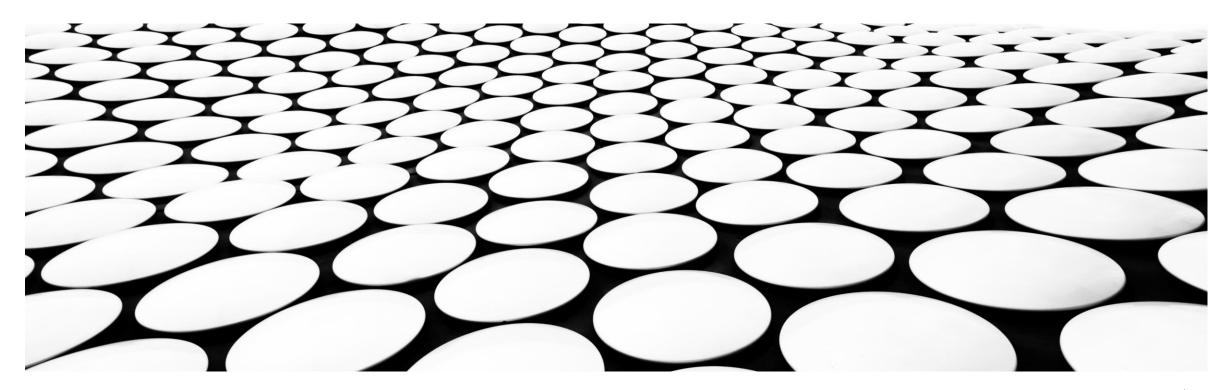
CONSTRAINT-SATISFACTION PROBLEMS

GREEDY AND RANDOMIZED SEARCHES





CONSTRAINT SATISFACTION PROBLEMS

- Part 1 Introduction
- Part 2 Greedy Searches
- Part 3 Randomized Searches

Part 1 Introduction



There is actually a new version! 2023.

Artificial Intelligence: Foundations of Computational Agents, 3rd Edition

David L. Poole and Alan K. Mackworth

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Source

A CSP is formulated with:

- A set of **variables** V₁, V₂, ... V_n
- Each variable has a **domain** D_{Vi} of possible values
- There are hard constraints on various subsets of the variables which specify legal combinations of values for these variables.
- A solution to the CSP is an assignment of a value to each variable that satisfies all the constraints.

EXAMPLE OF A CSP

Variables:

A, B, C, D, E represent activities

Domains:

- $\mathbf{D}_{\mathsf{B}} = \{1, 2, 3, 4\}$
- $\mathbf{D}_{\mathbf{C}} = \{1, 2, 3, 4\}$
- $D_D = \{1, 2, 3, 4\}$
- $\mathbf{D}_{\mathsf{F}} = \{1, 2, 3, 4\}$

■ Hard constraints:

$$(B \neq 3)$$
 and $(C \neq 2)$ and $(A \neq B)$ and $(B \neq C)$ and $(C < D)$ and $(A = D)$ and $(E < A)$ and $(E < B)$ and $(E < C)$ and $(E < D)$ and $(E \neq D)$

Soft constraints:

B and C should be as small as possible.

EXAMPLE OF A CSP

Variables:

A, B, C, D, E represent activities

■ Domains:

- $D_{B} = \{1, 2, 3, 4\}$
- $D_c = \{1, 2, 3, 4\}$
- $D_D = \{1, 2, 3, 4\}$
- $D_F = \{1, 2, 3, 4\}$

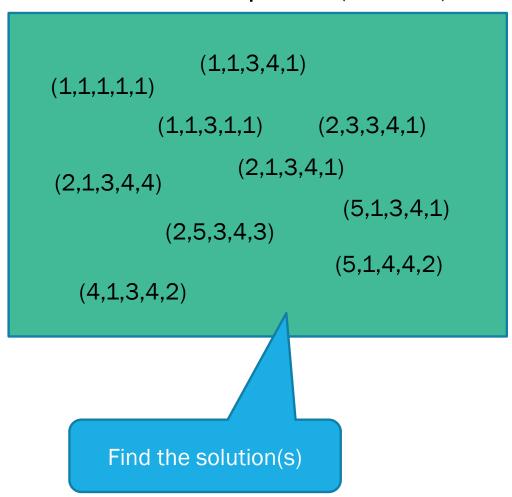
Hard constraints:

