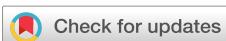


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Multiple mechanisms of spiral wave breakup in a model of cardiac electrical activity

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It has become widely accepted that the most dangerous cardiac arrhythmias are due to reentrant waves, i.e., electrical wave(s) that recirculate repeatedly throughout the tissue at a higher frequency than the waves produced by the heart's natural pacemaker (sinoatrial node). However, the complicated structure of cardiac tissue, as well as the complex ionic currents in the cell, have made it extremely difficult to pinpoint the detailed dynamics of these life-threatening reentrant arrhythmias. A simplified ionic model of the cardiac action potential (AP), which can be fitted to a wide variety of experimentally and numerically obtained mesoscopic characteristics of cardiac tissue such as AP shape and restitution of AP duration and conduction velocity, is used to explain many different mechanisms of spiral wave breakup which in principle can occur in cardiac tissue. Some, but not all, of these mechanisms have been observed before using other models; therefore, the purpose of this paper is to demonstrate them using just one framework model and to explain the different parameter regimes or physiological properties necessary for each mechanism (such as high or low excitability, corresponding to normal or ischemic tissue, spiral tip trajectory types, and tissue structures such as rotational anisotropy and periodic boundary conditions). Each mechanism is compared with data from other ionic models or experiments to illustrate that they are not model-specific phenomena. Movies showing all the breakup mechanisms are available at <http://arrhythmia.hofstra.edu/breakup> and at <ftp://ftp.aip.org/epaps/chaos/E-CHAOEH-12-039203/> INDEX.html. The fact that many different breakup mechanisms exist has important implications for antiarrhythmic drug design and for comparisons of fibrillation experiments using different species, electromechanical uncoupling drugs, and initiation protocols. © 2002 American Institute of Physics. [DOI: 10.1063/1.1504242]

Cardiovascular disease remains the most prevalent cause of death in the industrialized world. In the United States, an estimated 10% of all deaths are sudden and are mostly due to ventricular fibrillation, a fast-developing disturbance in heart rhythm that disrupts the coordinated contractions and renders the heart unable to pump blood effectively. After decades of research, researchers still are left with an incomplete understanding of how arrhythmias like ventricular fibrillation initiate and evolve. Although the advent of implantable devices has yielded much success in avoiding arrhythmic episodes in patients diagnosed with a predisposition to ventricular arrhythmia, antiarrhythmic drug therapy is not always successful. In some cases drug use actually *increased* mortality, findings that underscore the lack of understanding of the mechanisms responsible for fibrillation. Experimental work has shown that some atrial and ventricular arrhythmias begin with the presence of scroll waves of electrical activation that rotate at higher frequencies than the

heart's natural pacemaker, preventing normal function. In many cases, existing scroll waves have been found to break and to form new waves, which in turn yield further breakup and more waves. Many theories have been developed to explain how breakup occurs. In this paper, we use a single mathematical model of cellular electrical activity to demonstrate, categorize, and explain many of the mechanisms proposed here and elsewhere and to discuss the implications of the existence of multiple mechanisms. Movies showing all the breakup mechanisms are available at <http://arrhythmia.hofstra.edu/breakup> and at <ftp://ftp.aip.org/epaps/chaos/E-CHAOEH-12-039203/> INDEX.html.²³⁶

I. INTRODUCTION

Cardiovascular disease is the most common cause of death in the industrialized world, with serious health and economic impacts. Nearly one million deaths annually are caused by cardiovascular disease in the United States alone,

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or over 40% of all deaths.¹ Almost 25% of these are victims of cardiac arrest,¹ of whom an estimated 95% die before reaching the hospital.¹ Most of these are sudden cardiac deaths² attributed to ventricular fibrillation (VF), a fast-developing electrical disturbance in the heart's rhythm that renders it unable to pump blood. While implantable cardioverter defibrillators have been highly successful in terminating arrhythmic episodes in patients with diagnosed heart disease, studies indicate that more than half of sudden cardiac deaths arise in individuals with no previous symptoms.^{1,3} Atrial fibrillation, although not as immediately life-threatening as ventricular fibrillation, causes an estimated 15% of all strokes due to clot formation from stagnation of blood in the atria.¹ Thus cardiac fibrillation remains a serious health problem.

Fibrillation arises when the heart's usual electrical rhythm is disturbed. Whereas the heart's muscular contraction usually is smooth and coordinated due to a single wave of electrical excitation that signals the cells to contract, during fibrillation the normal electrical signal is masked by higher frequency circulating activation waves, leading to small and out-of-phase localized contractions. Although some cases of fibrillation may be attributed to rapid formation of impulses arising from multiple spontaneous foci,⁴ which is known to occur experimentally⁵ in cultured ventricular muscle and atrial tissue,^{6,7} the most prevalent hypothesis is that during fibrillation, at least one^{8–11} and possibly many^{11–17} three-dimensional spirals or scroll waves of electrical activation are present, which have been observed experimentally in many preparations. Therefore, the dynamical complexity that can be observed on the surface of the heart may be due to multiple scroll waves with short and long life spans due to collisions and various tissue heterogeneities, with the observed activity rendered more complex by the high degree of rotational anisotropy in the tissue.

Although the general processes that produce fibrillation have been characterized, the precise mechanisms responsible for its onset and maintenance are not yet understood. The consequences of incomplete knowledge of arrhythmia mechanisms have been illustrated dramatically in the results of several antiarrhythmic drug trials, most notably the CAST^{18,19} and SWORD²⁰ trials, in which mortality *increased* for post-myocardial infarction (MI) patients receiving pharmacotherapy compared to placebo. In the CAST trials, the drugs being tested reduced the occurrence of premature ventricular contractions (PVCs), phenomena that can trigger arrhythmias under the right conditions. By reducing the number of PVCs, it was hypothesized that the likelihood of arrhythmia initiation would be reduced as well. However, this did not turn out to be the case, as those PVCs that did occur were far more likely to induce fibrillation than without drugs. The CAST¹⁸ trial of encainide and flecainide was stopped after a mean follow-up of 10 months, since at that time a total of 148 deaths, 106 in the antiarrhythmic drug group versus 42 in the placebo group, had been registered out of the 1498 initial patients, producing a relative risk of 2.5. Similarly, the CAST II¹⁹ trial using moricizine was terminated after studying the effects of therapy during a 14-day exposure period in which a total of 20 deaths, 17 with

antiarrhythmic therapy versus 3 with placebo, had occurred out of 665 in the study group, yielding a relative risk of 5.6.

In the SWORD trial, the pure potassium channel blocker d-sotalol was tested on the assumption that prolongation of the action potential duration might be protective and reduce all-cause mortality in high-risk patients with MI and left ventricular dysfunction, a hypothesis based on studies using amiodarone, a class III antiarrhythmic drug which showed potential for improving survival rate. Previous experiments also had shown antiarrhythmic effects for d-sotalol, such as non-inducibility of ventricular tachycardia (VT) in rabbit preparations.²¹ The SWORD trial was terminated after a mean follow-up of 148 days because of an increase in mortality in patients taking d-sotalol (78 deaths versus 48 for placebo out of 3121 patients, with a relative risk of 1.65). From the results of these trials, it is clear that a detailed understanding of arrhythmogenic mechanisms is needed so that the experiences of the CAST and SWORD trials are not repeated. In addition, the failure of the PVC suppression hypothesis, as evidenced in the CAST trial results, suggests that more than one mechanism can produce fibrillation,^{22,23} in which case trying to suppress one mechanism possibly can enhance another.

Much of our understanding of arrhythmia mechanisms has come from experiments in different preparations, most of which have been conducted in single cells or in small tissue preparations using surface arrays of electrodes. Over the last decade, optical mapping techniques²⁴ that allow visualization of the surface potentials at all sites have advanced substantially, increasing our understanding of arrhythmia dynamics, but intramural dynamics have remained largely hidden. Recently developed transmural recording techniques such as transillumination²⁵ and optical fibers,²⁶ both of which use voltage-sensitive dyes, and fiberglass needle electrodes²⁷ may address this limitation by allowing further investigation of the intramural dynamics and illuminating some of the mechanisms underlying fibrillation.

On the other hand, for over half a century, computer simulations have complemented traditional animal experiments and have contributed to the understanding of arrhythmias. In the 1940s, Wiener and Rosenblueth²⁸ began the field of computational cardiac electrophysiology by using a simple cellular automata model to describe action potential dynamics and to investigate the conditions under which arrhythmias could develop. Despite the simplicity of their models, they explained how reentrant waves could circulate around obstacles and provided a theoretical framework for the circulating waves observed in cardiac tissue experiments by Mines²⁹ in 1913 and Garrey in 1914.³⁰ [McWilliams³¹ first suggested the concept of reentry as one of the mechanisms responsible for the onset of cardiac arrhythmias in 1887.] In the 1960s, Moe³² and collaborators³³ expanded the simple cellular automata model of Wiener and Rosenblueth by adding more states and introducing a degree of randomness in the refractory period duration. Their contributions produced a dispersion of refractoriness and under certain conditions allowed reentrant excitations (spiral waves) that did not require an anchoring obstacle to rotate and that could break into multiple wavelets reminiscent of experimentally

observed fibrillatory patterns. By the 1960s and early 1970s, continuous models of general excitable media were introduced and were used to demonstrate the existence of spiral waves in isotropic tissue. With increased computer power by the early 1990s, many mechanisms of spiral wave breakup were demonstrated in two dimensions.^{34–38} By the late 1990s and early 2000s, simulations have advanced to examine three-dimensional effects,³⁹ including rotational anisotropy,^{40,41} and are beginning to investigate the contributions of anatomical structures to arrhythmogenesis.^{42–45} Together, the simulation results of the last several decades have advanced spiral wave theory by proposing various mechanisms for the onset and evolution of spiral wave breakup.

In this paper, we discuss a number of mechanisms of spiral wave breakup that have been hypothesized to contribute to arrhythmia initiation and maintenance in homogeneous cardiac tissue. While some of these mechanisms (but not all) have been described before, each using one particular ionic model and thus requiring the use of several different models to show all the mechanisms, we intend to demonstrate all of them using one single model, for two reasons. First, illustrating all the mechanisms using only one model shows that they are model-independent phenomena. Second, analyzing how these different mechanisms relate to parameter regimes corresponding to different electrophysiological properties within the context of one model facilitates comparison of the requirements for each mechanism that can underlie the transition from tachycardia to fibrillation.

The rest of this paper is organized as follows. In Sec. II we review the restitution properties of action potential duration and conduction velocity, which are mesoscopic characteristics that can help in describing cardiac tissue, along with the different trajectories and dynamics of stable spiral waves. In Sec. III we discuss the simplified ionic model used and its parameters. Section IV describes six different mechanisms for spiral wave breakup in two dimension. In Sec. V we show a quasi-three-dimensional case where boundary effects can become important in some regimes. Section VI describes three different mechanisms that can occur in three dimensions (3D). In Sec. VII we discuss the ten mechanisms described earlier and the implications of our results. Section VIII presents conclusions and summarizes further prospects. Finally, in the Appendix, the equations and model parameters for all simulations, a description of the protocol used to measure restitution curves, and a brief discussion of numerical methods are presented. We note that although ten parameter sets are listed and ten breakup mechanisms are presented, there is not a one-to-one correspondence between them.

II. REVIEW

In this section we describe two mesoscopic characteristics found in cardiac tissue, namely action potential duration restitution and conduction velocity restitution. [Throughout this paper, the term mesoscopic is used to describe properties at scales intermediate between subcellular and whole organ.] These restitution properties incorporate in a functional form the ionic complexity underlying the relationship of pulse duration and velocity with respect to the previous activation

state. In addition, we describe many possible types of spiral wave tip trajectories in cardiac models.

A. Restitution of action potential duration and conduction velocity

When the heart beats at a faster rate than normal, such as during increased physical activity, the relative durations of systole and diastole are adjusted to ensure that both filling of the chambers and ejection of blood occur efficiently. An increase in frequency without a change in the systole duration would lead to a disproportionate decrease in the corresponding diastole duration, and at high frequencies, the ventricles would not be filled before contracting. For this reason, if a second action potential is initiated soon after the first, when not all ionic processes have recovered fully to their rest states, the duration of the second action potential is shorter than the first because the transmembrane current is reduced. It follows that an action potential duration (APD) is a function of both the previous APDs and the time between excitations, also known as the recovery time or diastolic interval (DI). The function depends on the different characteristics of all the ionic currents found in cardiac cells; however, the mesoscopic dynamics of the depolarization wave front and repolarization wave back, as well as the interaction between these two fronts, can be obtained by using simple experimental curves relating only APDs to DIs. These curves commonly are referred to as APD restitution curves (for example, see Fig. 4 and other figures throughout the text). Note that distinguishing the APD from the DI requires defining a voltage cutoff during repolarization. In general, a percentage of the voltage repolarization (e.g., 80%) is used as a threshold to separate the APD from the DI, and the cutoff is indicated by writing the percentage as a subscript (e.g., APD₈₀). Throughout this manuscript we use the 80% cutoff (APD₈₀) when calculating restitutions. In addition, we note that restitution curves measured in a single cell can differ from those obtained in cables or whole tissue due to the presence of electrotonic effects, as described further in Sec. VII. All APD restitution curves presented in this paper were obtained in one-dimensional (1D) cables (see the Appendix for more details).

A second fundamental mesoscopic property of excitable media and thus cardiac tissue is the restitution of conduction velocity. When a sequence of propagating pulses is produced, the influence of the preceding pulse on the subsequent one is reflected not only in its action potential duration but also in its propagation speed. Conduction velocity restitution, therefore, is the direct analog of APD restitution in the sense that it relates the speed of a pulse at a given site to the recovery time at that site or its preceding DI (for example, see Fig. 5 and other figures throughout the text). The CV depends on the orientation of the wave front with respect to the fiber axis of the cells. However, in a continuous medium with straight, parallel fibers, we can arbitrarily choose to define the fiber axis parallel to a coordinate axis. Conduction generally is slower in partially recovered tissue, so that the CV decreases with decreasing DI to a minimum velocity greater than zero. This means that propagation fails for any DI shorter than the minimum DI. Like the APD restitution,

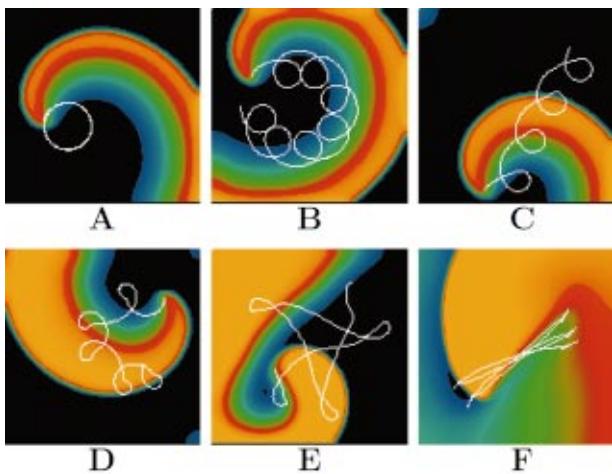


FIG. 1. (Color) Varieties of spiral wave tip trajectories. Shown are (a) circular, (b) epicycloidal (also known as meander with inward petals), (c) cycloidal, (d) hypocycloidal (also known as meander with outward petals), (e) hypermeandering, and (f) linear trajectories. Spirals are obtained with the model described in the Appendix by using parameter set 1 for (a)–(e) with progressively increasing excitability [(a) $\tau_d=0.41$; (b) $\tau_d=0.392$; (c) $\tau_d=0.381$; (d) $\tau_d=0.36$; (e) $\tau_d=0.25$] and by using parameter set 2 for (f). The voltage field colors range from orange and red (excited) to green and blue (refractory) to black (quiescent), and the levels can be compared to the voltage values in Fig. 3. Tissue size is 6.3×6.3 cm, with $\Delta x=0.025$ cm and $\Delta t=0.25$ ms.

CV restitution curves in this paper were calculated in 1D cables. Additional details are given in the Appendix.

The APD and CV restitution curves are fundamental to characterizing the wave dynamics of the system, since as a first approximation they reflect the mesoscopic effects of changes that occur in ionic currents and concentrations at the cellular level. The importance of restitution in understanding cardiac dynamics has been emphasized in numerous numerical^{34,35,46–50} and experimental studies.^{51–58}

B. Spiral wave tip trajectories

Spiral waves in cardiac tissue models and experiments can follow different types of paths,^{9,16,59–64} from circles to linear trajectories with sharp turns. In between there is a wide range of different trajectories that follow a series of winding, loop-like bends that turn upon themselves and are known as meandering trajectories (see Fig. 1). Although useful for analyzing the stability of spiral waves, to date no theory explaining spiral tip trajectories has been developed in terms of the APD and CV restitution curves, partly because tip trajectories depend not only on the wavelength⁶⁴ and the excitable gap,⁶⁵ both of which can be obtained from the restitution curves, but also on the critical radius of curvature^{66–68} (i.e., tissue diffusion and excitability given by the rate of rise and the threshold for excitation) and to some extent on electrotonic effects⁶⁹ (produced by the action potential shape and tissue diffusion). These last two elements in principle may be obtained by knowing the APD and CV restitutions at all possible cutoffs or thresholds (i.e., APD restitution curves formed using APD_{90} , APD_{80} , APD_{70} , etc.) to allow the effects of the shape of the action potential and interactions with neighboring cells to become apparent.

Nevertheless, predicting a spiral wave's period of rotation and tip trajectory as a function of model parameters is complex, and at present there is no analytical theory for spiral wave motion except in the weakly excitable limit.^{70,71}

Despite the lack of a general theory, some insights into which parameters can cause tip trajectories to change qualitatively among the different patterns of motion have been developed. The transition from circular to meandering motion originates by a supercritical Hopf bifurcation,^{63,72,73} which introduces a second frequency that adds modulated waves and whose onset has been explained rigorously in the large core regime by Hakim and Karma.⁷¹ Within the meander regime, the transition from epicycloidal to hypocycloidal occurs as the second frequency grows larger than the original one,⁶³ with cycloidal occurring in between when both frequencies are the same. The transition to linear core has been argued to occur⁶⁴ when the radius of rotation r produced by the faster frequency is much smaller than the spiral wavelength λ , with a rotation of the linear core at a slow rate proportional to r/λ .

In Fig. 1, we show examples of these trajectories obtained using the model described in Sec. III. Transitions such as those depicted can be obtained by varying either the sodium^{59,64,67} (excitability) or the calcium and/or potassium dynamics (wavelength).^{64,74} It is important to note that several of these trajectories have been observed experimentally in cardiac tissue,^{9,61,75,76} particularly linear cores [such as the ones shown in Figs. 1(e) and 1(f)], which apparently occur predominantly in normal cardiac tissue with a line of block approximately 1–2 cm long (see, for example, Figs. 2–5 in Ref. 16, Fig. 7 in Ref. 60, and Fig. 6 in Ref. 77).

To trace the tip trajectory, different methods have been used. For example, the so-called pivot method⁷⁸ tracks the spatially discretized grid points that did not cross a given subthreshold level of voltage in a previous period. This method only defines an *unexcited* region during a former period³⁹ and only works when the spiral wave moves very slowly and the tip trajectory is almost circular. Biktashev *et al.*³⁹ used a method that consisted of identifying the spatially discretized grid cell with neighboring nodes found in three different states that depended on a selected constant voltage. A similar method⁷⁹ differentiates between four states of the cells (exciting, excited, refractory, and rest) and identifies points that have neighbors in each of the four states. However, the accuracy of these two methods depends on the spatial resolution. Barkley *et al.*⁸⁰ used a method that is less sensitive to the effect of spatial resolution, which consists of finding the intersection between the contours of two variables. However, this method may only work for models like the FitzHugh–Nagumo (FHN),⁸¹ since one of the contours depends on the slow gate variable. Another method used efficiently for FHN-type models with two variables is to find the point of maximum cross product for the gradients of the two variables.⁸² We should mention that some of these methods do not work in three dimensions, especially when spiral waves are not perpendicular to the x – y plane.

Throughout this manuscript, we identify spiral wave tips as points with zero normal velocity at an arbitrarily chosen isopotential line that defines the boundary between the depo-

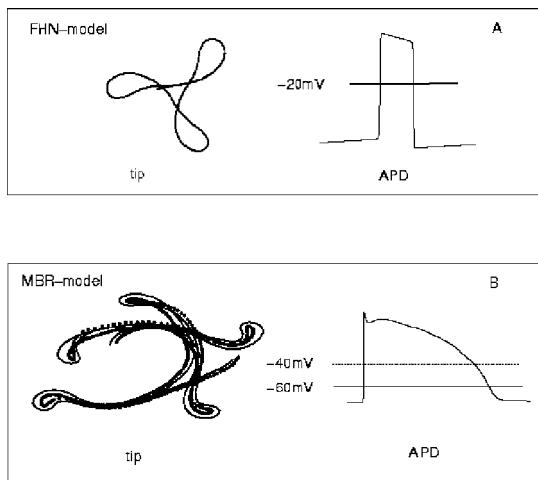


FIG. 2. Spiral tip trajectories found using the zero normal velocity method. (a) Trajectory found using an isopotential of -20 mV for the Fitzhugh–Nagumo model (Ref. 81). Since the depolarization and repolarization times are almost the same, it does not matter which isopotential value is chosen. (b) Tip trajectory of the eight-variable Beeler–Reuter model (Ref. 92) with a speedup in calcium dynamics by a factor of 2 (MBR model), using isopotentials at -60 mV (solid line) and -40 mV (dashed line). The dashed line is smaller because the gradual repolarization gives a shorter APD at -40 mV than at -60 mV . Although the specific trajectory changes slightly at different isopotential values, the overall shape of the trajectory remains the same.

larization and the repolarization wave back. This method, defined in Ref. 41, can be used at any given time with an interpolation routine, so that the spiral tip trajectory is found accurately and independently of the spatial resolution as a continuous trajectory in space as a function of time. With this method the trajectory of a scroll wave [three-dimensional (3D) spiral wave] can be obtained accurately, along with information about its curvature, twist, and torsion, which are important characteristics when analyzing scroll wave dynamics. Two other commonly used methods for determining spiral tip trajectories work equally well. The first method, which is the only method that has been used so far in both experiments¹⁷ and numerical simulations,^{17,83} uses a phase map for each recorded site as a function of time. The phase map assigns values between 0 and 2π depending on the location in phase space, or equivalently as a function of voltage as well as its time derivative, thereby avoiding the duplicate values of voltage found during the upstroke and during repolarization. Points in the tip trajectory correspond to phase singularities, which are the points where the wave front meets the back, thus producing singularity in the phase. This method has been shown to give the same results as the zero-normal velocity technique.⁸⁴ The second method follows the spiral wave trajectory by finding the points with null curvature over a given isopotential.^{67,85} The point with zero curvature is not very sensitive to slight changes in waveshape as compared to other characteristic points, such as the point of maximum curvature,⁶⁷ so that an accurate trajectory also may be obtained using this method.

Independently of the method used, the precision in positioning the spiral wave tip in cardiac tissue becomes a function of the spatially diffuse wave back because of the much slower repolarization period compared to depolarization, as

shown in Fig. 2. This unavoidable problem slightly changes the size of the trajectory depending on the isopotential or percentage of repolarization used. Nevertheless, as illustrated in Fig. 2, the basic morphology of the trajectory (e.g., linear, circular, or meandering) remains independent of the isopotential chosen. For models such as the FHN, where the wave front and wave back are thin boundary layers of width ϵ , this problem does not occur because the trajectories obtained with different isopotential values differ by less than ϵ .

III. IONIC MODEL

Throughout this paper, we use a previously described^{41,86,87} simplified mathematical ionic model for the cardiac action potential, whose purpose is not to replicate faithfully the microscale ionic complexity of cardiac cells, but rather to reproduce the action potential dynamics at a mesoscale level where restitution properties can be measured. The model was constructed so as to incorporate only the minimum set of ionic membrane currents necessary to reproduce generic restitution curves, and thus consists of three independent ionic currents. These currents can be thought as effective sodium, calcium, and potassium currents; however, we refer to them as fast and slow inward and slow outward currents as a reminder that they do not represent quantitatively measured currents. Despite their simplicity, these currents retain enough structure of the basic currents involved in cardiac excitation that their parameters can be varied to reproduce the restitution curves of more complex ionic models^{41,44,69} as well as those obtained from experimental data.^{41,45,88} Figure 3 shows examples of the model with parameters fitted to reproduce the action potential shapes and APD and CV restitution curves of two different ionic models as well as one set of experimental data.

