

William Daniels
CSCI 4202
Artificial Intelligence
Homework #6 03/08/15

First, we will convert all of the axioms into clause form:

(1) **move(x, s)**

$$AT(monkey, b, s_1) \vee ONCHAIR(s_1) \vee AT(monkey, x_1, move(x_1, s_1))$$

(2) **carry(x,s)**

$$\neg AT(monkey, b, s_2) \vee ONCHAIR(s_2) \vee AT(chair, x_2, carry(x_2, s_2))$$

(3) **climb(s)**

$$(3.1) \neg AT(chair, x_{3.1}, s_{3.1}) \vee AT(chair, x_{3.1}, climb(s_{3.1}))$$

$$(3.2) ONCHAIR(climb(s_{3.2}))$$

$$(3.3) \neg ONCHAIR(s_{3.3})$$

(4) **knock(s)**

$$\neg ONCHAIR(s_4) \vee AT(chair, c, s_4) \vee HB(knock(s_4))$$

(5) $\neg AT(monkey, a, s_5) \vee \neg AT(monkey, b, s_5), b \neq a$

Now, our state space starts as:

$$\neg ONCHAIR(s_0), \neg HB(s_0), AT(monkey, a, s_0), AT(chair, b, s_0), AT(banana, c, s_0)$$

which can be interpreted as various axioms of:

$$(6.1) ONCHAIR(s_1)$$

$$(6.2) \neg HB(s_0)$$

$$(6.3) AT(monkey, a, s_0)$$

$$(6.4) AT(chair, b, s_0)$$

$$(6.5) AT(banana, c, s_0)$$

We are trying to prove that $\exists s HB(s)$

Proof that a monkey can have a banana: (you'll notice our first step is to negate our assumption)
Since i'm using tex, making the nice 'tree' like diagram in the notes is difficult, so instead I'll be using the format: leftHandSide Axiom \rightarrow negated with right hand side axiom, Substitutions will be in parenthesis.

- (a) $\neg HB(s_6) \rightarrow 4 \left(\frac{knock(s_4)}{s_6} \right)$
- (b) $\neg ONCHAIR(s_4) \vee AT(chair, c, s_4) \rightarrow 3.2 \left(\frac{climb(s_{3.2})}{s_4} \right)$
- (c) $\neg AT(chair, c, climb(s_{3.2})) \rightarrow 3.1 \left(\frac{c}{x_{3.1}} \right), \left(\frac{s_{3.2}}{s_{3.1}} \right)$
- (d) $\neg AT(chair, x_{3.1}, s_{3.1}) \rightarrow 1 \left(\frac{b}{x_{3.1}} \right), \left(\frac{s_1}{s_{3.1}} \right)$
- (e) $ONCHAIR(s_1) \vee AT(monkey, x_1, move(x_1, s_1)) \rightarrow 3.3 \left(\frac{s_1}{s_{3.3}} \right)$
- (f) $AT(monkey, x_1, move(x_1, s_{3.3})) \rightarrow 5 \left(\frac{x_1}{b} \right), \left(\frac{move(x_1, s_{3.3})}{s_5} \right)$
- (g) $\neg AT(monkey, a, s_5) \rightarrow 6.3 \left(\frac{s_5}{s_0} \right)$
- (h) \square