$$(B \neq 3)$$
 and $(C \neq 2)$ and $(A \neq B)$ and $(B \neq C)$ and $(C < D)$ and $(A = D)$ and $(E < A)$ and $(E < B)$ and $(E < C)$ and $(E < D)$ and $(E \neq D)$

Soft constraints:

B and C should be as small as possible.

Solution space (A,B,C,D,E)



Given a set of variables, assign a value to each variable for:

Satisfiability:

Satisfy a set of hard constraints.

Optimization:

Minimize the value of a cost function. There is a cost associated with each assignment of a value to a variable. We are talking about soft constraints.

Constrained optimization problem

Mix of hard and soft constraints. We must satisfy a set of hard constraints, but we also try to optimize a cost function.

EXAMPLES OF PROBLEMS AS CSP

- 1. Simple scheduling
- 2. Knapsack
- 3. Travelling Salesman Problem (TSP)
- 4. Sudoku

Determine the time at which each professor must teach. The classes are all 1 hour long, and there is a single room.

Variables?
Domains?
Constraints?

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

Variables: P, J, A, Y, D, M

Domains: $D_p=3..6$, $D_j=3..4$, $D_A=2..5$, ...

Hard constraints: $P \neq J \neq A \neq Y \neq D \neq M$

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

Oh... and also... Jane, Anne and Dave want to teach as early as possible.

Cost function

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

Variables: P, J, A, Y, D, M

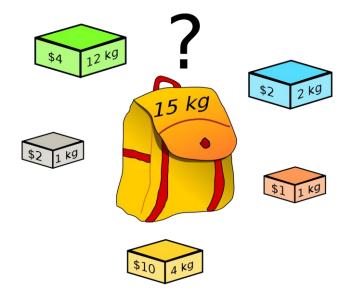
Domains: $D_P=3..6$, $D_j=3..4$, $D_A=2..5$, ...

Hard constraints: $P \neq J \neq A \neq Y \neq D \neq M$

Cost function: F = J + A + D

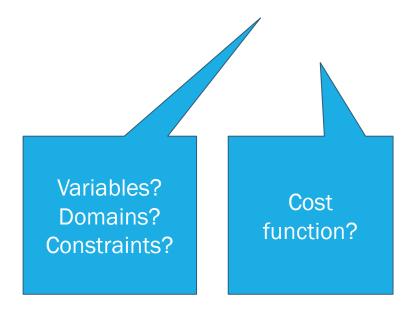
Goal for optimization: Minimize(F)

KNAPSACK PROBLEM

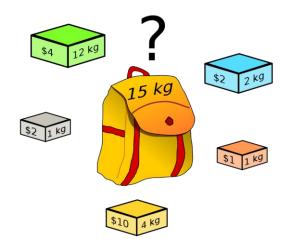


There is a knapsack of capacity M, and there are N articles of weight S_i, and value/cost C_i.

Choose the articles to place in the knapsack to maximize the cost of the knapsack.



KNAPSACK PROBLEM



Variables: X₁... X_n

Domains: $D(X_i)$ in [0,1] (item included or not)

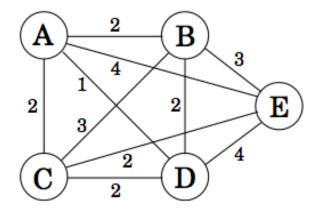
Hard constraint: $S_1^* X_1 + S_2^* X_2 + ... + S_n^* X_n < M$

Cost function: $F = C_1 * X_1 + C_2 * X_2 + ... + C_n * X_n$

Goal for optimization: Maximize(F)

TSP

Try to visit all cities in the minimum amount of time, returning to the starting city.