The model consists of three variables: the membrane voltage V , a fast ionic gate v , and a slow ionic gate w . Therefore, we refer to the model as the 3V-SIM (three-variable simplified ionic model).^{41,86,87} The three variables are used to produce a total membrane current $I_m = I_{fi}(V;v) + I_{so}(V) + I_{si}(V;w)$ given by the sum of the three independent phenomenological currents. The current $I_{fi}(V;v)$ is a fast inward inactivation current used to depolarize the membrane when an excitation above threshold is induced. It depends on the inactivation gate variable v and on a fast activation gate modeled by a Heaviside step function. The current $I_{so}(V)$ is a slow, time-independent rectifying outward current used to repolarize the membrane back to the resting potential. The current $I_{si}(V;w)$ is a slow inward inactivation current used to balance $I_{so}(V)$ and to produce the observed plateau in the action potential. It depends on the inactivation gate variable w and on a very fast activation gate variable d , which has been replaced by its steady-state function $d_\infty(V)$. Using the steady state function keeps the model as simple as possible; nevertheless, the variable d can be used instead of the steady-state function in order to reproduce specific action potential (AP) shapes⁴⁴ (see Fig. 3) and to include more detailed electrotonic effects in the model dynamics.⁶⁹

In the model, the slow currents $I_{so}(V)$ and $I_{si}(V;w)$ are independent of the fast current $I_{fi}(V;v)$, allowing the APD restitution curve and the CV restitution curve to be set inde-

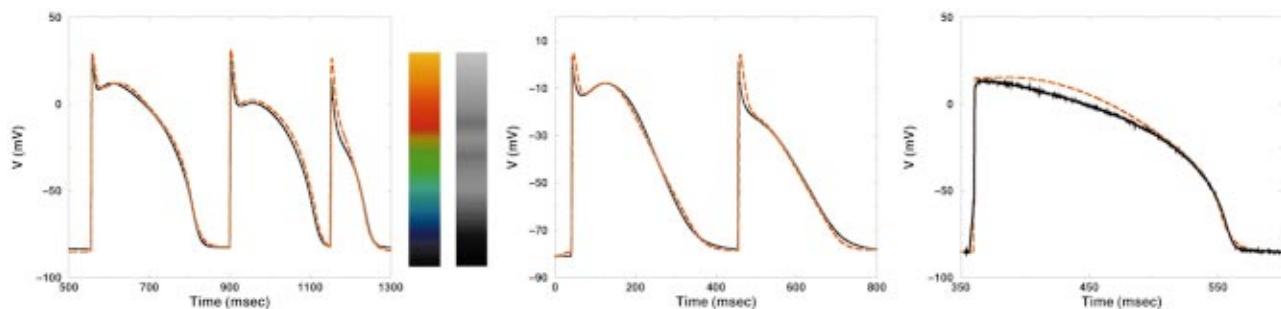


FIG. 3. (Color) Comparison of action potentials obtained using a variation of the model described in the Appendix with other models and experiments. (a) Three consecutive activations using the 8-variable Beeler–Reuter model (Ref. 92) (black) and the simplified model (Ref. 69) (red). (b) Two consecutive activations using the 24-variable Courtemanche *et al.* atrial model (Ref. 235) (black) paced at a 300 ms cycle length and the simplified model fitted to it (red) (Ref. 44). (c) Experimental optical AP from rabbit ventricle using cytochalasin-D (uncoupling drug) and the corresponding model fit (Refs. 45 and 88). The color and grayscale bars indicate the voltage color and gray scales used throughout this paper.

pendently. [The APD and CV restitution curves are found to be coupled at small diastolic intervals for small sodium conductances (low excitability), but as the excitability increases, the two curves decouple.⁸⁷] Six model parameters are needed to fit an arbitrary CV restitution curve: four time constants, τ_v^+ , τ_{v1}^- , τ_{v2}^- , and τ_d , corresponding to the opening and closing time scales for the fast variable v and the depolarization time, and two voltage thresholds, V_c and V_m , which are used to define the range of the membrane potential. Seven model parameters are used to fit an arbitrary APD restitution curve: five time constants, τ_w^- , τ_w^+ , τ_r , τ_{si} , and τ_0 , corresponding to the opening and closing time constants for the slow w gate variable and the time constants for the slow current; the threshold potential V_c^{si} ; and the activation width parameter k . The complete set of equations that describe the 3V-SIM in cardiac tissue is described further and summarized in the Appendix.

All simulations were performed by discretizing the equations in the appendix on a uniform mesh using a semi-implicit Crank–Nicholson scheme. Except where noted otherwise, Neumann (no-flux) boundary conditions were used to ensure no current leaks at the boundaries. The integration time step Δt and grid spacing Δx were chosen depending on the particular parameters of the model, especially the excitability, so as to give numerically resolved solutions. See the Appendix for more details.

IV. MECHANISMS OF SPIRAL WAVE BREAKUP IN TWO DIMENSIONS

The transition from a single spiral wave to multiple waves is accomplished via wave break, which in the strictest sense is always due, at least in two dimensions (2D), to conduction blocks that form whenever a wave encounters tissue that is absolutely refractory and fails to propagate. However, it is possible to differentiate among breakup processes based on electrophysiological and structural tissue properties and to classify them into different mechanisms in terms of the APD and CV restitution curves, tissue excitability, spiral period, and spiral tip trajectory, as well as initial conditions. In this section, we describe six mechanisms that lead to spiral wave breakup and analyze the source of the conduction blocks. We note that the numbering of mechanisms here and in other

sections is made only to facilitate clarity in referencing and discussion within this paper and not to indicate prevalence or importance.

A. Steep APD restitution

Although the breakup of spiral waves has been known to occur since the early numerical experiments of Wiener and Rosenblueth²⁸ and Moe,³² it was not until 1991 when the first 2D simulations using ionic cell models were performed.^{89–91} Those simulations showed that spiral breakup was possible even in a uniform medium without heterogeneities. Courtemanche and Winfree⁸⁹ showed that speeding up the dynamics of the calcium current by a factor of at least 2 in the Beeler–Reuter (BR) model⁹² could prevent spiral breakup. This modification of the BR model is denoted as the MBR model. Courtemanche³⁴ later explained the breakup seen in the BR model in terms of the steepness of the APD restitution curve.

Since the pioneering paper of Nolasco and Dahlen,⁹³ it has been known that steep APD restitution curves (those having a region with slope greater than one) can produce oscillations in APD via a Hopf bifurcation.^{46,49,94} These alternans can result in spiral wave breakup in 2D.^{34,35,95} When the slope of the restitution curve is greater than one, small changes in DI are magnified into larger changes in APD, whereas changes in APD due to changes in DI are damped out at smaller slopes. Because the minimum DI is greater than zero, for a fixed period, a long APD produced by the oscillations can demand a DI below the minimum and cause conduction block, as shown in Fig. 4 [for hands-on examples we refer to the JAVA applets in Ref. 96]. In the BR model, the slope of the APD restitution curve becomes greater than one at a period of about 310 ms (corresponding to a DI and APD of approximately 100 and 210 ms, respectively). Figure 4 shows transient oscillations leading to steady state when periodically pacing at a period of 320 ms (solid line), which is slightly above the point at which the slope exceeds one, using an initial DI of 205 ms. The dashed trajectory illustrates the transient oscillations and subsequent conduction block (denoted by the arrow) for a constant period of 295 ms, which is below 310 ms and thus within the region of the curve where the slope is greater than one. (A slightly different initial DI of 200 ms, rather than the value of 205 ms used

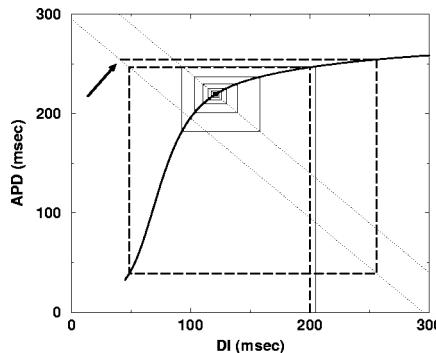


FIG. 4. Beeler–Reuter APD restitution curve obtained in a cable using the 3V-SIM illustrating the geometrical argument of Nolasco and Dahlen (Ref. 93) for oscillations of APD and conduction block. We show two cases in which a constant periodic stimulation is applied following an initial DI. Because the constant period of stimulation is the sum of APD and DI, the period T can be determined from the points at which a line at -45° intersects the axes, at $(0,T)$ and $(T,0)$, as shown. Two examples are shown: steady state obtained by pacing at $T=320$ ms using an initial DI of 205 ms (solid line), and conduction block obtained when pacing at $T=295$ ms using an initial DI of 200 ms (dashed line). The dynamics are displayed following a cobweb similar to a logistic map (see the text for more details). Because the 3V-SIM parameters are fitted to accurately represent the BR restitution curves using parameter set 3, the curve shown here is identical (Refs. 41, 69, and 87) to that obtained using the full BR model. The region with slope greater than one occurs for periods below about 310 ms ($DI \approx 100$, $APD \approx 210$), and the minimum DI possible before reaching conduction block is about 43 ms.

for the stable case, was used here to facilitate visualization of the trajectories.) In categorizing spiral wave breakup mechanisms, we distinguish between two types of breakup within this regime of steep APD restitution, one occurring close to the tip and within the first few rotations of the spiral,^{34,89,91} and another occurring farther from the tip and in some cases requiring many oscillations to develop.^{35,95,97} In both cases, if the spiral period (or, for meandering tip trajectories, the period imposed by the spiral tip throughout the tissue) is outside the region of the APD restitution curve with slope greater than one, restitution-induced breakup does not occur (as in the case of the MBR model).³⁴

1. Mechanism 1: Steep APD restution with breakup close to the tip

Courtemanche showed using a delay equation³⁴ that when the slope of the restitution curve is greater than one, abrupt changes in pulse duration affect the relationship between recovery and excitation, thereby modifying the speed of the wave back or “recovery front.” In other words, the steepness of the restitution curve decreases the speed of the wave back in the presence of recovery gradients, so that the steeper the restitution curve in a given region of DIs, the slower the velocity of the wave back in that region. Once the DI is in the region where the APD restitution slope is greater than one, the front and back velocities begin to separate, with the velocity of the back slowing considerably compared to the velocity of the front (see Figs. 5 and 6). Therefore, the wave back under these conditions propagates more slowly than the wave front, resulting in what Courtemanche called slow recovery fronts (SRFs). The divergence of velocities of the wave front and the wave back in the region where the

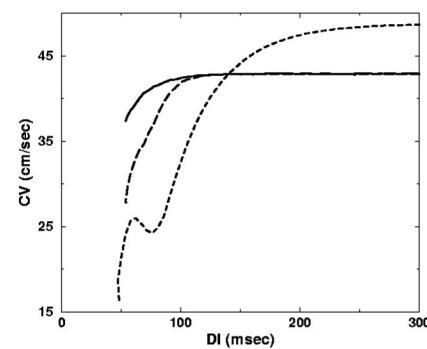


FIG. 5. CV restitution curve for the wave front (solid line) and wave back (long dashes) using parameter set 3. At large DIs (slope less than one) the front and back velocities are the same, but they diverge at small DIs corresponding to the region where the slope of the APD restitution curve is greater than one ($DI < \approx 100$ ms). The CV is measured at the center of a 1D cable 4 cm long. Although the velocity of the wave back is a useful theoretical tool, its measurement is not straightforward. When the wave back velocity is measured in a shorter cable (1.5 cm), electrotonic effects induced by the boundaries can change the curve substantially (short dashes).

slope of the APD restitution curve is greater than one ($DI < 100$ ms) can be observed by plotting the CV restitution for both the front and the back, as shown in Fig. 5. The wave back CV restitution can be obtained either by a delay equation^{46,98} once the APD and wave front CV restitutions are known or directly from numerical simulation.

However, it is important to mention that the determination of the CV restitution curve is not as straightforward for the wave back as it is for the wave front. While the front corresponds to the steep, rapid upstroke (on the order of 1 ms), the wave back experiences a much more gradual change in voltage (on the order of tens or hundreds of milliseconds). Therefore, the wave back can become distorted^{34,50,99} as it moves due to increased sensitivity to electrotonic effects, which makes characterization of its velocity more difficult.

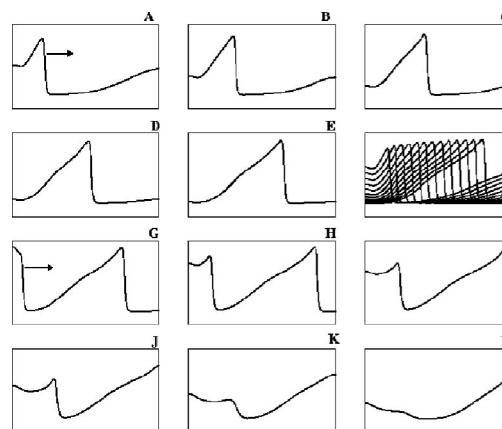


FIG. 6. Slow recovery front in the BR model in 1D. The x-axis represents the position along the 3.3 cm-long cable and the y-axis the voltage (−90 to 10 mV). Frames (a)–(e) show a wave induced at the left end of the cable at a DI of 60 ms. The front moved at a speed of 18.5 cm/s while the wave back moved at 11 cm/s, which made the shape of the APD change in time. Frame (f) shows a superposition of wave profiles 5 ms apart to highlight the different speeds of the front and back. Frames (g)–(l) show a newly initiated wave front interacting with the back of the previous wave. Because the front moved faster than the slow back of the previous wave, it was blocked and failed to propagate as it reached the minimum DI.

An example of how electrotonic effects can alter the CV restitution of the wave back can be seen in Fig. 5, where the short-dashed curve was calculated using a shorter cable than the one used to obtain the long-dashed curve, so that strong electrotonic effects with the boundaries are introduced. Note that the restitution of the wave front remains unaffected.

An example of propagating waves with SRFs and further development of conduction block in a one-dimensional cable can be seen in Fig. 6. In this case, waves were generated using the BR model at pacing cycle lengths in the region where the APD restitution curve is steep (slope greater than one). Therefore the velocity of the wave back (recovery front) became slower than that of the wave front. Panels (a)–(e) show a pulse introduced at the left edge of the cable 60 ms after a previous wave already had passed through the cable (i.e., a DI of 60 ms). Because the slope of the APD restitution curve at this small DI was greater than one, the wave front of the second pulse moved faster than its back, producing a slow recovery front (SRF) and a concomitant change in the wave shape. Figure 6(f) shows the wave fronts at different times of this pulse superimposed so that it is easier to observe that the front moved faster than the back. When a SRF exists, there is a minimum period T_{\min} of pacing in a one-dimensional cable below which it is impossible to produce a train of waves because the SRF has not moved enough and effectively blocks the following wave. This is shown in panels (g)–(l), where the back of a previous wave moved slowly enough to block propagation of the following excitation. In Fig. 6, the period of excitation is $T=75$ ms, much less than the minimum period $T_{\min} \approx 296$ ms, thus resulting in conduction block. Note that even though the period was short, it was still above the minimum period corresponding to DI_{\min} since it was able to produce an excitation, but the wave was blocked toward the center of the tissue due to the SRF.

Although steep APD restitution produces oscillations of APD even in a single cell or cable, the effects of the oscillations can become more complex in 2D and 3D systems, where the APDs vary throughout the tissue as fronts propagate. For large DIs, the front and back velocities of a wave are the same. However, once the DI is in the regime where the APD restitution slope is greater than one, the front and back velocities begin to separate, with the back slowing considerably compared to the front.

The divergence of the velocities of the front and back is manifested in 2D by the appearance of scalloping along the wave back, as shown in Fig. 7. The scallop does not occur at the tip itself due to the high curvature, slower velocity, and smaller difference between front and back velocities there. However, the scallop forms relatively close to the tip, typically within the first rotation of the spiral, because of the short DI produced as the wave quickly rotates. The longer APD and slower wave back of the scallop delay the recovery of the tissue's excitability. When the spiral turns and tries to invade the region of the scallop, it encounters refractory tissue, which causes conduction block and wave break. The break generally occurs within the first rotation of the spiral because the block tends to occur soon after the spiral turns. In addition, since the waves break before one rotation is

completed, no spirals exist with more than one rotation.

An example of the evolution of wave break close to the spiral tip due to scalloping is shown in Fig. 7. After the formation of a scallop close to the tip of the spiral wave (a), the spiral encountered refractory tissue and propagated along the existing wave back until it had enough excitable tissue available to turn (b)–(c). By this time a second scallop had formed closer to the tip. As the spiral continued to rotate (d)–(g), it turned back toward the location of the second scallop and finally collided with it (h)–(i), pinching off a new front that formed two counterrotating spirals (j)–(k). The right spiral was unable to turn, as it continued to encounter refractory tissue, but the left spiral turned and propagated toward the scallop on the original broken front (l), where it again encountered refractory tissue and broke (not shown).

Panels (m)–(n) show complex states that emerge as the system continued to evolve through wave breaks. Ultimately, however, the breakup was transient, as all wave fronts moved off the tissue and left behind only wave backs (last frame). This transience is not uncommon, and in fact the breakup resulting from this mechanism often is not sustained due to the large variation in wavelengths that eventually can leave no quiescent areas to support continued propagation.^{89,91} As the tissue size is increased, the system can support breakup for longer periods of time.¹⁰⁰

Breakup close to the tip produced by SRFs leading to scalloping can occur in models with steep APD restitution curves for spirals with periods in the slope greater than one regime. Examples of such models are the Beeler–Reuter model, as described in Refs. 34, 87, and 89; the four-variable Noble model,¹⁰¹ as seen in Refs. 87, 91, and 102; and the Luo–Rudy–I¹⁰³ model with altered parameter settings, such as in Ref. 104, where the maximum conductances of the calcium current and the time-dependent potassium current were changed.

2. Mechanism 2: Steep APD restitution with breakup far from the tip

For APD restitution curves having a region with slope greater than one, a range of periods can exist for which stable oscillations of APD can be sustained before conduction block is produced. The range of periods depends on the steepness of the APD curve, i.e., the width of the range of DIs for which the slope of the restitution curve is greater than one, and on how large the oscillations can become before reaching a DI smaller than DI_{\min} , which produces conduction block. For example, in the 3V-SIM using parameter set 3, corresponding to the BR model (Fig. 4), this region is very narrow (for periods between 285 and 315 ms)^{50,87} in comparison to the region shown in Fig. 8, where parameter set 4 (see the Appendix for parameters) was used to produce a restitution curve with a slower rate of change while still retaining a period of slope greater than one for DIs ≈ 110 ms (the region of periods with slope greater than one having stable alternans is about 80 ms, between 180 and 260 ms, as shown in Fig. 11).

While the cobweb diagram of Fig. 8 reflects only the dynamics of a single cell, it has been shown in spatially

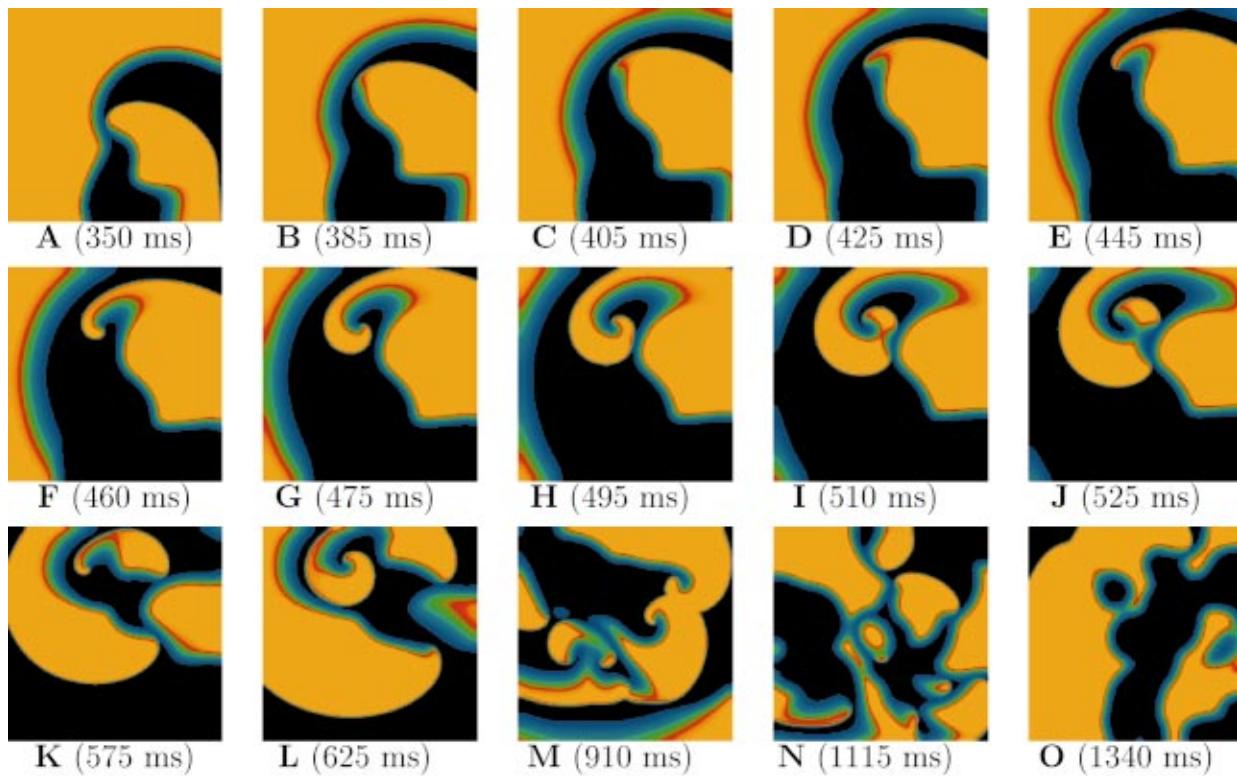


FIG. 7. (Color) Evolution of breakup close to the tip due to steep APD restitution using parameter set 3 in a 12.5×12.5 cm domain. Wave fronts were blocked by refractory regions due to scallops that had formed along wave backs because of the divergence of the front and back conduction velocities. Ultimately, the breakup was transient. The numerical parameters Δx and Δt were set to 0.025 cm and 0.25 ms, respectively.

extended systems that APD oscillations can vary throughout the tissue. When the entire medium exhibits the same long-short pattern in APD (a long APD produced on one beat and a short APD produced on the next beat, with the pattern repeating), the alternans is called concordant. However, due

to initial conditions⁵⁰ or conduction velocity restitution,^{50,105} concordant APD alternans (CA) can further develop into discordant APD alternans (DA), which occurs when some part of a medium oscillates long–short, while another area oscillates short–long. That is, on a given beat, there is a gradient of APD from long to short as the wave propagates through the medium, and on the subsequent beat, the gradient is reversed and becomes short to long. In this case, the APD produced at one site varies along the tissue and the alternans is out of phase. Both CA and DA are known to occur in cardiac tissue and have been observed in experiments when waves circulate along small paths or rings of tissue¹⁰⁶ or, equivalently, when high-frequency stimulation is applied periodically to linear strands of cardiac tissue⁹⁷ or isolated hearts.^{107,108} Clinically, beat-to-beat oscillations of APD correlate to T-wave alternans in the ECG, which often has been observed as a precursor to ventricular fibrillation and sudden death.¹⁰⁹ Alternans can play a role in spiral wave breakup, as we describe below following a discussion of how factors such as wave front curvature and CV restitution curve slope affect the development and evolution of alternans.

Panels (a)–(d) of Fig. 9 show the spatial distribution of APDs during discordant alternans produced in a 1D cable when pacing at a cycle length of 230 ms using parameter set 4. The APDs of all points along the cable on odd (even) beats are shown as a solid (dashed) black line, and the lines represent the steady state reached after prolonged pacing. Between every two out-of-phase regions is a node, where the APD does not oscillate on successive beats but remains the same. Previously⁵⁰ we demonstrated that along with cycle

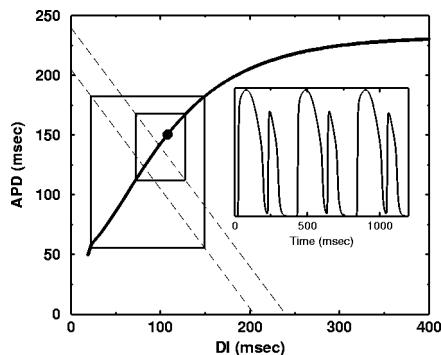


FIG. 8. APD restitution curve with slope greater than one for a model with a larger range of DIs in the slope greater than one region (due to reduced steepness and decreased DI_{min}) compared to the curve shown in Fig. 4, allowing alternans to develop over a wider range of periods before reaching conduction block. The circle indicates the point on the curve where the slope is one, with a period of about 260 ms ($DI \approx 110$ ms, $APD \approx 150$ ms). Periods below 260 ms display alternans; two examples with periods of 240 ms and 205 ms are shown. The dashed lines indicate the period of constant stimulation as the x - and y -intercepts and the rectangular regions illustrate the two alternating APD solutions. The inset shows the AP alternation resulting from periodic stimulation at 205 ms. Note that while the activations were produced at a constant period, the APD alternated between 180 and 52 ms and therefore the DI alternated between 25 and 153 ms. Note that the range of DIs that give stable alternans here is much larger than in Fig. 8. Parameter set 4 is used. See the text for further details.

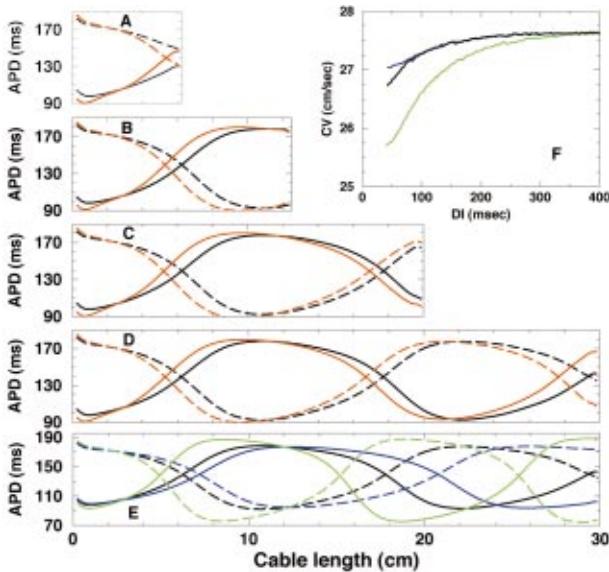


FIG. 9. (Color) (a)–(d) Discordant alternans in a 1D cable without (black) and with (red) curvature. The steady state spatial distributions of APDs over a cable for even (dashed line) and odd (solid line) beats at a basic cycle length of 230 ms are shown for four different cable sizes (6.25, 12.5, 20, and 30 cm) ($\Delta x = 0.025$ cm, $\Delta t = 0.1$ ms). Pacing site is at the left edge. Note how curvature shifts the node locations closer to the pacing site. (e) Distribution of nodes in a cable without curvature as a function of CV restitution, while keeping the APD restitution unaltered. Black shows the original distribution from (d), green shows a more packed distribution of nodes obtained when the CV restitution varies over a wider range of DIs, and blue shows a less packed distribution from a flatter CV restitution. Parameter set 4 was used. (f) CV restitution curves corresponding to the plots in (e), where the parameter values were varied from set 4 by changing τ_{v1}^- from 15.6 to 5 (blue) and 80 (green).

length, tissue size affects how many regions of opposite alternans phase can exist: for a given frequency, the longer the tissue, the larger the number of nodes. The positions and number of nodes depend on the APD and CV restitution curves⁵⁰ as well as on electrotonic effects^{110,111} and tissue heterogeneities.⁵⁰ Panels (e)–(f) of Fig. 9 show, for example, the effect of CV restitution on the node distribution, which can be analyzed by varying the parameter τ_{v1}^- in the 3V-SIM to obtain different slopes for the CV restitution curve.⁸⁷ Figure 9(f) shows in black the CV restitution curve obtained with the original parameter set 4, while blue and green indicate the curves obtained by setting τ_{v1}^- from 15.6 to 5 and 80, respectively. Figure 9(e) shows that when the CV restitution varies over a wider range of DIs, the node positions occur closer to the stimulus site, as demonstrated previously using iterative maps,⁵⁰ and the width of the alternans regions decreases, allowing more nodes to be formed (observe three nodes, just about three nodes, and only two nodes appear as the CV restitution is flattened).

