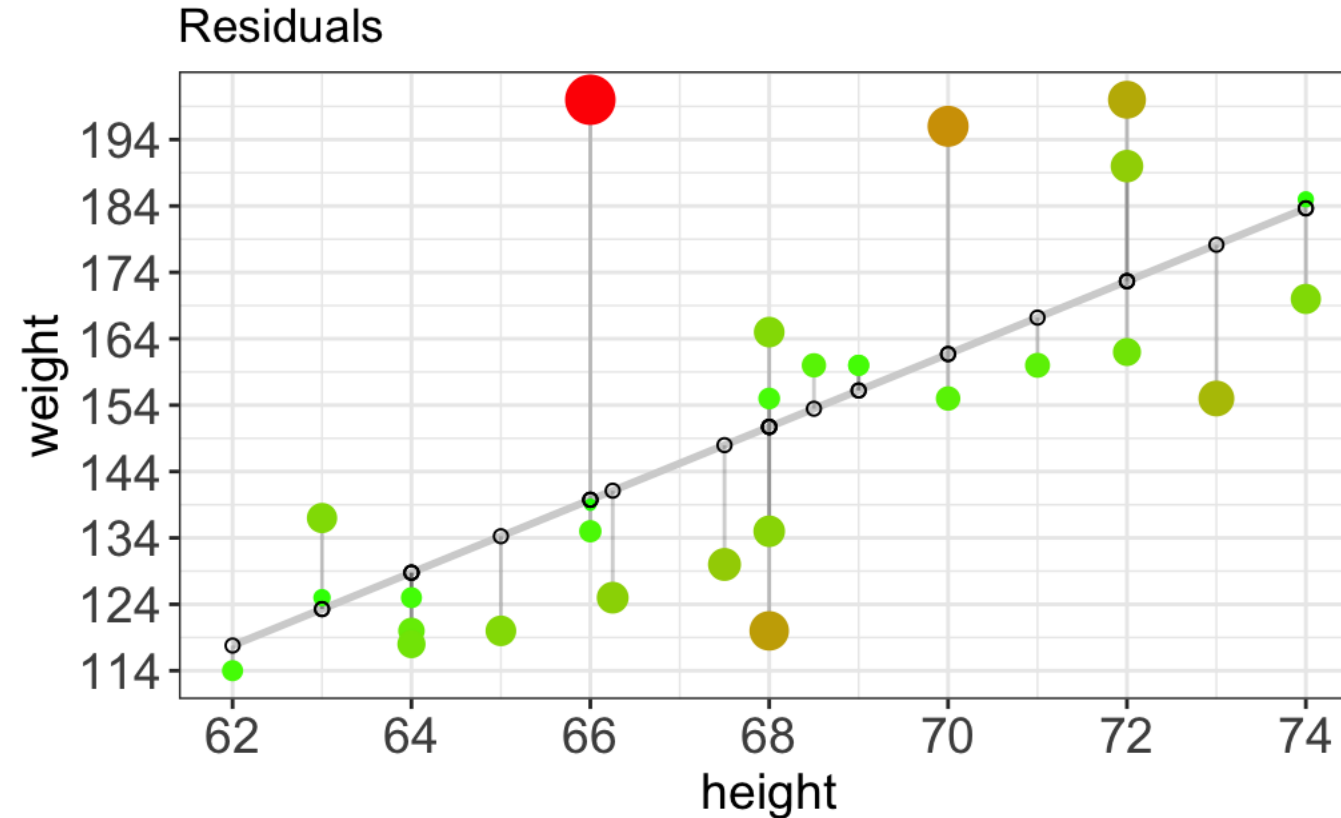
$$RSS = \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

$$MSE = \frac{1}{n} \sum_{i=1}^n (\hat{y}^{(i)} - y^{(i)})^2$$

- Goal: obtain least squares estimates of β to minimize MSE

Simple Linear Regression: Errors (Loss)