Variables: V1, V2, V3, V4, V5

Domains: D_{Vi}=A,B,C,D,E

Cost function: F = C(V1,V2) + C(V2,V3) + C(V3,V4) + C(V4,V5) + C(V5,V1)

Goal: Minimize F

Hard constraints could be added if a partial ordering was required, or a specific starting city, etc.

SUDOKU

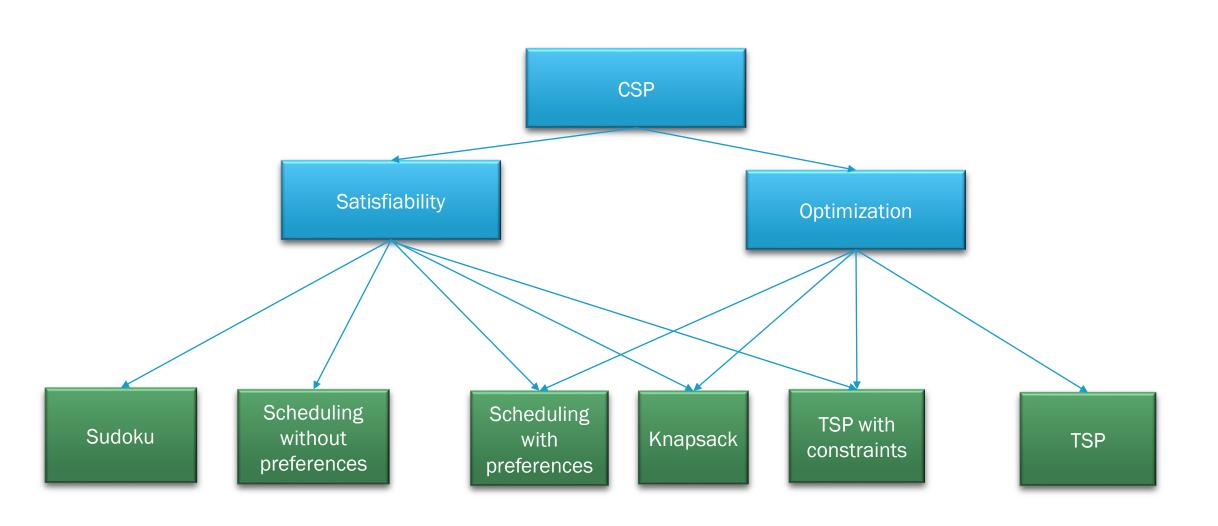
	3		2		6	
9		3		5		1
	1	8		6	4	
	8	1		2	9	
7						8
	6	7		8	2	
	2	6		9	5	
8		2		3		9
	5		1		3	

Variables: X_{11} ... X_{99} (indices are identifiers of row and column)

Domains: D(X_{ij}) in [1,9] Constraints: X_{ij} != X_{ik} pour j!= k X_{ij} != X_{kj} pour i!= k X_{ij} != X_{kw} pour 1 <= i,k <= 3 && 1 <= j,w <= 3 X_{ij} != X_{kw} pour 1 <= i,k <= 3 && 4 <= j,w <= 6 X_{ij} != X_{kw} pour 1 <= i,k <= 3 && 7 <= j,w <= 9

Cost function: None

Goal: Satisfy all hard constraints





- How to formulate problems as Constraint Satisfaction Problems
- Presentation of four classical problems that can be formulated as CSP:
 - Scheduling
 - Knapsak
 - TSP
 - Sudoku
- Difference between satisfiability and optimisation

Part 2 Greedy Search

Greedy search follows a STRATEGY to move forward systematically.

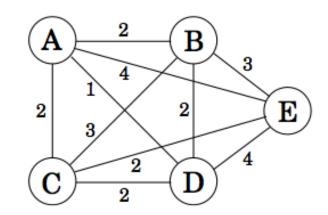
The strategy determines the next action to take.

