

# Wei Pan | Ph.D

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Male | Dec 1990

## Education

<b>Singapore University of Technology and Design (SUTD)</b> <i>Ph.D. in Engineering Product Development</i> Supervisor: Prof. Lujie Chen Full Presidential Graduate Scholarship	<b>Singapore</b> 2013–2018
<b>Zhejiang University</b> <i>B.Eng. in Optical Engineering (Honors Program)</i> GPA 3.60/4.0	<b>Hangzhou, China</b> 2009–2013

## Research Interests

Machine Vision, Computational Imaging, Computational Geometry, Computer Aided Design, Algorithm and Optimization

## Professional Experience

<b>OPT Machine Vision Tech Co., Ltd.</b> <i>R&amp;D Director, PI</i>	<b>Tokyo, Japan</b> 2021.01–Present
<ul style="list-style-type: none"><li>Leading a 20+ algorithm team, and responsible for core algorithms and 3D imaging systems in industrial machine vision</li><li>Focus on high-precision fast 3D imaging (structured light, line laser, phase deflectometry, photometric stereo), depth map/point cloud/mesh processing, industrial defect detection, 3D surface measurement, registration, robotic grasping, etc.</li><li>70+ invention patents filed, 10+ granted, many technologies mass-produced in Li-battery, 3C, automotive, medical, logistics industries, etc.</li></ul>	
<b>Guangdong OPT Machine Vision Tech Co., Ltd.</b> <i>Senior Algorithm Engineer</i>	<b>Dongguan, China</b> 2019.06–Present
<ul style="list-style-type: none"><li>Core module leader for structured-light 3D reconstruction, SciVision depth/point-cloud processing SDK, real-time rendering system</li><li><b>Principal Investigator / Key Member of Major Projects:</b><ul style="list-style-type: none"><li>Dongguan Major Science &amp; Technology Project (Key Fields R&amp;D Program - Key Technology Break-through): Intelligent Inspection Technology and Application for High-end Manufacturing Processes (Principal Co-PI, 2023–2025)</li><li>Guangdong Provincial Key Fields R&amp;D Program: Micron-level Real-time Vision Inspection Technology Research and System Development (Key Member, 2021–2024)</li><li>Dongguan Key R&amp;D Project (2020): Robotic 3D Vision Intelligent Grasping System R&amp;D and Application Demonstration (Key Member, 2020–2022)</li></ul></li></ul>	
<b>The University of Tokyo</b> <i>Collaborative Researcher, Supervisor: Prof. Takeo Igarashi</i>	<b>Tokyo, Japan</b> 2021.01–2021.12

- Deep learning-based sketch auto-generation and weaving pattern fast retrieval
- 3D modeling and textile garment automatic segmentation

### **South China University of Technology**

**Guangzhou, China**

*Collaborative Researcher, Supervisor: Prof. Xianmin Zhang*

*2019.10–2022.01*

High-precision 3D measurement and data processing algorithms in industrial inspection

### **Shenzhen University**

**Shenzhen, China**

*Postdoctoral Researcher, Supervisor: Prof. Guoping Qiu*

*2018.06–2019.05*

3D mesh filtering, automated 3D scanning system, robotic grasping, half-window Laplacian-based mesh denoising algorithm

### **Singapore University of Technology and Design**

*Ph.D. Candidate, Supervisor: Prof. Lujie Chen*

*2013.09–2018.03*

Ultra-large-scale rapid prototyping, voxelized model transformation algorithms, Lego automated assembly sequence planning

## **Early Research & Internship Experience**

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### **A\*STAR Institute of Materials Research and Engineering**

**Singapore**

*Research Intern, Supervisor: Dr. Liu Yanjun*

*2014.05–2014.09*

Plasmon-induced transparency nanostructures: spectral testing and FDTD simulation (COMSOL); published in *Nanotechnology* 26(2):025201 (2015)

### **Zhejiang University**

**Hangzhou**

*B.Eng. Thesis, Supervisor: Prof. Kuang Cuifang*

*2013.01–2013.07*

STORM super-resolution microscopy system: MATLAB convolution simulation + full C++ control and image processing software

### **University of Alberta**

**Edmonton, Canada**

*Exchange Student, Supervisor: Prof. Zubin Jacob*

*2012.09–2012.12*

Super-resolution microscopy (STORM & STEM) theory review and performance comparison

### **Kuang-Chi Institute**

**Shenzhen**

*Summer Research Intern, Supervisor: Dr. Guo Jie*

*2012.07–2012.08*

Metamaterial antenna design and simulation (COMSOL + CST); awarded Outstanding Intern

## **Services**

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- Technical Committee: icicv2025, icigp2025/2026, acmmm2024, mcaccv2022
- Conference Reviewer: aaai2026, eccv2025, cvpr2026, icicv2025, icigp2025, acmmm2024, mcaccv2022
- Journal Reviewer: EAAI, AUTCON, EJRS, BSPC, CVIU, KBS, TVCG, IJCV, CVMJ, Scientific Reports
- Journal Editorial Board: The Computational Vision and Imaging

## **Awards**

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- First Prize, Guangdong Machinery Industry Science and Technology Award, Guangdong Province, 2023
- First Prize, Guangdong Mechanical Engineering Society Science and Technology Award, Guangdong Province, 2023
- Second Prize, Henan Province Science and Technology Progress Award, Henan Province, 2023
- Singapore Presidential Graduate Scholarship, Singapore, 2013–2018
- Zhejiang University Outstanding Graduate, Hangzhou, China, 2013

