$$\begin{array}{lll}
1.(\omega) & (2) & = \int_{1}^{\infty} (w) = \sum_{i=1}^{N} \left[y_i - \frac{1}{\omega_0 + \sum_{j=1}^{N} w_j x_{ij}} \right]^2 \\
 & = A W \\
A & = \left[\frac{1}{\omega_0} x_{ij} x_{ij} x_{ij} x_{ij} \right] \\
A & = \left[\frac{1}{\omega_0} x_{ij} x_{ij} x_{ij} x_{ij} x_{ij} \right] \\
A & = \left[\frac{1}{\omega_0} x_{ij} x_{ij} x_{ij} x_{ij} x_{ij} \right] \\
A & = \left[\frac{1}{\omega_0} x_{ij} x_{ij} x_{ij} x_{ij} x_{ij} \right] \\
A & = \left[\frac{1}{\omega_0} x_{ij} x_$$

hw5_1

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$$P_{1} = 1 - b_{1}d = \frac{b_{1} - b_{1}}{b_{1} + b_{2}}, \qquad P_{2} = \frac{b_{1} - b_{2}}{b_{1} + b_{2}}.$$

$$W_i^{\dagger} = P_i^{\dagger} W_i^{\circ} \qquad \text{So } |W_i^{\dagger}| = C|W_i^{\circ}|$$

$$||W^{k}||^{2} = ||W^{k}||^{2} + ||W^{k}||^{2} = C_{0}^{k} [||W^{0}|^{2} + ||W^{0}||^{2}] = C^{k} |||W^{0}||^{2}$$

$$||W^{k}|| = C||W^{0}||.$$

$$\frac{dJ}{dP_{ik}} = \sum_{i=1}^{n} \frac{dJ}{dz_{i}} \cdot \frac{dZ_{i}}{dz_{i}} = \sum_{i=1}^{n} \left[\frac{1}{y_{i}} - \frac{1}{z_{i}} \right] \frac{dZ_{i}}{dP_{jk}}.$$

$$\therefore Z_{pJ} = \sum_{i=1}^{n} \left[\frac{1}{y_{i}} - \frac{1}{z_{i}} \right] \times_{i} \times_{i}^{T}$$

hw5_3

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```
In [1]: import numpy as np
        n=X.shape[0]
        z=np.zeros(n)
        for i in range(n):
            z[i]=X[i,:].dot(P.dot(X[i,:]))
        J=np.sum(z/y-np.log(z))
        g=1/y-1/z
        Jgrad=np.zeros((n,n))
        for i in range(n):
            xi=X[i,:]
            Jgrad += g[i]*xi[:,None]*xi[None,:]
        NameError
                                                   Traceback (most recent call last)
        <ipython-input-1-fb5251638f50> in <module>()
          1 import numpy as np
    ----> 2 n=X.shape[0]
          3 z=np.zeros(n)
          4 for i in range(n):
                z[i]=X[i,:].dot(P.dot(X[i,:]))
        NameError: name 'X' is not defined
In [ ]: Xp=X.dot(P)
        z=np.sum(Xp*X,axis=1)
        J=np.sum(z/y-np.log(z))
        g=1/y-1/z
        Gx=g[:,None]*X
        Jgrad=X.T.dot(Gx)
```

4. (a) We set $\hat{W}_2 = argmin_{w_2} J(w_1, w_2)$.

$$\nabla_{W_1} J_1(W_1) = \frac{\partial J(W_1, \hat{W_2})}{\partial W_1}$$

=
$$\frac{9 \text{ J (m', m')}}{4 \text{ J (m', m')}} + \frac{9 \text{ M}^{2}}{4 \text{ J (m', m')}} = \frac{9 \text{ M}^{2}}{4 \text{ M}^{2}} + \frac{9 \text{ M}^{2}}{4 \text{ M}^{2}}$$

Meanwhile $\nabla_{w_2} J_{cw_1, w_2} |_{w_1 = \hat{w}_2}$ since \hat{w}_2 minimize $J_{cw_1, w_2} |_{w_1 = \hat{w}_2}$.

As we learn in question 1

$$\dot{Y}_{:} = Ab$$
. where $A = \begin{bmatrix} e^{-a_{i}x_{i}} \\ \vdots \end{bmatrix}$

16, We could see the loss function hs
$$J = \sum_{i=1}^{n} (y_i - \hat{y_i})^2$$
.

As we learn in question 1

 $\hat{y_i} = Ab$. where $A = \begin{bmatrix} e^{-a_i x_i} & e^{-a_d x_i} \\ e^{-a_i x_n} & e^{-a_d x_n} \end{bmatrix}$

and $\hat{b} = \operatorname{argmin} \operatorname{Jca.bs} = (A^T A)^T A^T \Upsilon$.

(c)
$$\frac{1}{2} \int_{a_{i}}^{b_{i}} da_{i} da_{j} = -2 \frac{1}{2} \frac{1}{2} \left(y_{i} - \hat{y}_{i} \right)^{2} da_{j}$$