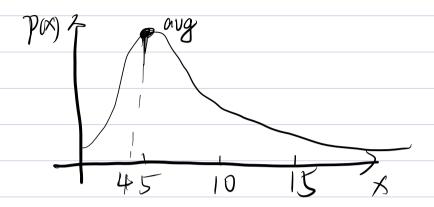
I Probability Theory Review
1. Random vonidhe
X takes a value in X (set of possible values)
according to the outcome of an event. Associated with $rv. X$ is a distribution $P(X=x)$
that describes the frequency of the events
Example: Discrete r.v. indicator variable # of people in a room
$\mathcal{X}=\{0,1\}$ $\mathcal{X}=\mathbb{Z}_{+}$
Probability mass function (p.m.f.)
$P(X=x)=probability of x occurring (\sum_{x\in x} P(X=x)=1)$
$0 \leq \beta(\chi = x) \leq 1$
Continuous rv. sensor reading NER
probability density function (p.df.)
p(x) = Likelihood of x = not precise the prob
$p(\alpha \in x \in b) = \int_a^b p(x) dx \cdot (\int p(x) dx = 1, o \neq p(x), \forall x)$
Notation: $P(X=x) = p(x) = P_{X}(x) = P_{X}(x)$
Example Dictionation
Example Distribution:
Bernoulli (coin)
$\mathcal{N} = \{0, 13, \pi = \text{prob that } 1 \text{ occurs} \}$
$ \begin{cases} P_{\times}(0) = 1 - \pi \\ P_{\times}(1) = \pi \end{cases} \Rightarrow P(x) = \pi^{\times}(1 - \pi)^{1 - \times} $
$P_{X}(t) = T$
· poisson (# of arrivals in a fixed time period)
$X_1 = X_1 = \{0, 1, 2, \dots\}$, $\lambda = \text{overage a misul rate}$

 $p(x) = \frac{1}{x!} e^{-\lambda} \lambda^{x}$



· Normal (Gaussian)

R=R · u= mean = Var

N = Standard devotion

 $p(x) = \frac{1}{\sqrt{2\pi a^2}} e^{-\frac{1}{2a^2}(x-u)^2}$ 11-20 M - 0 M - 10 M - 20 M -

Central Limit Theorem (CLT) Sum of N 7.0. -> Bravesian distribution

for large N.

Joint distribution

distribution over more than
$$1 \text{ r.v.}$$

probability / likelihood of $X=x$ or $Y=y$:

 $P(X=x, Y=y) = p(X,y)$

Magnhal distribution

alistribution over one variable in the joint

$$P(X=x) = \sum_{y \in Y} P(X=x, Y=y)$$

$$P(X) = \sum_{y \in Y} p(X,y) dy \quad marginalization"$$
(because it is written on the margin of the table.)



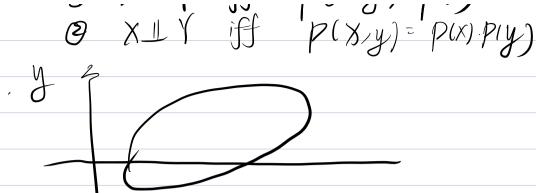
Conditional distribution

distribution of one r.v. when the value

of another r.v. is given $P(X=x \mid Y=y) = \frac{P(X=x, Y=y)}{P(Y=y)}$

3- Statistical independence
distribution of a r.v. does not change
given the value of another r.v.

10 X ILY iff D(X)Y)=D(X)



24. Bayes' Rule
$$P(y|x) = \frac{P(x|y) \cdot p(y)}{P(x)}$$

get ply(x) only from p(x|y) ply)

$$E_{X}(f(x)) = \sum_{x \in X} f(x) \cdot p(x)$$

• mean
$$E[x] = \int x p(x) dx = Mx$$
• Vortionce $Vor[x] = E[(X - E(x))] = Ox^2$

$$= E[x^2] - (E(x))^2$$
• Covariance $Cov(x,y) = Exy[(X - E(x))(y - E(y))]$

$$= \int (X - Mx)(y - My)p(x,y)dxdy$$

$$= E[x](xy) - E[x)E[y] = Ox^2y$$

$$= E[x](xy) - E[x](xy) - E[x](xy) = Ox^2y$$

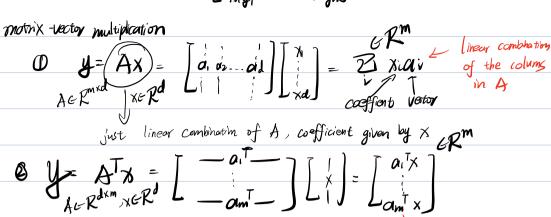
$$= E[x](xy) - E$$

I. Linear Algebra

1. Column Vector: $8 \in \mathbb{R}^d$ $X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ (usually column centric)

2. Matrix

A of $\mathbb{R}^{m \times n}$ A in \mathbb{R}^n A in $\mathbb{R}^$



inner products between columns of AV Vertor X

$$X = \begin{bmatrix} x_1 \\ y_4 \end{bmatrix}, x_2 = \mathbb{R}^d$$

Notation
$$p(X_1, X_2, ..., X_d) = p(X)$$
véctor

$$\int p(x) - dx = 1 \iff \int \int p(x_1, x_2, \dots, x_d) dx_1 - dx_d = 1$$

$$M = \begin{bmatrix} M_1 \\ M_2 \end{bmatrix} = E[X] = \int_{\mathbb{R}^d} X p(x) dx$$

CoVariance motrix

2deg.

$$= \left[(\chi_1 - u_1)^2 (\chi_1 - u_1)(\chi_2 - u_2) \right]$$

(X,-U,) (X2-N2) (X2-U2)2

$$= \begin{bmatrix} \lambda_1 & \lambda_2 \\ \lambda_1 & \lambda_2 \end{bmatrix}$$

3. multivariant. Graussian

