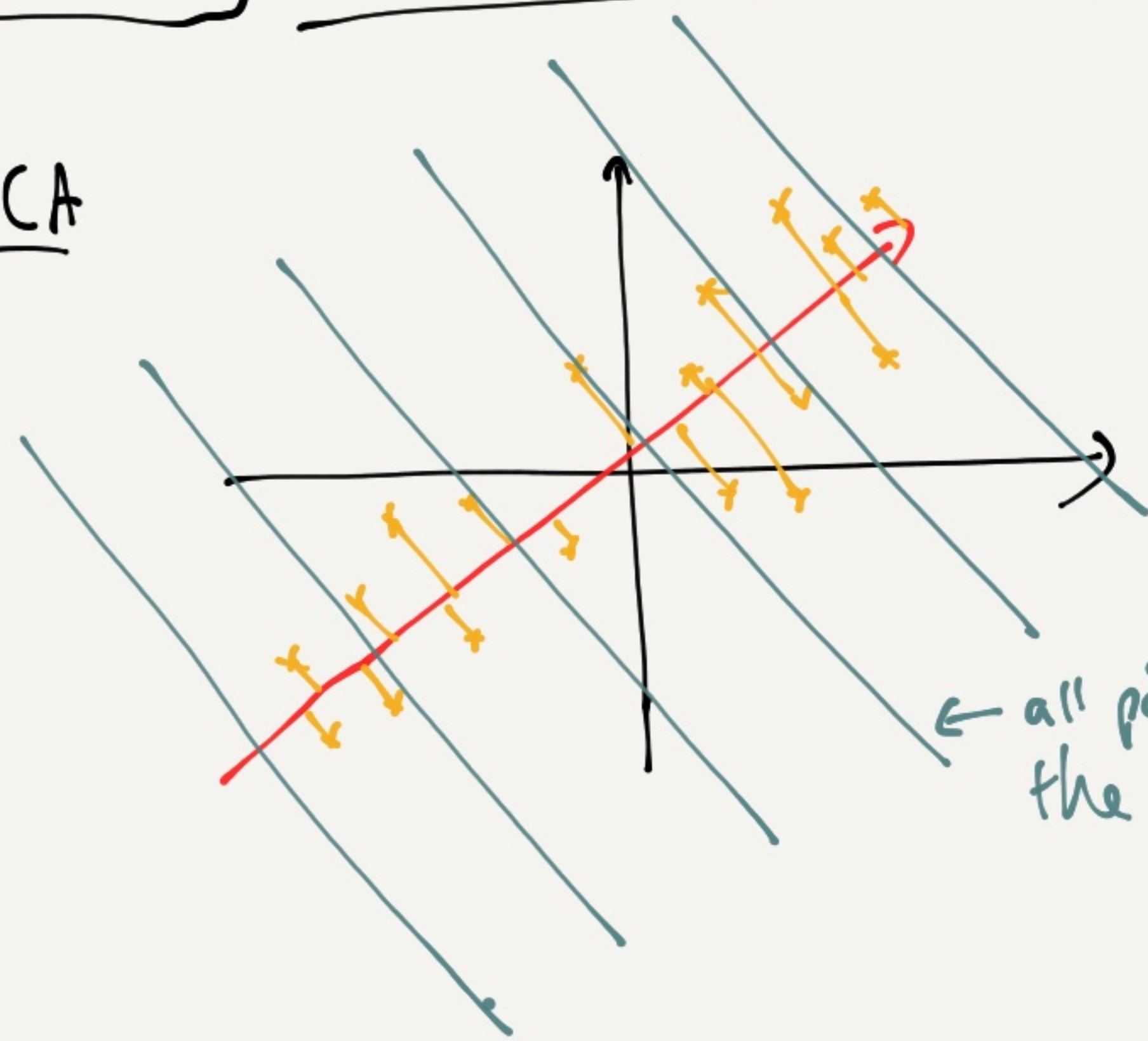


Lecture 11 - Nonlinear Dim. Reduction.

