

Zones Trajectories (l, τ)		TRANSITION (p, x_0 , x_1)		
	(WPAWN2, h5, h6)	(BKING, f5, g6)	(WPAWN, h6, h7)	(BKING, g6, h7)
Z1, a(h6)	Freeze			
Z1, a(d4) a(h8) (2,3)	(2,2)	(2, 2)	freeze	
Z1, a(c2)a(d4) (2,2)	(2, 2)	(2, 2)	freeze	
Z1, a(h8) (1, 3)	(1, 2)	(1, 2)	(1,1)	freeze
Z1, a(h7) (1, 3)	(1, 1)	(1, 1)	freeze	
Z1, a(g6)a(h7) (2, 3)	(2, 2)	(1, 2)	(1,1)	freeze