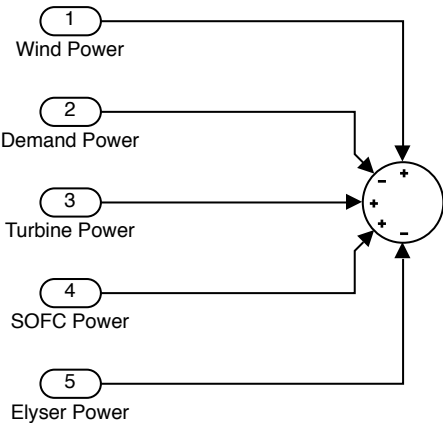
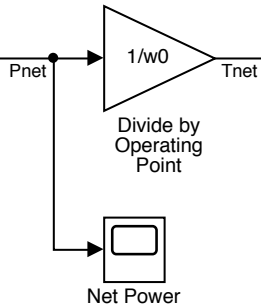


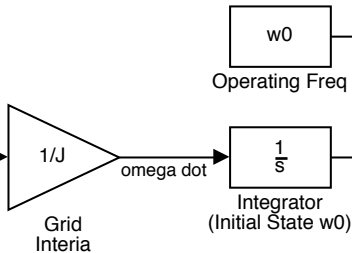
Input Powers



Convert To Torque



Grid Dynamics



Error Output

