Chapter 3 - Second-Order Differential Quations In this chapter we look at livear second-order (lecture?) ODES of the form $Q_2(x) \frac{d^2y}{dx^2} + Q(x) \frac{dy}{dx} + Q_0 y = Q(x)$ Our goal is to find two linearly independent solutions to the equation, say y, (x) and y2(x). the overall solution is then just a trear combination of y, and yz, so we write $y(x) = c, y, (x) + c_2 y_2(x)$

often we will be given two initial conditions of the form $y(k) = y_0$, $y'(k) = y_0'$, which allow us to solve for c, and c_2 .

Or we night be given too boundary conditions of the form $y(a) = y_0$ and $y(b) = y_0$, which which again allow us to solve for c, and c_2 .

As at the start of the course, you may be asked to use to verify a giver solution, or be asked to use the boursons values to two the virgue value of the boursons values to two the virgue value of the down the course.

Ex. If
$$f_{1}(x) = 1 + x$$
 and $f_{2}(x) = x^{3}$, then

$$W = \begin{vmatrix} 1+x & x^{3} \\ 1 & 3x^{2} \end{vmatrix} = 3x^{2} + 3x^{3} - x^{3}$$

$$= 2x^{3} + 3x^{2}$$

$$= 2x^{3} + 3x^{2}$$

$$= 6x^{3} + 3x^{2}$$

$$= 6x^{3$$

. Ex Caren that y=c,ex+c2ex is a solution Fo y"-y=0, find the values of c, and C2 if y(o)=0, y(1)=(. Substituting in we get y(0) = c, +c2 = 0 --- 0 3(1) = c,e + c2 = 1 So Dimplies $G = -C_2$ Herce - C2e + 52 = 1 c2(=-e)=1 $c_2\left(\frac{1-e^2}{e}\right)=1$ $c_2 = \frac{e}{1-e^2}$ = $\frac{e}{1-e^2} = \frac{e}{e^2-1}$ Livear hoperderse Définition: A set et functions are said to be Crearly dependent if there exists non-zero constants c, c2, c3, ---, cx such that $c(f(x) + c_2 f_2(x) + c_3 f_3(x) + --+ c_n f_n(x) = 0$ Défaition: If the set of factions are not linearly reperdent we say that they are treaty independent - which nears that the only solution to the above equation is $C_1=0$, $C_2=0$, $C_3=0$, ..., $C_n=0$ Ex. X and 5X are trearly dependent suce = = × + (2x) = 0

. Exi Siz²x, Cos²x, and I are linearly dependent suce 1.5,2 x + ______ : Coi2x + _____ ! = 6 Ex X and X2 are trearly independent Since ___ X + ___ X = 0 has no solution other than the brind one. Ex Six and Cos x are linearly independent. Ex 1, x, and ex are linearly independent. It is often vors difficult to determine linear ndependence just by looking at the function, or solving the equation, and hence we often appeal to the following theorem.

. Miessen: Suppose f, , f2, f3, fr are all at least (n-1) trues differentiable and the determinant $W = \begin{cases} f_1 & f_2 & f_3 & --- & f_1 \\ f_1' & f_2'' & f_3'' & --- & f_1'' \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & f_m & f_m & f_m & f_m & --- & f_m & \ddots & \vdots \\ f_m & \vdots \\ f_m & \vdots \\ f_m & \vdots \\ f_m & \vdots \\ f_m & f_m &$ is non-zero; then the set of faction is linearly independent Note: We call this matrix the Wronskian Note: If W=0 we conclude rothing, and must appeal to the definition. W=0= Nothing Note: [W \openderce] \wedge = 0 \widehat{\text{Dependence}} \widehat{\text{W=0}} happerderce => Nothing

 $= e^{x} \left(x^{3} e^{2x} + 4x^{2} e^{2x} + 2xe^{2x} + x^{2} e^{2x} + 4xe^{2x} + 2e^{2x} + 2e^{2$ - Xex (x2ex+4xe2x+2e2x-2xex) + x2ex (xex+2e2x-xex-ex) = 20³x Here f, fz, fz one linearly independent.