It is important to mention that nodes are not always stationary. In some cases they can migrate to the pacing site,^{97,111} and as they disappear new nodes are formed at the other end [the two-variable Karma model³⁵ is a numerical model that exhibits the migration of nodes with its original parameter settings]. Although the behavior in shorter cables is similar to a truncated version in longer cables, there can be differences. For instance, a short tissue may not contain a

node, even though a node can occur in a longer tissue at a location within the length of the short tissue.⁵⁰ For example, compare panels (a) and (b) in Fig. 9, where electrotonic effects in the short tissue produce CA whereas DA is produced in a longer cable. More dramatic examples can be observed depending on the electrotonic effects of the model.⁵⁰

Wave front curvature also can affect the position and distribution of nodes. Comtois and Vinet¹¹² showed that loading effects due to curvature in an activation wave can increase its duration substantially (more than 40% in their simulations using the BR model), but only at very high curvatures corresponding to circles of radius 0.25–1 mm, which can be close to the critical radius of propagation⁶⁵ and thus difficult to capture in a restitution protocol of extended systems. Our numerical simulations show less than 5% difference in APD restitution curves when using planar versus curved wave fronts. A more important effect of curvature on wave front propagation is the decrease in conduction velocity as a function of curvature¹¹³ (see the eikonal equation).^{65,114} This additional variation in velocity changes the position of the nodes, as shown in panels (a)–(d) in Fig. 9, where the APD distribution for curved fronts is displayed in red in a 1D cable reduction of a target wave simulation in which the distance from the pacing site (left edge) is the radius.

Although longer lengths often can support more nodes, this is not always the case. At high frequencies, the shorter APD can be blocked as a node is being formed because the oscillations can become so large that the wave no longer can propagate. Where the short APD becomes blocked, only the fronts corresponding to the long impulses far from the stimulation point and produced every other beat are sustained, and the alternans progress to what is known as 2:1 block far from the stimulation site. Figure 10 shows how conduction block can form at a given frequency (here, $T = 212$ ms) as the cable length is increased, with longer cables developing block sooner (if block is generated at all). Only CA is present for the 6.25 cm cable, while DA develops in the 12.5 cm cable, and conduction block occurs in cables 20 and 30 cm long. The conduction block forms sooner in the 30 cm long cable and takes longer to develop in the 20 cm cable. In both cases, the block is produced far from the stimulation site, as shown experimentally.⁹⁷ Although we have shown that, CV restitution aside, electrotonic effects play a role in the development of the block, further analysis is needed in order to quantify its onset. We should note that the cable sizes used in these examples are unphysiologically large, since the model parameters were tuned to facilitate explanation. Nevertheless, the dynamics is generic, as the distribution and position of nodes as well as the range of periods that support alternans depend on the APD and CV restitution curves and electrotonic effects.^{69,111}

The relationship between cable length, number of nodes, and frequency of stimulation for a given model can be observed in a parameter space diagram.^{50,115} Figure 11 shows the different node regimes for the 3V-SIM fitted to parameter set 4. The diagram on the left-hand-side corresponds to plane waves and the one on the right-hand-side to 1D reductions of target wave patterns where curvature effects are included. At

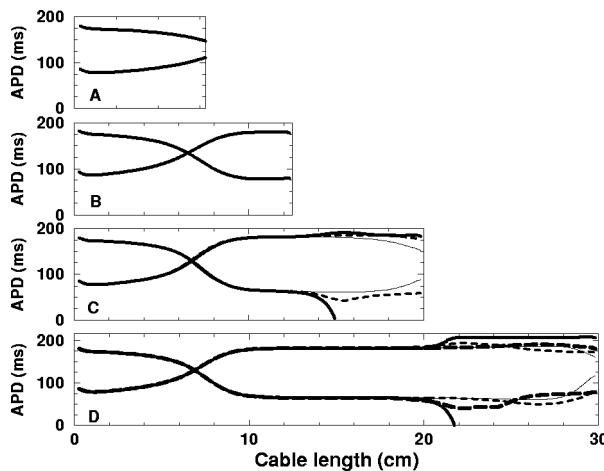


FIG. 10. Size-induced conduction block in a cable with discordant alternans using parameter set 4. The steady state is shown for alternate beats as solid lines. Previous beats, before steady state is reached, are shown as dashed and thinner lines in the longer cables. Although one node forms in a cable of length 12.5 cm, the longer cables do not support multiple nodes because conduction block occurs. Note that only one wave every two beats propagates along the whole cable, leading to what is called 2:1 block. The cable lengths are the same as in Fig. 9, but the period of stimulation is 212 ms instead of 230 ms.

long cycle lengths ($T > \approx 260$ ms), only stable nonoscillating solutions are obtained, while at short cycle lengths, conduction block (dark gray) occurs in much the same way as in Fig. 4. Alternans solutions lie between these two regimes. For a given pacing cycle length (constant stimulation frequency), CA (white below 260 ms) occurs only in short cables, while DA (three shades of gray indicating the progression from one to two to three nodes as the color darkens) only appears in cables greater than a minimum length, with multiple nodes emerging as the cable length increases.^{50,97} Note that any number of nodes can be present before conduction block is formed. It is important to note, as mentioned earlier, that the different region sizes and distributions shown in Fig. 11 are a function of both the APD and the CV restitution curves. The wider the range of DIs where the slope of the APD restitution is greater than one, the larger the region for alternans. Similarly, the wider the range of DIs where the CV restitution varies, the more densely packed are the nodes in space [see Figs. 9(e)–9(f)]. Curvature effects do not alter the transitions between regions substantially, with the predominant effect being an increase of the 2:1 block region for curved fronts at smaller periods. Far from the pacing site the distribution for plane waves and circular waves coincide as the curvature of the circular waves decreases.

Because of the spatial heterogeneity generated in APD and the eventual possibility of 2:1 conduction block, DA can lead to wave breaks and further generation of reentrant (spiral) waves when present in two and three dimensions, as has been shown numerically^{35,95,105} and experimentally.¹⁰⁷ Since a spiral wave acts as a source of periodically paced waves, breakup can occur if its period of rotation falls within the alternans region. Figure 11 shows that this breakup is a function of both period and tissue size. Therefore, we emphasize that depending on its period, a spiral wave can be unstable and break into multiple waves in a large domain while re-

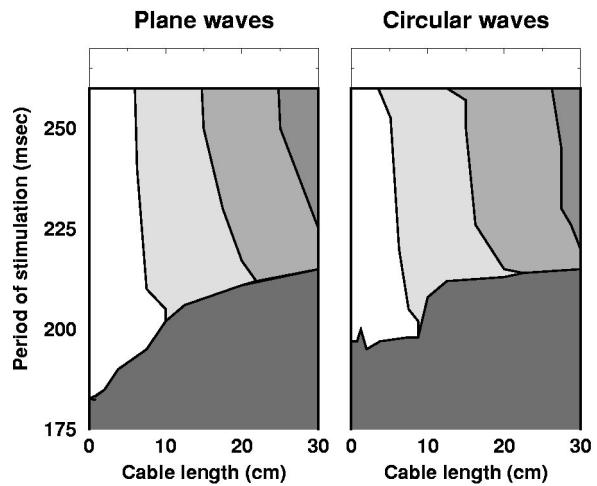


FIG. 11. Behavior of cables of different lengths and stimulation periods. The first figure illustrates the locations of regimes in a 1D cable without curvature, while the second includes curvature effects. Above the top horizontal line at 260 ms, stable, nonoscillatory behavior is observed. In the dark gray regime at the bottom, conduction block occurs. In between are regimes of concordant alternans (white) and discordant alternans with one (light gray), two (medium-light gray), and three (medium gray) nodes. For shorter cables, alternans is concordant, while at longer lengths only discordant alternans is observed, with the number of nodes increasing with size. The figures are similar with and without curvature effects, with curvature mainly changing the regimes by inducing block for larger cycle lengths in short cables. Longer cables than shown here would include additional DA regions with more nodes. We note that these plots indicate only the presence of alternans and not the magnitude, which in general increases as the period decreases. Parameter set 4 was used.

mainly stable in a smaller domain.³⁵ Figure 12 illustrates how DA can lead to the breakup of a spiral wave. Parameter set 4, used throughout this section, was designed to produce spiral waves with circular tip trajectories and an APD restitution curve with slope greater than one over a broad range of DIs to allow a large region for alternans. Varying the size of the circular core can change the period of rotation and can allow the transition from stable waves to alternans and finally to conduction blocks. The tissue size is 30×12.5 cm (as mentioned earlier, the size is unphysiologically large, but the purpose here is simply explanatory). The first panel of Fig. 12 shows a spiral wave with a period of 265 ms ($\tau_d = 0.415$), which remains stable since the period is above the largest alternans period of 260 ms (see Fig. 11). As the excitability is slowly increased by setting τ_d to 0.41, the spiral wave period decreases to 220 ms and the resulting APD oscillations develop into discordant alternans. Early oscillations (b) grow in magnitude until the difference in the long and short APDs is great (c), with one APD much longer than the next. After two more rotations (d), conduction block is almost formed far from the tip (stimulation site) as in Fig. 10, and two rotations later (e) conduction block and spiral breakup occurs. Panels (e)–(g) show consecutive snapshots of the wave break as it forms. Once initiated, the breakup process continues (h)–(j), but the core and the three inner rotations of the spiral remain unaffected.

The location of the initial wave break relative to the spiral core can be changed by further decreasing the period of rotation (equivalent to the stimulation period), as shown in

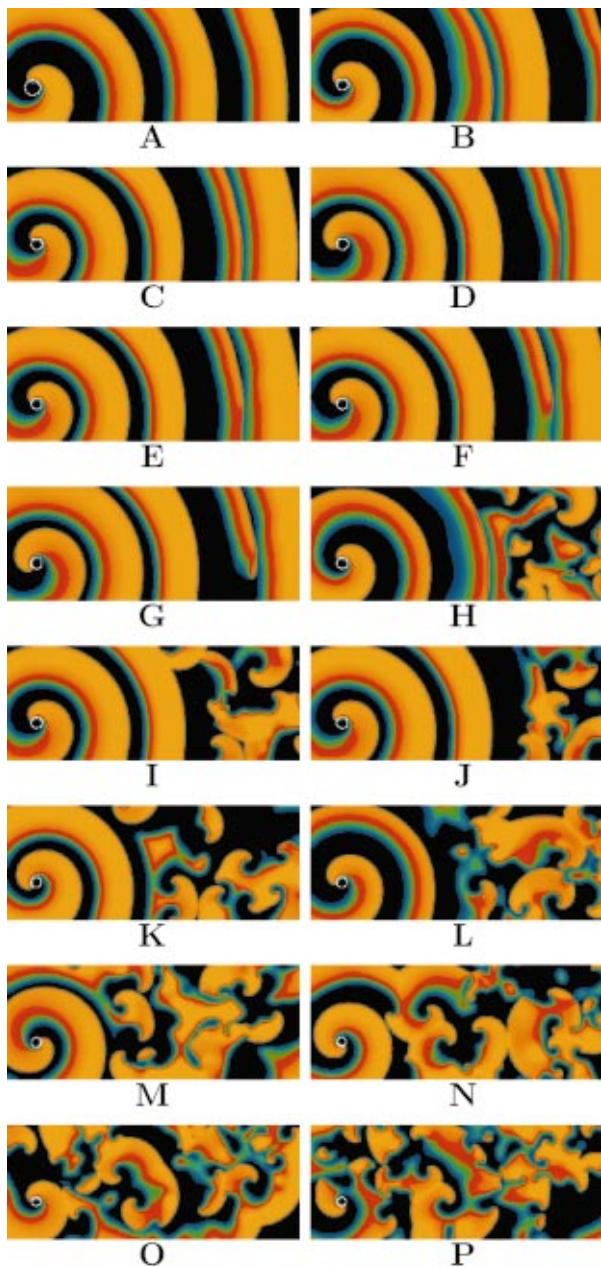


FIG. 12. (Color) Discordant alternans-induced breakup far from the tip in a 30×12.5 cm domain using parameter set 4. Panel (a) shows the steady state of a stable spiral wave with a period of 265 ms. After decreasing the period to 220 ms by slightly increasing the excitability ($\tau_d=0.41$), as can be seen by the change in core size, APD oscillations developed and grew over several seconds. Panels (b) and (c) show the dynamics 2.652 and 3.516 s after the parameter change. When a short APD following a long APD could not continue to propagate, it broke, as in Fig. 10 [(d), (e), (f), and (g) correspond to 3.948, 4.380, 4.392, and 4.440 s]. Additional breakup occurred, but only far from the spiral tip, while the tip itself and the three innermost spiral rotations remained protected, as in (h), (i), and (j) (7.092, 7.668, and 16.675 s). After changing τ_d further to 0.407, the period of rotation was shortened and the distance beyond which wave break occurred was moved progressively closer to the tip of the spiral, leaving only two rotations intact [(k) and (l), 9.456 and 11.856 s]. Increasing the excitability again ($\tau_d=0.405$) decreased the period further, so that only one spiral rotation remained unbroken [(m) and (n), 13.056 and 14.256 s]. A final decrease of the period to 160 ms ($\tau_d=0.4$) left less than one full spiral rotation intact, and eventually the entire medium was filled with broken waves [(o) and (p), 15.456 and 17.256 s]. Note that frames (k)–(p) continue the time series but were created by modifying parameters (spiral period). Without these modifications to τ_d , the breakup remains restricted to a certain region of the tissue far from the spiral tip (source), as shown in Figs. 10 and 11. Simulations were performed using $\Delta x=0.025$ cm and $\Delta t=0.1$ ms.

Fig. 11). Panels (k)–(l) of Fig. 12 show breakup occurring closer to the core, with only the first two spiral rotations remaining intact, as the period is further decreased by slowly increasing excitability ($\tau_d=0.407$). An additional decrease in period ($\tau_d=0.405$) leaves only one rotation intact (m)–(n), and finally at a period of 160 ms ($\tau_d=0.4$) no full rotations remain (o)–(p), with breakup pervading the entire medium and only a small spiral wave circulating around a small core that eventually disappears by colliding with another wave. Similar behavior has been shown in the two-variable Karma model [see Fig. 6(d) in Ref. 35].

Spiral wave breakup far from the tip due to discordant alternans can occur in any model having a steep APD restitution curve and a spiral period in the slope greater than one regime, provided that the spiral tip follows a circular or low meander trajectory, or perhaps if it is pinned to a scar or inhomogeneity that causes the period of rotation to lie in the steep region. Models that can break in this manner include the Karma model,³⁵ the 1962 Noble model,¹⁰¹ and the Bär model as in Ref. 116. Discordant-alternans-induced breakup also has been observed experimentally in rapidly paced tissue preparations.^{97,108} Recently, stable spiral waves surrounded by multiple breaking waves as in panels (h)–(n) of Fig. 12 have been shown to occur experimentally and in simulations;¹¹ however, their occurrence in that case was attributed to different densities in the background current between the right and left ventricle. Nevertheless, it is interesting to note that such patterns can be obtained in homogenous tissue. It is important to mention that even when the slope of the APD restitution curve is greater than one over a wide range of DIs (as discussed in this section), an abrupt change in DI can lead to a large change in APD and breakup as in mechanism 1 can occur.

3. APD restitution curve with one region of slope greater than one and two regions of slope less than one

An interesting special case of the steep APD restitution curve slope mechanisms can occur when two regions with slope less than one are present on either side of the steep part of the curve. Physiologically, a second region with slope less than one can occur in ionic action potential models where the currents responsible for the AP plateau (mostly calcium) do not activate fully at very short DIs. These alterations in cell dynamics lead to action potentials with very small plateaus at high frequencies of stimulation. Therefore, the APDs vary little at the shortest DIs and can produce a second region in the restitution curve with slope less than one. The 1962 Noble model¹⁰¹ for Purkinje fibers exemplifies this phenomenon. The slope of its APD restitution curve is less than one for periods greater than 256 ms and for periods less than 123 ms, with a region of slope greater than one at periods between 123 and 256 ms.⁸⁷ It is important to note that the 1962 Noble model does not include a calcium current in its formulation, since the calcium current was not discovered until a few years later, and instead one of its potassium currents is responsible for the plateau. Another model showing two regions with slope less than one, which was developed more recently and includes a greater number of ionic currents, is

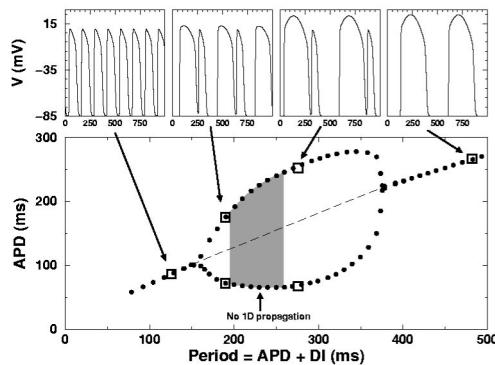


FIG. 13. APD vs cycle length (APD+DI) for the 3V-SIM using parameter set 5, which produces two regions with APD restitution curve slope less than one and consequently two Hopf bifurcations, one at 375 ms and the other at 150 ms. The small figures on top show the voltage as a function of time for the four cycle lengths indicated by the squares (from left to right, 125, 188, 276, and 485 ms). Stable behavior is observed for the smallest and largest cycle lengths, while APD alternans occurs for the intermediate cycle lengths. The gray area indicates periods for which conduction block occurs in a 1D ring. The 1:1 solution branch (dashed line) exists in this region but is unstable.

the canine model by Fox *et al.*¹¹⁷ In that model, the slope is greater than one for periods between 145 and 210 ms and is less than one for all other periods, down to a minimum of about 85 ms.

Using parameter set 5, the 3V-SIM produces an APD restitution curve with two regions having slope less than one, for periods greater than 375 ms and for periods less than 150 ms. Figure 13 shows the maximum and minimum APD oscillations as a function of cycle length obtained by simulating propagating waves in 1D rings of various sizes.⁸⁷ For periods of stimulation greater than 375 ms and below 150 ms, it is possible to obtain stable nonoscillating waves (see top right and left plots), while for periods in between, oscillations of APD (see top two center plots) can be obtained along with a region of conduction block, shown in gray, where no propagation is possible on a ring. The dotted line in the alternans regime denotes the unstable steady state branch, which can be obtained using a control algorithm.¹¹⁸ Because of the second region with slope less than one, the conduction velocities of the wave front and back not only diverge, as described earlier, but also merge back together at short DIs, as shown in Fig. 14, where the inset indicates the difference in the front and back velocities as a function of DI.

Under these conditions, a stable spiral wave can be supported if its period of rotation is large and falls in the region where the APD restitution curve has slope less than one, while breakup will occur if the period lies in the region with slope greater than one, since there can be SRFs or DA, as in breakup mechanisms 1 and 2. However, if the period is small and falls in the second region with slope less than one, then the solution can be either a stable spiral wave or breakup, depending on the initial conditions.⁸⁷

Panels (a) and (b) in Fig. 15 show the two possible solutions obtained when the period of rotation is 75 ms, using parameter set 5 with $\tau_d = 0.355$. In (a), a spiral wave was initiated from a broken pulse⁸⁹ propagating into quiescent tissue. As the spiral rotated, SRFs led to breakup and com-

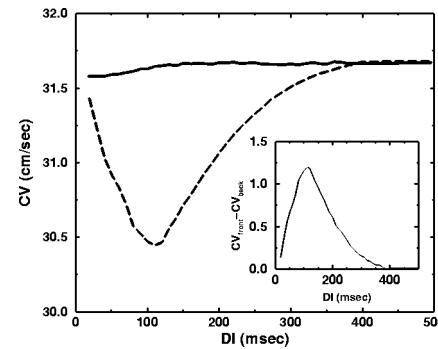


FIG. 14. CV restitution curves for the wave front (solid line) and wave back (dashed line) corresponding to the APD restitution curve with two regions of slope less than one (parameter set 5). While the front and back velocities initially diverge as the DI is decreased, the difference in velocities decreases as the second region with slope less than one is approached. Therefore, stable pulses can occur at short as well as long DIs, as shown in the top left-hand inset of Fig. 13.

plex spatiotemporal dynamics⁸⁷ in the same way as observed in the Noble model^{91,102} and similarly to Fig. 7. In (b), a stable spiral wave was achieved also from a broken pulse but following a train of impulses at short intervals so that the spiral never reached the periods between 150 and 375 ms that can lead to conduction block and breakup. The spiral actually was initiated in a smaller tissue (to prevent breakup that would result from the presence of long DIs far from the initiating broken pulse), following which the size was increased gradually until reaching the same size as in panel (a). Two aspects of these spiral wave dynamics are noteworthy. First, at short periods two solutions are possible depending on initial conditions and tissue size, either a stable spiral wave in a small tissue after preconditioning pulses at small periods or spiral breakup and complex spatiotemporal dynamics with no preconditioning or in a larger domain, due to the presence of long DIs in the tissue. Second, a stable spiral wave formed at a short period will remain stable in any tissue size, unlike mechanism 2 where spiral waves may destabilize and break in a large enough tissue. However, if the period of a spiral is slowly increased, even a stable spiral will experience breakup as in mechanism 2 when the period becomes larger than that corresponding to the Hopf bifurcation (approximately 150 ms for this model). Panels (c)–(f) in Fig. 15 show the evolution of the stable spiral wave in panel (b) as the period is increased from 75 ms to about 180 ms [by slowly changing τ_d from 0.3547 to 0.359 (c), 0.37 (d) and finally to 0.382 in (e)]. In (e) the period is about 180 ms (greater than the period for the first Hopf bifurcation ~ 150 ms), at which point discordant alternans begins to develop, as shown in the center of the figure where the wavelength changes abruptly. It is important to recognize that this is not a slow recovery front or scallop, as in mechanism 1, but is in fact a node separating the long APD region from the short. The oscillations eventually grow and lead to breakup and multiple spirals (f), following mechanism 2. Note that the density of waves is different between (a) and (f), due to the different sizes of their tip trajectories. A denser set of waves can be obtained at higher excitabilities (smaller values of τ_d) as the tip trajectories become epicycloidal and hypocycloidal (not shown).

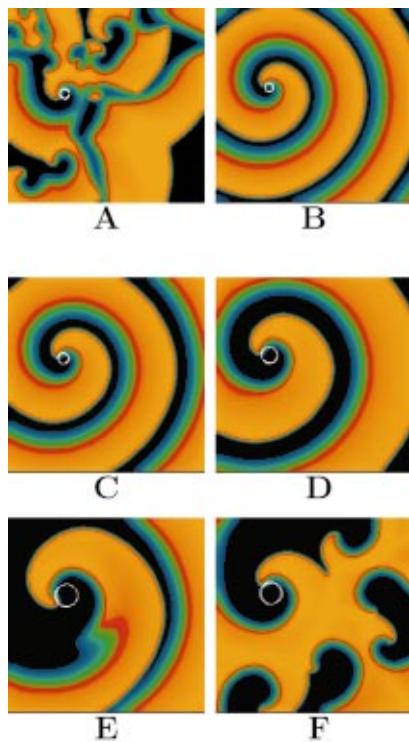


FIG. 15. (Color) Range of possible dynamics of the 3V-SIM using parameter set 5, which leads to an APD restitution curve that has two regions with slope less than one ($\Delta x = 0.025$ cm, $\Delta t = 0.25$ ms). Panels (a) and (b) show two different dynamics, spiral wave breakup and a stable spiral wave, obtained with the same parameters but using different initial conditions. (c)–(d) The spiral wave from panel (b) remained stable as the period was increased. (e)–(f) When the period is increased to about 180 ms, the spiral wave becomes unstable, and breakup from discordant alternans leads to various spiral waves. Tissue size is 10×10 cm.

