

Programming Language Concepts

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The Heap

- ◆ Two routines provided by a memory manager
 - `p=new(n)`: allocate a memory region of size `n`
 - `delete(p)`: return the memory region to the manager
- ◆ The mem manager tracks
 - what regions have been allocated and their sizes
 - what regions are available for allocation
 - free list
- ◆ *Heap overflow* occurs when a call to *new* occurs and the heap does not have a large enough block available to satisfy the call
 - May happen due to fragmentation

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Memory Management in PLs

- ◆ C/C++: manual memory management
 - programmers manage memory: `malloc/free`, `new/delete`
 - pros: efficient/flexible
 - Cons: error prone; dangling pointers/free twice; memory leak; security risks
- ◆ Java/Lisp/Scheme: automatic memory management (GC)
 - No "delete" operations for programmers
 - GC collects memory of objects that are no longer used
 - pros: programmer convenience (programming at a high level)
 - easier to get the program right; no problem such as dangling pointers
 - cons: inflexible; GC may not be suitable for real-time systems

Scheme Memory Cells

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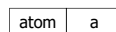
Scheme S-Expressions

- ◆ Symbolic expressions: either an atom or a list
- ◆ Atoms
 - symbols, e.g., `A`, `append`, `name`, etc.
 - numeric literals, e.g., `1`, `3.14`, etc.
 - Booleans, `#t` or `#f`
- ◆ Lists: elements within parenthesis
 - e.g., `(A B C D)`
 - Can be nested; e.g., `(A (B C (D E) F) (G H))`

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Internal Representation of S-Expressions (all pointers)

- ◆ Everything represented by cells
- ◆ Atom cells



- ◆ Cons Cells: for general dotted pairs

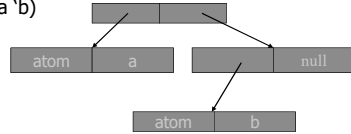


- both `car` and `cdr` are pointers to other cells
- there is a special value for null pointers

Examples

◆Atoms and lists represented by cells

- '(a b) = (list 'a 'b)



Storage Allocation for Lists

- ◆ In Scheme, storage allocation is implicit
- ◆ For atoms: when Scheme encounters an atom, it allocates an atom cell
- ◆ Storage allocation for (cons e1 e2)
 - allocate a new cons cell c
 - allocate cells for e1 and e2 to represent them in mem
 - set the car part of c to point to the representation of e1
 - set the cdr part of c to point to the representation of e2
 - return a pointer to c
 - example: '(a b) = (cons 'a (cons 'b '()))

Implementation of List Operations

◆Implementations of car, cdr, null?, pair?

- (car x): if x points to a cons cell, return the car part; otherwise error
- (cdr x): if x points to a cons cell, return the cdr part; otherwise error
- null?: returns true if it's a null pointer
- pair?: returns true if it points to a cons cell
- atom? = not pair? and not null?

The representations can represent more than lists

- (cons 'a 'b): not a list, but can still be represented
 - The representation can in general represent binary trees



- This is in general called dotted pairs
- This can be used to represent, for example, trees
- list? decides whether something is a proper list: keep applying cdr will always returns a list
 - (list? (cons 'a 'b)) = #f

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Garbage Collection (Ch 8.5.3)

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Garbage Collection

◆Garbage:

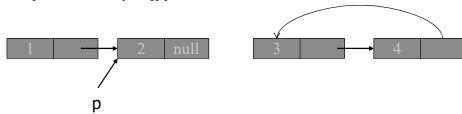
At a given point in the execution of a program P , a memory location m is *garbage* if no continued execution of P from this point can access location m .

◆Scheme: automatic garbage collection

- memory: a list of cells
 - A free list tracks what the unused cells are
- When the running program needs new cells, they are from the free list
- When the free list is below some threshold, the run-time system performs GC to reclaim garbage cells
 - Detect garbage during program execution

A Running Example

```
(define p '(1 2 3 4))  
(define p (cdr p))  
(set-cdr! (caddr p) (cdr p))  
(set-cdr! p '())
```



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Mark-and-Sweep Algorithm (BFS or DFS)

◆ Need

- One tag bit for each cell
- List of memory cells directly accessible to the program
 - Called the root set

◆ Algorithm

- Initialization: set all tag bits to 0.
- First pass (mark): start from each cell in the root set; follow all pointers; change tag bits of reachable cells to 1
- Second pass (sweep): place all cells with tag = 0 on the free list

◆ Pros: straightforward

- ◆ Cons: two passes; need to stop the program from running; poor real time performance

Reference Counting

- ◆ Each cell has a reference count (RC).
 - It records the number of references that point to the cell
- ◆ Initialize the reference counts when a data structure is first created
- ◆ For an operation involving pointers, like (define q p)
 - The reference count for p's node is increased by 1
 - the reference count for q's node is decreased by 1
 - If it becomes 0, reclaim it to the free list and decrease the reference count of anything it points to; maybe a snowball effect
 - q's value get p's value

But not all garbage is collected...

◆ Cons

- Cannot reclaim circular data structures
- Space overhead
- Runtime overhead for reference account adjustments

◆ Pros

- GC work is divided
 - Occurs whenever mem is allocated or during pointer assignments
- better real-time performance

Copy Collection

- ◆ Heap partitioned into two halves
 - From space, to space
 - Only the from space is active
- ◆ All allocation is performed in the from space
- ◆ When GC starts,
 - Reachable nodes in the from space copied to the to space
 - Swap the from and the to space
 - Note: The accessible nodes are packed, orphans are returned to the free_list, and the two halves reverse roles.
- ◆ Pros: Faster than mark-sweep; reduce storage fragmentation
- ◆ Cons: reduces the size of the heap space

Garbage Collection Summary

- Modern algorithms are more elaborate.
 - Most are hybrids/refinements of the above three.
- Functional languages have garbage collection built-in
 - Rely on GC to destroy old values
- In Java, garbage collection is built-in.
 - runs as a low-priority thread.
 - Also, System.gc may be called by the program
- C/C++ default garbage collection to the programmer.