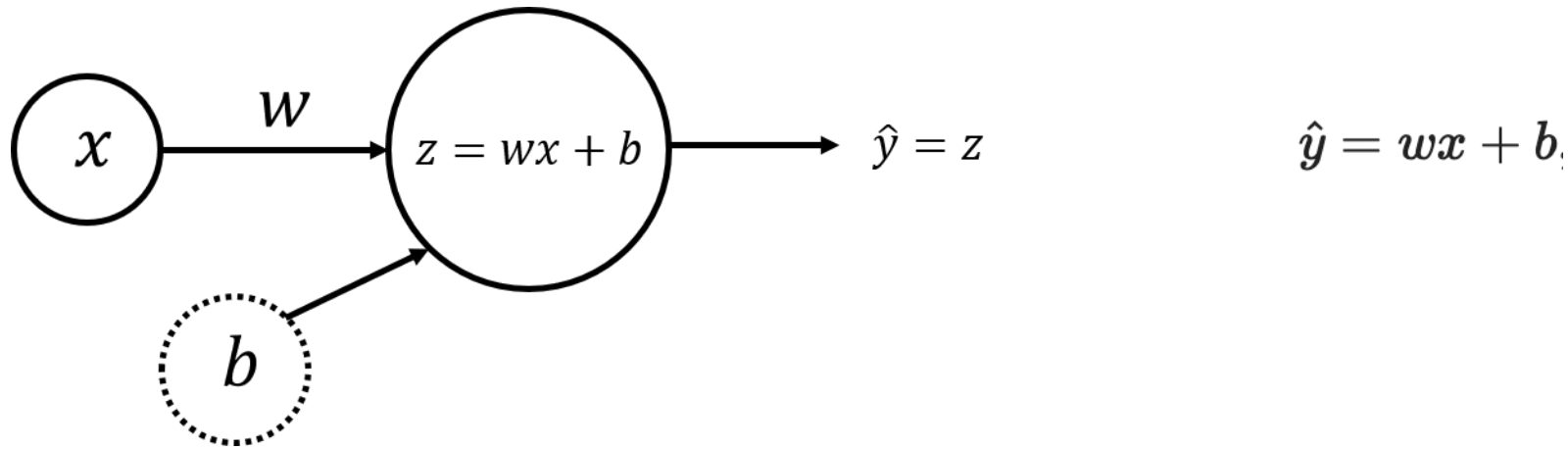
Errors, visualized



Hands-On!

SLR with Perceptron

- We will construct a 'neuron' corresponding to a SLR model, and train with **gradient descent**



- Weight** (w) and **bias** (b) are the parameters that will get updated when you **train** the model
- As in the previous SLR model, the goal is to identify parameters that minimize the average loss function: **cost function**

$$\mathcal{L}(w, b) = \frac{1}{2m} \sum_{i=1}^m (\hat{y}_i - y_i)^2$$

Training the model

- After defining the model structure,
 - initialize parameters to some random values (or set to 0) and
 - **update** as the training progresses
- For each training example (x_i, y_i) , predict \hat{y}_i :

$$z_i = wx_i + b,$$

$$\hat{y}_i = z_i,$$

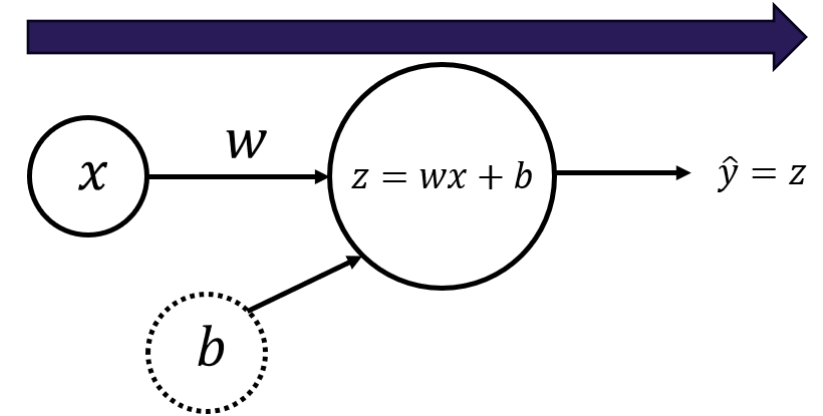
where $i = 1, \dots, m$

- Training examples are a vector X of size $(1 \times m)$
- Perform scalar multiplication of X by a scalar w , adding b .