B. Mechanism 3: Bistability, hysteresis, and 2:1 block

Bistability in cardiac tissue is a phenomenon where a given frequency of stimulation results in one of two possible APDs, depending on the initial conditions. The shorter APD is obtained naturally when pacing at a constant frequency, with every pacing beat producing an activation (1:1 response), while the longer APD occurs when only one activation is produced for every two pacing beats (2:1 response). This scenario can be visualized by plotting the APD as a function of the pacing cycle length (period) instead of the DI. Figure 16(a) shows an example of this bistability in APD using parameter set 6, with the inset showing the normal APD restitution curve as a function of DI ($DI_{\min} = 11$ ms, $APD_{\min} = 61$ ms, and thus the minimum period T_{\min} is 72 ms). Note that for clarity of exposition and to avoid confusion among different mechanisms, parameter set 6 was designed to produce bistability using an APD restitution curve with slope less than one for all DIs. Nevertheless, bistability can occur with or without steep APD restitution and alternans.¹¹⁹

The main plot in Fig. 16 shows the 1:1 response branch (solid line) as a function of the pacing cycle length. As the pacing cycle length is decreased gradually below T_{\min} , conduction block occurs, so that only one activation is induced for every two pacing beats (thus jumping into the 2:1 branch, shown by the dashed line). Because the period of stimulation

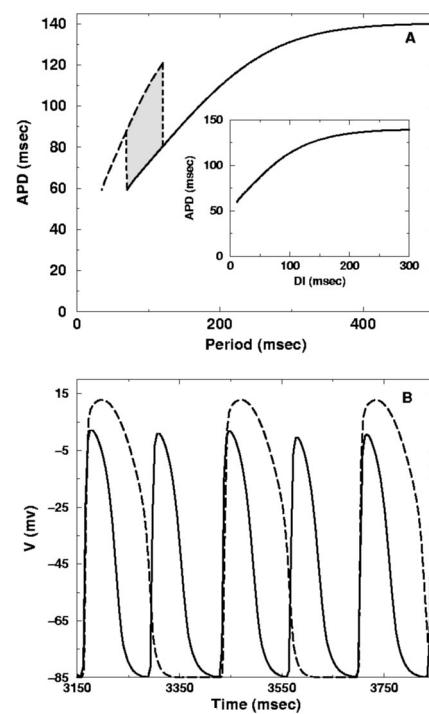


FIG. 16. Bistability and hysteresis of APD. (a) The solid and dashed lines show the 1:1 and 2:1 branches, respectively. The width of the region of periods that can access two stable solutions is about 70 ms in this case. (b) Voltage traces obtained at two different sites from the simulation shown in Fig. 17. Close to the core (solid line), every rotation of the spiral was propagated, but farther away (dashed line), every other impulse was blocked, resulting in 2:1 conduction. The 2:1 trace was shifted in time so that the upstrokes of the 2:1 trace coincide with the upstrokes in the 1:1 trace to facilitate visualization and comparison of the resulting APDs. Note that the APD was sufficiently long in the 2:1 region to prevent propagation of every other impulse. Parameter set 6 was used, with $\tau_d = 0.115$ in (a).

T is fixed, the following APD can be obtained from the APD restitution curve (inset) using a DI given by $DI_{\min} + T$. Since this DI is large, the resulting APD also is large. As the cycle length is decreased further, the APDs for the 2:1 response branch can be obtained, as shown in Fig. 16 as a dashed line. If the cycle length now is gradually increased above T_{\min} , the system remains on the 2:1 branch rather than dropping immediately to the available 1:1 branch because the APD produced is large and every other stimulus comes too early in the refractory period to generate a response, thereby creating a region of bistability. The system shifts back to the 1:1 branch only when the period of stimulation is larger than $DI_{\min} + APD$ from the 2:1 branch, again allowing an activation to be produced once for every beat. The difference in dynamics depending on whether the cycle length is being increased or decreased is an example of hysteresis, an effect found in many nonlinear systems. Bistability and hysteresis have been observed in a variety of cardiac experimental preparations including sheep Purkinje fibers and papillary muscles,¹²⁰ sheep atria,¹²¹ guinea pig ventricular cells,¹²² and frog¹¹⁹ and rabbit¹²³ ventricular tissue. The range of cycle lengths in the hysteresis region depends partly on the slope of the restitution curve, but mostly on the size of the DI_{\min} and APD_{\min} , and has been shown experimentally to vary from several milliseconds to as long as hundreds of milliseconds.¹¹⁹

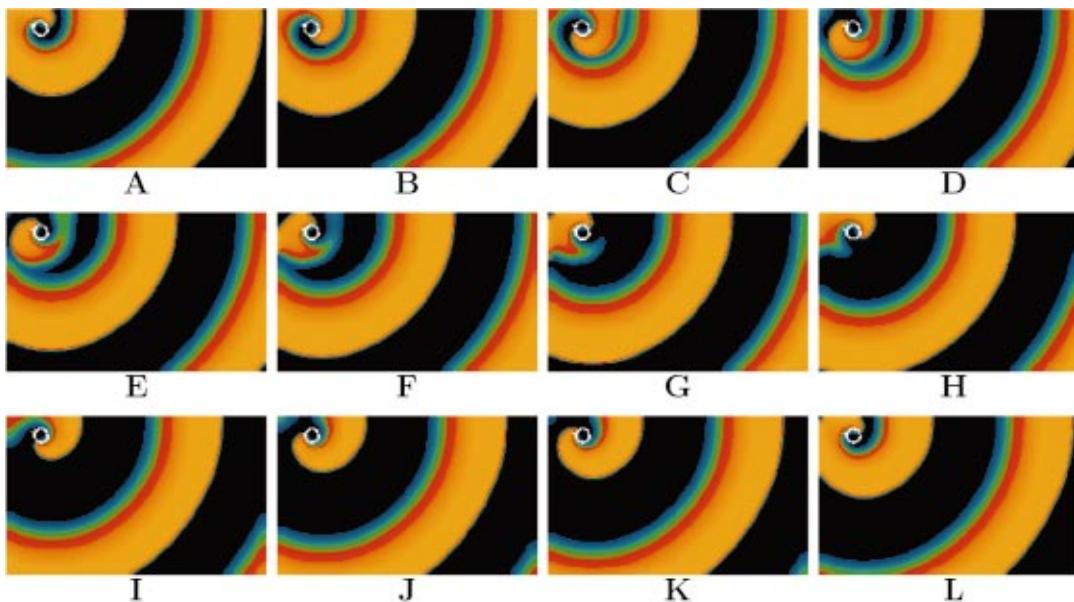


FIG. 17. (Color) Spiral wave with 2:1 conduction block far from the tip. Tissue size is 16.25×10 cm ($\Delta x = 0.025$ cm, $\Delta t = 0.25$ ms), and parameter set 6 is used. Because the period of the spiral wave lies in the window of APD bistability, both 1:1 and 2:1 solutions exist. After spiral wave initiation following a plane wave propagating from left to right, sites near the tip conducted at the same frequency as the spiral. Farther from the tip, however, longer DIs occurred before the first rotation of the newly created spiral arrived, resulting in longer APDs. When the subsequent spiral rotation arrived at these distant sites, the tissue had not yet recovered from the long APDs. As a result, conduction block occurred, and a 2:1 conduction pattern was initiated. Figure 16(b) shows voltage traces for a site in the 1:1 region and for another site in the 2:1 region. The frames shown are separated by approximately 21 ms.

In a spatially extended system, it is possible for some regions of the tissue to experience 2:1 block while the rest of the tissue conducts every impulse. This situation can arise when a target or spiral wave stimulus encounters a gradient of recovery region (DIs) produced by a previous wave.¹²⁴ Figure 17 shows two rotations of a spiral wave induced by a broken wave that demonstrate this effect. The spiral was initiated at the top of the domain, and its period fell within the range of periods with both 1:1 and 2:1 solutions available. Near the tip of the spiral, the small DIs produced small APDs and waves of short wavelength, all of which propagated successfully. However, slightly farther away from the spiral tip, the tissue was quiescent longer before the first rotation of the spiral arrived (a)-(b), producing larger DIs that resulted in long APDs on the 2:1 solution branch and longer wavelengths. The second rotation of the spiral then was blocked when it reached these sites (c)-(f). Therefore, away from the tip, only every other spiral rotation propagated successfully. The spiral continued to rotate (g)-(i), and after the longer DIs occurred far from the tip, the next impulse propagated successfully through the entire tissue (j)-(l). In this example, the broken end of the wave did not generate a reentrant wave, since the entire tissue surrounding the tip was in the region of 2:1 block and since the boundaries were close to the spiral tip. Similar 2:1 conduction block during the rotation of a spiral wave has been demonstrated using a variation of the Luo–Rudy–I (LR–I) model⁶⁷ and a cellular automata model.¹²⁴ We note that the CV restitution curve in this case is relatively flat. As the restitution of the CV increases (steeper slope), the conduction velocity for small DIs near the tip decreases. Therefore, the spiral period can increase to a value that lies outside the bistable region, preventing the breakup.

C. Mechanism 4: Bistability and Doppler shift by tip trajectories

In Sec. IV B, we showed for a given set of parameter values how a spiral with a very short rotation period can propagate every rotation (1:1 branch) close to the tip and only every other rotation (2:1 branch) far from the tip. When bistability is present in a model, rotating spiral waves in some cases can access the same state dynamically without the need of presetting initial recovery gradients as in Fig. 17. Transitions between the 1:1 and 2:1 branches can occur instead due to Doppler shift in the spiral's frequency induced by meander in the tip trajectory. Essentially, the rotating and meandering spiral functions as a moving source of periodic waves. Because of the Doppler effect, the frequency is higher in the direction in which the spiral is moving. Figure 18 shows an example of the Doppler effect produced by a moving spiral wave. The cycloidal tip trajectory causes the spiral rotations to pack together more closely in the direction in which the spiral is moving (to the left), resulting in a higher frequency along the left side of the tissue and a lower frequency along the right. This stable spiral with a cycloidal trajectory is obtained using the 3V-SIM with parameter set 6 but with a slight increase in its excitability ($\tau_d = 0.365$). Similar Doppler shift behavior has been observed experimentally in cardiac preparations¹²⁵ and in the Belousov–Zhabotinsky (BZ) reaction under an electric field.¹²⁶

In the case shown in Fig. 18, the smallest period produced by the Doppler effect still is greater than the minimum period allowed for propagation (the period obtained at DI_{min}), so that no conduction blocks occur and no transitions to the 2:1 branch are present, resulting in a stable (but non-

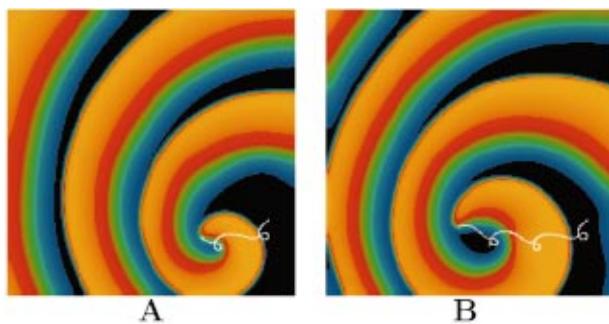
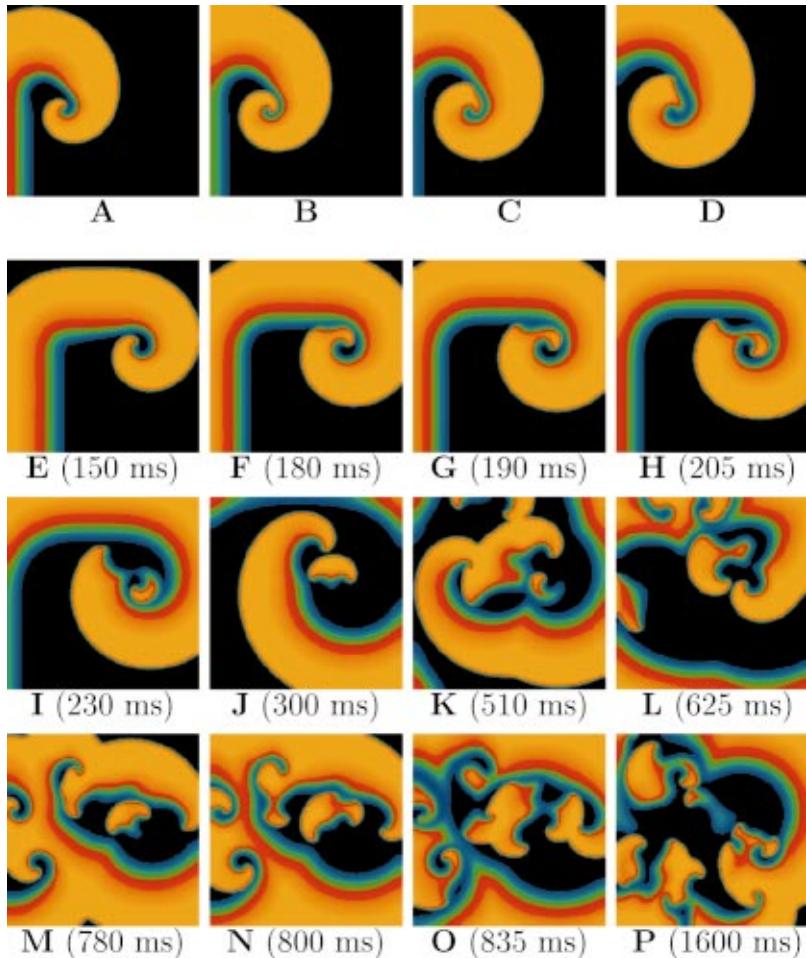


FIG. 18. (Color) Stable spiral wave with cycloidal trajectory obtained using parameter set 6 with $\tau_d=0.365$. The wave fronts became more closely packed on the left-hand side of the domain because the spiral was moving in that direction. The Doppler shift in frequency also decreased the period of waves to the left, resulting in the observed shorter wavelength. Tissue size is 11.25×11.25 cm with $\Delta x=0.025$ cm and $\Delta t=0.25$ ms.

stationary) spiral wave. However, certain trajectories can impose larger Doppler shifts on the period and bring it below the minimum period for propagation, which produces conduction block. Figure 19 shows an example of these types of conduction blocks occurring for a spiral wave following a small circular or epicycloidal trajectory. Panels (a)–(d) illustrate the block of a wave tip that follows a tight spiral because of a very small loop (parameter set 6, $\tau_d=0.38$). However, for slightly larger loops ($\tau_d=0.385$ – 0.39) the spiral tip succeeds in propagating each time the spiral makes an inner



loop (inward petal) since the area in front of the tip now has a large enough DI to allow the tip to propagate, but the shift in frequency is enough to produce conduction block away from the tip in the rotation and initiate reentry as shown in panels (e)–(h). As the spiral is formed [(e)–(h)] and the tip turns tightly (because of its short period of rotation), the spiral encounters a DI smaller than DI_{min} and is blocked. However, the tip continues to propagate because it remains on the 1:1 branch even while adjacent parts of the wave have jumped to the 2:1 branch (i). Eventually, as more tissue becomes available for excitation, the two broken ends propagate into areas with longer DIs that allow the resumption of 1:1 conduction, now forming new spirals because they are able to propagate (j). The newly generated spirals evolve and repeat the initial breakup process, as shown in the left lower corner of panels (m)–(o). Because of the wide distribution of refractory periods throughout the tissue, which can correspond to either short or long APDs falling into the 1:1 or 2:1 regime, respectively, the dynamics become increasingly complicated as new wave breaks continue to form. However, for the first two beats after the break it is possible to obtain the same type of voltage trace as in Fig. 16(b) for points close to and far from the tip, indicating the presence of regions with 2:1 conduction. Note that unlike mechanisms 1 and 2, there are no slow recovery fronts or alternans of APD since in this case the slope of the APD restitution curve is never greater than one, as shown in Fig. 16(a).

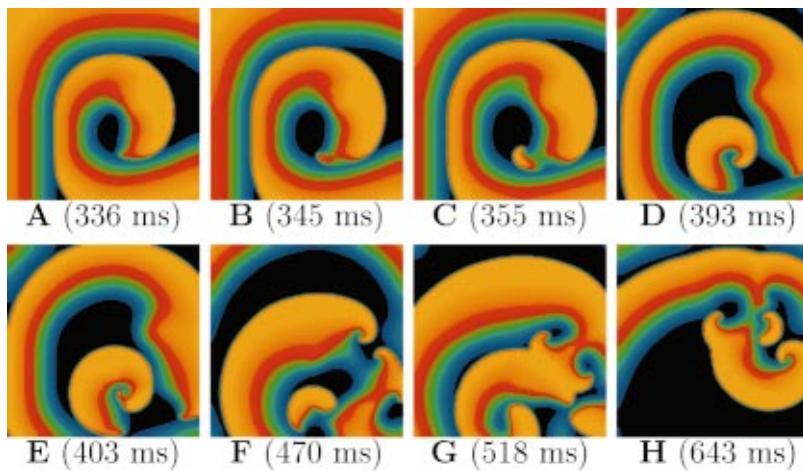


FIG. 20. (Color) Breakup of a spiral wave whose tip followed a hypocycloidal trajectory using parameter set 6 with $\tau_d=0.3$. The Doppler shift induced by the meandering tip caused the period to fall below the minimum period for propagation, causing 2:1 block and wave break (a)–(c). As the wave continued to meander, regions with 2:1 conduction block continued to develop (d)–(h). Tissue size is 11.25×11.25 cm with $\Delta x = 0.025$ cm and $\Delta t = 0.25$ ms.

Breakup resulting from Doppler shift-induced 2:1 block also can be obtained in some of the hypocycloidal trajectories when the outer loops are able to produce a large frequency shift, as in the case obtained using $\tau_d=0.25\text{--}0.3$. Figure 20 shows how a spiral wave in the hypocycloidal regime breaks as the tip make an outer loop and the shift in frequency is enough to produce conduction block (a)–(d) and multiple wave breaks (e)–(h). The broken waves in Fig. 20 do not fill the domain as densely as those in Fig. 19 because of the difference in the sizes of the hypocycloidal trajectory and the small circular core of Fig. 19, which allowed waves to break more often and to pack more closely together than in the present case. Because of the large trajectories in the hypocycloidal cases compared to the tissue size, the breakup was transient in many of the simulations as in the example of mechanism 1, lasting only a few seconds before all spirals eventually extinguished from collisions with other waves and with the boundaries. However, in the circular core case (Fig. 19), breakup was continuous during the full 10 s simulated.

Meandering trajectories are not the only types that can produce a Doppler shift in a spiral wave leading to breakup. In the linear core regime, where spiral waves follow long lines of block (for models with very flat restitutions, the linear core size is approximately $CV_{\max} \times APD/2$)⁸⁷ with sharp turns, Doppler shift can cause 2:1 conduction blocks and wave breaks. Figure 21 shows such an effect when the model is brought into the linear core regime by setting τ_d to 0.115. The first frame (a) shows the spiral at the beginning of its second rotation after initiation from a broken pulse. As the spiral tip makes a sharp turn (b)–(c), the Doppler shift causes part of the wave to get too close to the adjacent spiral rotation, so that it breaks as it falls below the minimum period for propagation (d)–(f), much as in panels (e)–(h) of Fig. 19. The two broken ends eventually recombine (h)–(j), but on the next rotation the conduction block is large enough (k)–(m) to prevent the two waves from reconnecting, and two new spirals are formed (n). Eventually new spirals break in the same way, resulting in turbulence (o)–(p). Note that due to the long linear core, the domain appears anisotropic, although it is not.

An interesting case arises when the Doppler shift occurs

at the spiral tip itself. Sharp turns in the tip trajectory can bring the tip of the spiral wave below the minimum period and halt its propagation, as shown previously in panels (a)–(d) of Fig. 19 for small circular trajectories and as shown in Fig. 22 for linear cores. After the tip is blocked, a *secondary wave of depolarization* can evolve and continue the spiral's rotation. Leon *et al.*¹²⁷ previously observed this behavior using a modified version of the BR model in an anisotropic domain. They referred to this phenomenon as a *secondary wave of repolarization* instead, because a pronounced repolarization region formed between the stopped original tip and the newly formed one. In the example of Fig. 22, only the new wave is observed without the repolarization island due to the very high excitability of the system and almost flat restitution, so that we use the term secondary wave of depolarization in this case. Leon *et al.*¹²⁷ modified the BR model by increasing the sodium conductance and eliminating the *j* gate, thereby decreasing the minimum DI from 43 to 25 ms and increasing the minimum APD. Enhanced by the anisotropy of the system, these changes created a window of bistability that allowed the cessation of the tip's motion due to Doppler shift and the formation of a secondary wave of depolarization.

Doppler shift due to spiral wave drift has been observed in cardiac preparations arising from either experimentally induced¹²⁵ or naturally occurring^{9,128} electrophysiological heterogeneity. In simulations, breakup by Doppler shift was first observed and described by Bär *et al.*^{36,129} using a two-dimensional simplified model for CO oxidation where breakup is produced by meander. However, in some cases additional breakup in their model is produced by a *backfiring* effect that allows new waves to be generated in the wake of previous ones, which makes characterization of the breakup more complicated. The Luo–Rudy–I model¹⁰³ also exhibits breakup by Doppler shift with calcium dynamics speeded up by a factor of between 2 and 2.8, as seen in Fig. 4 of Ref. 130 and in Fig. 40 in Sec. VII. It is important to indicate that this breakup mechanism shown in different regimes corresponding to various tip trajectories does not require steep APD restitution. In fact, both the LR–I model with calcium speedup (2–2.8) and the Bär model have relatively flat restitution curves, where the slope is always less than one. We

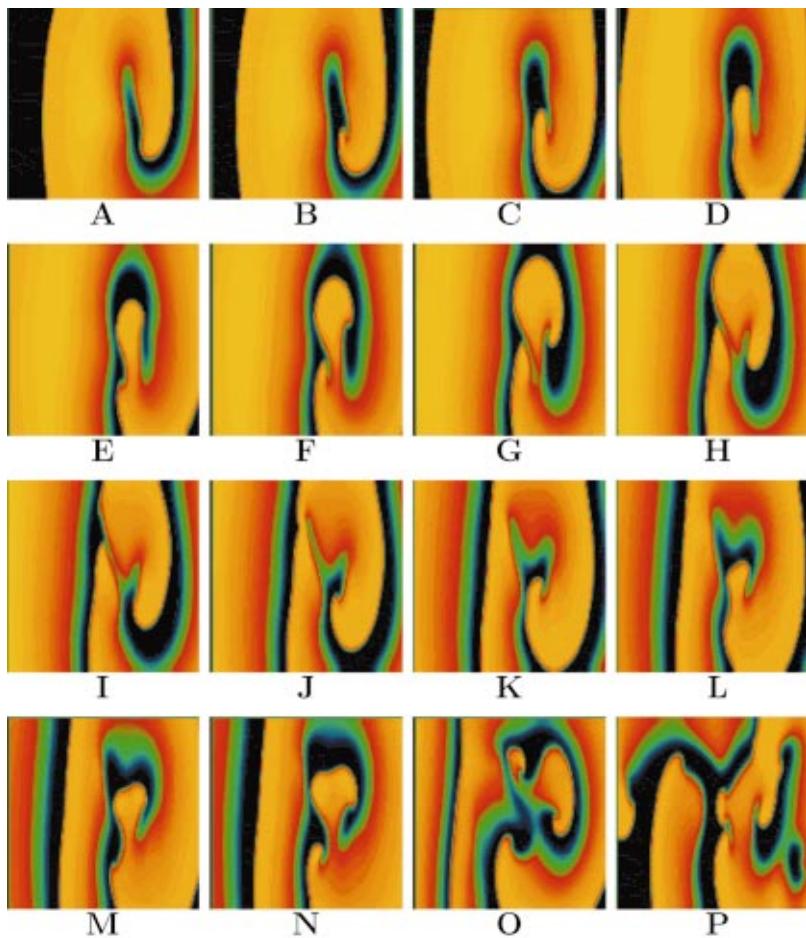


FIG. 21. (Color) Breakup of a spiral wave following a linear core due to the Doppler effect. As the spiral tip turned sharply (a)–(c), part of it moved too close to a previously generated wave. The Doppler effect reduced the period below the minimum period for propagation, and wave break ensued (d)–(f). The break mended (h)–(j), but when the break occurred again during the next rotation (k)–(m) new spirals were formed (n). As the breakup evolved, the dynamics became increasingly complex (o)–(p). Note that the linear core caused the tissue to appear anisotropic, when in fact it was isotropic. Parameter set 6 with $\tau_d = 0.115$ was used. Tissue size was 8.8×8.8 cm with $\Delta x = 0.016$ cm and $\Delta t = 0.18$ ms.

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note that for breakup by this mechanism to occur, a bistability window and a tip trajectory that can reach conduction block by a Doppler shift in frequency are necessary. This is most easily achieved for flat restitutions where the minimum DI is small and the minimum APD is large.

D. Mechanism 5: Biphasic APD restitution curve

So far only APD restitution curves that are monotonically decreasing functions of DI have been considered. However, some studies^{131–133} have found APD restitution curves with a range of DIs for which the APD prolongs to a local

maximum as DI decreases. These *biphasic* APD restitutions have been shown to lead to complex dynamics in 1D maps¹³⁴ and to spatiotemporal chaos in 1D rings.¹³⁵ However, the precise ionic mechanisms responsible for the supernormal phase still are not understood fully; furthermore, some experiments have shown that their existence may depend on the protocol used to measure the restitution curve.^{133,136} Nevertheless, we include a brief discussion for completeness.

Experiments have shown different possible shapes and slopes for biphasic APD restitution curves. In addition, as mentioned previously, the physiological phenomena that pro-

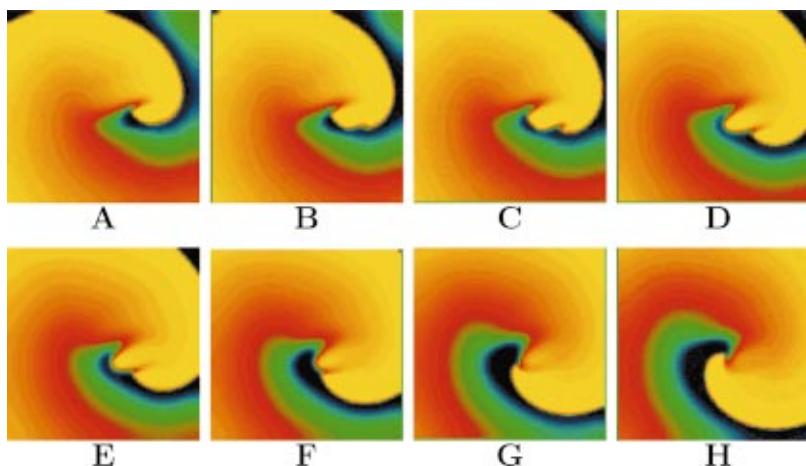


FIG. 22. (Color) Secondary waves of depolarization due to Doppler shift occurring at the spiral tip itself using parameter set 7. The period at the tip fell below the minimum necessary for propagation, causing the tip to halt its motion (a). However, a second wave of depolarization developed (b)–(c), moved around the stalled and now repolarizing original tip (d)–(f), and continued the motion of the tip (g)–(h). Tissue size was 4×4 cm with $\Delta x = 0.016$ cm and $\Delta t = 0.18$ ms.