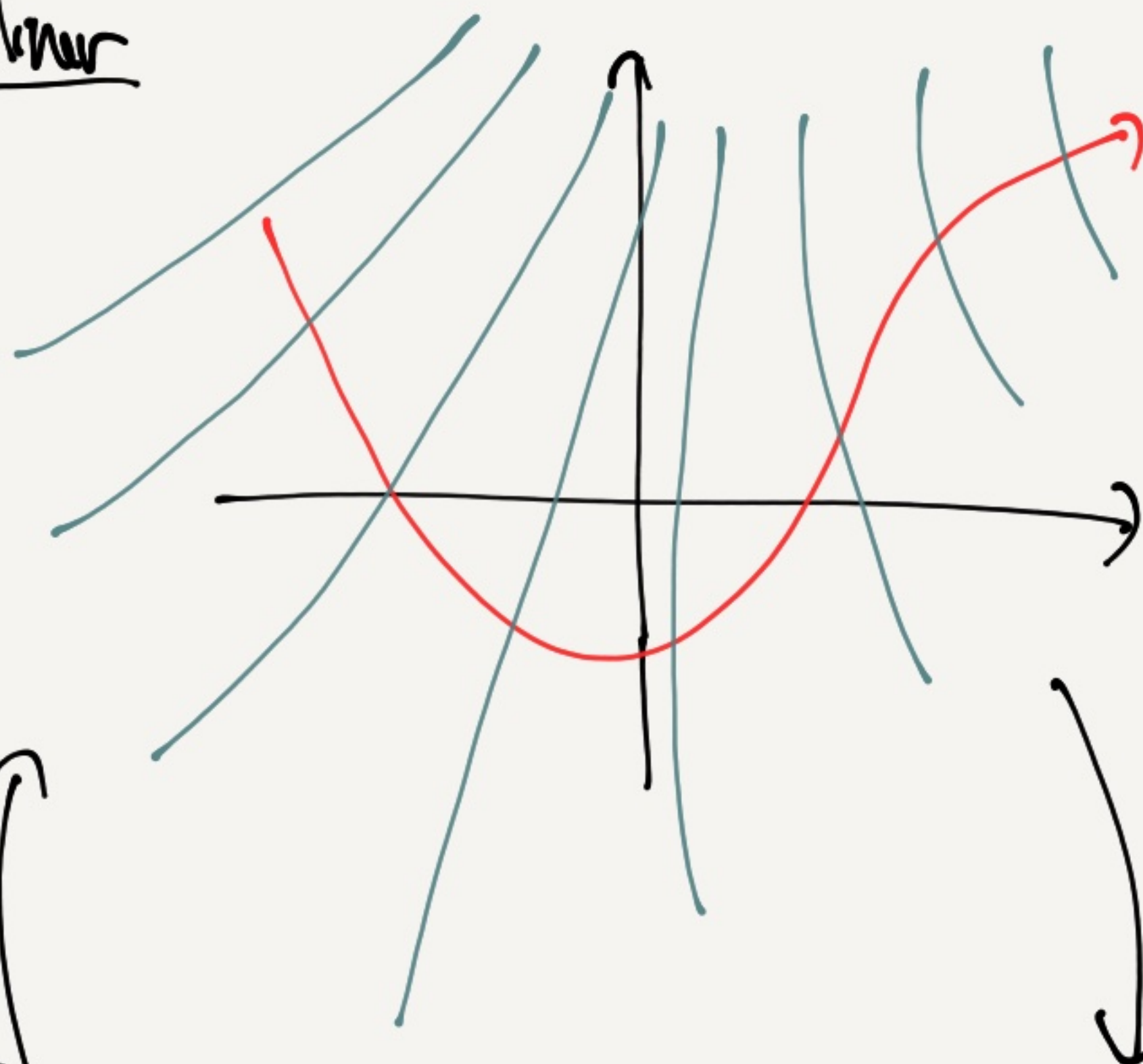
CS5487 Lecture Notes (2022B)
Prof. Antoni B. Chan
Dept of Computer Science
City University of Hong Kong