$$Z = wX + b,$$

$$\hat{Y} = Z,$$

- This set of calculations is called **forward propagation**



Training the model

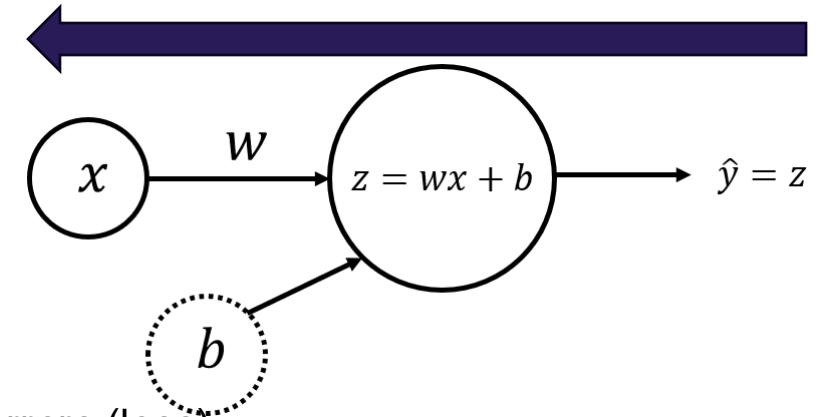
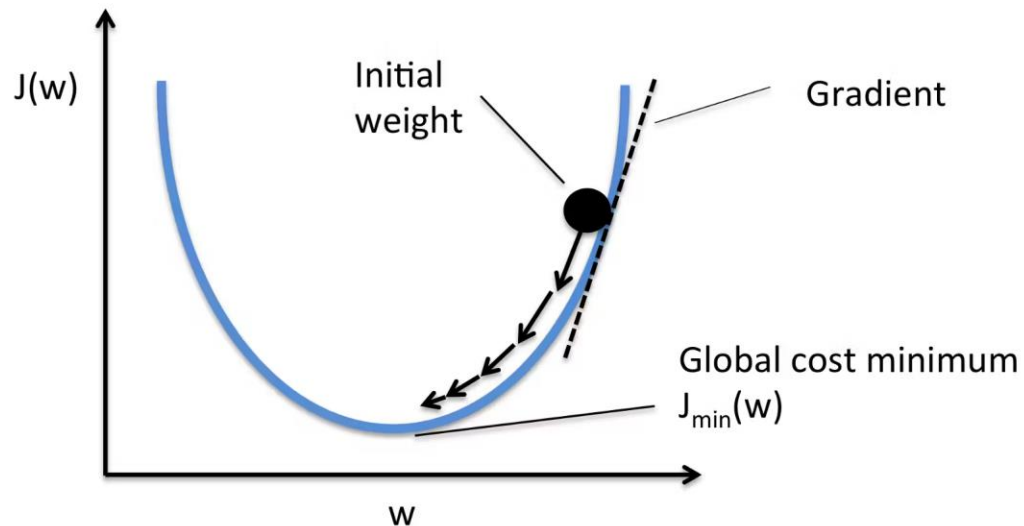
- Given \hat{Y} , calculate the cost function

$$\mathcal{L}(w, b) = \frac{1}{2m} \sum_{i=1}^m (\hat{y}_i - y_i)^2$$

— Aim is to optimize the cost function during training, hence minimize the errors (loss)

- We minimize the cost function by use of an optimization algorithm, like **gradient descent**

— Attempt to identify parameter values that minimize the cost function by taking partial derivatives of the cost function



We calculate partial derivatives as:

$$\frac{\partial \mathcal{L}}{\partial w} = \frac{1}{m} \sum_{i=1}^m (\hat{y}_i - y_i) x_i,$$

$$\frac{\partial \mathcal{L}}{\partial b} = \frac{1}{m} \sum_{i=1}^m (\hat{y}_i - y_i)$$