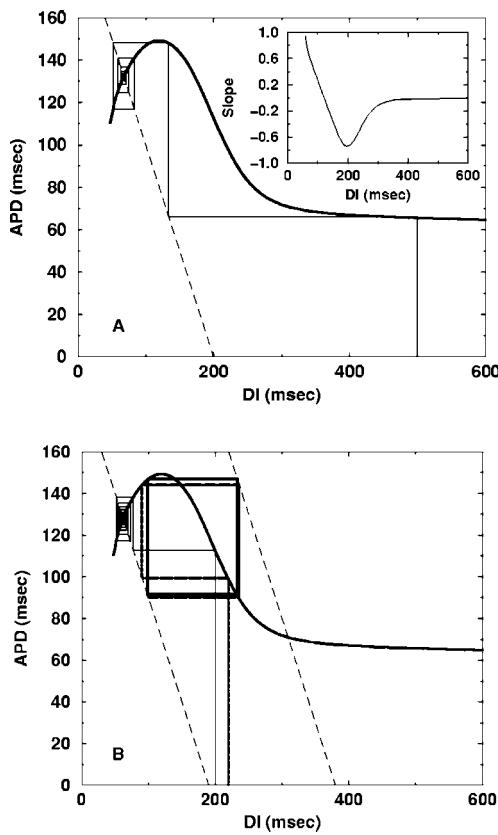


FIG. 23. Oscillations due to a biphasic APD restitution curve. The shape of the restitution curve was based on observed restitution curves obtained from rabbit ventricular preparations (Ref. 131). Even when the slope of the restitution curve never exceeds one in magnitude (see the inset), conduction block can form and lead to breakup. (a) For a period of 200 ms, a stable fixed point can be obtained even when using an initial condition with a large DI. (b) For the shorter period of 190 ms (dashed line shows the period and twice the period), two different initial conditions can result in either a stable solution (solid line) or in 2:1 block (dotted line). Parameter set 8 was used.

duce the biphasic restitution curves observed experimentally have not yet been identified. Therefore in the context of the 3V-SIM, we obtain a biphasic restitution curve by adding an extra current that deactivates at short DIs (see the Appendix and parameter set 8). We note that our intent here is only to replicate the mesoscopic restitution characteristics observed in experiments and not to reproduce the ionic basis. The shape of the restitution presented here is based on those obtained in rabbit ventricle preparations;¹³¹ however, biphasic restitutions also have been measured in humans.¹³³

When the supernormal part of the restitution curve has a region with slope greater than one in magnitude, the complex dynamics^{134,135} naturally would lead to spiral breakup in 2D, as shown for negatively sloped restitution curves with slope greater than one in magnitude.¹³⁷ However, even when the magnitude of the restitution curve never exceeds one, the biphasic shape of the restitution curve can produce small variations in recovery (i.e., values of DIs) that can lead to conduction block, as shown in Fig. 23.

In 2D, the conduction block generated by the biphasic portion of the APD restitution curve at certain DIs can cause spiral wave breakup. Figure 24 shows an example of how breakup can develop under these conditions. An initially uniform spiral (a) develops a thicker wavelength as it turns and finds smaller DIs (b) and eventually breaks as a result of 2:1 block (c)–(d), as described in Fig. 23. The local maximum in APD due to the biphasic restitution can lead to different wavelengths, large depressions in the wave back, and subsequent occurrences of 2:1 block (e)–(l).

E. Mechanism 6: Supernormal conduction velocity

Like the APD restitution curve, the conduction velocity restitution curve also has been found in some experiments not to be a monotonically decreasing function. In the cardi-

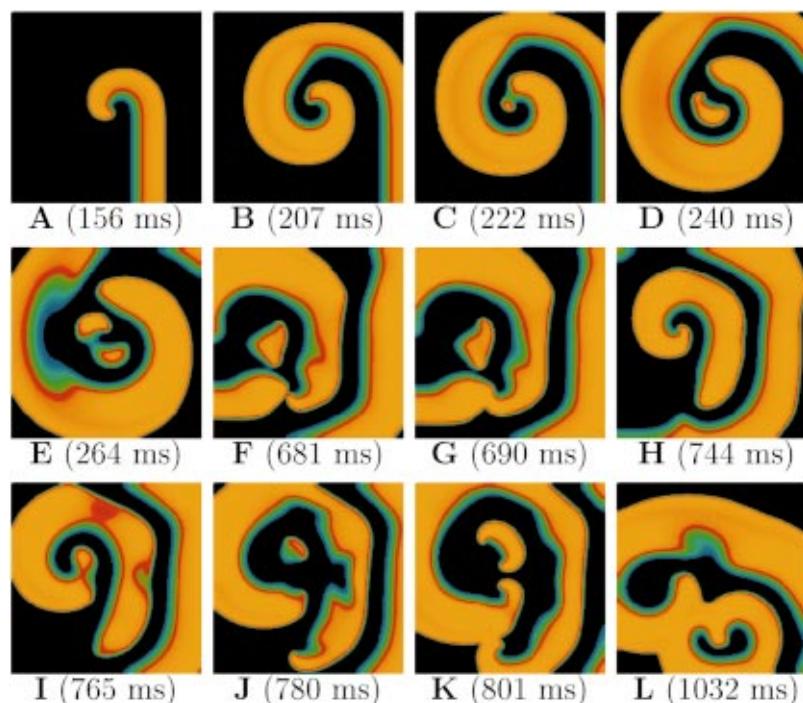


FIG. 24. (Color) Spiral wave breakup due to a biphasic APD restitution curve using parameter set 8. Although the spiral initiated uniformly (a), its wavelength increased as it turned and encountered smaller DIs (b). Soon after, conduction block formed and caused breakup (c)–(d). As the breakup evolved (e)–(l), large variations in wavelengths, wide depressions in the wave back, and subsequent occurrences of 2:1 block occurred. Tissue size is 5×5 cm with $\Delta x = 0.025$ cm and $\Delta t = 0.25$ ms.

ology literature, such CV restitution curves are called supernormal (rather than biphasic). Supernormal CV also can be expressed as supernormal excitability, which is commonly represented as the dependence of excitation threshold on diastolic interval.¹³⁸ Experiments have demonstrated supernormal conduction in the His–Purkinje system,¹³⁸ papillary muscles,¹³⁹ and the outflow tract of the right ventricle,^{140,141} as well as in a related excitable system, the 1,4-cyclohexanedione BZ reaction.^{142,143} Simulations using supernormality have produced chaotic dynamics in 1D maps¹³⁸ and spiral wave breakup in a modified FHN model.³⁸ Although measurement protocols often are indirect and its existence in most regions of the heart is questionable,¹⁴⁴ we include supernormality as a possible arrhythmogenic mechanism, as in the case of biphasic restitutions, mostly for completeness.

Supernormal conduction, if it exists in cardiac tissue, may be arrhythmogenic by producing conduction blocks due to rapidly moving waves that collide and stack together at small DIs, as shown in the BZ reaction.¹⁴² The solid curve in Fig. 25(a) shows an example of a supernormal CV restitution obtained using the 3V-SIM with parameter set 9, while the dashed line illustrates a normal curve for comparison (using $\tau_{v2} = 15$). Figure 25(b) shows the corresponding APD restitution curve, whose slope never exceeds one. The rapid waves generated by supernormality rush toward relatively slow-moving wave backs and practically slam into them, breaking and generating new waves, as shown in Fig. 26. The breaks tend to develop fairly near the spiral tip because the small DIs at the tip produce waves that conduct supernormally. Scalloping also develops and leads to wave break, but in this case the scallops form because the supernormal conduction velocity generates heterogeneity of refractoriness, rather than from the steep APD restitution mechanism, since the slope of the APD restitution curve never exceeds one in this example [see Fig. 25(b)]. In addition, because the DI_{min} is very small in this case, some second waves of repolarization as in Fig. 22 can occur once breakup has started [see Figs. 26(c) and 26(d)]. To demonstrate that the breakup is due to the supernormality, we show in Fig. 26(i) a stable spiral wave obtained using the same parameters but excluding supernormality (see the dashed lines in Fig. 25).

V. MECHANISM OF SPIRAL WAVE BREAKUP IN QUASI-3D

Mechanism 7: Periodic boundary conditions with hypermeandering tip trajectories

To this point, only rectangular shapes with no-flux boundary conditions have been used in all the simulations and no anatomical structure has been considered. However, periodicity is an important feature of cardiac structure and can affect the stability of spiral waves. Using periodic boundary conditions along two parallel edges of a 2D surface essentially forms a cylinder, which represents to a first degree a simplified geometry for some of the regions in the heart (such as the area between a valve rim and a blood vessel, or a ventricle and the septum), while still retaining the computational simplicity of a 2D plane. Figure 27 illus-

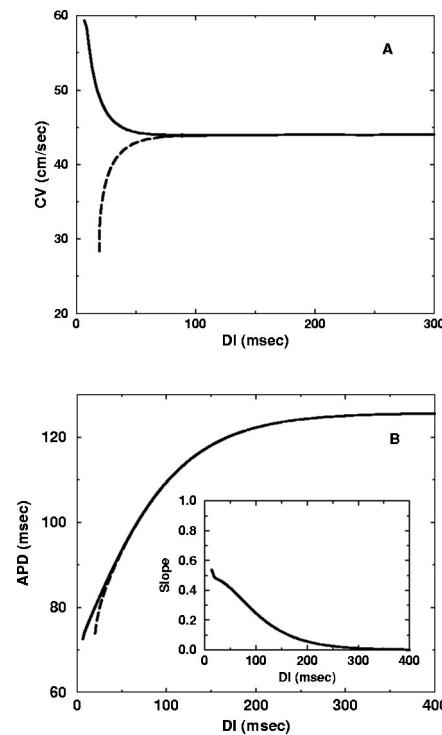


FIG. 25. CV (a) and APD (b) restitution curves for parameter set 9, which produces supernormal conduction velocity. Solid lines indicate the restitution curves used with supernormal conduction velocity, while the dashed lines are associated with a more usual CV restitution curve (by using parameter set 9 but with $\tau_{v2}^- = 15$). The slope of the APD restitution curve never exceeds one, as shown in the inset of (b).

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trates how a 2D plane with periodic boundary conditions on the left and right can be wrapped into a cylinder. Because such a cylinder is constructed from periodic conditions on a plane and not from cylindrical coordinates in space, surface curvature effects are not included. Although experimental results from chemical spiral waves on spherical surfaces¹⁴⁵ have shown that spiral tip dynamics are not affected by the curvature of the surface, curvature may induce breakup due to loading effects in some situations.¹⁴⁶

The dynamics of a spiral wave on a cylinder depend on the size of the tissue relative to the wavelength of the spiral. If the perimeter of the cylinder (i.e., the distance between the edges with periodic boundary conditions) is large compared to the spiral wave tip trajectory, the boundaries play no role in the tip dynamics and the trajectory is the same for both periodic and no-flux boundary conditions, as shown in panels (a) and (b) of Fig. 28 using parameter set 1 [same spiral as in Fig. 1(e)]. However, the interaction between colliding fronts (coming from both sides due to periodicity) produces some regions with different patterns of refractoriness using periodic boundary conditions compared to no-flux. The dispersion of refractoriness changes as the perimeter is decreased further [Fig. 28(c)], but the spiral wave trajectory remains protected and unperturbed until the perimeter becomes comparable to the wavelength of the spiral [panels (d)–(e) of Fig. 28], at which point the spiral tip becomes perturbed by self-generated incoming waves. In related previous work, Yermakova *et al.*¹⁴⁷ studied the dynamics of spiral waves periodi-

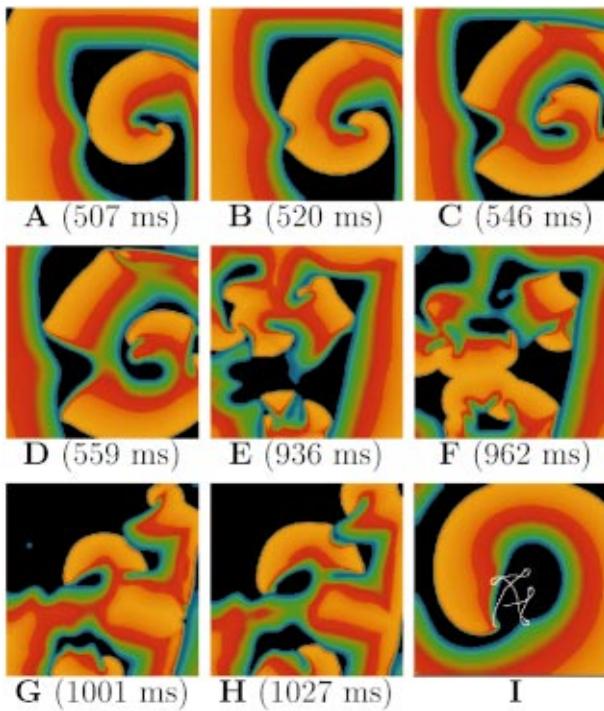


FIG. 26. (Color) Breakup due to supernormal conduction velocity using parameter set 9. (a)–(d) Breakup occurred as the spiral sped toward the wave back in several locations, including at the left, where the spiral caught up to and collided with the previous wave back, and at the right of the medium, where boundary effects also played a role. Additional wave breaks occurred as the medium evolved. (e)–(f) The wave in the upper right sped up and collided with the back of the previous wave, resulting in a wave break. (g)–(h) As the wave in the upper right central portion of the domain sped toward the scalloped back of another wave, it began to break. (i) Stable hypermeandering spiral wave with no breakup obtained when the supernormal component of the CV restitution curve is excluded [dashed line in Fig. 25(a)]. Tissue size is 8.85×8.85 cm with $\Delta x = 0.022$ cm and $\Delta t = 0.2$ ms.

cally perturbed with plane waves and showed that when the pacing frequency is higher than that of the spiral wave, a drift is induced on the spiral wave tip. The same results are obtained using periodic boundary conditions when the cylinder perimeter is comparable to the wavelength of the spiral,^{99,148} since the wave front generated by the spiral propagates outward and is forced to collide with the spiral

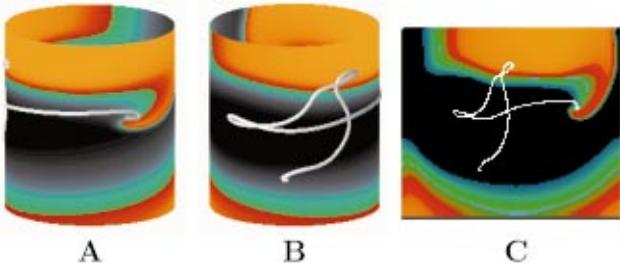


FIG. 27. (Color) Periodic boundary conditions along two parallel edges of a 2D sheet transform it to the topological equivalent of a cylinder. The voltage plot shown with its tip trajectory on the cylinder in (a) and rotated by 120° in (b) depicts the same data as shown in the rectangular domain in (c). Hereafter, the domains are shown only as 2D sheets. The height of the cylinders was reduced by 40% to aid in visualization. Parameter set 1 is used as in Fig. 1(e). Tissue size is 7.3×6.32 cm with $\Delta x = 0.0316$ cm and $\Delta t = 0.2$ ms.

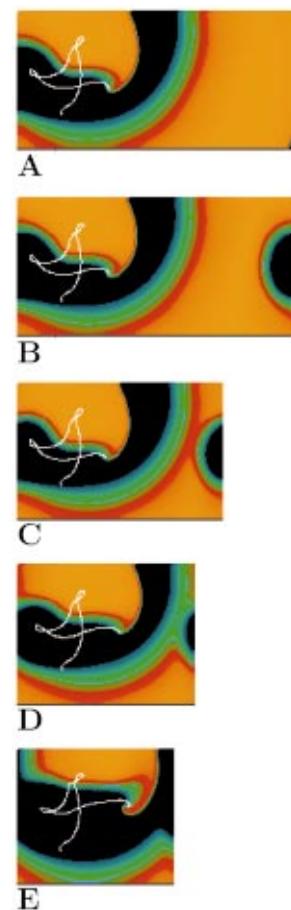


FIG. 28. (Color) Effects of periodic boundary conditions on domains of decreasing length using the 3V-SIM with parameter set 1. (a) Tip trajectory and voltage image with no-flux boundary conditions imposed on all four boundaries (size $12.64 \text{ cm} \times 6.32 \text{ cm}$). (b) Tip trajectory in a tissue of the same size as (a) using periodic boundary conditions at the left and right edges and no-flux boundary conditions on the top and bottom. (c)–(e) Tip trajectories using periodic boundary conditions in progressively shorter domains (perimeter decreased from 12.64 cm to 9.5 , 7.9 , and, 7.3 cm , respectively). Although the trajectories are the same for (b) and (c), differences in repolarization are apparent. Note that for the shortest perimeters (d) and (e) the tips and their trajectories begin to diverge from the originals and start to drift. Spatial and temporal resolutions are set to $\Delta x = 0.0316$ cm and $\Delta t = 0.2$ ms throughout.

periodically as the spiral rotates, with the collision period dependent on the conduction velocity and the cylinder's perimeter.

Figure 29 shows how periodic boundary conditions and the size of the domain affect the evolution of a spiral wave following a circular core. The two plots in panels (a) and (b) show four snapshots during one rotation for two domains that are identical except that (b) has periodic boundary conditions at the left and right edges; all other boundary conditions are no-flux, and parameter set 1 is used with $\tau_d = 0.415$. Because the spiral wave interacts with itself under periodic boundary conditions, differently shaped quiescent regions form at the right-hand side of the domain depending on the boundary conditions. When periodic boundary conditions are used, the quiescent region develops sooner because it was stimulated earlier by an encroaching wave that passed across the periodic boundary. As the perimeter of the cylinder is decreased from 4.74 to 4.55 cm in Fig. 29(c), the spiral

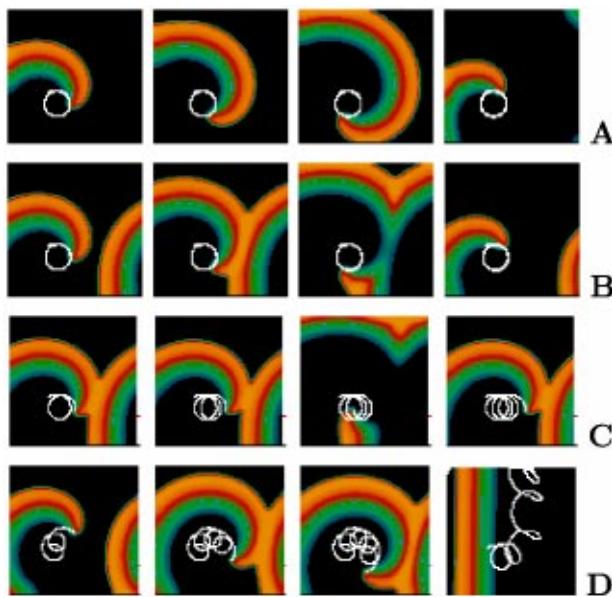


FIG. 29. (Color online) Effects of periodic boundary conditions on spiral tip trajectories. Parameter set 1 is used with $\tau_d=0.415$ [except in (d)], $\Delta x=0.0316$ cm, and $\Delta t=0.2$ ms. (a) Four snapshots during one rotation of a spiral wave with circular core in a square domain with no-flux boundary conditions. (b) Same as in (a), but with periodic boundary conditions on the left and right edges. (c) Drift induced by incoming waves in the periodic case once the length was decreased from 4.74 to 4.58 cm and the period of rotation was longer than the time required to travel along the entire length. Under these conditions, waves interacted with the spiral tip and produced drift. (d) The first three panels show an unperturbed meandering spiral wave following an epicycloidal trajectory using $\tau_d=0.35$. When the length was decreased slightly to 4.55 cm, the spiral drifted, which caused it to vanish at the boundary (as shown by the trajectory remaining in the last panel), leaving a stable planar wave front that circulated around the cylinder indefinitely.

wave tip is perturbed by incoming waves (since the period of rotation is smaller than the time required to travel once around the cylinder) and a drift in the tip trajectory develops. This drift is purely an effect of the boundaries and is independent of the type of tip trajectory [i.e., circular or meandering, see Fig. 29(d)] and of the model used.⁸⁷ The only requirement is that the cylinder perimeter is smaller than the spiral wavelength, so that the spiral tip can interact with the waves it generates. If the perimeter is small enough, drift can cause the spiral tip to migrate to a no-flux boundary and disappear, leaving only a plane wave as shown in the last panel of Fig. 29(d).

Once drift is present, a further decrease in the cylinder's perimeter makes the spiral wave encounter its own incoming waves sooner, equivalent to pacing a spiral wave at a frequency much faster than its own and resulting in an increase in the drift velocity.¹⁴⁷ Once the perimeter is smaller than the tip trajectory, no spiral wave activity can be sustained. However, for spiral waves in the hypermeandering linear regime, there is a window of cylinder perimeters between drift and termination for which spiral waves will break.^{99,148} The breakup is produced because the hypermeandering wave tip repolarizes some regions along the cylinder unevenly.⁸⁷ Therefore, the incoming waves produced by the spiral itself can block the tip trajectory and form new spiral waves. Activations can disappear when the spirals annihilate with the no-flux boundaries. Figure 30 shows a sequence of voltage plots of spiral wave breakup on a small cylinder with perimeter 7.11 cm using parameter set 1. The spiral wave shown in (a) collides with a portion of itself moving to the right across the periodic boundary in (b). The new and old fronts merge (c), but interaction with the wave back causes only a small fragment of the original spiral to remain (d). As the spiral

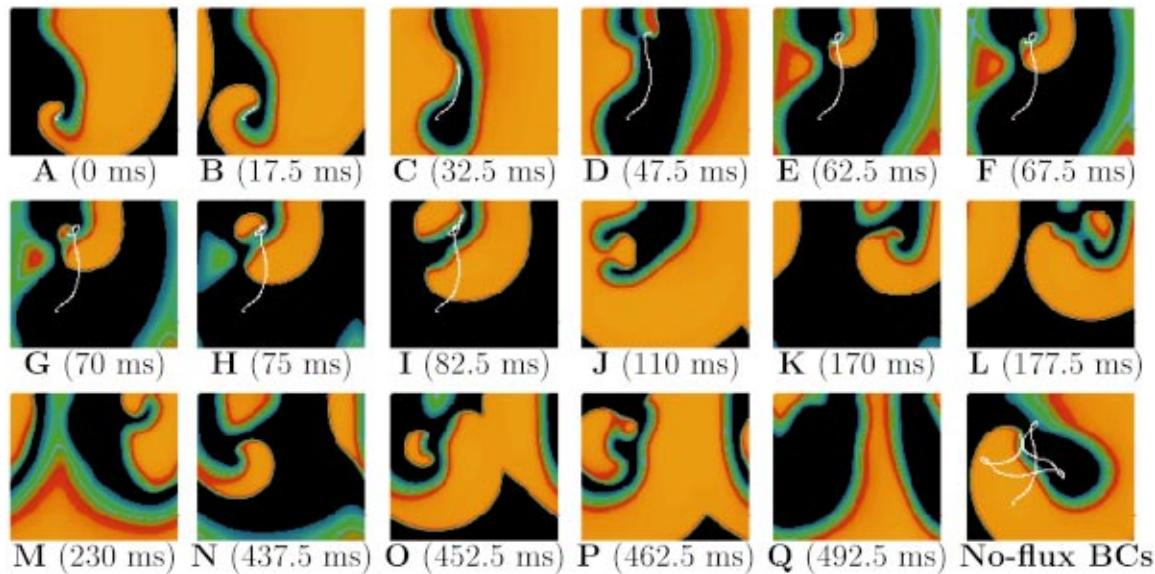


FIG. 30. (Color) Evolution of periodic boundary condition-induced breakup of a spiral wave with a hypermeandering tip trajectory in a 7.11×6.32 cm domain. Because the tip meandered, regions were repolarized unevenly, allowing conduction blocks and subsequent wave breaks to develop, as described in the text. The tip trajectory is shown in frames (a)–(i) but is discontinued in the remaining frames because multiple spiral waves are present. Ultimately, the breakup was transient, as all the wave fronts eventually were absorbed by the no-flux boundaries (top and bottom) (q). As shown in the last panel, no breakup occurred when no-flux boundary conditions were used on all edges in the same size domain. Parameter set 1 was used with $\Delta x=0.0316$ cm and $\Delta t=0.2$ ms.