- Kuang-Chi Talent Scholarship, Shenzhen, China, 2012
- First Prize, 5th Zhejiang University Optics Design Competition (sole first prize in laser listening group), Hangzhou, China, 2012
- First-Class Academic Excellence Scholarship, Zhejiang University, Hangzhou, China, 2009
- Outstanding Student Honor, Zhejiang University, Hangzhou, China, 2009–2013 (annual)
- Scholarship for Excellent Students in Sports and Arts, Zhejiang University, Hangzhou, China, 2009–2013 (annual)

## Skills

**Languages:** Mandarin (Native), English (Fluent), Japanese (Elementary)

**Programming:** C++, Python, MATLAB

**Interests:** Badminton, Soccer, Swimming

## Publications

1. **Pan Wei**, Yuhao Wu, Wenming Tang, et al. An improved graph attention network for semantic segmentation of industrial point clouds in automotive battery sealing nail defect detection. *Engineering Applications of Artificial Intelligence*, 2026, 163(1): 112793.
2. **Pan Wei**, Jiang Bin-feng, Tang Wen-ming et al. Gap measurement method based on projection lines and convex analysis of 3D point cloud. *Measurement Science and Technology*, 2024, 35(10): 105024.
3. Lu Lei, Bu Chenhao, Su Zhilong, ..., **Pan Wei**. Generative deep-learning-embedded asynchronous structured light for three-dimensional imaging. *Advanced Photonics*, 2024, 6(4): 046004.
4. Zhang Qinghui, Liu Feng, Lu Lei, ..., **Pan Wei**. Reconstruction of transparent objects using phase shifting profilometry based on diffusion models. *Optics Express*, 2024, 32(8): 13342-13356.
5. Fung Sheldon, **Pan Wei**, Lu Xuequan et al. DeSC: Learning Deep Semantic Descriptor for NeRF Registration. *IEEE TVCG*, 2025 (in press).
6. Fung Sheldon, Lu Xuequan, ..., **Pan Wei**, Liu Xiao, Li Hongdong. SemReg: Semantics constrained point cloud registration. *ECCV 2024*.
7. Wang Weijia, **Pan Wei**, Dai Chaofan et al. Segmentation-driven feature-preserving mesh denoising. *The Visual Computer*, 2024, 40: 6201-6217.
8. Wang Weijia, **Pan Wei**, Liu Xiao et al. Random screening-based feature aggregation for point cloud denoising. *Computers & Graphics*, 2023, 116: 64-72.
9. Liu Jiaxiang, ..., **Pan Wei\*** et al. Deep learning-enabled 3D multimodal fusion of cone-beam CT and intraoral mesh scans for clinically applicable tooth-bone reconstruction. *Patterns* (Cell Press), 2023, 4(9).
10. **Pan Wei**, Gong Yuanhao, Tang Wenming et al. HLO: Half-kernel Laplacian operator for surface smoothing. *Computer-Aided Design*, 2020, 121: 102807.

## Invention Patents (70+ total)

Granted Patents (selected).....

- **CN119006550B** Neural Radiance Field Registration Method, System and Product (2025)
- **CN119919533B** Downsampled Single-frequency Phase Unwrapping Method (2025)
- **CN117275032B** CAD Drawing Geometric Contour Extraction Method and System (2025)
- **CN114324168B** Surface Defect Detection Method and System (2024)

- **CN113178013B** Triangle Mesh Filtering Method, Device, Equipment and Medium (2023)
- **CN112802077B** High-precision Point Cloud Normal Estimation Method (2023)
- **CN113269860B & WO2022257594A1(PCT)** High-precision 3D Data Real-time Progressive Rendering Method and System (2021)
- **CN110120069B** Laplacian-based Triangle Mesh Filtering Method (2019)
- **CN109702738B** 3D Object Recognition-based Robotic Hand-eye Calibration Method (2019)

[Recent Filed \(2023–2025, selected\)](#).....

- **CN120807339A** Periodic Texture Smoothing with Adaptive Threshold and Position Constraints (2025)
- **CN120777999A** Automated Debugging and Calibration System and Method (2025)
- **CN120689197A** Bit-field Multi-channel Fusion Reversible Grayscale Method (2025)
- **CN120598883A** Complex Surface Defect Detection via Phase Deflectometry + Photometric Stereo (2025)
- **CN120388003A** Multi-cost Fusion Speckle Structured Light Stereo Matching (2025)
- **CN120339358A** Surface Reconstruction via Phase Deflectometry + Photometric Stereo (2025)
- **CN119919533A** Downsampled Single-frequency Phase Unwrapping (2025)
- **CN118982691A** Differential Chain Code-based Contour Matching (2024)
- **CN118967759A** RGB-D Point Cloud Registration via Semantic Information (2024)
- **CN118823038A** Image Region Contour Representation Method (2024)
- **CN118397020A** Fast Image Region Segmentation and Contour Extraction (2024)
- **CN118154810A** Discrete Orthogonal Polynomial-based 3D Data Filtering (2024)
- **CN117793547A** Depth Map Jitter Correction via Differential Fitting (2024)
- **CN117606363A** Non-contact Gap Measurement via Convex Hull and Centroid Projection (2024)
- **CN117172266A** Dot-matrix QR Code Localization and Decoding (2023)
- **CN116958415A** Focus 3D Reconstruction Based on Structured Light (2023)
- **CN116188561A** Irregular Object Area and Volume Measurement (2023)

(Full list available on patent platform)