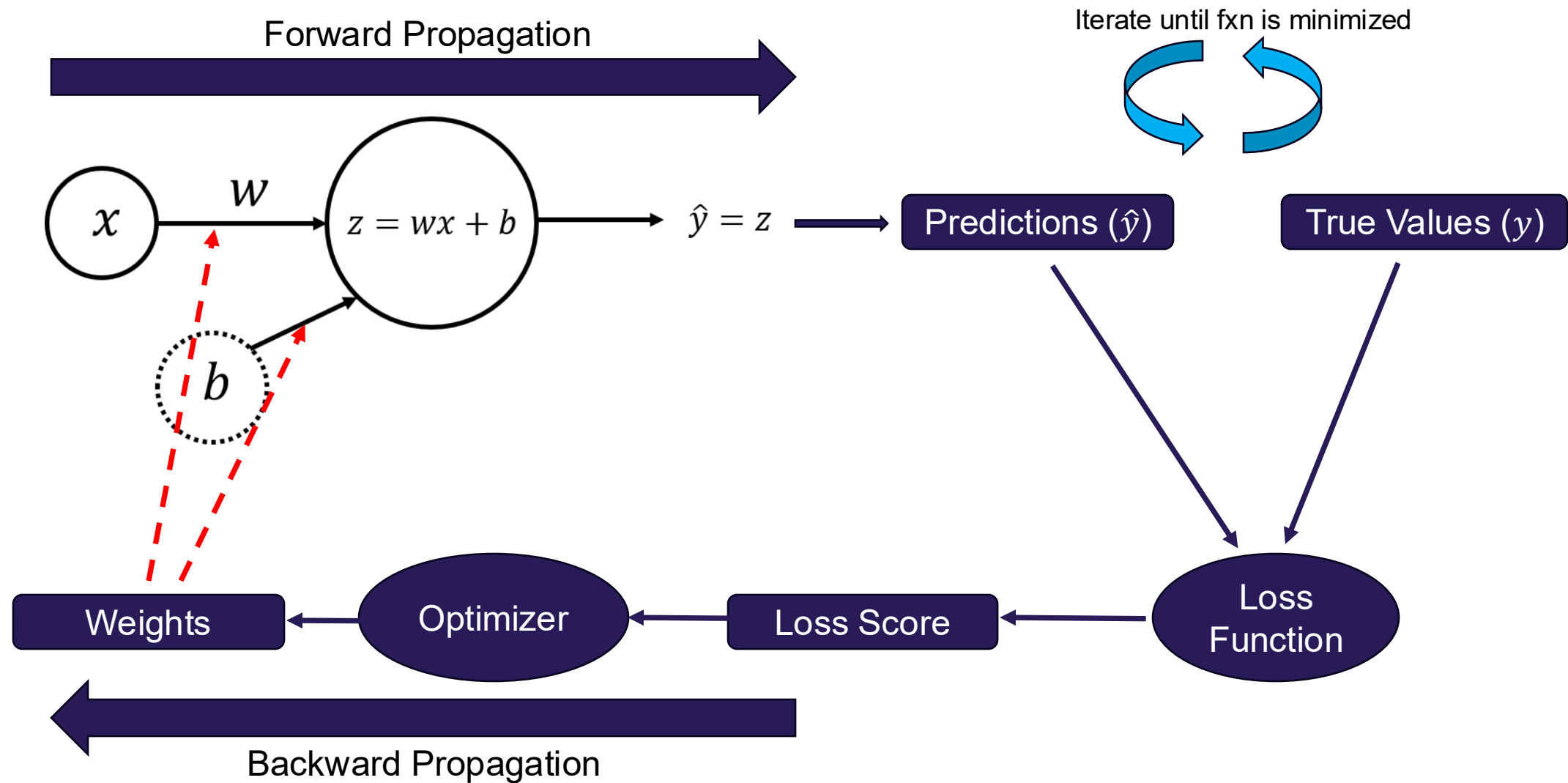
We then update the parameters iteratively using the expressions:

$$w = w - \alpha \frac{\partial \mathcal{L}}{\partial w},$$

$$b = b - \alpha \frac{\partial \mathcal{L}}{\partial b}, \quad \text{where } \alpha \text{ is the learning rate}$$