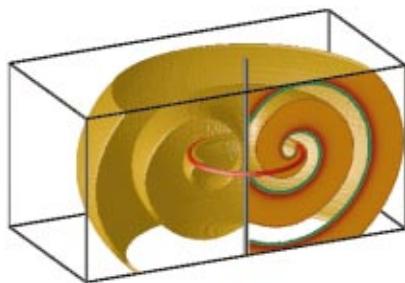


FIG. 31. (Color) Three-dimensional scroll wave. A 2D slice showing the voltage profile of a spiral wave is shown on the right-hand side. The gold scroll-shaped surface tracks the wave front in 3D, and the red circle shows the instantaneous location of all spiral wave tips in all slices, otherwise known as a filament or vortex line. Half the domain is shown for clarity.

continues to turn (e)–(f), it encounters the wave back and fragments into multiple waves (g)–(i). These two fronts merge again (j), but further breakup occurs as the fronts continue to interact with the wave backs (k)–(p). Ultimately, the no-flux boundary conditions, at the top and bottom of the cylinder, absorb all the wave fronts (q), leaving behind only quiescent tissue. The last frame of Fig. 30 shows how the same initial condition in the same size domain but with all no-flux boundary conditions results in a stable hypermeandering spiral wave. Similar breakup due to periodic boundary conditions has been obtained in Ref. 87 using both the FHN model with linear cores^{59,60} on a cylinder with a perimeter of 280 grid points and using the BR model on small cylinders with the speed of calcium dynamics increased by a factor of two (MBR), which in 2D tissues using no-flux boundary conditions generates stable spiral waves.^{34,89}

VI. MECHANISMS OF SPIRAL WAVE BREAKUP IN 3D

While atrial tissue may be thin enough to be considered effectively two-dimensional (leaving aside its complex geometry, fiber structure, and regional variations in conduction velocity and action potentials),^{23,149} the ventricles are substantially thicker and three-dimensional effects may need to be considered. In particular, since the early experiments of Garrey³⁰ in 1914, who showed using canine hearts that fibrillation in the thinner right ventricle ceased when it was disconnected from the thicker left ventricle, the inclusion of a third dimension presents what has been since then a controversial open question: *is ventricular fibrillation purely a three-dimensional effect?*

The issue of whether ventricular fibrillation is intrinsically three-dimensional is a fundamental claim largely substantiated by the concept of a minimum mass necessary for fibrillation (more specifically perhaps, would be a minimum size in relation to wavelength) first hypothesized by Garrey.³⁰ Among other things, he showed that pieces of ventricular muscle with a surface area of less than 4 cm^2 that had been shaved from the left ventricle stopped fibrillation, whereas the remaining portion of the left ventricle continued to fibrillate until 75% of the ventricle had been removed. Dillon *et al.*¹⁵⁰ and Kavanagh *et al.*¹⁵¹ found comparable results also in canine ventricles when part of the ventricles were inactivated by a transmural infarct, leaving the rest of the

tissue quasi-2D. Zipes *et al.*¹⁵² suggested that fibrillation emanated only from the thicker left ventricle after they chemically depolarized the left ventricles of canine hearts and observed that fibrillation transitioned to sustained monomorphic tachycardia with a period of about 160 ms. Similarly, conversion from fibrillation to tachycardia in Langendorff-perfused rabbit hearts was obtained by Allessie *et al.*,¹⁵³ Breithardt *et al.*,¹⁵⁴ and Schalij *et al.*¹⁵⁵ when the intramural layers of the ventricles were eliminated by necrosis coagulation caused by freezing the endocardium with liquid nitrogen. This procedure left a surviving epicardial layer about 1 mm thick¹⁵⁴ (quasi-2D), and in contrast to the infarction-induced thinning experiments, freezing seemed to preserve the electrophysiological properties¹⁵⁵ that otherwise potentially could alter the dynamics of electrical waves. More recently, two experiments of tissue reduction in porcine hearts, one¹⁰ using freezing and the other⁷⁵ using sequential cuts of $2 \times 4 \text{ cm}$ portions of the fibrillating tissue parallel to the epicardium, also found evidence supporting the critical mass hypothesis, with a minimum mass of about 20 g needed to support fibrillation and a decreasing number of spiral waves as the tissue mass was decreased. The main conclusion of ventricular thinning experiments, emphasized by Winfree,^{156,157} is that hearts below a critical electrically active muscle thickness do not fibrillate, but instead support stable forms of tachycardia that can be associated with a single spiral wave. The minimum thickness, however, needs to be determined with respect to the wavelength¹⁵⁸ and perhaps the size of the tip trajectory.⁶⁴

In numerical simulations, the inclusion of a third dimension has been shown to widen the range of parameters that produce breakup for some of the 2D breakup mechanisms,^{87,159} although the parameter ranges increase only by 5%–10%. More importantly, however, simulations in 3D have shown the existence of purely three-dimensional breakup mechanisms^{39–41,86} that have no analogs in 2D. In the following sections we discuss three mechanisms of 3D scroll wave breakup: negative tension in homogeneous tissue, twist instability in the presence of rotational anisotropy, and low coupling and discrete effects, also in the presence of rotational anisotropy.

A. Mechanism 8: Negative tension in the low excitability regime

In 3D, while a spiral wave becomes a scroll wave, the spiral tip expands from a single point to a one-dimensional line called a vortex line or filament. The simplest form of a scroll wave is a straight vortex obtained trivially when 2D spiral waves are stacked perpendicular to their plane of rotation over a finite thickness. Scroll waves like this both were first found in experiments with the Belousov–Zhabotinsky chemical reagent and were proposed to exist in myocardium by Winfree in 1973,¹⁶⁰ and were first observed in ventricles extending upright 10–20 mm from endocardium to epicardium by Chen *et al.*¹⁶¹ in 1988 and by Frazier *et al.*¹⁶² in 1989. Vortex filaments, however, need not be straight lines, but instead can curve, bend, and twist,^{16,163–165} and sometimes form closed rings confined inside the medium without touching any boundaries.^{166,167} Figure 31 shows an example

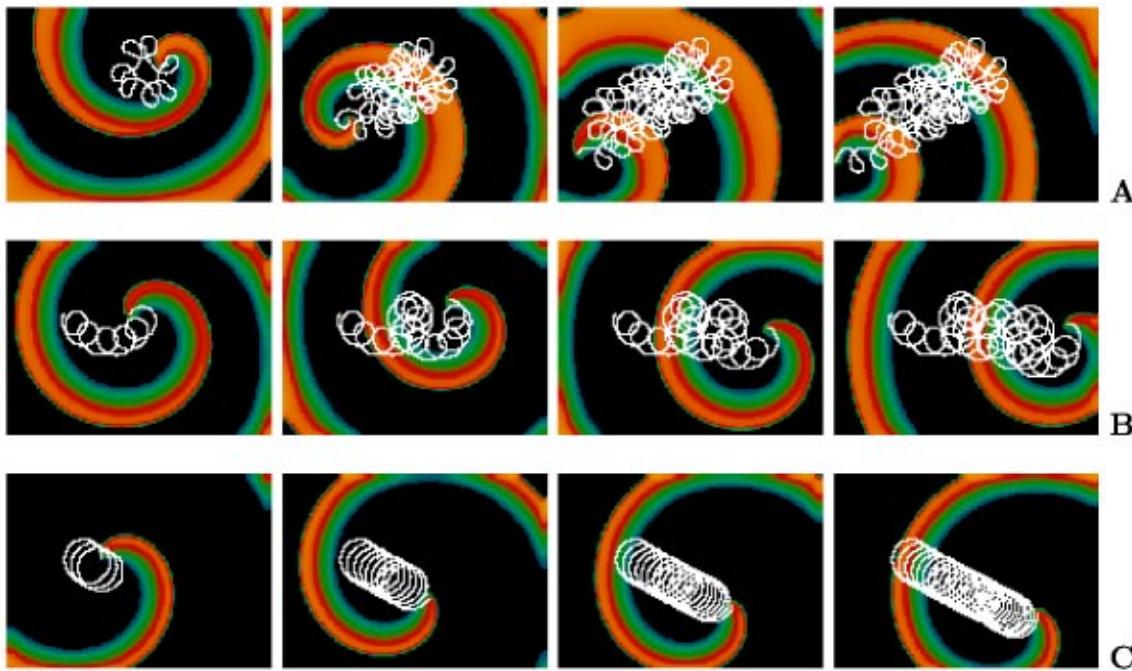


FIG. 32. (Color online) Examples of contracting and expanding scroll rings. Each row shows four snapshots of a 2D plane (parallel to the scroll axis of symmetry as in Fig. 31, with the left edge corresponding to zero radius) showing the evolution of a scroll wave. The ring in (a) is in the negative tension regime and follows a hypocycloidal trajectory as it drifts along the z -axis, contracts and eventually disappears [frames at 1.216, 3.832, 5.48, and 5.568 s]. The rings in (b) and (c), which are in the negative tension regime, expand rather than contract as they also drift along the z -axis [frames in (b) at 1.12, 2.16, 3.1, and 4.22 s; frames in (c) at 1.036, 2.772, 3.262, and 4.55 s]. Sometimes boundary effects can stabilize a scroll ring, so that a shrinking ring does not collapse but equilibrates with its mirror image in the z -direction (Ref. 87), and an expanding ring can change direction and shrink once it reaches the boundaries. Parameters correspond to parameter set 1 using $\tau_d = 0.35, 0.39$, and 0.416 in (a), (b), and (c), respectively, with tissue size 10×7.5 cm, $\Delta x = 0.025$ cm and $\Delta t = 0.1$ ms.

of such a scroll ring. In Fig. 31 the wave front, shown in gold (over half the domain for clarity), forms a scroll-shaped surface. Note how the spiral tip evolves from a point to a line (or vortex), which in this case closes to create a ring (vortex ring), shown in red. On the right-hand side, the 2D colored voltage image showing a spiral corresponds to what is seen throughout the tissue as a plane is rotated about the axis pictured in black.

Numerical simulations of vortex rings have shown a wide range of dynamical behavior in various parameter regimes. While twisted and knotted scroll rings can be stable,^{168,169} untwisted scroll rings drift along the ring symmetry axis as they shrink or expand with velocities inversely proportional to the ring's radius.^{170,171} They shrink, contract, and disappear when the excitability of the system is normal or high and expand when the excitability is low.¹⁷⁰ There are some small parameter regimes in which boundaries can stop drift or even reverse the initial drift direction.^{87,172–174} 3D calculations of a scroll ring can be performed in 2D cylindrical coordinates (ρ and z) whenever the ring symmetry axis is aligned with the z -axis since, due to the symmetry involved, all angular dependencies become zero ($\partial/\partial\phi = 0$). Examples of scroll ring drift using the 3V-SIM for the high and low excitability limits are shown in Fig. 32, where two-dimensional cuts on the $\rho-z$ -plane similar to the 2D voltage color contour shown in Fig. 31 are used with the axis of symmetry on the left. Figure 32(a) shows four snapshots during the contraction of a scroll wave in the normal-high

excitable limit and in a regime where spiral waves follow hypocycloidal meander patterns. As the scroll radius (plotted on the horizontal axis) decreases (scroll contraction), the vortex ring follows the hypocycloidal trajectory and drifts along the z axis. The last frame shows the moment before the ring collapses. Panels (b)–(c) show the evolution of two scroll waves, following epicycloidal and circular trajectories respectively, in the opposite regime, the low excitability limit, where scroll waves expand. In both cases, the expanding rings also drift along the z -axis. It is important to note that, as mentioned in Sec. I, tip trajectories can be modified by changing either the excitability or the wavelength, so that a tip trajectory does not necessarily indicate tension regime (for example, circular core regimes can exist for both the high and low excitability limits).

Biktashev *et al.*³⁹ based on Keener's asymptotic theory for reaction-diffusion systems,^{175,176} obtained a vortex filament evolution equation for the no-meander limit and introduced the concept of *filament tension* to describe the radial growth of an untwisted circular filament. The filament tension is the proportionality coefficient γ in the local radial velocity of a circular filament ($V_r = dr/dt = -\gamma/r$). When γ is positive (high excitable limit), scroll rings shrink and any perturbation to a straight filament tends to disappear. On the other hand, when γ is negative (low excitability), scroll rings expand and any small perturbation to an initial straight filament grows exponentially.³⁹ Therefore, the term positive tension can be applied for $\gamma > 0$ where small perturbations de-

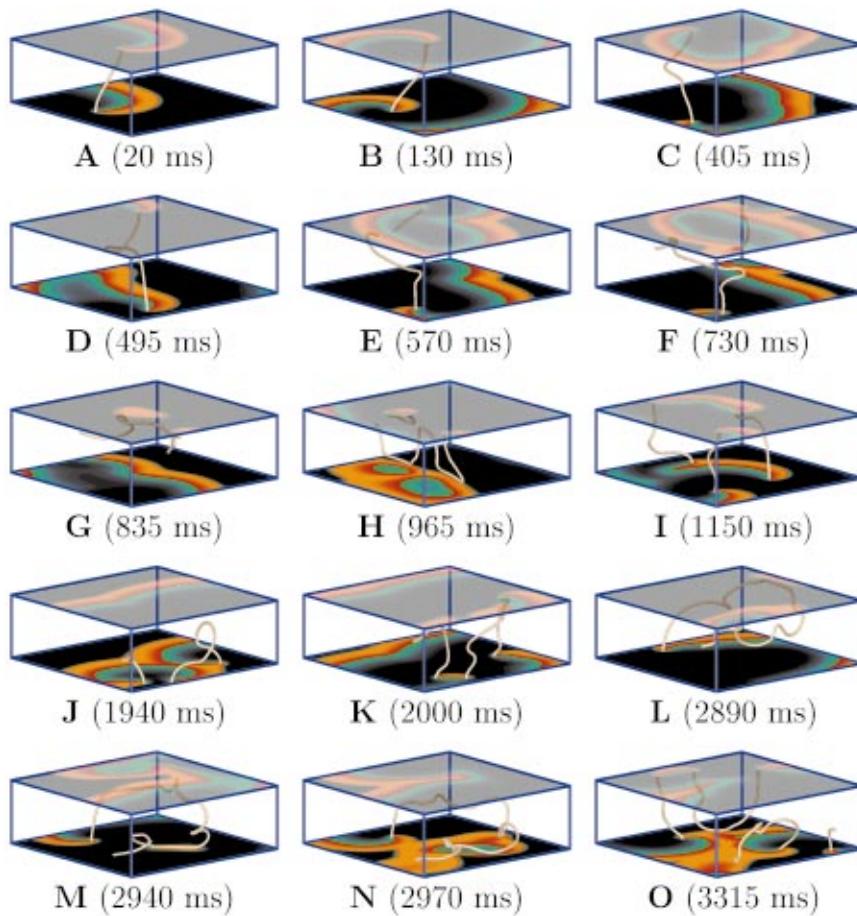


FIG. 33. (Color) Evolution and breakup of a three-dimensional vertical scroll wave due to negative tension in the low excitability limit in a slab of dimensions $6.32 \times 6.32 \times 2.21$ cm. A small perturbation was applied to the initial filament. The voltage is shown for the bottom of the tissue and semi-transparently for the top to allow filament visualization throughout the tissue. Note that as the vortex elongated because of the negative tension, it touched the boundaries and formed multiple scroll waves. The vertical dimension has been stretched by a factor of 1.4 to allow easier visualization of the filaments. Parameter set 1 was used with $\tau_d = 0.416$, $\Delta x = 0.0316$ cm, and $\Delta t = 0.25$ ms.

cay and negative tension for $\gamma < 0$ where small perturbations grow.

When a straight scroll wave is induced in the negative tension regime, it remains straight unless a small perturbation is applied. Biktašev *et al.*³⁹ showed, using the FHN model in a low excitability regime, that if a perturbation is applied to a straight vortex filament, the vortex will elongate and curve until it collides with the boundaries, thereby breaking up and generating a second vortex. These vortices subsequently will produce new vortices by expanding and touching the boundaries or by encountering conduction blocks that form new vortex rings (or ring fragments when touching boundaries). On the surface of the medium, the evolution of these vortices produces complex voltage activation patterns. Figure 33 shows an example of how a transmural filament evolves under these conditions, using the 3V-SIM with the parameters from Fig. 32(c). From the initial perturbation (a), the filament elongates (b)–(d) until it hits the boundary (e) and forms a second filament. Both filaments continue to elongate (f) and at times can disappear from one or both surfaces of the tissue and become intramural (g)–(h). Further evolution yields additional filaments, some by conduction blocks and some by collisions (i)–(k). Negative tension can substantially elongate a vortex (l)–(n) before it fragments again into multiple waves (o).

In cardiac tissue, the low excitability limit is reached when not enough oxygen is being supplied to the cells. This

generally occurs during hypoxia or ischemia produced, for example, soon after a coronary occlusion.

B. Mechanism 9: Fiber rotation with twist instability

Ventricular muscle is composed of elongated cells arranged roughly end-to-end to form fibers that conduct about three times faster along their axes than across. The fibers are arranged in sheets roughly parallel to the epicardial and endocardial surfaces, but their fiber axis rotates continuously from epicardium to endocardium.^{177,178} Peskin's¹⁷⁹ derivation of the ventricular fiber architecture from mechanical principles predicts a total fiber rotation of about 180° between walls, which is in close agreement with what has been measured in dissection experiments.¹⁸⁰ According to experiments, this high angle of rotation seems to remain roughly constant for the right and left ventricles, despite the differences in thickness, and occurs in many mammalian species.¹⁵⁶

In previous numerical studies^{41,86,87} of vortex dynamics in parallelepipedal slabs of ventricular muscle with various wall thicknesses and fiber rotation rates, it was found that rotational anisotropy can have a destabilizing effect on scroll waves in the high excitability limit. One of the effects of fiber rotation on scroll waves is the induction of a phase delay on the waves across the layers forming the thickness of the tissue. Figure 34 shows an example of this delay for a

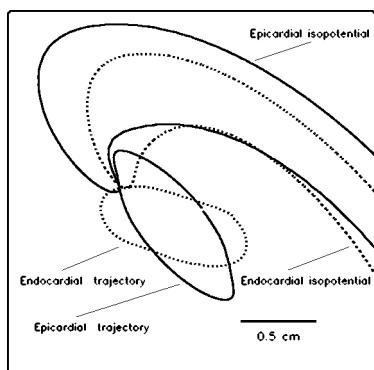


FIG. 34. Different timing of turns in 3D tissue with rotational anisotropy. Elliptical trajectories (produced by anisotropy) of a scroll wave are shown for the top (solid line) and bottom (dashed line) of a slab with 26° in fiber rotation. While the spiral on the epicardium (solid line) has passed the pivot turn already, the spiral on the endocardium (dashed line) has not yet started its pivot turn. As a result, the vortex has developed a twist in its phase intramurally (as shown in Fig. 35). Parameter set 1 is used with $\tau_d = 0.416$, using an anisotropy ratio of 5:1.

scroll wave in the circular core regime in a slab 0.22 cm thick and with a total of 26° in fiber rotation. Superimposed are the trajectories of the scroll wave produced at the simulated top (epicardium) and bottom (endocardium) portions of the slab during one period of rotation. The anisotropy (which is modeled by a conductivity tensor where propagation is about three times faster along the fibers axes than across and transmurally, see Ref. 41 for further details) transforms the circular trajectories into ellipses, which are not perfect because of diffusion in the z -direction. A voltage contour (at 85% of repolarization) of the scroll wave (spiral wave) at each surface is also plotted at one instant in time. Figure 34 shows that while the spiral wave on the epicardium has already completed the pivot turn on the curved section of the distorted elliptical trajectory, the spiral on the endocardium is just starting its pivot turn. Each time there is a pivot turn in the scroll trajectory (twice per period for a circular core that has been elongated), this phase lag induces a twist in the vortex line that is not uniformly distributed along its length, as in the case of sproing,^{78,181} but rather is highly localized.^{41,86,87} The magnitude of the localized twist grows as the fiber rotation rate is increased, and the twist can produce elongation of the vortex filament as it travels along it.^{41,86,87}

For scroll waves in the high excitability limit, where spiral waves tend to follow hypermeandering or linear core trajectories with high angle pivot turns, twist can produce large enough elongations to cause the filament to collide with boundaries and to produce new vortices. Figure 35 illustrates this process, with twist represented by plotting the normal vectors ($\mathbf{N} = \nabla V / |\nabla V|$, shown in blue) of the spiral wave tip equally spaced along the vortex line.⁴¹ In the first panel the normal vectors at the top of the vortex are pointing to the right while those at the bottom are pointing to the left, indicating that the spiral at the top surface has already rotated around the pivot turn while the one at the bottom has not (as shown in Fig. 34). The change in orientation occurs in the tissue between the top and bottom layers, where a highly

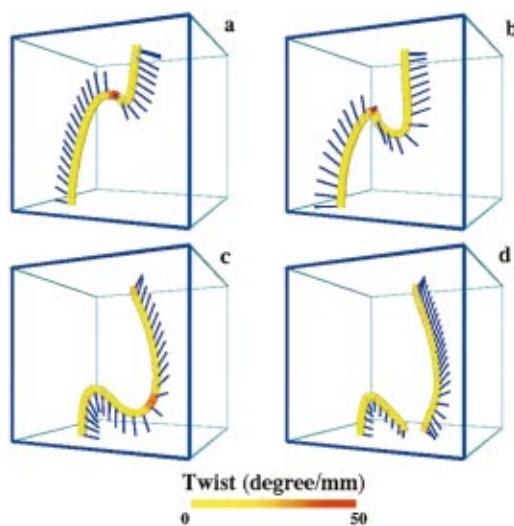


FIG. 35. (Color) Intramural twist and vortex elongation. Four snapshots of a transmural vortex using the 3V-SIM fitted to the MBR model (parameter set 1) in a slab 0.75 cm thick, using an anisotropy ratio of 5:1 with a fiber rotation rate of $12^\circ/\text{mm}$ (Ref. 41). The normal vectors shown in blue illustrate the direction of the spiral wave tips along the vortex and indicate an intramural highly localized twist (shown in red) produced by a phase difference (see the text and Fig. 34). As the twist propagated through the vortex line (at about 20 cm/s), it elongated and collided with a boundary, splitting the original filament into two segments, one that remained transmural and one corresponding to a half vortex ring. Spatial and temporal resolutions were $\Delta x = \Delta y = 0.025$ cm, $\Delta z = 0.0125$ cm, and $\Delta t = 0.2$ ms.

localized transition denoted by a large degree of twist develops. This twisted section of the filament travels transmurally along the filament as the lagging phase of the scroll wave finishes the pivot turn (b)–(c), resulting in elongation and curving of the filament that cause it to collide with a boundary and generate a new vortex (d). Although the breakup mechanism is different from the negative tension mechanism, the observed vortex elongation and collisions with boundaries are similar. This twist-induced destabilization of vortex filaments occurs above a critical thickness that depends on the tissue fiber rotation rate. In Refs. 41 and 86, the relation between fiber rotation rate, thickness, pivot turn angle of spiral wave tip trajectory, and breakup was discussed in great detail. It was shown that while fiber rotation induces twist, the total amount of twist accumulated ultimately is determined by the trajectory of the spiral wave tip. For a given rotation rate, the sharper the pivot turn in the tip trajectory, the larger the twist induced by the lagging phase. Therefore, models that are in parameter regimes where their spiral waves show pronounced “petals,” in which the trajectory makes a loop and crosses its own path as in the MBR model (which exhibits short petal distance ~ 2 – 3 mm, with a high total angle of rotation $\sim 180^\circ$),⁸⁶ require a lower fiber rotation rate to induce breakup in 3D compared to models with faster sodium kinetics like the LR-I model (with the speed of calcium dynamics increased by a factor of three to produce stable spirals), whose trajectories also have sharp turns but have smaller pivot angles.^{87,130} Compare, for example, the trajectories in panels (e) and (f) of Fig. 1, which are similar to the MBR and LR-I models with faster calcium dynamics,^{87,130} respectively.

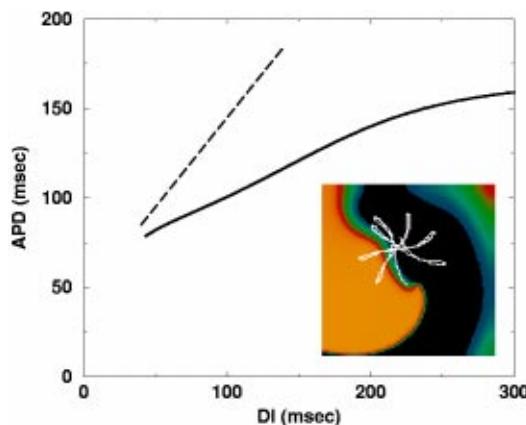


FIG. 36. (Color online) APD restitution curve with slope less than one obtained using parameter set 10. The dotted line has slope one. The inset shows a stable 2D spiral wave and its tip trajectory using the same parameter values. Tissue size is 4.3×4.3 cm with $\Delta x = 0.0214$ cm and $\Delta t = 0.115$ ms.