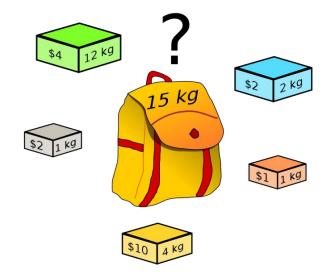
A greedy search is considered a heuristic search (and not a blind search) because domain knowledge can be included in the strategies.

The algorithm will go back (backtrack) when it reaches a dead end.

CLASSIC PROBLEMS

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6





	3		2		6	
9		3		5		1
	1	8		6	4	
	8	1		2	9	
7						8
	6	7		8	2	
	2	6		9	5	
8		2		3		9
	5		1		3	

GREEDY SEARCH TO SOLVE A SUDOKU

	3		2		6	
9		3		5		1
	1	8		6	4	
	8	1		2	9	
7						8
	6	7		8	2	
	2	6		9	5	
8		2		3		9
	5		1		3	

Strategy 1:

- Fill in numbers from row 1 to 9.
- Go from left to right for each row.
- Use the smallest number that satisfies the constraints.

GREEDY SEARCH TO SOLVE A SUDOKU

	3		2		6	
9		3		5		1
	1	8		6	4	
	8	1		2	9	
7						8
	6	7		8	2	
	2	6		9	5	
8		2		3		9
	5		1		3	

Strategy 2:

- Explore columns in order of most constrained to less constrained.
- Fill in the columns from top to bottom.
- Use a number at random that satisfies the constraints.

GREEDY SEARCH FOR PLANNING

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

Greedy strategy #1:

Alphabetical order, smaller non-conflicting value

Α	D	J	М	Р	Υ
2	3	4	1	5	?

GREEDY SEARCH FOR PLANNING

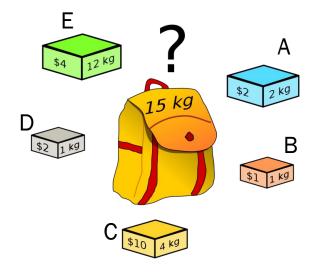
teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

Greedy strategy #2:

Most contrained to least constrained domain

J	D	Υ	А	Р	М
З	4	2	15	6	1

GREEDY SEARCH FOR KNAPSACK

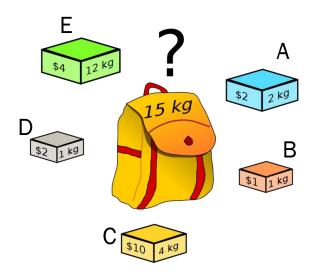


Greedy Strategy #1:

Choose the highest value first. For two equal values, choose the least heavy.

С	D	А	В	Total	
10\$	2\$	2\$	1\$	15\$	
4kg	1kg	2kg	1kg	8kg	

Now we are in front of a constrained optimization problem



Greedy Strategy #2:

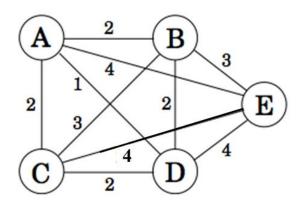
Choose heaviest first. If two equal weights, choose highest value.