- This set of calculations is called **backward propagation**

Training the model



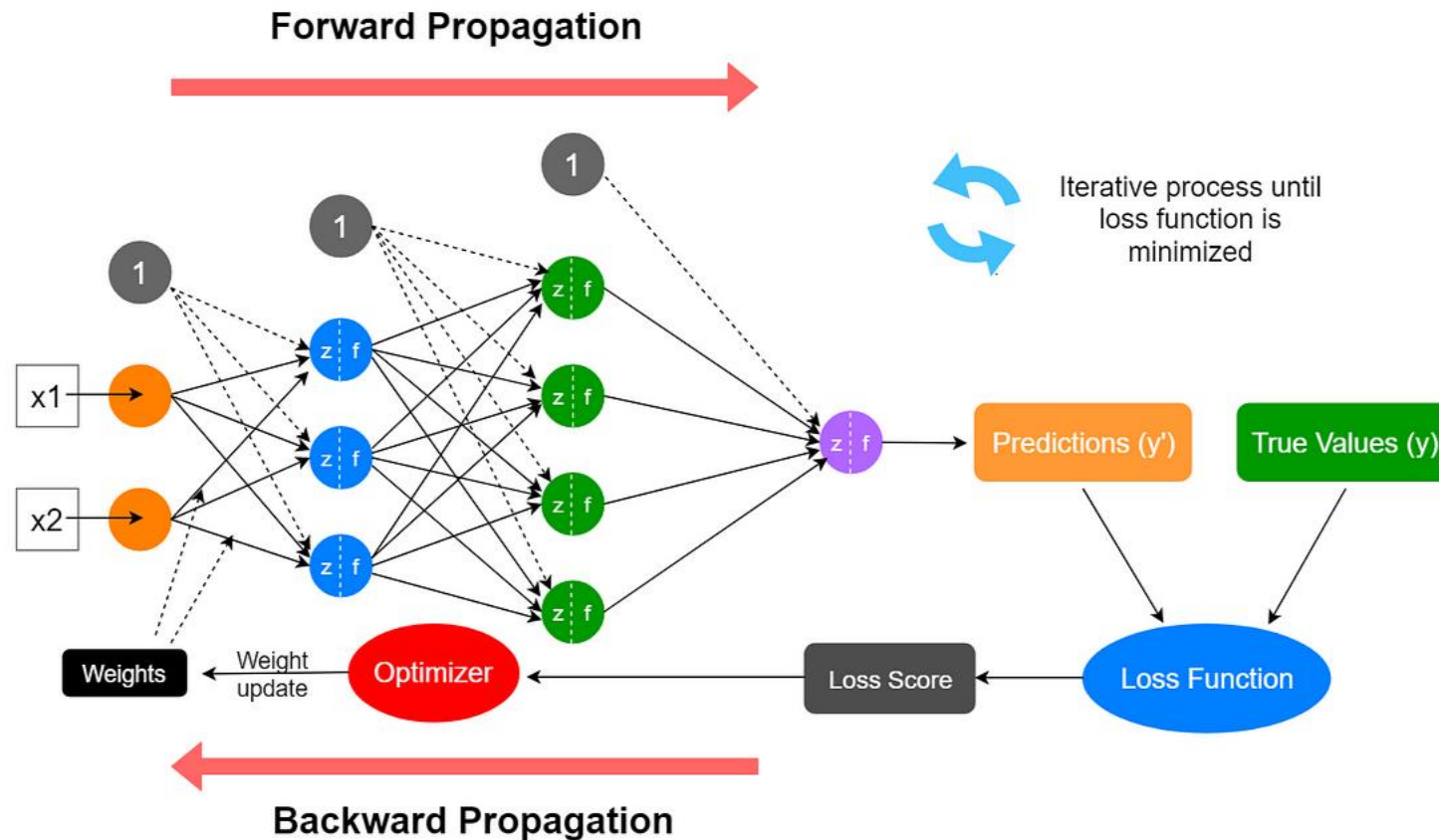
Methodology to build a neural network

- Define the neural network structure (# of input units, # of hidden units, etc)
- Initialize the model's parameters
- Loop (iterate)
 - Implement forward propagation (calculate the perceptron output)
 - Implement backward propagation (to get the required corrections for the parameters)
 - Update parameters
- Make predictions with “best” parameters

Hands-On!