To emphasize that twist-induced breakup in tissue with fiber rotation is a function of the fiber rotation rate and the spiral wave trajectory,^{41,86,87,130} and not of the rotation rate and the slope of the APD restitution curve, as argued in Ref. 74, we illustrate this mechanism using parameter set 10, which produces spiral waves with linear core and has an APD restitution curve with slope less than one (see Fig. 36). Figure 37 shows breakup of an otherwise stable 2D spiral wave (see Fig. 36, inset) in a 3D slab (4.3×4.3 cm and 0.645 cm thick) with 180° of total fiber rotation ($28^\circ/\text{mm}$ rotation rate). The simulation was performed using $\Delta x = \Delta y = 0.0214$ cm, $\Delta z = 0.0107$ cm, and $\Delta t = 0.115$ ms, and the results were verified by using $\Delta z = 0.00535$ cm to ensure that breakup was not due to inadequate resolution of the fiber rotation. Because the pivot turn is not as pronounced as in the MBR model, a higher fiber rotation rate is needed for breakup compared to the MBR model.^{41,130} A straight scroll wave is used as an initial condition (a). As the scroll wave rotates and evolves, the filament buckles as it elongates due to the traveling twiston^{41,86} (b)–(f), forming a target pattern at the lower surface as the bent part of the filament approaches until it breaks into two vortices, one transmural and one half ring, when it touches the lower boundary (g). Half rings can expand further and break as they touch other boundaries (h)–(j). As time progresses the activity becomes increasingly irregular as more vortices are created and annihilated either by elongations or by conduction blocks (k)–(r). Note the creation of a single intramural scroll ring (m)–(n), which in an isotropic medium would collapse and disappear, but which here elongates and breaks at the boundaries due to the anisotropy, producing more vortices that sustain the fibrillatory-like behavior. Because the minimum APD produced in this model is larger than that of the MBR model, the density of scroll waves is smaller than in the MBR¹³⁰ and MBR-like simulations.⁴¹

C. Mechanism 10: Decreased cell coupling and discrete effects

While so far we have considered cardiac tissue as a continuous medium, experimental evidence accumulating since

the 1980s has suggested that the discrete nature of the cells and the anisotropic distribution of intracellular connections^{182,183} can lead, in some cases, to discontinuous effects in propagating waves. In particular, it has been shown that cellular discreteness can affect the excitability and safety factor for propagation that can lead to reentry without the presence of spatial differences in refractory periods.^{52,184,185} These types of discrete effects become stronger as tissue becomes ischemic^{186,187} or when cell density is nonuniform.¹⁸⁸ For instance, cultured monolayers of chick embryo cells as well as cellular automata studies have shown that spiral wave breakup can occur when cell coupling is decreased.¹⁸⁸

Panfilov and Keener^{40,189} made the first studies of scroll waves in parallelepipedal slabs with rotational anisotropy where low coupling was considered. Using a piecewise linear FHN-model, they observed that rotational anisotropy could destabilize scroll waves and produce breakup.⁴⁰ The scroll wave instability resulted from the discrete anisotropic refractoriness, which can produce patchy propagation failure at low coupling strengths (or, equivalently, coarse spatial resolutions).^{190–193} In 3D tissue, the introduction of fiber rotation can allow patchy propagation failure to develop at slightly higher coupling strengths. Like the twist instability, breakup occurs as a function of tissue thickness for a given fiber rotational rate and cell coupling strength,⁴⁰ but otherwise the two mechanisms are quite different. In this case, propagation failure due to discrete effects occurs preferentially in the transverse and transmural directions and is amplified by the rotational anisotropy.

To show this effect, we use the same parameters as for the twist mechanism (set 10) in a slab of similar thickness as that shown in Fig. 37, but with a much smaller rotation rate in which breakup due to twist does not occur. In this case the slab size is 1.7×1.7 cm and 0.77 cm thick, with a total of 100° of fiber rotation. Therefore, the fiber rotation rate is $13^\circ/\text{mm}$, which is less than half of that used in the twist breakup example, and the spatial coupling used ($0.00062 \text{ cm}^2/\text{s}$) is much smaller than in the twist example ($0.001 \text{ cm}^2/\text{s}$). The spatial resolution used to demonstrate both mechanisms is the same, 0.0214 cm (although in this case we use $\Delta x = \Delta y = z$ since the rotation rate is smaller). Figure 38 shows five equally spaced layers of the slab as a column at one instant in time, with the top voltage contour plot corresponding to the epicardium. The first column (a) shows the initial intramural scroll wave. As the scroll wave evolves, propagation failure begins to occur (b)–(d), eventually leading to multiple waves (e)–(h). Because this breakup is due to low coupling, the breakup disappears at larger coupling values (e.g., larger than twice the value used here), leaving a stable scroll wave,⁴⁰ since twist-induced breakup for this thickness and rotation rate (almost the same thickness and half the rotation rate as in Fig. 37) does not occur for this parameter set. We note that unlike mechanism 9, no specific tip trajectory is necessary for breakup to occur.

The same effect can be achieved by using a coarser spatial resolution, as in Ref. 40, rather than by decreasing the coupling, since what is important is a reduction in the ratio $D/\Delta x^2$. The spatial resolutions used in Ref. 40 for the FHN model breakup were 0.09 and 0.125 cm. In our case an

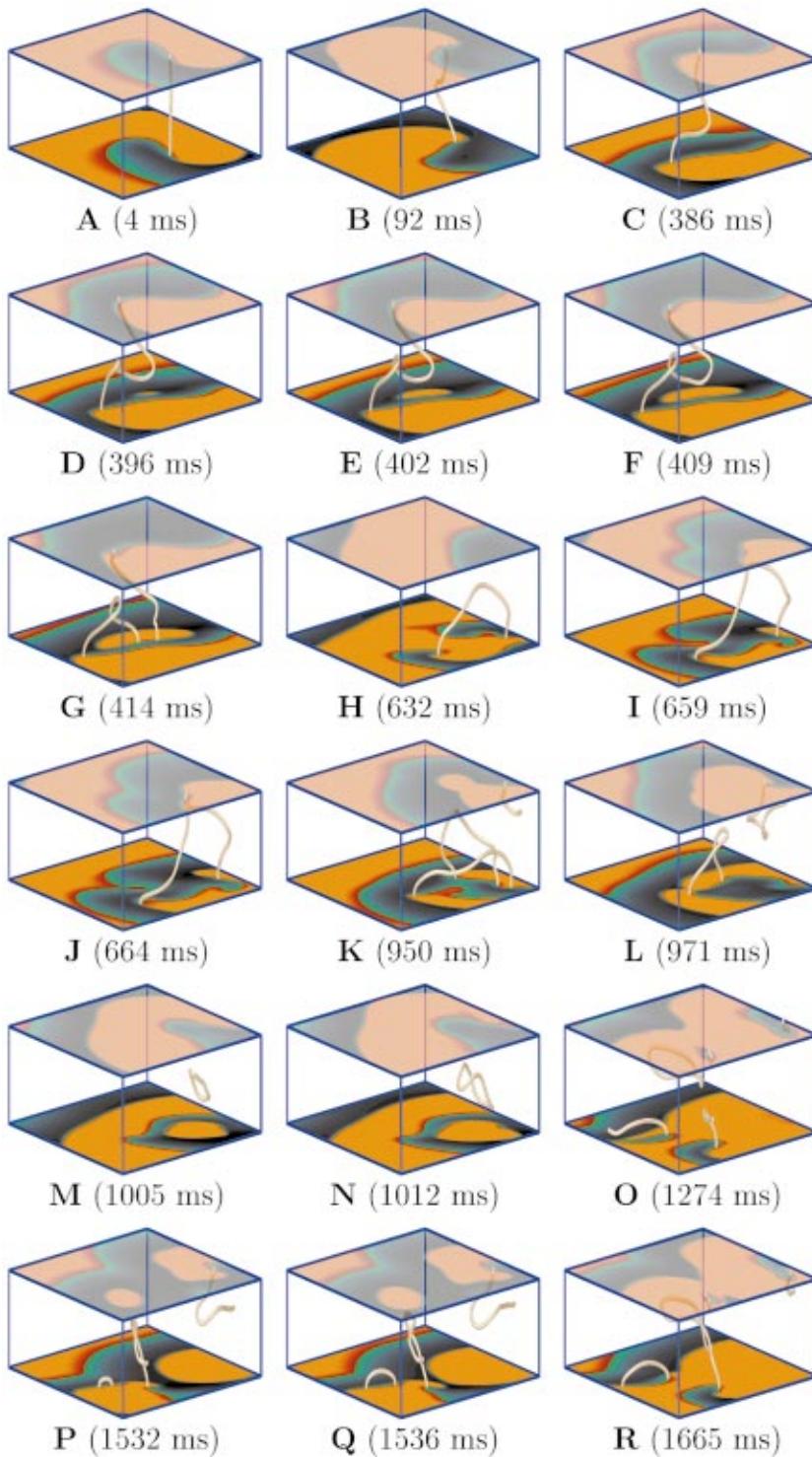


FIG. 37. (Color) Breakup and complex dynamics due to filament twist using parameter set 10 in a 3D slab of tissue with 180° of total fiber rotation and using an anisotropy ratio of 5:1. Tissue size was $4.3 \times 4.3 \times 0.645$ cm with $\Delta x = \Delta y = 0.0214$ cm, $\Delta z = 0.0107$ cm, and $\Delta t = 0.115$ ms. An initially straight filament (a) rotated and evolved, accumulating twist and elongating (b)–(d). A target pattern appeared at the lower surface as the bent part of the filament approached it (e)–(f) until the filament touched the lower boundary and broke into a transmural filament and one half ring (g). Later, a half ring expanded and became two transmural filaments upon touching the boundary (h)–(j). Elongations and conduction blocks continued to occur (k)–(r), sustaining the fibrillation-like dynamics. Using the same parameter values in 2D produced a stable spiral wave (see Fig. 36, inset). To facilitate visualization, the vertical dimension has been stretched by a factor of 2.

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equivalent rescaling corresponds to 0.086 cm and produces the same results (note that this rescaling involves decreasing the number of grid points used to represent the voltage). It is important to mention that when including discrete effects, either by discretizing directly the cardiac cells as in Ref. 185 or by using a coarse spatial resolution, caution is required when choosing the protocols and model parameters, since numerical artifacts leading to unrealistic results sometimes can be induced. As an example, Fig. 39 shows how coarse discretization can lead to incorrect spiral trajectories due to lattice pinning. The spiral wave from the coarse simulation

(a) pins to the computational grid, producing an almost rectangular trajectory instead of the correct circular one (b) and yielding a much longer period of rotation.

VII. DISCUSSION

A. The role of APD and CV restitution curves

Although the shape of restitution curves cannot solely predict spiral tip trajectories [e.g., circular cores can be obtained for both flat and steep APD restitution curves, as in Fig. 1(a) and Fig. 12, respectively], they are useful to explain

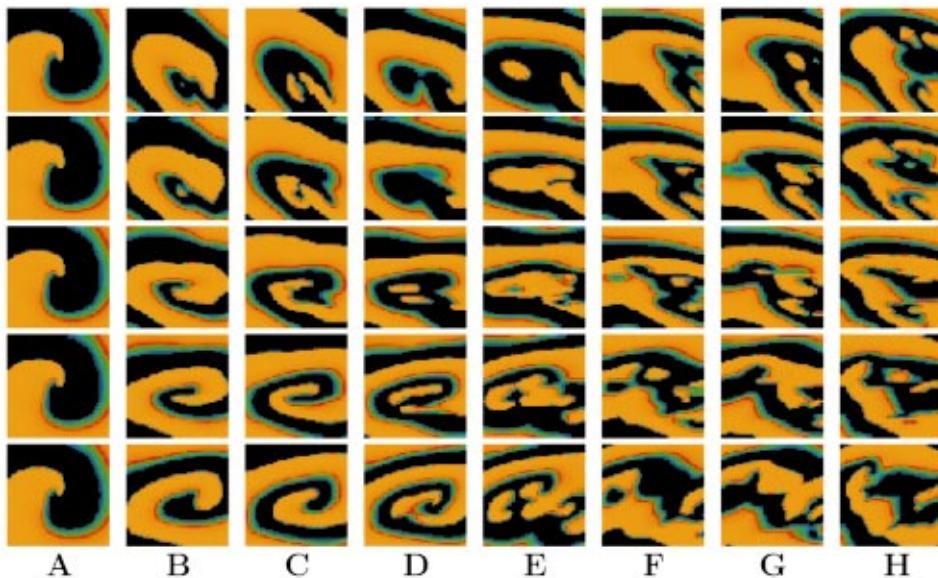


FIG. 38. (Color) Breakup in 3D due to discrete effects and low coupling with rotational anisotropy, using parameter set 10, in a 3D slab of tissue ($1.7 \times 1.7 \times 0.77$ cm) with 100° of total fiber rotation and using an anisotropy ratio of 5:1, $\Delta x = 0.0214$ cm, and $\Delta t = 0.115$ ms. Voltage plots of the top and bottom surfaces, along with three evenly spaced interior surfaces, are shown at eight different times (after 0, 679, 736, 955, 1231, 1541, 1576, and 1771 ms). The initially straight scroll wave became distorted due to the rotational anisotropy and the low coupling induced breakup. Note that breakup does not occur when the same simulation is performed using larger coupling values.

and to determine some regimes in which certain conduction blocks can develop and produce spiral wave breakup. Throughout Sec. IV six different mechanisms for breakup in 2D were described depending to some extent on their APD and CV restitutions.

1. Steep APD restitution curves

The first two mechanisms originate when the APD restitution curve has a slope greater than one over some range of DIs, which can produce APD alternans and conduction blocks at high frequencies. While in principle both mechanisms can be considered as one, we make a distinction based on two factors: the steepness of the APD restitution curve and the frequency of the source. If the APD restitution curve is abruptly steep (i.e., has a narrow range of DIs over which the restitution is much greater than one), then the region for possible periods with oscillating APDs that result in stable alternans rather than conduction block is narrow. Therefore, spiral waves will break close to the tip as they form, since

conduction blocks will be present whenever a DI falls out of the stable alternans region, as shown in Figs. 4 and 7. We refer to this breakup as mechanism 1 or breakup by an abruptly steep APD restitution.

If instead the APD restitution curve is steep but not abruptly steep (i.e., has slope greater than one for a relatively large range of DIs), then the region for stable alternans is wider and there is a greater chance for a spiral wave to form without generating conduction blocks. Nevertheless, under these conditions, the conduction velocity restitution can affect the behavior of the spiral wave and produce breakup. It has been shown that when tissue is periodically stimulated at a frequency in the alternans region, variations in velocity due to CV restitution can induce discordant alternans^{50,105} along the tissue, which in turn can lead to conduction blocks.^{97,108} The distribution of nodes that separates the discordant alternans regions becomes a function of the CV restitution.⁵⁰ In particular, nodes occur closer to the stimulus site and pack together more densely as the CV restitution changes over a wide range, as shown in panels (e) and (f) of Fig. 10. Therefore, for a spiral wave whose period is in the alternans region, the CV restitution curve will dictate if discordant alternans and block can form in a specific tissue size.^{50,97} In Fig. 11 we show how, for a given frequency, conduction block depends on the distance from the source. This means that the stability of a spiral wave whose frequency is in the alternans region is a function of size,³⁵ so that a spiral wave that is stable in a square domain of length L may not necessarily be stable in a domain of length r^*L ($r > 1$), as illustrated in Fig. 12. Unlike mechanism 1, which occurs rather quickly and close to the tip, the breakup due to discordant alternans develops over time, requiring many beats to form and with the distance of the breakup region from the tip depending on the period. Therefore, we distinguish it as a separate mechanism.

It is important to note that even when the APD restitution curve is abruptly steep, breakup by discordant alternans still can be produced (by pacing periodically at a constant frequency in the region of alternans). However, since the range of periods for stable alternans is very narrow (for ex-

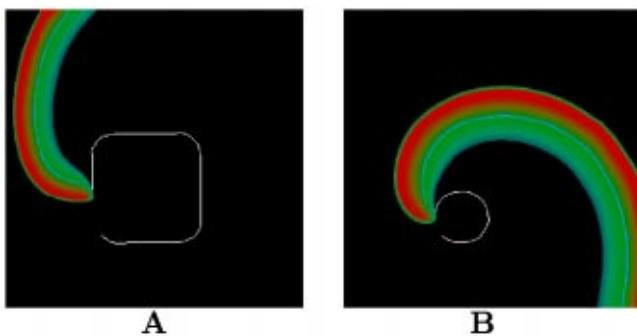


FIG. 39. (Color online) Lattice pinning resulting from coarse discretization in the low excitability regime. (a) Spiral wave trajectory pinning to the lattice. (b) Spiral wave trajectory obtained by decreasing the spatial resolution by 10%. The pinning occurs because the curvature at the spiral tip is close to the critical radius of curvature, so that only those adjacent cells on one side of the tip become excited [causing the straight line motion seen in (a)] until the spiral rotation rotates enough for the tip to turn. As a result, the trajectory is very different and the period is completely wrong.

ample, 30 ms using parameter set 3 compared to 85 ms for set 4), spiral waves with abruptly steep APD restitutions are more likely to break up by mechanism 1 than by mechanism 2. One possible exception to this hypothesis could occur if a spiral were able to pin to an inhomogeneity of a size such that the period lay precisely in the alternans region. Similarly, breakup by mechanism 1 can occur in models with steep (but not abruptly steep) APD restitution curves whenever a large change in cycle length occurs.

2. Non-steep APD restitution curves

Without diminishing the significance of steep APD restitution curves as a breakup mechanism, especially since their relevance has been shown in a number of experiments,^{51,194,195} it is important to recognize that there are a number of other mechanisms that also can cause spiral wave breakup. In fact, one of the most widely used ionic models for cardiac simulations, the Luo–Rudy–I,¹⁰³ breaks up with calcium dynamics speeded up by a factor of between 2 and 2.8, despite its flat APD restitution. The LR–I model has a much faster (and more realistic) sodium conductance than its predecessor, the BR model,⁹² resulting in a smaller DI_{min} (25 vs 46 ms) and a relatively high APD_{min} , producing a fairly flat APD restitution. Even when the calcium is speeded up by two (to decrease the maximum APD from about 360 ms to a more physiological value of about 230 ms), the restitution curve is flat, with slope less than one (Fig. 40). Because of its high excitability, small refractory period, and large wavelength, the model follows linear core trajectories with sharp turns that can block wave propagation due to the Doppler shift in the frequency, as shown in Fig. 21 in the discussion of mechanism 4.

Other possibilities for spiral wave breakup in two dimensions that do not require steep APD restitutions are the cases of nonmonotonically decreasing restitution curves, such as in the cases of biphasic APD (mechanism 5) and supernormal CV (mechanism 6) restitution curves. With a biphasic APD restitution curve, even when the magnitude of the slope never exceeds one, the prolongation of APD as the DI is decreased (over a certain range of DIs) can block subsequent waves, thereby causing breakup. Similarly, a supernormal CV restitution curve causes waves at short DIs to move more quickly than waves at long DIs. In this way, waves can stack and even block by collisions as spirals turn. Other mechanisms that do not require a steep or otherwise specifically shaped APD or CV restitution curves to produce breakup are discussed below. Mechanisms not involving steep APD restitution may be relevant in the study of atrial fibrillation, where extensive experimental evidence has shown that the rate adaptation of atrial tissue diminishes or is eliminated after prolonged periods of fibrillation.^{196,197}

3. Quantifying restitution

While details of restitution curves such as shape, steepness, and the DI_{min} can be important in determining spiral wave stability and are a principal tool in classifying the vari-

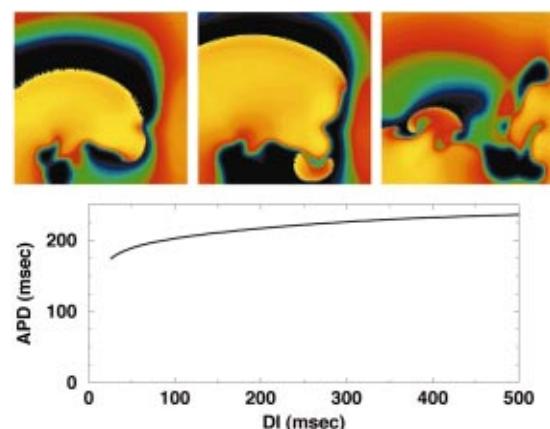


FIG. 40. (Color) Breakup in the LR–I model with calcium speeded up by a factor of 2. The first two panels show the initial breakup as the spiral wave turns, blocks, and breaks. The third panel shows the voltage profile after a few more wave breaks have occurred. Because of the large wavelength and the linear core, the breakup was transient, and eventually all waves left the area. The lower panel shows the APD restitution curve for the LR–I model with calcium speeded up by a factor of 2, which has slope less than one everywhere. Similar breakup is also obtained when the calcium dynamics are up to 2.8 times faster than with the original parameters (Ref. 130). Tissue size is 4×4 cm with $\Delta x = 0.02$ cm, and $\Delta t = 0.025$ ms.

ous breakup mechanisms of this paper, we should mention two important issues regarding their measurements, particularly in experiments.

First, APD restitution can be measured either in isolated cells or in intact tissue. Although both are similar since they represent the same system, differences can arise due to cell coupling. For example, the maximum APD measured in an isolated cell and in a cell in a tissue preparation can vary substantially due to electrotonic effects, especially as a function of excitability. This effect has been seen in experiments, where the APD in isolated myocytes has been estimated to be 10%–15% longer than in tissue,¹⁹⁸ and can be observed readily in numerical simulations. In the same manner, the value of the minimum diastolic interval measured in an isolated cell depends on the strength and duration of the stimulus and is much shorter than the minimum diastolic interval for propagation obtained in tissue. Therefore, the shapes obtained from tissue and isolated cells may differ in the sense that for isolated cells, the APD_{max} may be higher and the DI_{min} smaller, allowing more variation in slope. As a result, in some extreme cases alternans can be seen in isolated cells but not in tissue. Since arrhythmias form in tissue rather than in single cells and electrotonic effects certainly are present, we believe that the restitution obtained in tissue is the relevant curve for this analysis.

Second, the restitution relations in real cardiac tissue do not depend only on the previous diastolic interval, but in fact there is *memory* of previous activations.¹⁹⁹ That is, there is an adaptation of APD to variations in cycle lengths which is believed to be due, among other things, to changes in electrochemical gradients and permeability arising from differences in accumulation of intracellular sodium and calcium and extracellular potassium as well as the nonequilibrium values of the ionic currents at different rates of stimulation.^{55,133,200,201}

Because of memory, there are different protocols commonly used to measure APD restitutions, and indeed one difficulty in using APD restitution curves as a predictor of spiral wave instability is determining an effective and useful measurement protocol. The so-called *steady-state restitution* curve is obtained by pacing the cardiac preparation at a fixed cycle length for a large number of beats (until the preparation reaches a steady state), after which the last DI and APD are recorded at that cycle length to provide a point on the APD restitution curve. Repeating the same protocol for various cycle lengths and measuring one point for each cycle length constructs the full curve. Another protocol measures the *S1–S2 restitution at a given cycle length*. Here, a train of more than 20 stimuli at a fixed cycle length (S1) is used to set the tissue memory to that particular cycle length. Once a steady state is reached, a single premature stimulus (S2) is applied. The APD of the premature stimulus and the preceding DI provide a point on the restitution curve. Repeating the S1 train *at the same cycle length* and varying the time of the premature stimulus S2 provides a full restitution curve. A variant of the S1–S2 protocol uses a third stimulus S3^{136,199} (or more) designed to reach shorter DIs and APDs than are accessible only by using successively closer stimuli. While the steady state protocol yields one APD curve, the S1–S2 produces an entire family of restitution curves since different S1 cycle lengths yield different restitution curves,^{55,202} all of which have various slopes and shapes, bringing into question which restitution is the relevant one. Furthermore, the steady-state and S1–S2 protocols are limited in that they can be used only in quiescent tissue and not during an arrhythmic episode, which also calls into question the relevance of these restitution curves to fibrillation initiation. During an arrhythmia, the only option for measuring restitution is the so-called *dynamic protocol*,^{194,203} in which voltage traces from many sites are used to obtain DI, APD pairs, which are then plotted together. A similar approach can be taken in the absence of an arrhythmia by introducing stimuli at random intervals and measuring all DI, APD pairs.

While the steady state and S1–S2 restitutions produce relatively clean curves, the dynamic protocol typically yields a cloud of points rather than a clearly discernible restitution curve. The cloud is due in part to the fact that measuring DIs and APDs from an extended system during an arrhythmia can include loading effects from curved fronts as well as double potentials with short APDs resulting from recordings close to the core of reentrant waves.^{16,75}

Currently it is believed that the dynamic restitution is the most useful predictor of spiral wave behavior, since it is measured under the conditions of arrhythmia. One possible method of extracting useful information from the cloud of points obtained is to plot the restitution curve using a density plot. If the DIs and APDs are binned, the restitution curve can take on a third dimension by plotting the number of points falling into the given DI, APD bin as a height. In this way, although outlying points remain in the plot, preference is given to the DI, APD pairs that appear most often, and a structure can emerge as points measured close to reentrant waves and due to loading effects are reduced to the background.

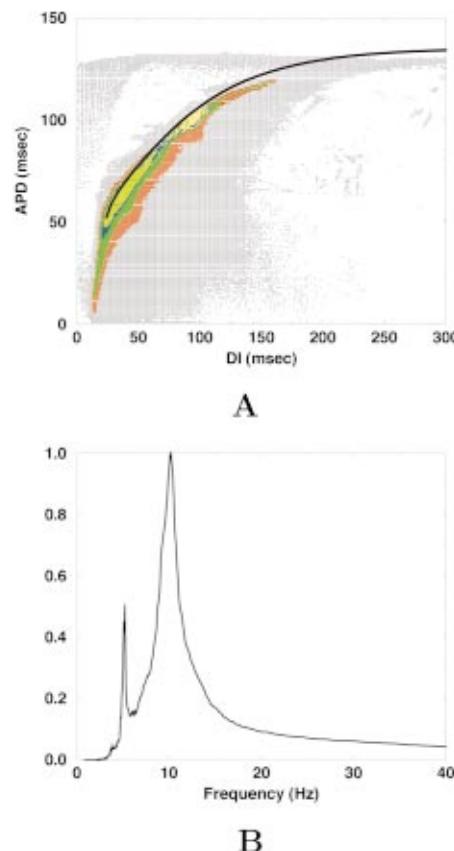


FIG. 41. (Color) (a) Density plot of restitution. DI, APD pairs are gathered from all sites over a 5 s simulation and grouped into 0.5-ms-wide bins. A point is plotted for each DI, APD pair whose bin was visited at least twice during the simulation, representing 92% of the total data collected. The points appearing as a diffuse black “dust” were visited up to 500 times and represent 17% of the data. Bins visited more often were color-coded: up to 1000 visits, red; up to 2000 visits, green; up to 2500 visits, blue; more than 2500 visits, yellow. Those DI, APD pairs visited most often cluster closely around the model’s APD restitution curve, shown in black. (b) Power spectrum of frequencies obtained during the same simulation. The two yellow regions in the density plot, with cycle lengths near 100 and 200 ms, correspond to the peaks in the spectrum of 10 and 5 Hz, respectively.