PCA



← all points on this line have the same PCA coefficient

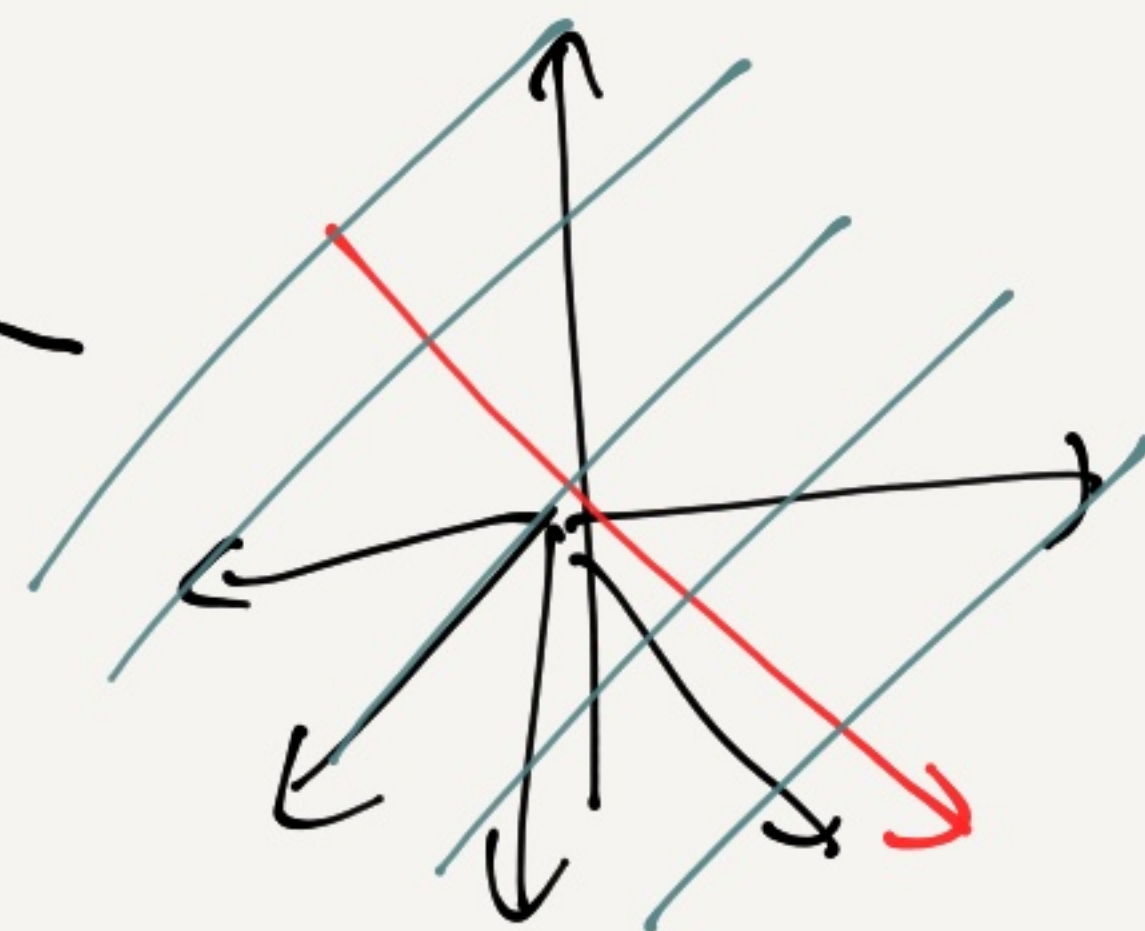
Nonlinear



nonlinear projection onto nonlinear function.

Φ : apply xformation & kernel trick

nonlinear function in original space



linear function in high-dim space

Kernel PCA:

Data: $\{x_1, \dots, x_N\}$

Apply feat xform: $x_i \rightarrow \phi(x_i)$

$$[x_1, \dots, x_N] = X \rightarrow \Phi = [\phi(x_1) \dots \phi(x_N)]$$

• Assume xformed data is centered: $\sum_i \phi(x_i) = 0$

• Covariance matrix in high-dim space:

$$C = \frac{1}{N} \sum_{i=1}^N \phi(x_i) \phi(x_i)^T$$

(Note: zero mean)

• Find (λ_j, v_j) eigenvalue/eigenvectors.

$$C v_j = \lambda_j v_j$$

$$\frac{1}{N} \sum_{m=1}^N \underbrace{\phi(x_m) \phi(x_m)^T}_{a_{m,j}} v_j = \lambda_j v_j$$

Hence, v_j has the form $v_j = \sum_{i=1}^N a_{ij} \phi(x_i) = \Phi a_j$

$$\text{where } a_j = \begin{bmatrix} a_{1j} \\ \vdots \\ a_{Nj} \end{bmatrix}$$

i.e. eigenvector is a linear combo of $\phi(x_i)$'s.