E	A	D	Total	
4\$	2\$	2\$	8\$	
12kg	2kg	1kg	15kg	

GREEDY SEARCH FOR TSP

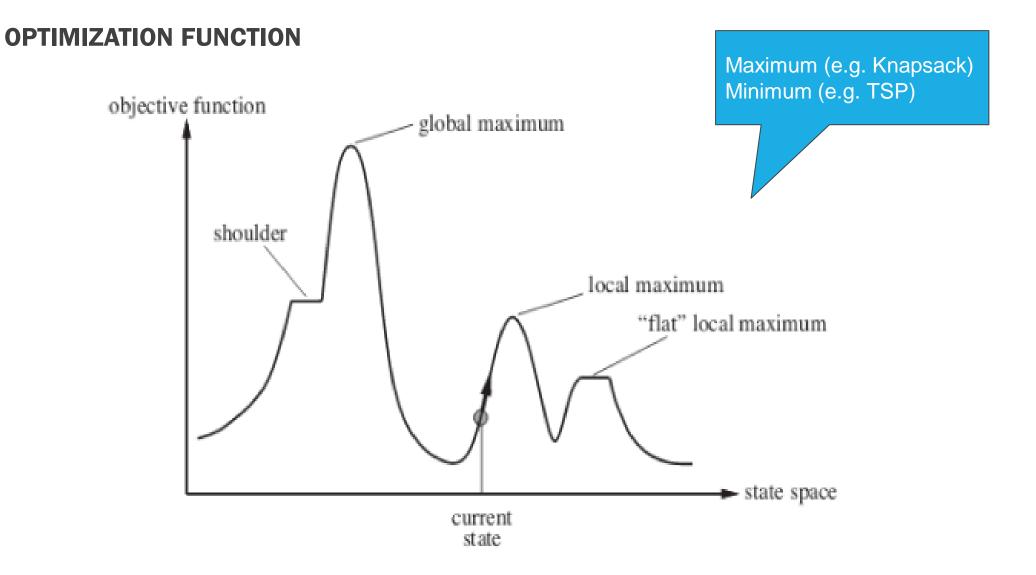
Greedy strategy:

Go to the closest city. If 2 equal choices, select in descending alphabetical order (Z..A).



It is a pure optimisation problem (if starting city is not constrained)

T1	T2	T3	T4	T5	Back	Cost
D	А	С	В	E	D	
	1	2	3	3	4	13



OPTIMIZATION FUNCTION

Local maximum (or minimum): There exists a better solution that cannot be reached by making local moves according to the cost function.

Global maximum (or minimum): Where the optimal solution is found. Where the cost function is minimized (or maximized).

Plateau: An area of the search space which provides no clue as to where to go since all neighbors seem locally equal in their evaluation of the cost function.



- Greedy search definition
- Examples of using strategies on 4 classic examples
- Limitations of greedy search

Part 3 Randomized Searches

THE ROLE OF RANDOMNESS

RANDOMNESS - At the heart of the idea of exploitation vs exploration.

Exploitation:

Following a strategy (such as greedy)

Exploration:

 Make "random" choices (at least other than what is guided by the strategy)

RANDOMIZED SEARCHES

Random restart

- We try to create a first complete solution.
- We restart from the beginning with a new starting point.

Random step

We introduce random steps within the construction of a solution.
 Sometimes we take a path that is not locally the best.

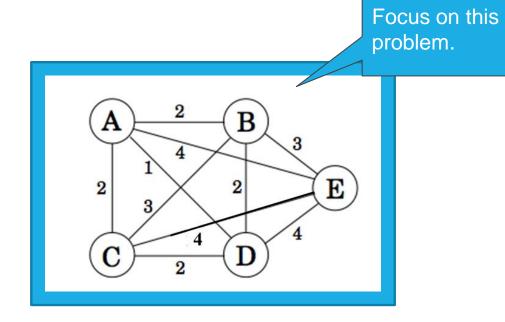
Random modification

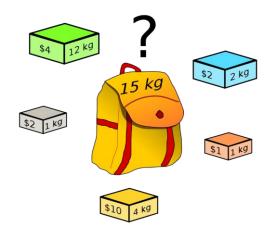
- We create a first complete solution.
- We then modify parts of the solution following some random strategy.