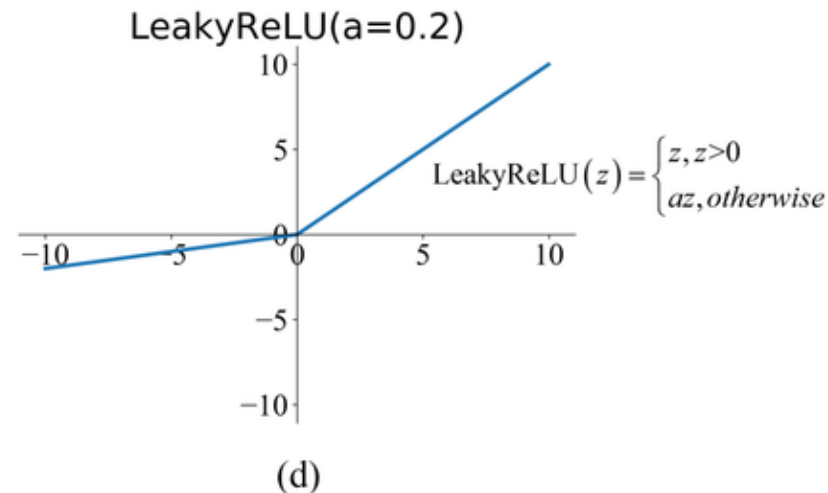
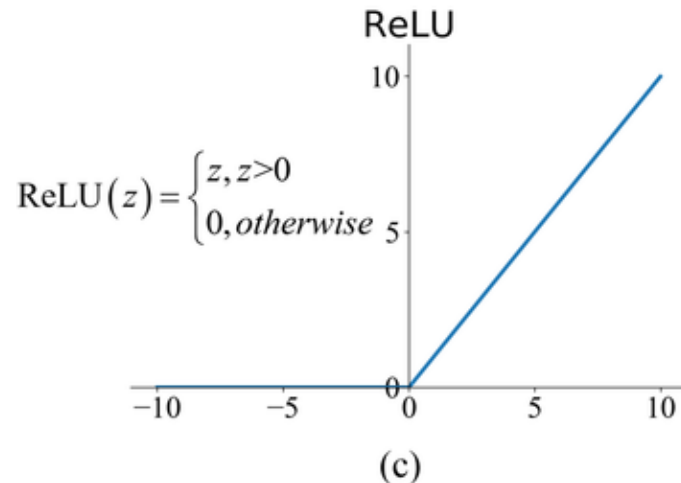
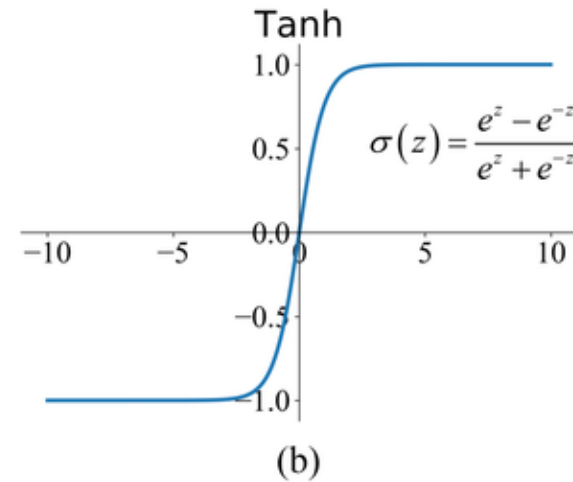
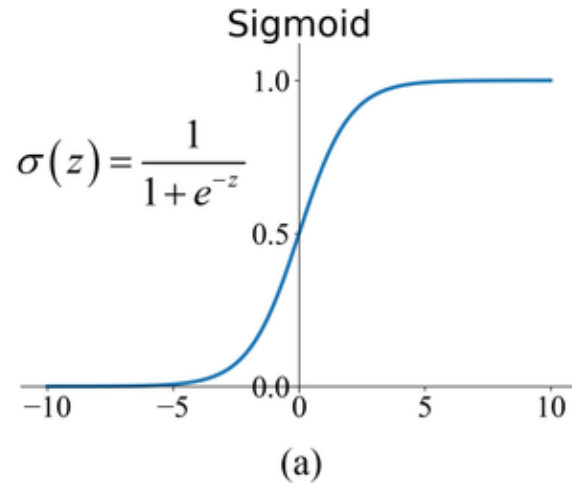
Let's Dive Deep! An Introduction to Deep Learning