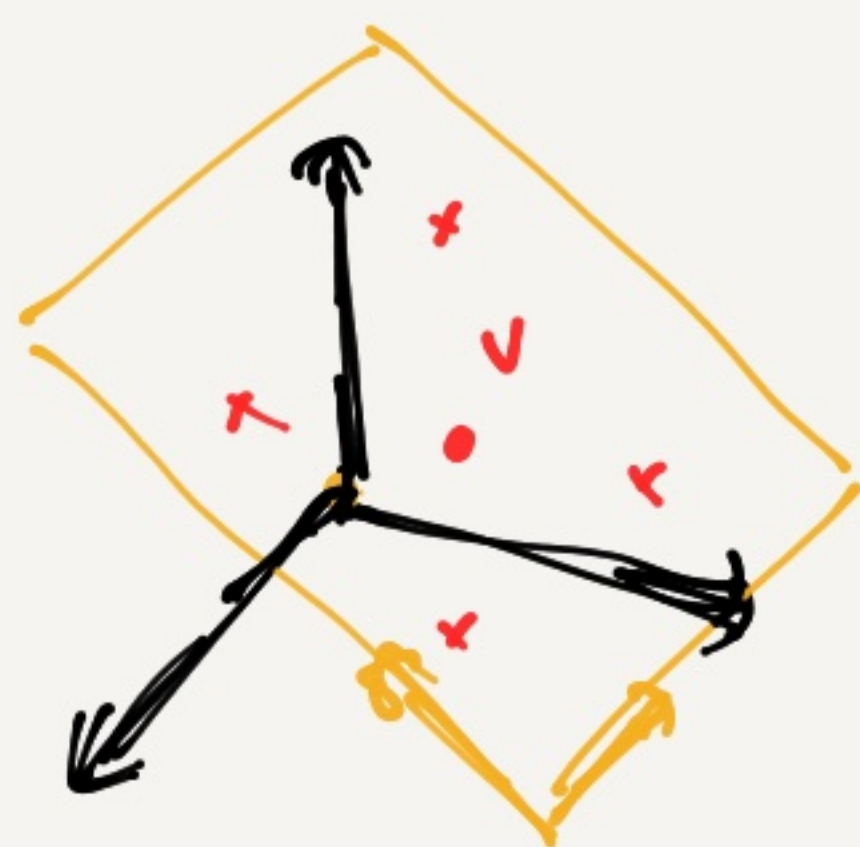
We need to find a_j

Substitute for $v_j = \Phi a_j$

$$\frac{1}{N} \sum_m \underbrace{\phi(x_m) \phi(x_m)^T}_{\Phi} \Phi a_j = \lambda_j \Phi a_j$$

$$\frac{1}{N} \underbrace{\Phi \Phi^T \Phi}_{\Phi} a_j = \lambda_j \Phi a_j$$

eigenvector is linear combo of $\phi(x_i) = \text{span}(\phi(x_1), \dots, \phi(x_N))$



An equivalent set of eqns is to project into the coordinates of span of Φ , & solve there.

\Rightarrow premultiply by Φ^T

$$\Rightarrow \frac{1}{N} \underbrace{\Phi^T \Phi}_K \underbrace{\Phi^T \Phi}_K a_j = \lambda_j \underbrace{\Phi^T \Phi}_K a_j$$

\swarrow kernel trick

$$\Rightarrow \boxed{K K a_j = N \lambda_j K a_j}$$

① if K is invertible, then solve:

$$\boxed{K a_j = N \lambda_j a_j}$$

② if K is not invertible, the only difference is there eigenvectors w/ $\lambda_j = 0$, but these are not PC's because $\lambda = 0$. Solve ① anyways.

Verify: suppose (a_j, λ_j) are eigenvector/value of K
s.t. $K a_j = N \lambda_j a_j$, $\lambda_j \neq 0$, $a_j^T a_j = 1$

original eqn:

$$\underbrace{K}_{N \lambda_j} a_j = N \lambda_j \underbrace{K}_{N \lambda_j} a_j$$

$$\underbrace{N \lambda_j}_{N \lambda_j} K a_j = \underbrace{N \lambda_j}_{N \lambda_j} \underbrace{N \lambda_j}_{N^2 \lambda_j^2} a_j$$

$$N^2 \lambda_j^2 a_j = N^2 \lambda_j^2 a_j \quad \checkmark$$

PC should be normalized

$$\underbrace{v_j^T u_j}_{=1} = a_j^T \Phi^T \Phi a_j = a_j^T \underbrace{K}_{= N \lambda_j} a_j = N \lambda_j a_j^T a_j$$

$$\text{Thus, rescale } a_j \leftarrow \frac{1}{\sqrt{N \lambda_j}} a_j$$

Kernel Centering

How to center the feature space?

centered features:

$$\tilde{\phi}(x_0) = \phi(x_0) - \frac{1}{N} \sum_{k=1}^N \phi(x_k)$$

mean in f.s.

$$= \phi(x_0) - \frac{1}{N} \underline{\Phi} \underline{1}$$

1 vector = $\begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$

centered data:

$$\tilde{\underline{\Phi}} = \underline{\Phi} - \left[\frac{1}{N} \underline{\Phi} \underline{1} \right] \underline{1}^T = \underline{\Phi} - \frac{1}{N} \underline{\Phi} \underline{1} \underline{1}^T = \underline{\Phi} (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T)$$