CLASSIC PROBLEMS

teacher	min	max
Peter	3	6
Jane	3	4
Anne	2	5
Yan	2	4
Dave	3	4
Mary	1	6

	3		2		6	
9		3	_	5		1
	1	8		6	4	
	8	1		2	9	
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	6	7		8	2	
	2	6		9	5	
8		2		3		9
	5		1		3	

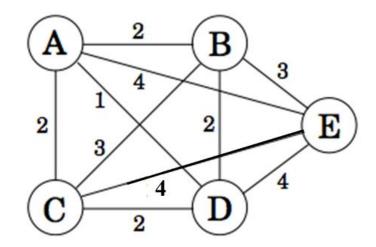




GREEDY SEARCH FOR TSP

Greedy strategy:

Go to the closest city. If 2 equal choices, select in descending alphabetical order (Z..A).



T1	T2	T3	T4	T5	Back	Cost
D	A	С	В	E	D	
	1	2	3	3	4	13

RANDOM RESTART

Algorithm for search with random restart

- We try to create a first complete solution.
- We restart from the beginning with a new starting point.

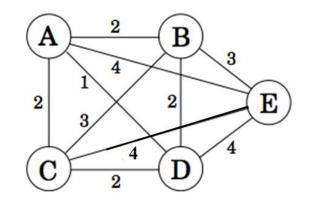
RANDOM RESTART

First solution...

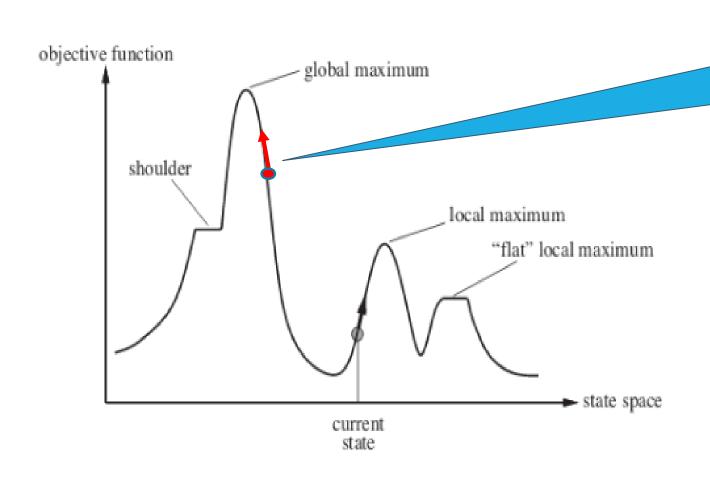
T1	T2	T3	T4	T5	back	Cost
D	А	С	В	E	D	
	1	2	3	3	4	13

We start over...

T1	T2	T3	T4	T5	T1	Cost
С	D	А	В	E	С	
	2	1	2	3	4	12



RANDOM RESTART



If we restart here, we are in better position to reach the global maximum.

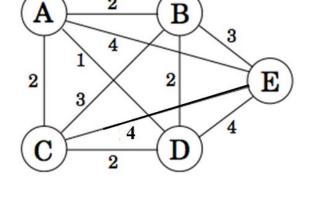
RANDOM STEP

Algorithm for search with random step

 We introduce random steps within the construction of a solution. Sometimes we take a path that is not locally the best.

RANDOM STEP

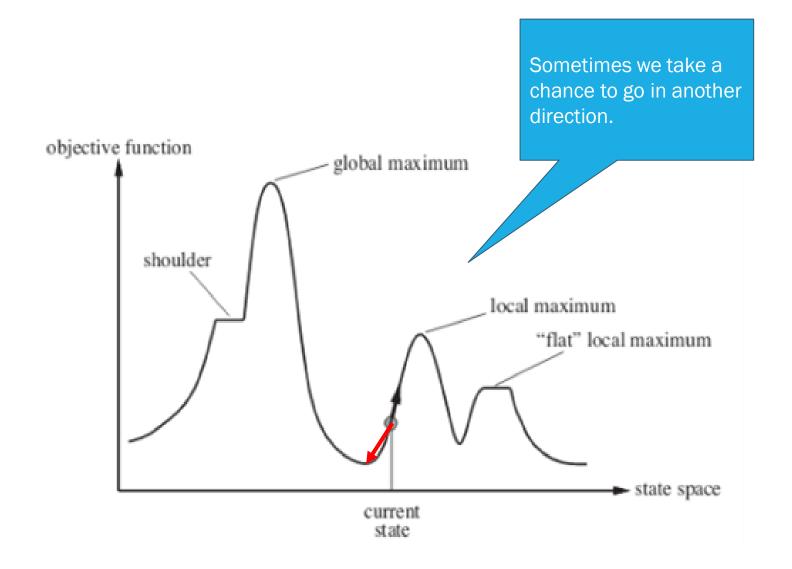
Choose B even if it has a highest cost.