Figure 41(a) shows a density plot example obtained from 5 s of simulated fibrillation (using parameter set 6, mechanism 4, shown in Fig. 19). The data were collected from all sites throughout the full 5 s and produced a highly scattered distribution. To construct the density plot, the DIs and APDs were rounded to the nearest 0.5 ms, thereby creating DI and APD bins. The number of DI, APD pairs obtained for each bin value were counted and plotted for that DI and APD with a color to represent the frequency of occurrence for that DI, APD pair. Those bins visited between 2 and 500 times are shown as the black “dust” and include 17% of the total data. (Those bins visited only once, constituting 8% of the total data, are not shown.) Bins visited a larger number of times are color-coded as follows: 501–1000 times, red, containing 12% of the data; 1001–2000 times, green, with 6% of the data; 2001–2500 times, blue, with 6% of the data; and greater than 2500 times (up to a maximum of more than 38 000), yellow, consisting of 51% of the data. The values shown in the figure take on an increasingly discernible structure as less-visited DI, APD pairs are excluded. For compari-

son, the model's APD restitution curve obtained from plane waves is shown in black, and it can be seen that the density plot clusters around this curve more and more tightly at those DI, APD pairs visited most frequently. In particular, the small APDs produced by curved fronts and wave tips are eliminated, and the minimum APD and DI of the denser clusters match those of the restitution curve. While this example uses data from a simulation, rather than experimental data, we believe a similar approach may be useful in clearing up cloud-like dynamic restitution curves obtained experimentally.

Figure 41(b) shows the normalized power spectrum corresponding to the data in (a), which resembles those observed experimentally.^{17,204} A dominant frequency of about 10 Hz is present (even in the absence of a dominant spiral wave), along with a secondary peak at half the value of the first (corresponding to the frequency of the 2:1 block region). These regions are visited preferentially in the restitution density plot, as can be seen by the clustering of DI, APD pairs visited most often (colored yellow) around the cycle lengths corresponding to the two frequency peaks (10 Hz and 100 ms, 5 Hz and 200 ms). Despite the width of the large peak and the presence of a wide range of other frequencies in smaller amounts, use of the density plot allows a restitution curve structure to emerge. We anticipate that a similar procedure should help to clarify a useful restitution curve from experimental data.

The CV restitution curve²⁰⁵ has not been studied as broadly as its APD counterpart, mostly because its measurement becomes complicated since fiber orientation and three-dimensional effects distort propagating fronts. Therefore, it is still largely unknown how CV restitution depends on previous activations. Although it has been shown²⁰⁶ that maximum longitudinal and transverse CVs are not significantly affected by basic cycle length in normal tissue, it is unknown whether the shape of the curve may change. Furthermore, during ischemia cellular coupling and thus upstroke velocity change with cycle length,^{187,207} so that at least the maximum conduction velocity becomes a function of cycle length, and memory effects on CV may become important.

B. The role of initial conditions

Initial conditions, in many cases, are also important determinants of spiral wave stability. A striking example of this is shown in the case of steep APD restitution curves that have a second region with slope less than one at short DIs, such as the 1962 Noble model¹⁰¹ and the Fox *et al.*¹¹⁷ models. When such regions exist, periodic pacing at short or long cycle lengths where the slope is less than one results in stable waves (for small domains), while in between there is a region of cycle lengths where the slope is greater than one, and thus alternans develops and conduction block may occur. Therefore, spiral waves with long periods falling in the region of slope less than one with long DIs are stable, while spirals with short periods falling in the other region of slope less than one can be either stable or unstable depending on initial conditions and tissue size, as shown in panels (a) and (b) of Fig. 15. Where panel (a) shows a complex spatiotem-

poral pattern due to continuous wave breaks, panel (b) shows a stable spiral wave. In both cases, all parameters were the same, and the only difference was the initial conditions.

While the previous example illustrates the effect of initial conditions on the onset of breakup, it requires specific initial conditions; however, other mechanisms require only a simple spatial gradient in DIs to produce conduction blocks. An example is the rate-dependent bistability and hysteresis of APD (mechanism 3), in which the passing of a previous wave can lead to a gradient of recovery, causing parts of the tissue to be on the 1:1 branch while others are on the 2:1 branch and resulting in a wave break, as shown in Fig. 17.

Discordant alternans-induced breakup (mechanism 2) also can depend on initial conditions, again to a lesser extent than in the first example. When a spiral wave is initiated in uniform tissue, the breakup typically takes many beats to occur, as the oscillations due to conduction velocity restitution grow slowly before developing conduction block. However, discordant alternans can be generated immediately following a gradient of recovery;⁵⁰ therefore, if the spiral wave is initiated in tissue with an existing gradient of refractoriness, the oscillations can grow faster and breakup can occur rather quickly.

The biphasic APD restitution curve (mechanism 5) also is sensitive to initial conditions, as seen in the cobweb diagram of Fig. 23. Because of the presence of a region with negative slope in the middle of an otherwise positively sloped curve, different initial conditions for the same period can produce both stable and unstable solutions for a given frequency. Another example is negative tension (mechanism 8), discussed in the following section, in which the difference in obtaining a stable scroll wave or turbulence depends on initial conditions. While a straight scroll wave will be stable, any small deviation from that will result in breakup.

C. The role of thickness (2D vs 3D)

Even though restitution relations and initial conditions are very important in explaining 2D conduction blocks, structural effects manifested in 3D can have relevant consequences in the destabilization of three-dimensional reentrant waves (scroll waves) and their vortex filaments as well. In Sec. VI three different mechanisms for spiral wave breakup in 3D are discussed. The first, negative tension (mechanism 8), develops as the excitability of the medium is decreased, which can occur physiologically when cardiac tissue is deprived of oxygen and becomes ischemic. In such cases any small perturbation applied to the vortex filament of a scroll wave grows. Vortices can then, after many rotations, elongate, curve and twist intramurally, until they collide with a boundary and break, producing a new vortex and scroll wave. This process can repeat itself, leading to multiple scroll waves and turbulence. Similarly, in twist-induced breakup (mechanism 9), vortices elongate and break at boundaries. However, unlike negative tension, this mechanism occurs in the high excitability limit, physiologically corresponding to healthy tissue, and the breakup requires many fewer rotations. It is important to note that while mechanism 8 can arise in completely homogenous tissue,

mechanism 9 is a consequence of the natural anisotropic fiber rotation found in cardiac tissue. Mechanism 10 is enhanced by,⁴⁰ but does not require,^{190–193} fiber rotation. Breakup due to this mechanism depends on low coupling and discrete cell effects, which grow more pronounced as the tissue becomes ischemic.

We note that while ischemia is a complicated condition that induces numerous physiological alterations in cardiac tissue, some of its most important effects are reductions in excitability and cell coupling. The reduced excitability may possibly shift the dynamical state of the tissue into the negative tension regime, thereby activating that breakup mechanism. In addition, the poor cell coupling may induce wave breakup as in mechanism 10. The twist instability mechanism, on the other hand, becomes less important in this parameter regime.

Although mechanism 10 in principle can occur in 2D tissue but is amplified in 3D by anisotropic fiber rotation, mechanisms 8 and 9 are purely three-dimensional and they need a minimum thickness to develop. Vortex lines are constrained to be locally normal to any boundary at which they attach (sealed boundaries that conserve current), and in very thin layers this requirement can prevent elongation in both mechanisms. Mechanism 9, in addition, has a thickness limit as a function of fiber rotation rate,^{41,130} below which the twist induced is not enough to elongate vortex filaments substantially.

It is important to note that whereas in 2D conduction blocks are a requirement for breakup, in 3D they are not necessary even when they occur, since breakup can be produced purely by topological changes in the vortex filaments, which have no counterpart in 2D. Once multiple vortices are created, the complex behavior and interactions between vortices can render the system more turbulent. For example, conduction blocks between waves can suddenly generate intramural vortex rings that can eventually contract and disappear [see Fig. 42(a)], or they can expand and even fuse with other existing vortices [see Fig. 42(b)] if they have the same phase. Conversely, in other cases, vortex rings can be generated not by conduction block but by elongation and vortex self-pinching, as shown in Fig. 42(c). Even knotted twisted rings have been shown to fuse under certain conditions.²⁰⁸ Although equations of motion have been derived for scroll waves in various regimes and under certain conditions,^{39,47,176,209,210} the dynamics of their interactions remain largely uncharacterized.

D. The role of spiral tip trajectories

As noted in Secs. IV–VI, the type of tip trajectory can be a crucial determinant of spiral wave stability for certain mechanisms. In mechanisms 1 and 2, any tip trajectory will produce breakup as long as the period of rotation lies in the region of slope less than one. On the other hand, mechanism 4 requires not only a relatively flat APD restitution curve and a small DI_{min} , but also a highly meandering or sharply turning tip trajectory, so that the waves emitted by the moving spiral tip will have a Doppler shift (as shown in Fig. 18) and

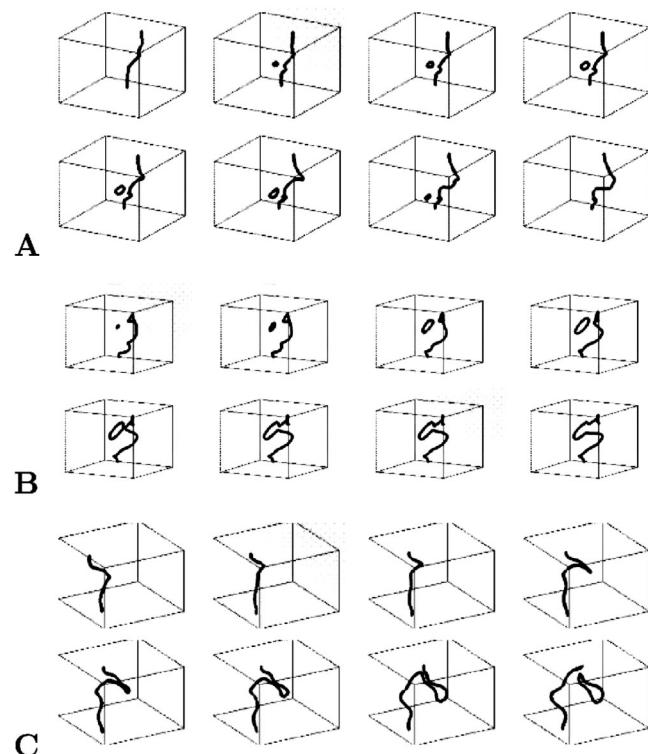


FIG. 42. Vortex interactions. (a) A vortex ring is created and collapses again without touching the transmural filament. (b) A vortex ring is created and fuses with an existing transmural filament because its phase matches the filament phase at the fusion site. (c) A vortex ring is pinched off from a transmural filament as it elongates. All parameters are set as in Fig. 35.

see shorter cycle lengths, resulting in conduction block (Figs. 19 and 20) whenever the shift lies below the period for propagation.

In the presence of periodic boundary conditions (mechanism 7), the type of spiral wave trajectory also is important. When the wavelength of a spiral is comparable to the length of the tissue with periodic boundaries, drift can be induced on the spiral wave by the interaction of self-generated incoming waves with the spiral tip, as illustrated in Fig. 29. Spiral wave drift along the ventricles, which can be produced by periodicity or by other means,²¹¹ has been shown to produce fibrillation-like signals in the ECG.^{8,212} Furthermore, breakup into multiple waves also can occur due to the periodic boundary effects as the movement of a hypermeandering spiral wave can cause complex gradients in repolarization, which can lead to conduction blocks as the spiral wave breaks, as shown in Fig. 30.

The type of tip trajectory is also important in the 3D breakup mechanism of filament twist instability (mechanism 9), where sharp pivot turns in the trajectory are required. The rotational anisotropy of the medium causes the turn to take place at slightly different times across layers, producing a phase lag. Each time the pivot turn occurs, twist builds up in the filament, which the filament tries to eliminate through elongation (rather than by diffusion, as in sproing^{78,181}). When the turn is sufficiently sharp, enough twist can accumulate to destabilize the filament, which elongates so much that it eventually collides with the boundaries and breaks in

two. This instability decreases and has little effect for tip trajectories with mild pivot turns and circular cores even at high degrees of rotational anisotropy.^{41,86,130}

It is important to note that the tip trajectory can have an important role in determining the sustainability of breakup. Sustained breakup is more likely to occur whenever the tip follows small cores (compared to the tissue size), such as in the Karma model,⁹⁵ the Bär model,^{36,116} the Noble model,^{87,91} some versions of the FHN model,¹² and a number of models of the BZ reaction. In contrast, breakup is more likely to be transient when the tip trajectory is large, such as in the meandering and hypermeandering regimes, as shown using the BR model^{34,89} and the LR-I model.⁸⁷ As the tissue size is increased relative to the tip trajectory, the duration of transient breakup also tends to increase.¹⁰⁰

E. Limitations

A number of limitations of the present study should be mentioned. First, this manuscript has presented a set of mechanisms that can occur in homogeneous tissue, while in reality, cardiac muscle contains a variety of intrinsic inhomogeneities. Nevertheless, this survey can serve as a foundation and framework for the analysis of mechanisms that can occur with or without heterogeneities. Many of the mechanisms operative in homogeneous tissue should continue to occur in heterogeneous tissue, but some may be enhanced or suppressed, while other new mechanisms certainly occur due to specific heterogeneities. For example, differences in cell dynamics have been found between the left and right ventricles, which may be important in arrhythmia development.¹¹ Likewise, different cell types exist along the thickness of the ventricular wall (epicardial, M, and endocardial cells), whose dynamics at large pacing cycles can vary greatly^{213–215} and may destabilize waves under certain conditions.^{216–218} Furthermore, natural dispersion in APD throughout the tissue may facilitate the formation of conduction blocks²¹⁹ or allow the development of sponginess when the spiral period is shorter at one end of the vortex line, leading to breakup of scroll waves.^{78,181}

In addition, we do not describe effects of geometric structure that can contribute to arrhythmogenesis, such as curvature effects;¹⁴⁶ nonuniform fiber orientation producing drift;²¹¹ abrupt changes in fiber direction at sites like the papillary muscle insertions in the ventricles,²²⁰ which can provide anchoring sites for reentrant waves; and path structures for reentry, such as the pectinate muscles,^{76,221} the pulmonary veins,⁴² and the Purkinje system.²²² Furthermore, we have neglected noise²²³ and memory effects,^{199,201,224,225} mechanical contraction,²²⁶ triggered activity including early afterdepolarizations,²²⁷ randomly distributed heterogeneities,²²⁸ and localized heterogeneities such as scars^{229–231} and ischemic regions,²³² all of which have been shown to promote reentry and breakup. However, the analysis and effects of these and other types of native or illness-induced inhomogeneities on the breakup of scroll waves is beyond the scope of this paper.

VIII. CONCLUSIONS

This paper has shown and classified a number of different mechanisms for spiral wave breakup in 2D and 3D tissues on the basis of the conditions necessary for their occurrence in cardiac tissue. APD and CV restitution curves can produce various types of breakup due to their steepness or due to their specific shapes for certain periods, although other mechanisms exist even when APD and CV restitution curves are relatively flat. In some cases, initial conditions can play a crucial role in determining whether or not breakup will develop. The trajectory of the spiral wave tip also can be important for some breakup mechanisms to occur, as repolarization differences due to tip meander can lead to conduction block, and differences in pivot turns in 3D tissue with rotational anisotropy can destabilize transmural filaments. Finally, although spirals can break by a number of mechanisms in 2D, fully 3D tissue is needed for certain mechanisms to develop. All of the mechanisms discussed in this paper can operate in fully homogeneous and isotropic tissue, except for the 3D twist- and discreteness-induced mechanisms, which require rotational anisotropy.

Which breakup mechanism or mechanisms are responsible for the transition from tachycardia to fibrillation in the human heart is still unclear. Experimental evidence in various animal models can be interpreted to support several mechanisms, including steep APD restitution^{51,194,195,203} and tip trajectories,^{11,233} as well as one^{8–11} or many spirals.^{11–17} However, our intent here is to give a survey of possible arrhythmogenic mechanisms, any number of which may be present in a given patient or preparation. Numerous questions about how these mechanisms may operate deserve further study, including whether one or several mechanisms tend to underlie fibrillation, how fibrillation caused by various mechanisms may be differentiated, which mechanisms may be associated with other types of heart disease like ischemia and heart failure, and how to provide effective treatment to prevent fibrillation.

The last question in particular takes on more importance in light of the fact that multiple mechanisms may be capable of inducing fibrillation; therefore, pharmacotherapy studies designed to develop new drugs that target one breakup mechanism need to ensure that they do not activate, facilitate, or enhance other mechanisms that may exist. For example, flattening restitution can prevent mechanisms 1 and 2, but we can speculate that breakup may still persist or resume if by doing so a small refractory period and large wavelengths are produced, thus facilitating mechanism 4. Similarly, lowering the sodium conductance may suppress breakup by mechanisms 7 and 9 as the tip trajectory is changed, but could in principle enhance 8 and 10 if the sodium change is extreme. It appears that the best way to suppress all of the mechanisms discussed here is conversion of the tip trajectory to a large circular core, a conclusion similarly reached by Samie *et al.*^{233,234} and Efimov *et al.*⁶⁴ As mentioned in Sec. II, the tip trajectory can be made circular and increased in size by enlarging the excitability gap or by decreasing the sodium or calcium conductances. However, decreasing the sodium conductance, as suggested in Ref. 64,

may have arrhythmic effects due to mechanisms 8 and 10 if the excitability is too low. Therefore, reducing the calcium conductance, as in Ref. 233, may be a good approach (with or without a concomitant small decrease in the sodium conductance), but the effects of low calcium on contraction need to be addressed.

To validate or dispute such approaches to arrhythmia prevention, additional studies of the dynamics of these and other breakup mechanisms in realistic cardiac geometries including variations in cell types is needed. In some cases, the parameter regimes in which the breakup occurs may be widened, making the breakup easier to occur. In other cases, structural effects may vary the roles of a breakup mechanism and conceivably new breakup mechanisms will emerge.

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APPENDIX

In this appendix, we describe the simplified ionic model introduced in Sec. III and used through this manuscript (unless specifically noted otherwise) to simulate cardiac electrical dynamics. The dynamics of the transmembrane potential V_m is governed by the cable equation $\partial_t V(\mathbf{x},t) = \nabla \cdot (D \nabla V) - (I_{\text{fi}}(V,v) + I_{\text{so}}(V) + I_{\text{si}}(V,w))/C_m$, where the ionic currents determine cell dynamics, C_m represents the membrane capacitance (set to $1 \mu\text{F}/\text{cm}^2$), and the diffusion tensor D

defines tissue structure and anisotropy described in Sec. VI. Except for the last two mechanisms, all simulations are isotropic, so that D is a diagonal matrix whose off-diagonal elements are 0 and whose diagonal elements are $0.001 \text{ cm}^2/\text{ms}$. This is the most commonly used value in the literature, but it assumes a surface to volume ratio of 5000/cm, corresponding to a fairly small cell radius of around $4 \mu\text{m}$.⁹⁶ The two gate variables of the model, v and w , follow first order equations in time:

$$\partial_t v(\mathbf{x},t) = (1-p)(1-v)/\tau_v^-(V) - p v / \tau_v^+(V),$$

$$\partial_t w(\mathbf{x},t) = (1-p)(1-w)/\tau_w^-(V) - p w / \tau_w^+(V),$$

where $\tau_v^-(V) = (1-q)\tau_{v1}^-(V) + q\tau_{v2}^-(V)$ and

$$p = \begin{cases} 1 & \text{if } V \geq V_c \\ 0 & \text{if } V < V_c \end{cases}, \quad q = \begin{cases} 1 & \text{if } V \geq V_v \\ 0 & \text{if } V < V_v \end{cases}.$$

The two gate variables and the transmembrane potential vary from 0 to 1. Therefore, when comparing with other models or experiments, V_m needs to be rescaled, as shown in Fig. 3. The three currents are given by the following:

$$I_{\text{fi}}(V,v) = -v p (V - V_c) (1 - V) / \tau_d,$$

$$I_{\text{so}}(V) = V (1 - p) / \tau_0 + p / \tau_r, \text{ and}$$

$$I_{\text{si}}(V,w) = -w (1 + \tanh(k(V - V_c^{\text{si}}))) / (2 \tau_{\text{si}}).$$

Although we refer to this model as the 3V-SIM because it consists of three variables, there are two variations we commonly use, one with two variables (obtained by eliminating gate variable w and the I_{si} current), which produces simple flat APD restitution models as in sets 2 and 7. The second variation, as mentioned in Sec. III, replaces the steady-state function $d_\infty(V)$ given by $(1 + \tanh(k(V - V_c^{\text{si}})))$ with a gate variable d , which is used to reproduce more accurately the AP shapes of other models,^{44,69} as shown in Figs. 3(a) and 3(b).

In Sec. IV an extra current is added in order to obtain a biphasic APD restitution curve. This current is used in conjunction with parameter set 8 and an extra variable denoted here as y and obeying the following:

$$I_{\text{biph}} = pp(y) * 0.355 / \tau_r,$$

where $pp(y) = 1$ for $y > 0.1$ and $pp(y) = 0$ otherwise, and

TABLE I. Parameter values used for the 3V-SIM to produce the simulations included in this study.

Parameter	Set 1	Set 2	Set 3	Set 4	Set 5	Set 6	Set 7	Set 8	Set 9	Set 10
τ_v^+	3.33	10	3.33	3.33	3.33	3.33	10	13.03	3.33	10
τ_{v1}^-	19.6	10	19.6	15.6	12	9	7	19.6	15	40
τ_{v2}^-	1000	10	1250	5	2	8	7	1250	2	333
τ_w^+	667	...	870	350	1000	250	...	800	670	1000
τ_w^-	11	...	41	80	100	60	...	40	61	65
τ_d	0.25	0.25	0.25	0.407	0.362	0.395	0.25	0.45	0.25	0.115
τ_0	8.3	10	12.5	9	5	9	12	12.5	12.5	12.5
τ_r	50	190	33.33	34	33.33	33.33	100	33.25	28	25
τ_{si}	45	...	29	26.5	29	29	...	29	29	22.22
k	10	...	10	15	15	15	...	10	10	10
V_c^{si}	0.85	...	0.85	0.45	0.70	0.50	...	0.85	0.45	0.85
V_c	0.13	0.13	0.13	0.15	0.13	0.13	0.13	0.13	0.13	0.13
V_v	0.055	...	0.04	0.04	0.04	0.04	...	0.04	0.05	0.025

$$\partial_t y(\mathbf{x}, t) = (1-p)(1-y)/400 - py/25.$$

The 13 model parameters used in the various examples are given in Table I. Further description of model parameters and their functions can be found in Ref. 87. We note that the numbering of the sets is purely for convenience, and does not indicate that a given parameter set corresponds to any particular breakup mechanism(s).

To calculate APD restitution curves, we used an S1–S2 protocol in a 1D cable. Since the 3V-SIM does not incorporate memory effects, the restitution curve obtained is independent of the protocol used. Therefore, restitution curves were measured by initiating an S1 stimulus from rest, and then the DI preceding the S2 stimulus was varied to obtain points on the curve. Linear interpolation was used to provide the precise time associated with the voltage cutoff of 80% repolarization. CV restitution curves were calculated in a similar manner in 1D cables using points away from the stimulus site to avoid stimulus artifact. Linear interpolation again was used in determining all times because the velocity depends sensitively on the time measurements. In some cases, smaller value of Δt were used to calculate CV restitution curves to attain more accurate velocities.

All simulations were performed using an exact integration scheme for the gate variables and a Crank–Nicolson scheme for the voltage as described in Ref. 41, thus allowing larger time steps compared to the forward Euler scheme. We have verified that similar results can be obtained using forward Euler with $\Delta t = 0.05$ ms. However, it is important to mention that even though all simulations (except for mechanism 10, because of the low coupling effect) are resolved, in some circumstances, such as in the low excitability limit, the tip trajectory regimes as a function of parameters may vary slightly as the time constant for integration is decreased further. That is, a small percentage shift in the range of values of τ_d (excitability) may be needed to obtain results identical to the figures as the time constants for integration are varied. However, the results are valid at the resolutions given throughout this paper.

For the periodic boundary cases, where a cylinder is approximated by making the horizontal direction of a 2D domain periodic, the solution of the tridiagonal matrix in the Crank–Nicolson scheme acquires two additional entries at the corners and becomes cyclic tridiagonal. We solve this matrix by adding corrections to the Thomas algorithm (used in the zero flux boundary conditions) based on the perturbation correction Sherman–Morrison method. Therefore, a tridiagonal matrix of the form

$$A_i^- V_{i-1}^1 + A_i^0 V_i^1 + A_i^+ V_{i+1}^1 = F_i(V_i^{t+\Delta t/2}),$$

$$A_i^- V_{i-1}^2 + A_i^0 V_i^2 + A_i^+ V_{i+1}^2 = 0,$$

$$A_i^- V_{i-1}^3 + A_i^0 V_i^3 + A_i^+ V_{i+1}^3 = 0,$$

where $V_0^1 = V_n^1 = V_n^2 = V_0^3 = 0$ and $V_1^2 = V_n^3 = 1$, has a solution of the form

$$V_i^{t+\Delta t} = V_i^1 + (V_n^1(1-V_1^3) + V_1^1 V_n^3) V_i^2 + V_1^1(1-V_n^2) \\ + V_n^1 V_1^2) V_i^3) / [(1-V_n^2)(1-V_1^3) - V_1^2 V_n^3].$$

For the 1D reductions of target waves in the description of mechanism 2 and the 2D reductions of scroll waves in the description of mechanism 8, where radial coordinates are used, the value at $r=0$ is obtained by approximating the solution of the transmembrane potential to a polynomial; therefore, the radial Laplacian at that point can be approximated locally by $4(V_{1,j} - V_{0,j})/\Delta x^2$.

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