Centered kernel matrix

$$\tilde{\underline{K}} = \tilde{\underline{\Phi}}^T \tilde{\underline{\Phi}} = (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T)^T \underbrace{\underline{\Phi}^T \underline{\Phi}}_{\underline{K}} (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T)$$

$$\tilde{\underline{K}} = (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T) \underline{K} (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T)$$

test kernel:

$$\tilde{K}(x_*, x_j) = k(x_*, x_j) - \frac{1}{N} k_*^T \underline{1} - \frac{1}{N} \underset{\substack{\uparrow \\ \text{jth row of } K}}{k_j^T} \underline{1} + \frac{1}{N} \underline{1}^T \underline{K} \underline{1}$$

Summary: KPCA

- 1) Calculate kernel matrix: $\underline{K} = [k(x_i, x_j)]_{i,j}$
- 2) Center the kernel: $\tilde{\underline{K}} = (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T) \underline{K} (\underline{I} - \frac{1}{N} \underline{1} \underline{1}^T)$
- 3) Find the top D eigenvectors: $\tilde{\underline{K}} \underline{a}_j = \lambda_j \underline{a}_j, j=1 \dots D$
- 4) Scale: $\underline{a}_j \leftarrow \frac{1}{\sqrt{\lambda_j}} \underline{a}_j$
- 5) project data x_* : $z_{*,j} = \tilde{\underline{K}}_*^T \underline{a}_j$
 $z_{*,j} = \sum_{i=1}^N a_{i,j} \tilde{K}(x_*, x_i)$

Note: original problem needs d -dim eigenvector
kernel problem " N -dim eigenvector

Pick problem that is more efficient.

PS 10-15: Kernelized FLD \rightarrow kernel disc. analysis.

Pre-image Problem

Given PCA coeff z , we can reconstruct \hat{x} , e.g.
 zeroing x .

$$\hat{x} = \sum_j v_j z_j$$

What about KPCA?

- Given z , what is the high-dim feature?

$$\hat{\phi} = \sum_j v_j z_j = \sum_j \Phi a_j z_j = \Phi \left(\sum_j a_j z_j \right) \leftarrow \begin{array}{l} \text{linear combo of } \phi(x_i) \\ \hat{\phi} \in \text{span}(\Phi) \end{array}$$

BUT, not all points $\text{span}(\Phi)$ have a corresponding x !



Example: let $\phi(x) = \begin{bmatrix} x^2 \\ x \end{bmatrix}$

$$x_1 = 1 \Rightarrow \phi(x_1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$x_2 = 2 \Rightarrow \phi(x_2) = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

$$\text{let } \hat{\phi} = \phi(x_1) + \phi(x_2) = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

what is \hat{x} s.t. $\hat{\phi} = \phi(\hat{x})$?
 there is no \hat{x} possible.

Approximate Pre-Image

general problem: $\hat{\phi} = \Phi \alpha = \sum_i \alpha_i \phi(x_i)$ given

Find: $\hat{x} = \underset{x}{\operatorname{argmin}} \|\phi(x) - \hat{\phi}\|^2$ find the x that gives the closest ϕ in the f.s.

$$\hat{x} = \underset{x}{\operatorname{argmin}} k(x,x) - 2 \sum_i \alpha_i k(x,x_i) + \underbrace{\sum_i \sum_j \alpha_i \alpha_j k(x_i,x_j)}_x$$

$$\hat{x} = \underset{x}{\operatorname{argmin}} k(x,x) - 2 \sum_i \alpha_i k(x,x_i)$$

Soln 1: nearest neighbors

select $x \in X$ (training data)

Soln 2: solve optimization problem numerically w/ package.

Soln 3: Suppose $k(x,x)=1$, $k(x_i,x_j) \geq 0$ (e.g. Gaussian)

$$\hat{x} = \underset{x}{\operatorname{argmin}} - \sum_i \alpha_i k(x,x_i) = \underset{x}{\operatorname{argmax}} \underbrace{\sum_i \alpha_i k(x,x_i)}_{\langle \phi(x), \hat{\phi} \rangle} = \underset{x}{\operatorname{argmax}} \left(\sum_i \alpha_i k(x,x_i) \right)^2$$

assume homogeneous kernel, $k(\|x-x'\|^2)$

iterative algo.

$$\hat{x} \leftarrow \frac{\sum_i \alpha_i k'(\|x_i - \hat{x}\|^2) x_i}{\sum_i \alpha_i k'(\|x_i - \hat{x}\|^2)}$$

Similar to mean-shift w/ weights α_i on each point x_i