T1	T2	Т3	T4	T5	Coût
С	D	В			
	2				

Use probabilities to manage this choice.

RANDOM STEP



Algorithm for search with random modification

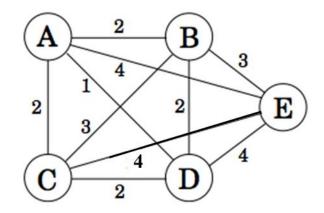
- We create a first complete solution.
- We then modify parts of the solution following some random strategy.

First solution...

T1	T2	T3	T4	T5	retour	Coût
D	А	С	В	Е	D	
	1	2	3	3	4	13

We exchange cities (modification)...

T1	T2	T3	T4	T5	retour	Coût
D	Α	С	Е	В	D	
	1	2	4	3	2	12

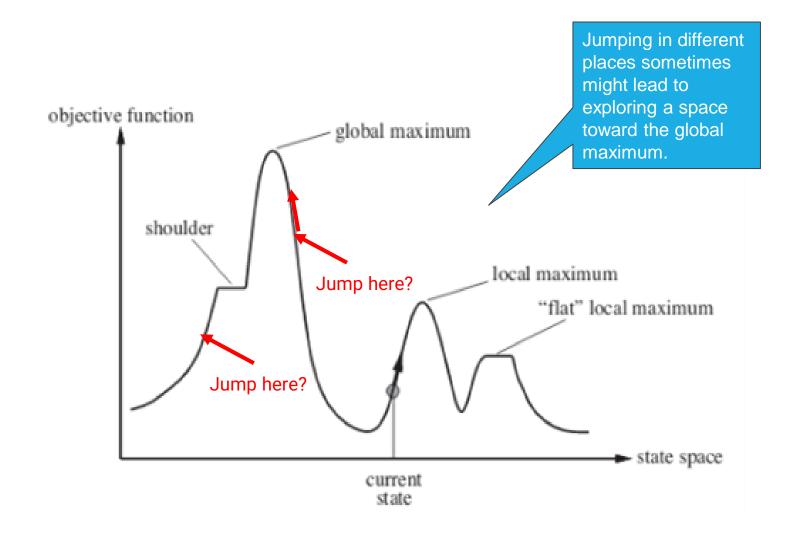


Generic algorithm:

- Start with an initial (random / greedy) solution
- Repeat for N iterations:
 - Make local changes
 - If better (according to cost function):
 - Keep change
 - Else
 - Keep change (according to some probability)

The algorithm also keeps track of the best solution so far

Variations exists on how to calculate/adjust such probability



RANDOMIZED SEARCHES

Random restart

- We try to create a first complete solution.
- We restart from the beginning with a new starting point.

Random step

We introduce random steps within the construction of a solution.
 Sometimes we take a path that is not locally the best.

Random modification

- We create a first complete solution.
- We then modify parts of the solution following some random strategy.

EVALUATION OF RANDOMIZED SEARCHES

How to evaluate?

If we introduce random in the algorithm, we must repeat it many times to measure an average of its performance.

The performance could be in terms of runtime and/or quality of the obtained solution(s).



- Randomized searches
- Algorithms:
 - Random restart
 - Random step
 - Random modification



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