The *deep* in deep learning: successive layers of data representation



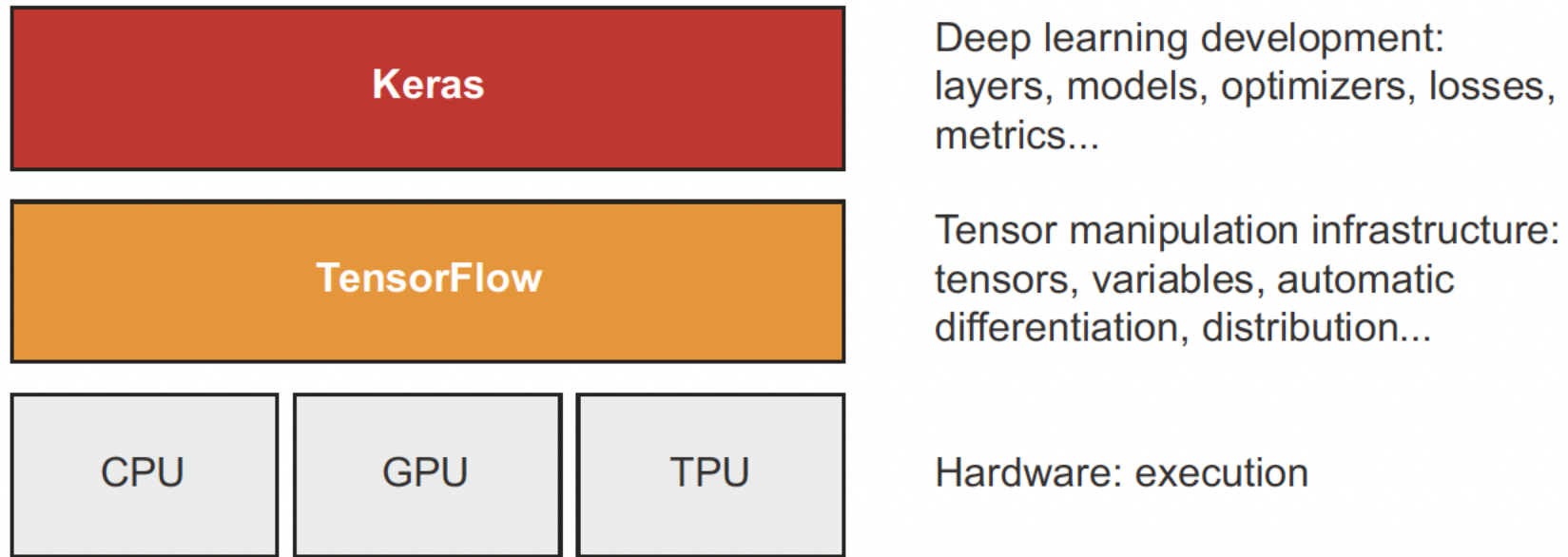
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Commonly used activation functions



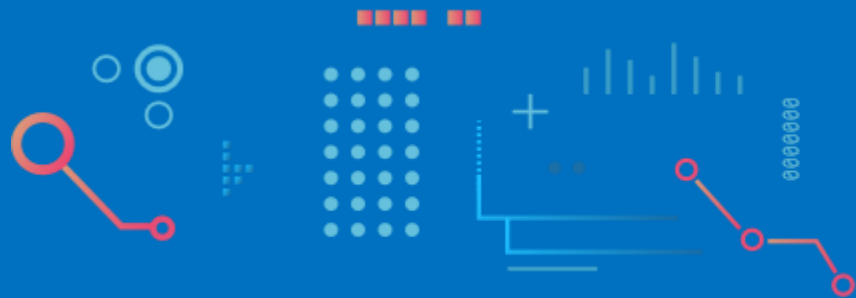
Let's Dive Deep! An Introduction to Deep Learning

You don't have to build neural nets from scratch — somebody already did this for you!



Hands-On!

Questions?



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